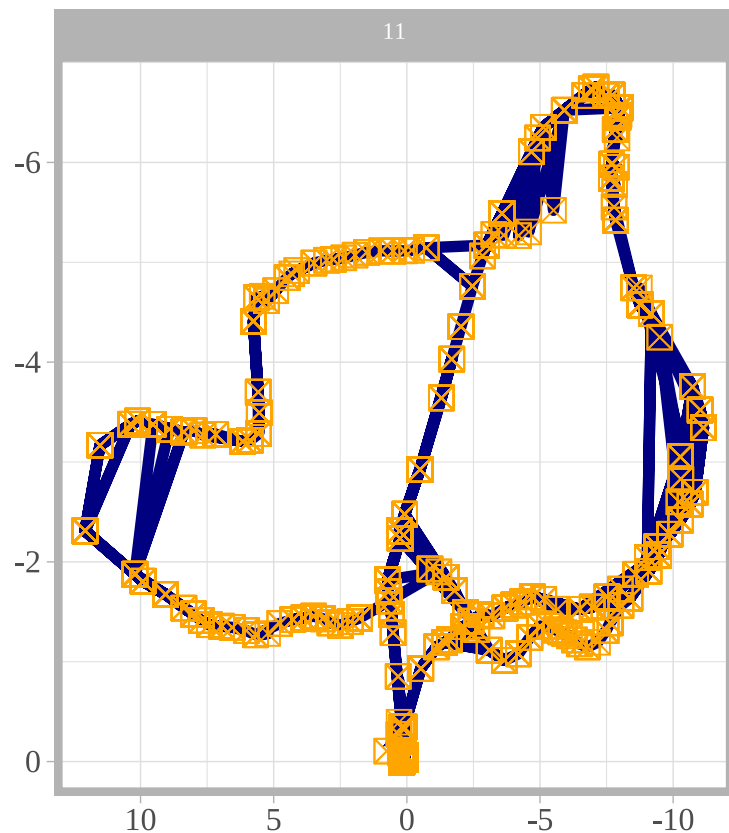
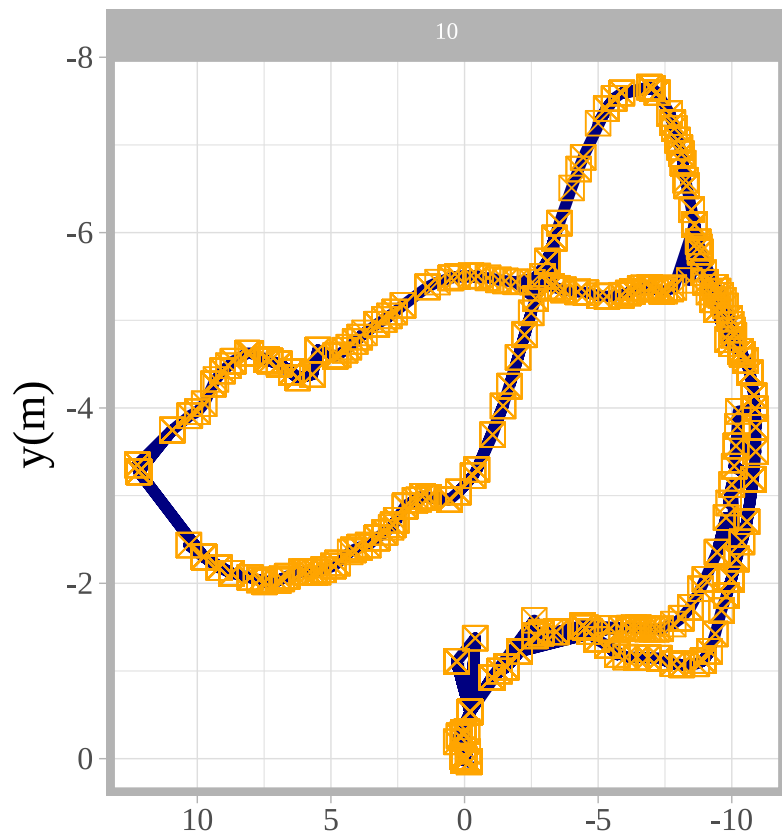


Estimated Trajectory



x(m)