

Algorithms: Design and Analysis, Part II

The Bellman-Ford Algorithm

Space Optimization

Quiz

Question: how much space does the basic Bellman-Ford algorithm regaine? [pick the strongest true statement.] [m= #& edges, n= #& vertices] (A) O(N2) - O(1) for each of N2 subproblems O(mn) Q (n3) (D (m2)

Predecessor Pointers

Note: only need the ACi-1,v]'s to compute the ACi,v]'s.

=> only need O(h) to remember the current and last rounds of subproblems

Conly O(1) per destination!)

Concern: without a filled-in table, how do ne reconstruct the actual Shortest paths?

Exercise:

Find analogous

uptimizations

for our

previous

Of algorithms

Computing Predecessor Pointers

Idea: comprée a second take B, where B(i,v) = 2nd-to-last vertex on a shortest s->v path with & i edges. (or NULL if no such paths exist)

("predecessor pointers")

locantination : Account the input araph 6 has no

leconstruction: Assume the input graph (has no regative cycles and we correctly compute the BLivi's.

Then: tracing back predicescor pointers — the BLN-1, vi's —

From u to s yields a shortest s-v path.

Correctives from opinal substructive of shortest paths)

Computing Predecessor Pointers

le call: A[i,v] = min (A[i-1,v]) Base case: & (0'N)= NULL To comple BLind with 170: for all veV Case 1: BSi,v] = BSi-1,v] Case 2: wachieving the minimum cie, therew last hop)

Correctness: composation of Asi, is brute-force search

(hough the (1+ in-deger)) possible optimal solutions, BSi, is just

(aching the last hop

To reconstruct a regarine-cost cycle:

breconstruct a regative-cost cycle: use depth-first search to check for a cycle of predecessor on the pointers after each rand (must be a negative cost cycle).