# Normalizing Flow history



**General coupling layer** Let  $x \in \mathcal{X}$ ,  $I_1$ ,  $I_2$  a partition of [1, D] such that  $d = |I_1|$  and m a function defined on  $\mathbb{R}^d$ , we can define  $y = (y_{I_1}, y_{I_2})$  where:

$$egin{aligned} y_{I_1} &= x_{I_1} \ y_{I_2} &= g(x_{I_2}; m(x_{I_1})) \end{aligned}$$

where  $g: \mathbb{R}^{D-d} \times m(\mathbb{R}^d) \to \mathbb{R}^{D-d}$  is the *coupling law*, an invertible map with respect to its first argument given the second. The corresponding computational graph is shown Fig 2. If we consider  $I_1 = [\![1,d]\!]$  and  $I_2 = [\![d,D]\!]$ , the Jacobian of this function is:

$$\frac{\partial y}{\partial x} = \begin{bmatrix} I_d & 0\\ \frac{\partial y_{I_2}}{\partial x_{I_1}} & \frac{\partial y_{I_2}}{\partial x_{I_2}} \end{bmatrix}$$

Where  $I_d$  is the identity matrix of size d. That means that  $\det \frac{\partial y}{\partial x} = \det \frac{\partial y_{I_2}}{\partial x_{I_2}}$ . Also, we observe we can invert the mapping using:

$$x_{I_1} = y_{I_1}$$
  
 $x_{I_2} = g^{-1}(y_{I_2}; m(y_{I_1}))$ 

We call such a transformation a coupling layer with coupling function m.

Additive coupling layer For simplicity, we choose as coupling law an additive coupling law g(a;b) = a + b so that by taking  $a = x_{I_2}$  and  $b = m(x_{I_1})$ :

$$y_{I_2} = x_{I_2} + m(x_{I_1}) \ x_{I_2} = y_{I_2} - m(y_{I_1})$$

#### 2014

Dinh, Laurent, David Krueger, and Yoshua Bengio. "Nice: Non-linear independent components estimation."

$$y_{1:d} = x_{1:d}$$
 (4)

$$y_{d+1:D} = x_{d+1:D} \odot \exp(s(x_{1:d})) + t(x_{1:d}),$$
 (5)

where s and t stand for scale and translation, and are functions from  $R^d \mapsto R^{D-d}$ , and  $\odot$  is the Hadamard product or element-wise product (see Figure 2(a)).

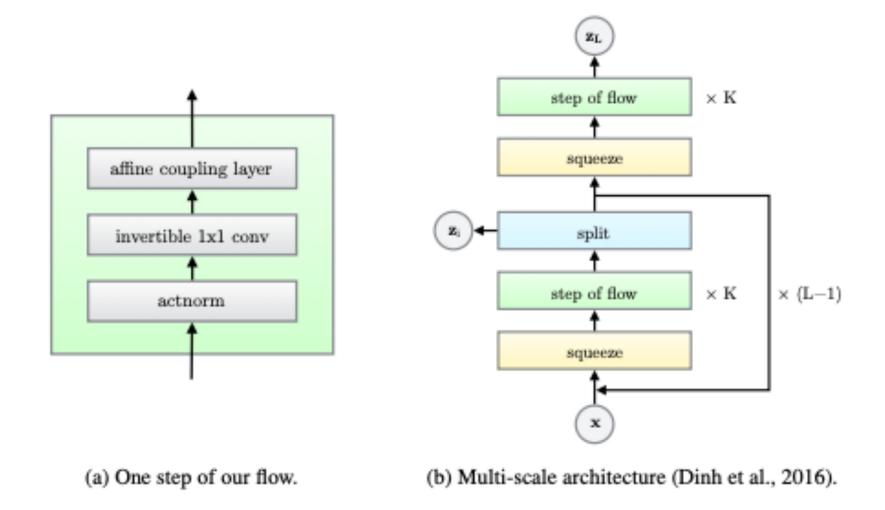
#### 3.3 Properties

The Jacobian of this transformation is

$$\frac{\partial y}{\partial x^{T}} = \begin{bmatrix} \mathbb{I}_{d} & 0\\ \frac{\partial y_{d+1:D}}{\partial x_{1:d}^{T}} & \operatorname{diag}\left(\exp\left[s\left(x_{1:d}\right)\right]\right) \end{bmatrix}, \tag{6}$$

### 2016

Dinh, Laurent, Jascha Sohl-Dickstein, and Samy Bengio. "Density estimation using real nvp."



## 2018

Kingma, Durk P., and Prafulla Dhariwal.

"Glow: Generative flow with invertible 1x1 convolutions."