

Coping with NP-completeness: Approximation Algorithms

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Advanced Algorithms and Complexity
Data Structures and Algorithms

Outline

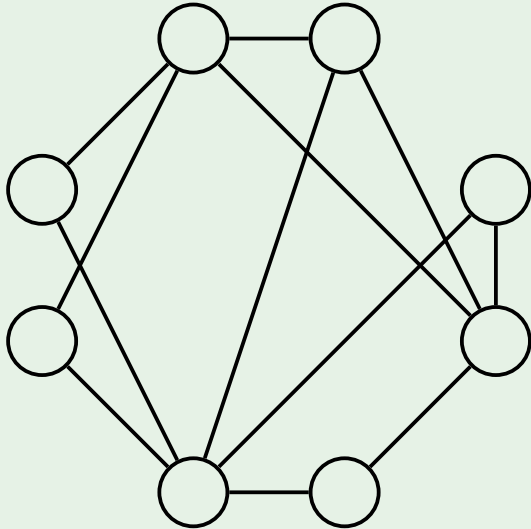
- 1 Vertex cover
- 2 Traveling salesman
 - Metric TSP
 - Local search

Vertex cover (optimization version)

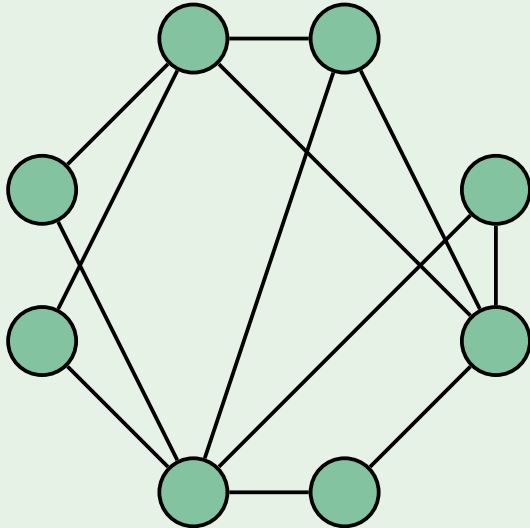
Input: A graph.

Output: A subset of vertices of minimum size that touches every edge.

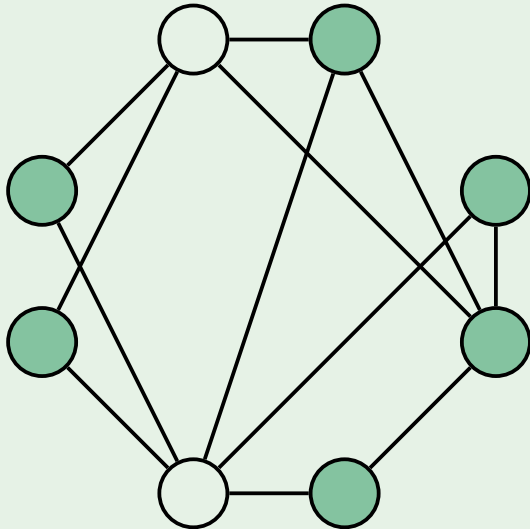
Example



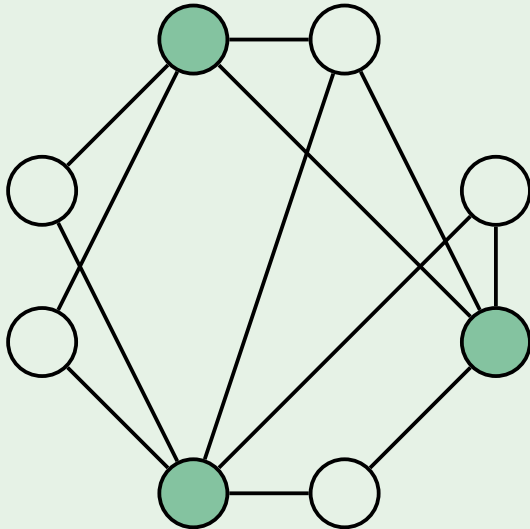
Example



Example



Example



ApproxVertexCover($G(V, E)$)

$C \leftarrow$ empty set

while E is not empty:

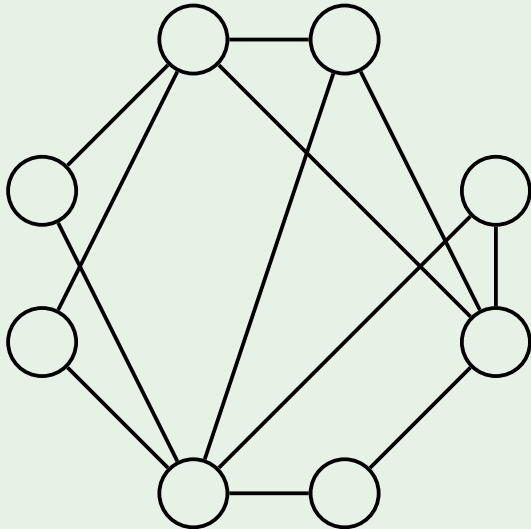
$\{u, v\} \leftarrow$ any edge from E

 add u, v to C

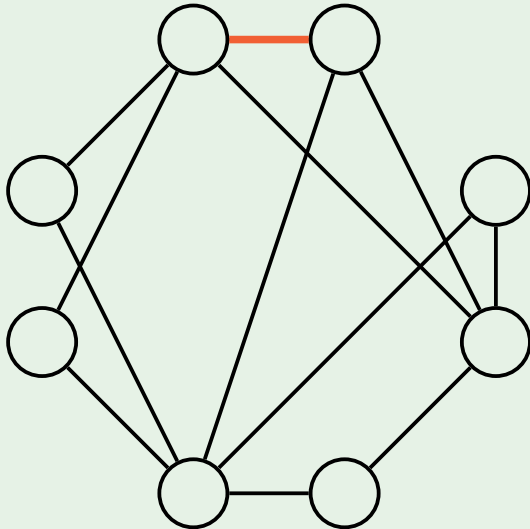
 remove from E all edges incident to u, v

return C

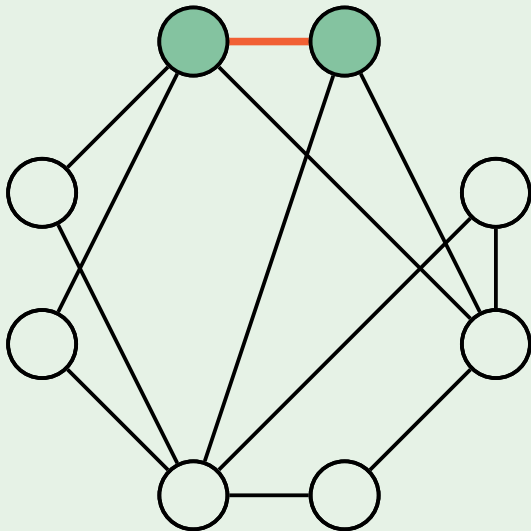
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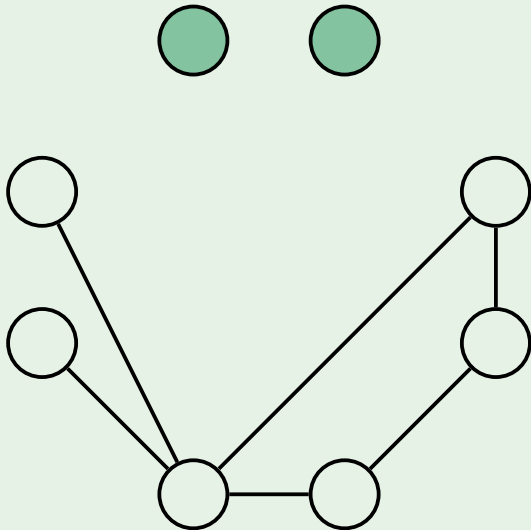
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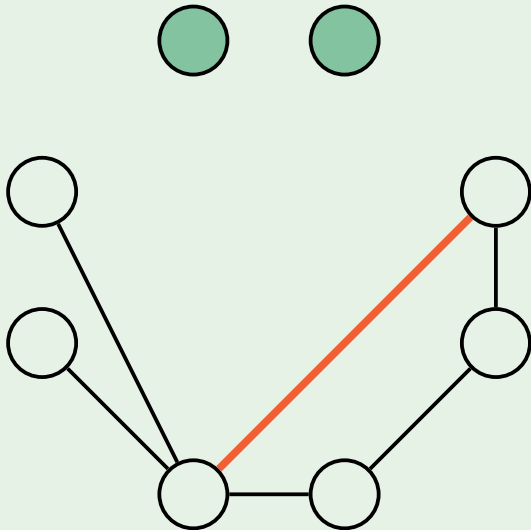
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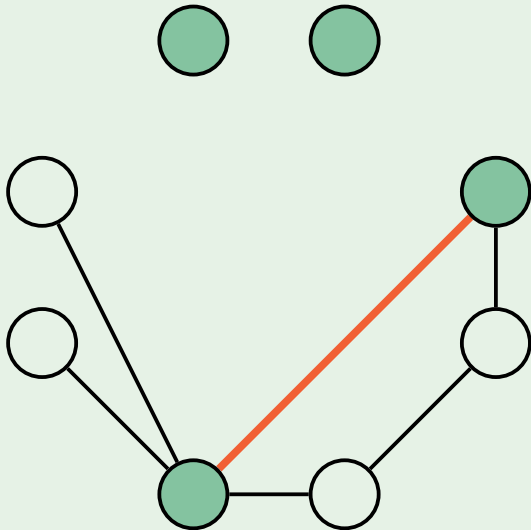
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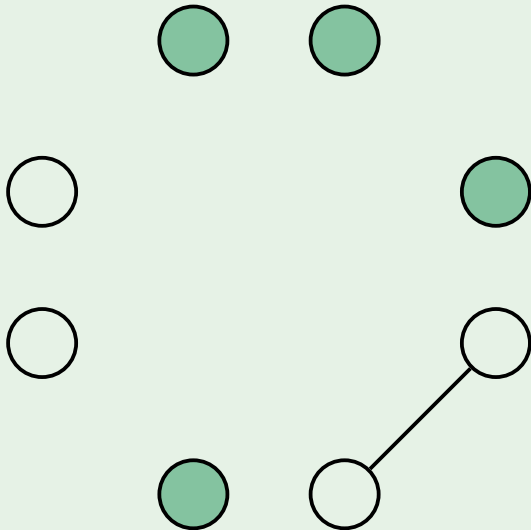
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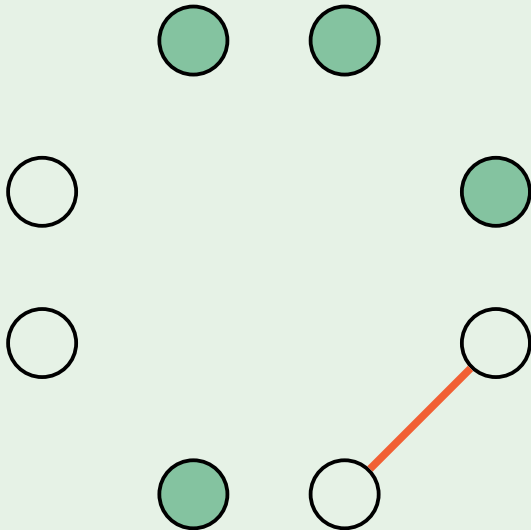
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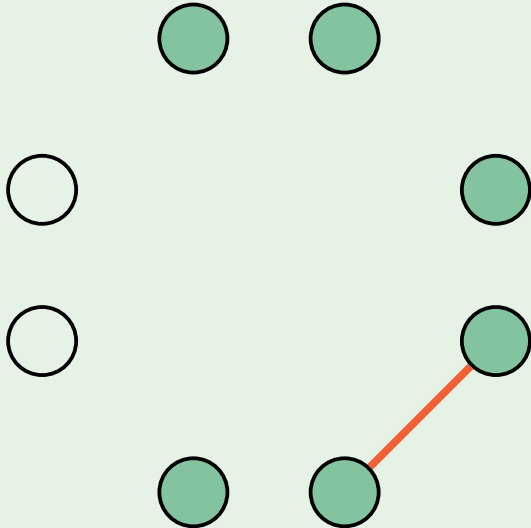
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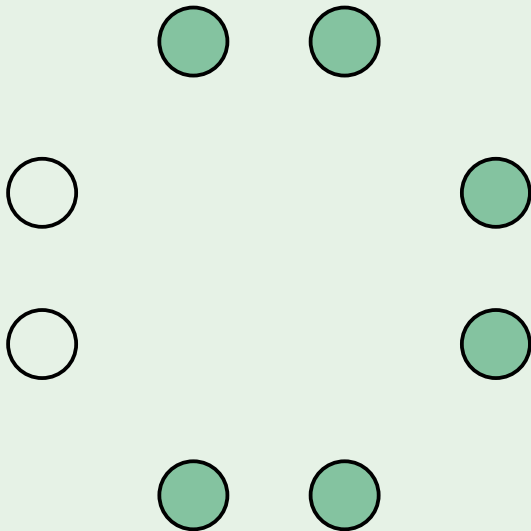
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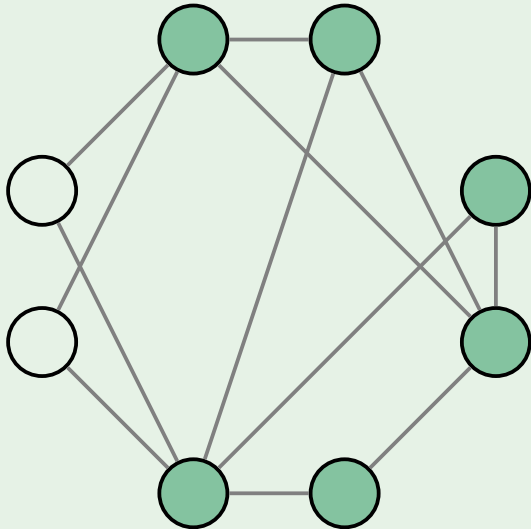
Example



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Lemma

The algorithm `ApproxVertexCover` is 2-approximate: it returns a vertex cover that is at most twice as large as an optimal one and runs in polynomial time.

Proof

- The set M of all edges selected by the algorithm forms a matching

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- Any vertex cover of the graph has size at least $|M|$

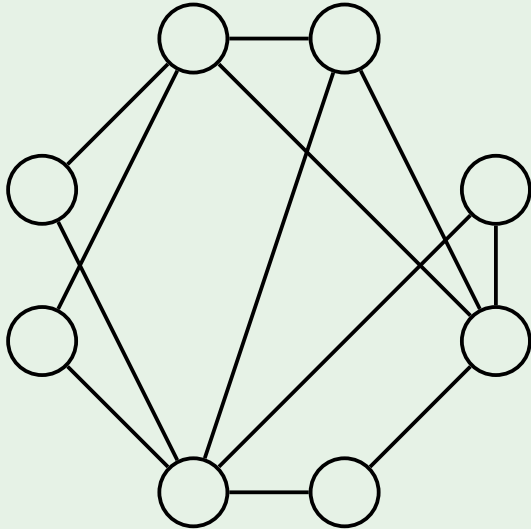
Proof

- The set M of all edges selected by the algorithm forms a matching
- Any vertex cover of the graph has size at least $|M|$
- The algorithm returns a vertex cover C of size $2|M|$, hence

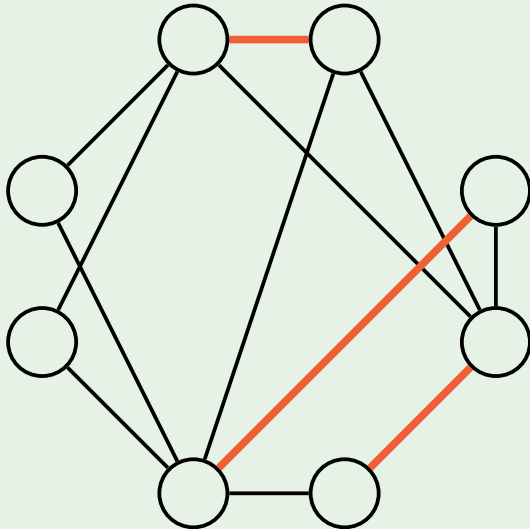
$$|C| = 2 \cdot |M| \leq 2 \cdot \text{OPT}$$



Example



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Summary

- We don't know the value of OPT, but we've managed to prove that

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- This is because we know a **lower bound** on OPT: it is at least the size of any matching

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Final Remarks

- The bound is tight: there are graphs for which the algorithm returns a vertex cover of size twice the minimum size.

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- No 1.99-approximation algorithm is known.

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Metric TSP (optimization version)

Input: An undirected graph $G(V, E)$
with non-negative edge weights
satisfying the triangle inequality:
for all $u, v, w \in V$,
 $d(u, v) + d(v, w) \geq d(u, w)$.

Output: A cycle of minimum total length
visiting each vertex exactly once .

Lower Bound

- We are going to design a 2-approximation algorithm: it returns a cycle that is at most twice as long as an optimal cycle: $C \leq 2 \cdot \text{OPT}$

Lower Bound

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- Since we don't know the value of OPT , we need a good lower bound L on OPT :

$$C \leq 2 \cdot L \leq 2 \cdot \text{OPT}$$

Minimum Spanning Trees

Lemma

Let G be an undirected graph with non-negative edge weights. Then $\text{MST}(G) \leq \text{TSP}(G)$.

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Proof

By removing any edge from an optimum TSP cycle one gets a spanning tree of G . □

ApproxMetricTSP(G)

$T \leftarrow$ minimum spanning tree of G

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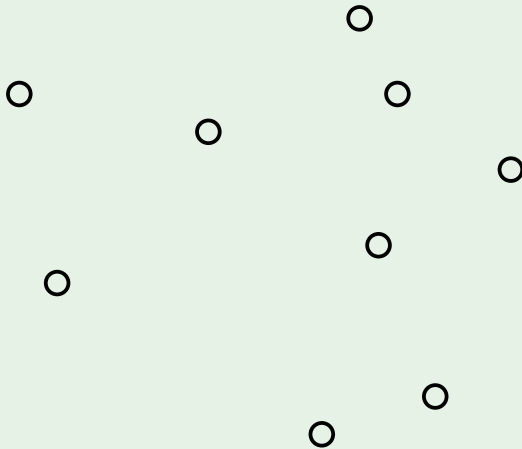
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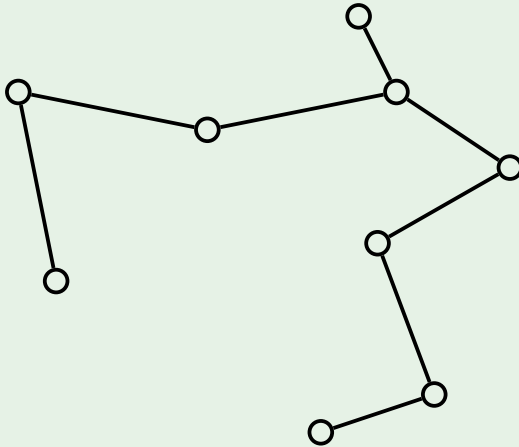
find an Eulerian cycle C in D

return a cycle that visits vertices in
the order of their first appearance in C

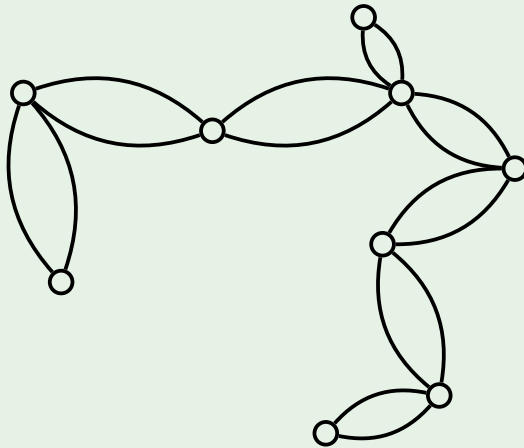
Example: points on a plane



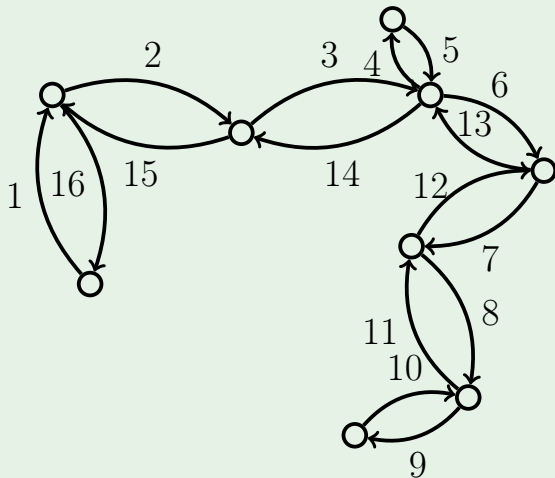
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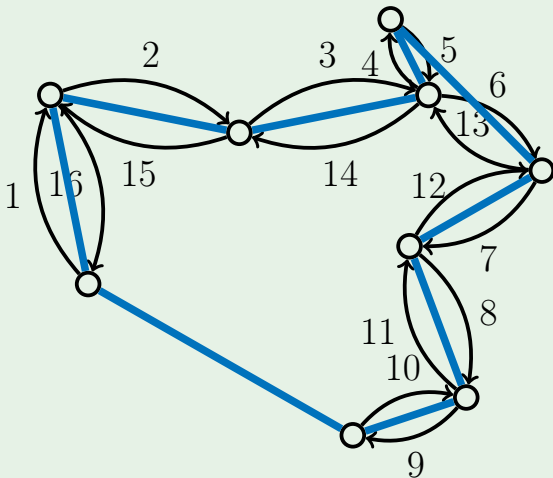
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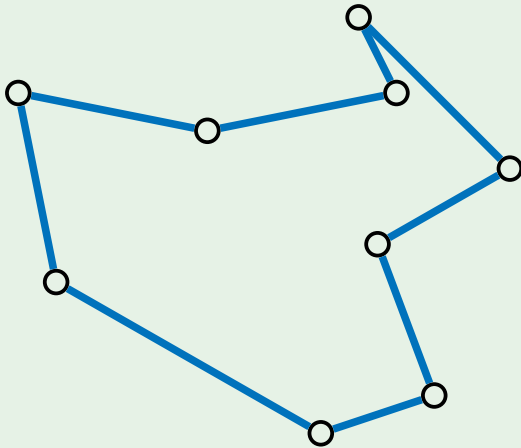
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Proof

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- Bypasses can only decrease the total length. □

Final Remarks

- The currently best known approximation algorithm for metric TSP is Christofides' algorithm that achieves a factor of 1.5

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- The currently best known approximation algorithm for metric TSP is Christofides' algorithm that achieves a factor of 1.5
- If $P \neq NP$, then there is no α -approximation algorithm for the general version of TSP for any polynomial time computable function α

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LocalSearch

$s \leftarrow$ some initial solution

while there is a solution s' in the neighborhood of s
which is better than s :

$s \leftarrow s'$

return s

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- Computes a local optimum instead of a global optimum
- The larger is the neighborhood, the better is the resulting solution and the higher is the running time

Local Search for TSP

- Let s and s' be two cycles visiting each vertex of the graph exactly once

Local Search for TSP

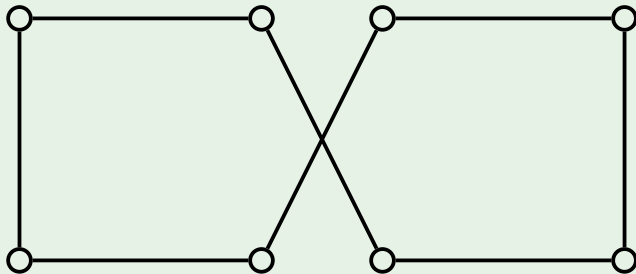
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Local Search for TSP

- Let s and s' be two cycles visiting each vertex of the graph exactly once
- The distance between s and s' is at most d , if one can get s' by deleting d edges from s and adding other d edges
- Neighborhood $N(s, r)$ with center s and radius r : all cycles with distance at most r from s

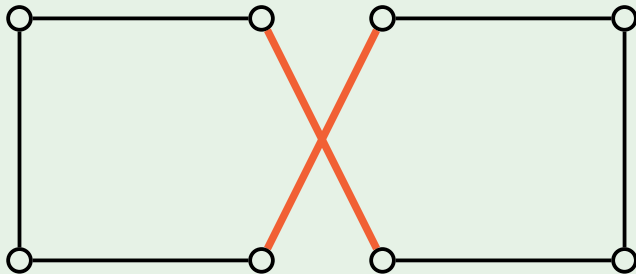
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Changing two edges in a suboptimal solution:



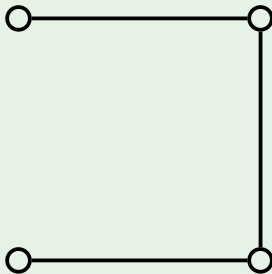
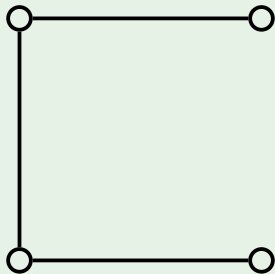
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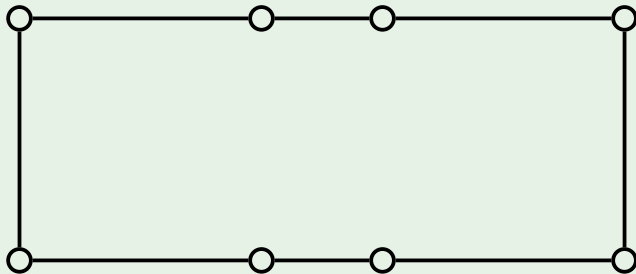
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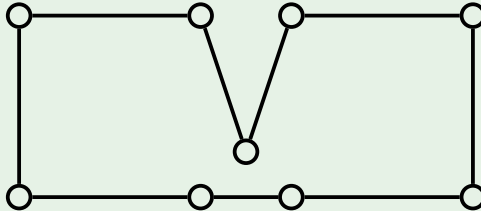
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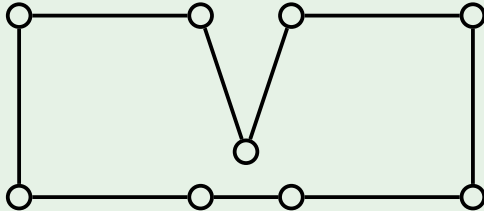
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A suboptimal solution that cannot be improved by changing two edges:



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Need to allow changing three edges to improve this solution

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- Trade-off between quality and running time of a single iteration

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- Trade-off between quality and running time of a single iteration
- Still, the number of iterations may be exponential and the quality of the found cycle may be poor
- But works well in practice

Coping with NP-completeness

- special cases
- intelligent exhaustive search
- approximation algorithms