

A Synchronous Embedding of Antescofo, a Domain-Specific Language for Interactive Mixed Music

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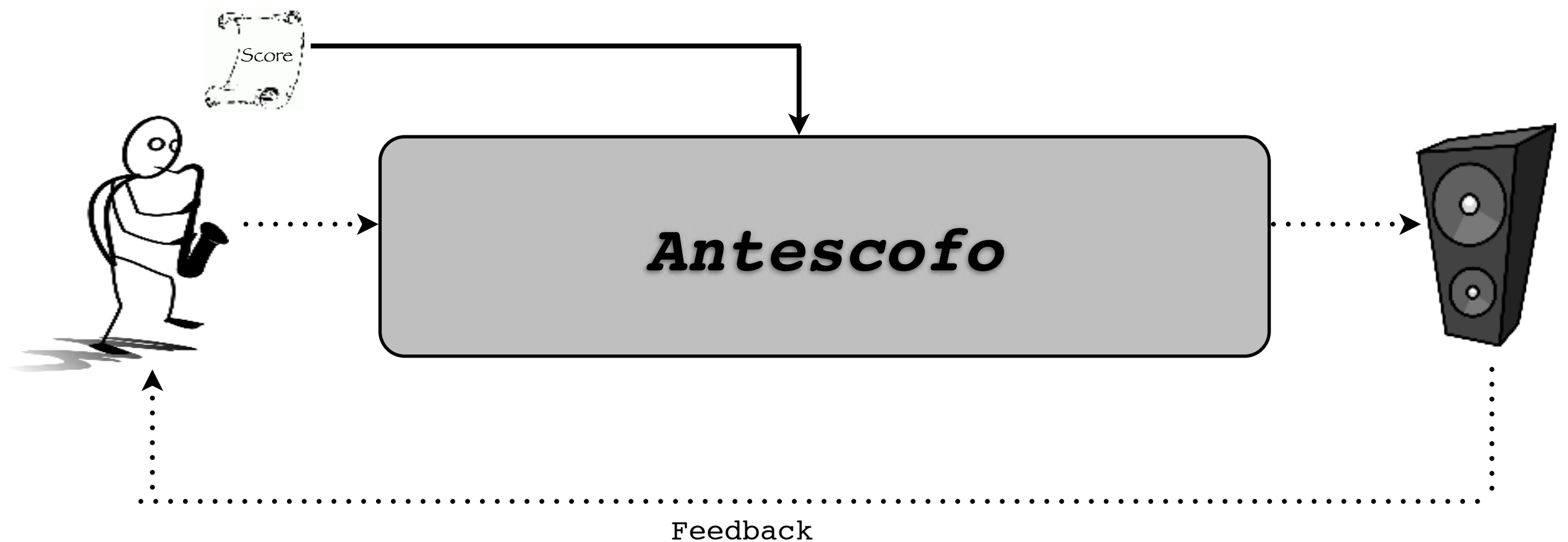
Mixed Music and Antescofo

[Cont 2008]



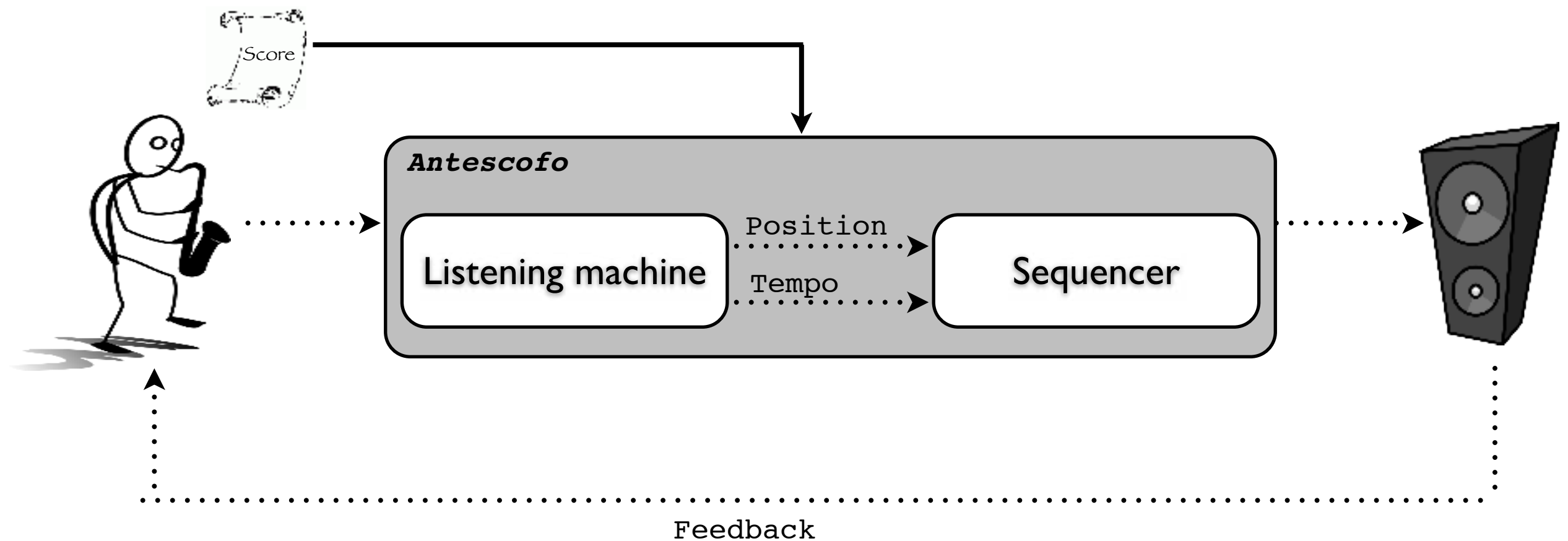
Mixed Music and Antescofo

[Cont 2008]



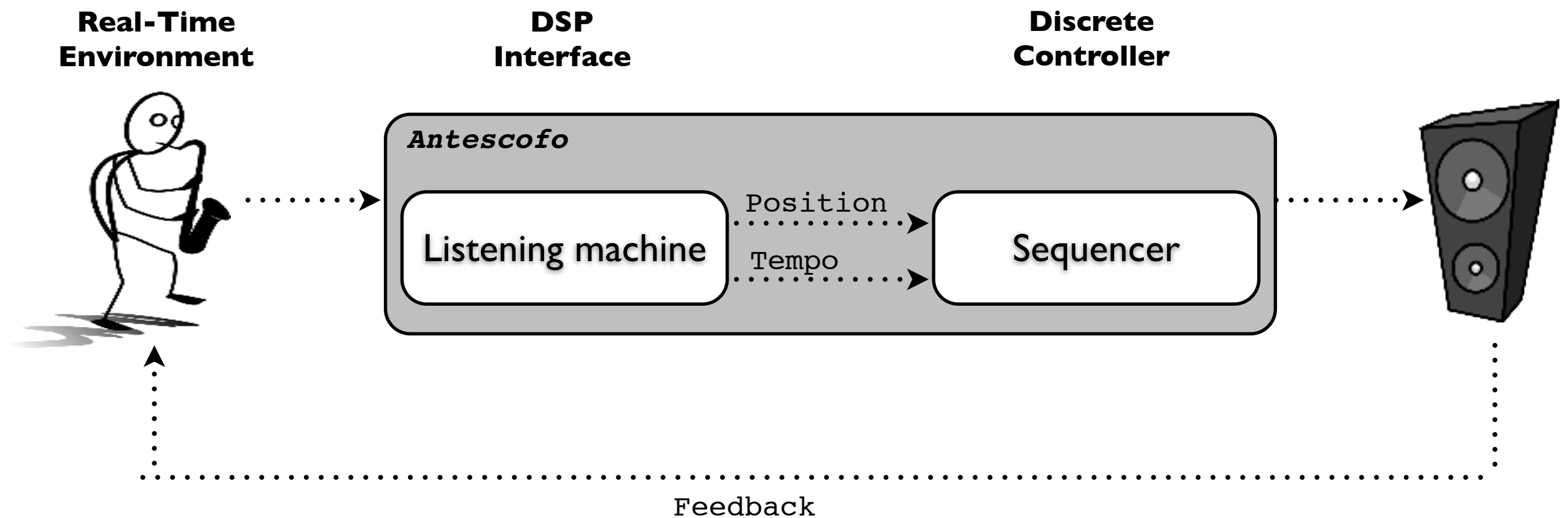
Antescofo Architecture

[Cont 2008]



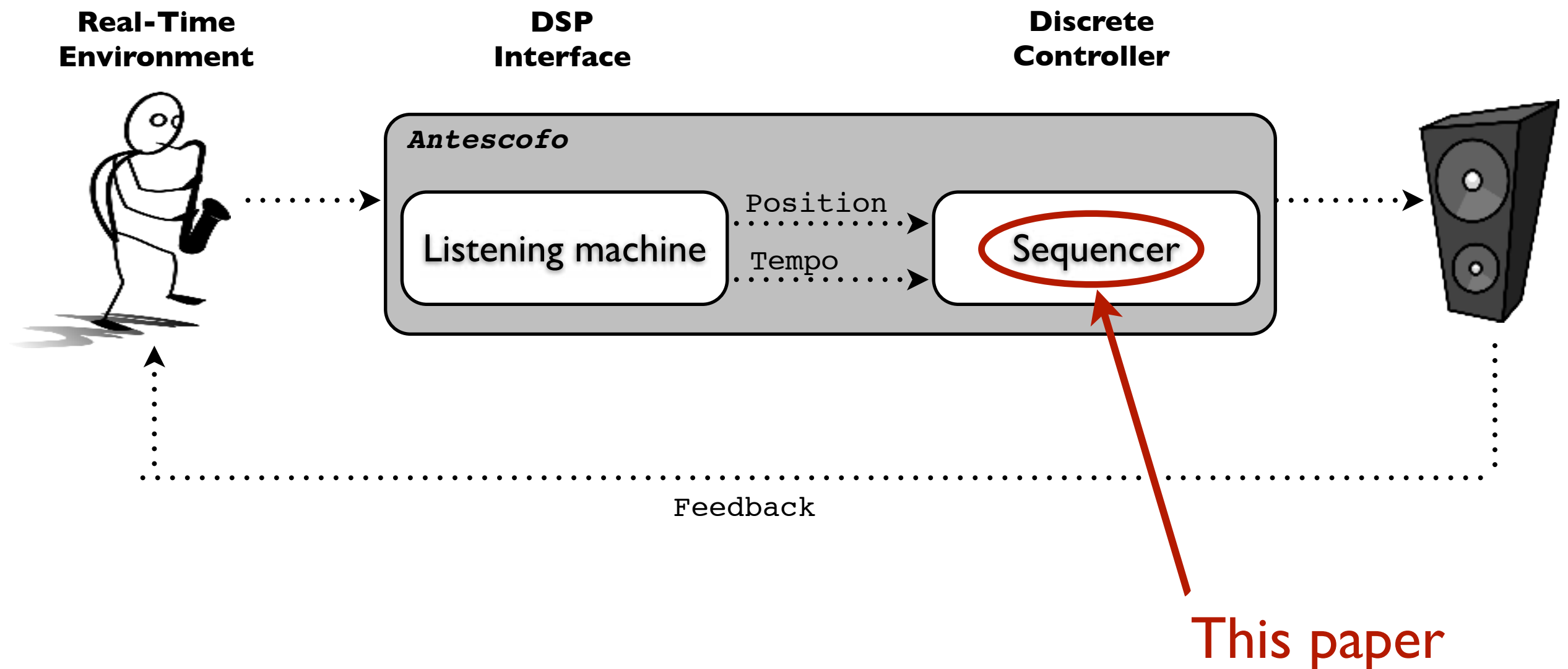
Antescofo Architecture

[Cont 2008]



Antescofo Architecture

[Cont 2008]



I. The Antescofo Language

- Description
- Synchronization and error handling strategies

II. Semantics

- Formalization
- The three predicates

III. Implementation

- Architecture
- Embedding in ReactiveML

The Antescofo Language

The Antescofo Language

Goal: Jointly specify electronic and instrumental parts

[Echeveste et al. 2012]

Libre brusque
(♩ = 92)

Pierre Boulez
(*1925)

(♩ = 92) *rall.* (♩ = 66)

batt. (archet normal)

Violon

f *fff* *mf* *ff*

Spatialization: F -11/-18/-18/2.0

1 2 3 4 5 6 7 8 9

Inf. Rev.

reverb. time: 60"

Spatialization: F -11/-18/-18/2.0

♩ = 90 msec.

Sampl. IR

MIDI: 93 90 85 84 82 80 79 77 76 75 74

reverb. time: 60"

Spatialization: F -11/-18/-18/2.0

Sampler

♩ = 93 msec.

pizz.

MIDI: [74 73 70 69 68 67 66 65]

Spatialization

MR -4/-12/-24/2.0

Freq. Shift.

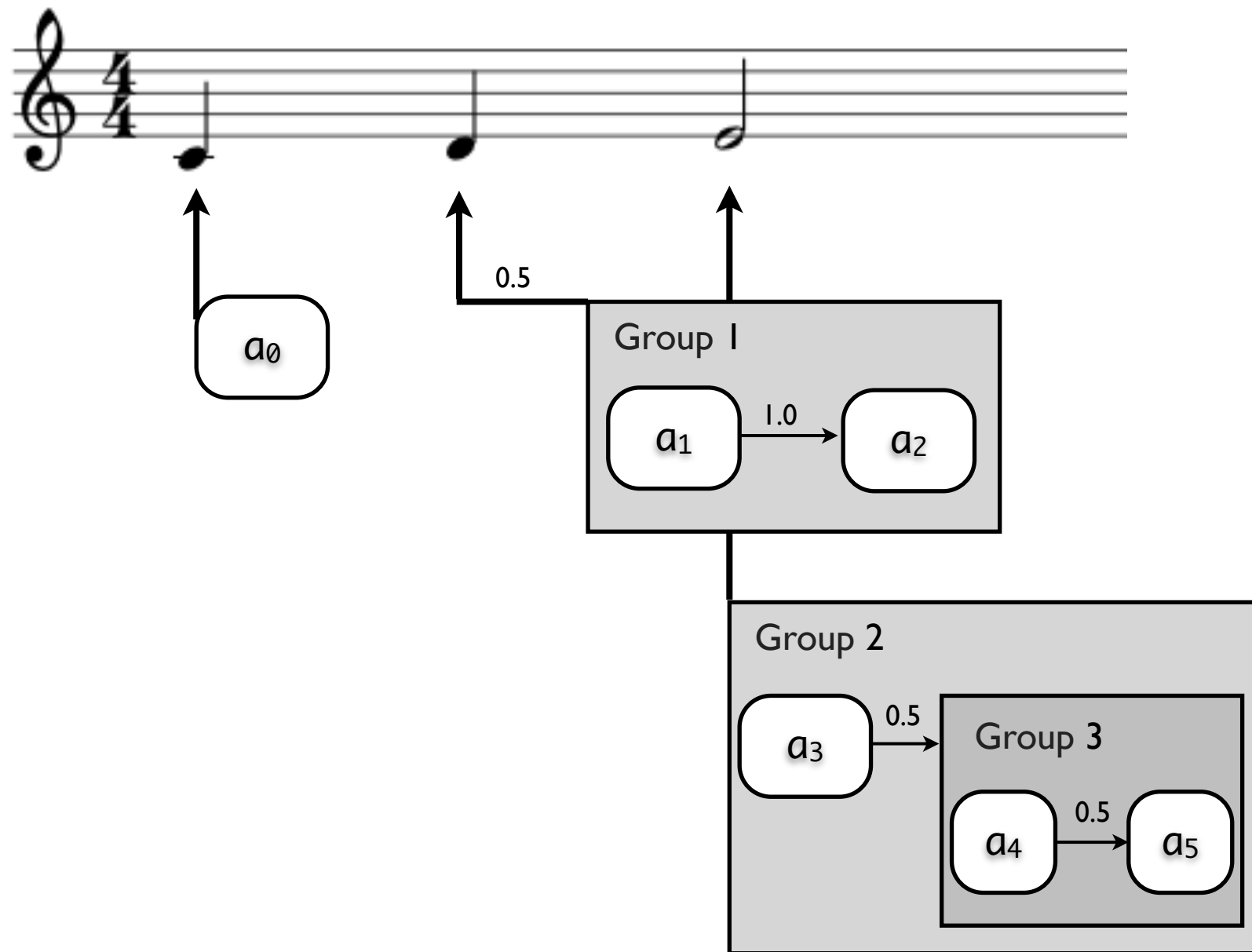
Spatialization

The image displays a musical score for 'Libre brusque' by Pierre Boulez. The score is written for a Violon (violin) and includes electronic parts. The Violon part starts with a tempo of 92 bpm and a dynamic of *f*. It features a series of notes with a 7-measure rest, followed by a *fff* dynamic, then *mf*, and finally *ff*. The electronic parts include 'Inf. Rev.' (reverb time 60"), 'Sampl. IR' (MIDI data: 93 90 85 84 82 80 79 77 76 75 74, reverb time 60"), and a 'Sampler' (MIDI data: [74 73 70 69 68 67 66 65]). The Sampler part includes a tempo of 93 msec and a 'pizz.' (pizzicato) marking. The score also includes spatialization parameters for each part: F -11/-18/-18/2.0 for Violon, Inf. Rev., and Sampl. IR; and MR -4/-12/-24/2.0 for the Sampler. The Freq. Shift part is also present but has no notes. The score is divided into two sections by a vertical dashed line, with a tempo change to 66 bpm in the second section.

The Antescofo Language

Goal: Jointly specify electronic and instrumental parts

[Echeveste et al. 2012]



The Antescofo Language

Goal: Jointly specify electronic and instrumental parts

[Echeveste et al. 2012]

```
NOTE 65 1.0
0.25 GROUP tight partial
    { 1.0 'a_11'
      1.0 'a_12' }

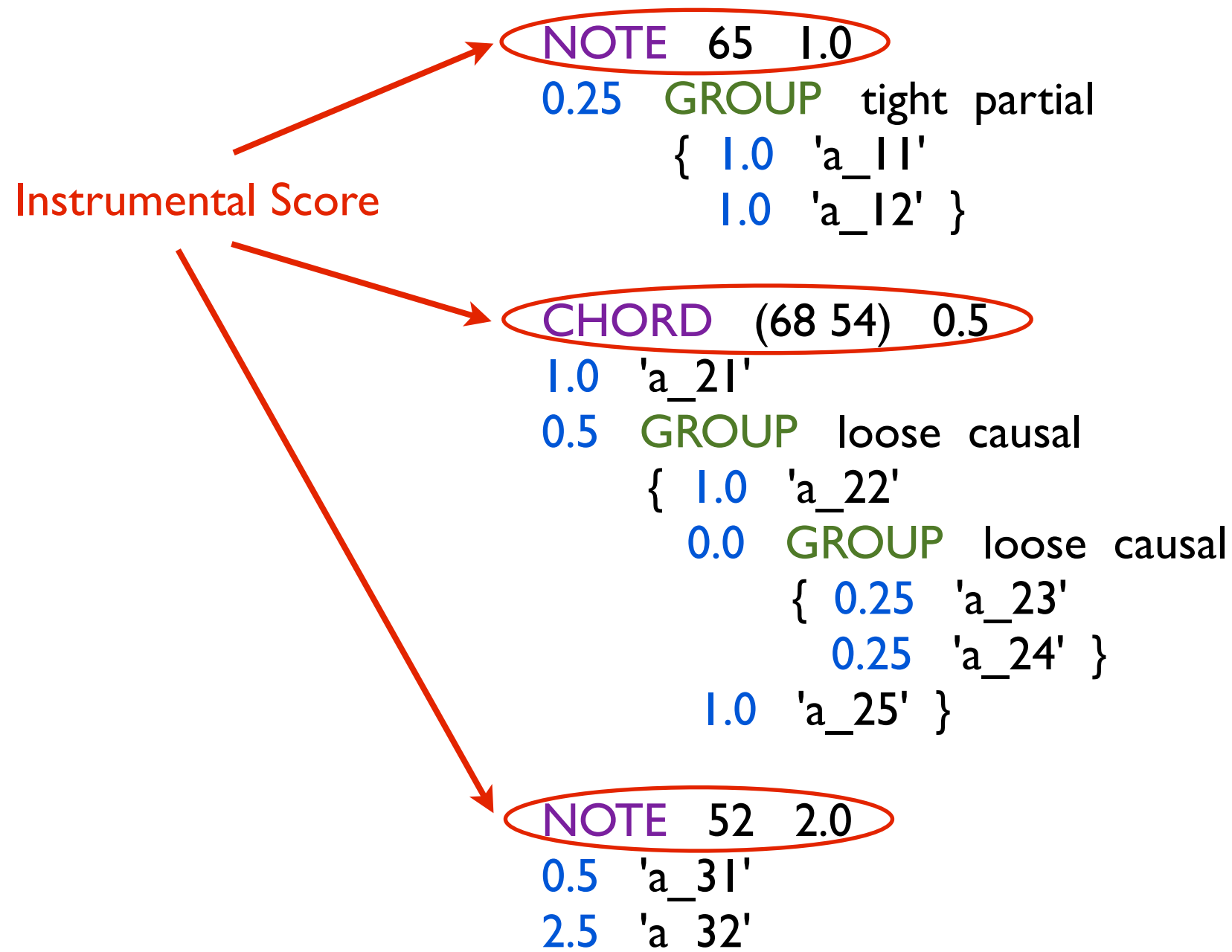
CHORD (68 54) 0.5
1.0 'a_21'
0.5 GROUP loose causal
    { 1.0 'a_22'
      0.0 GROUP loose causal
        { 0.25 'a_23'
          0.25 'a_24' }
      1.0 'a_25' }

NOTE 52 2.0
0.5 'a_31'
2.5 'a_32'
```

The Antescofo Language

Goal: Jointly specify electronic and instrumental parts

[Echeveste et al. 2012]



The Antescofo Language

Goal: Jointly specify electronic and instrumental parts

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0.5 'a_31'
2.5 'a_32'

Electronic Score

The Antescofo Language

Goal: Jointly specify electronic and instrumental parts

[Echeveste et al. 2012]

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    0.25 'a_24' }
  1.0 'a_25' }
```

Delay relative to the tempo

```
NOTE 52 2.0
0.5 'a_31'
2.5 'a_32'
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The Antescofo Language

Goal: Jointly specify electronic and instrumental parts

[Echeveste et al. 2012]

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NOTE 52 2.0
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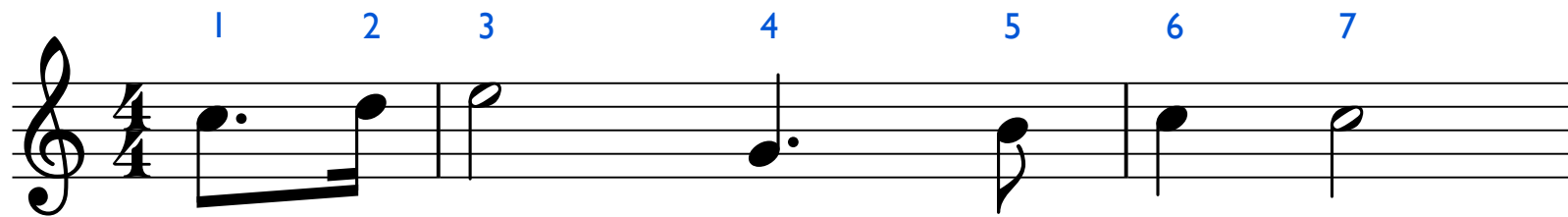
Group Attributes



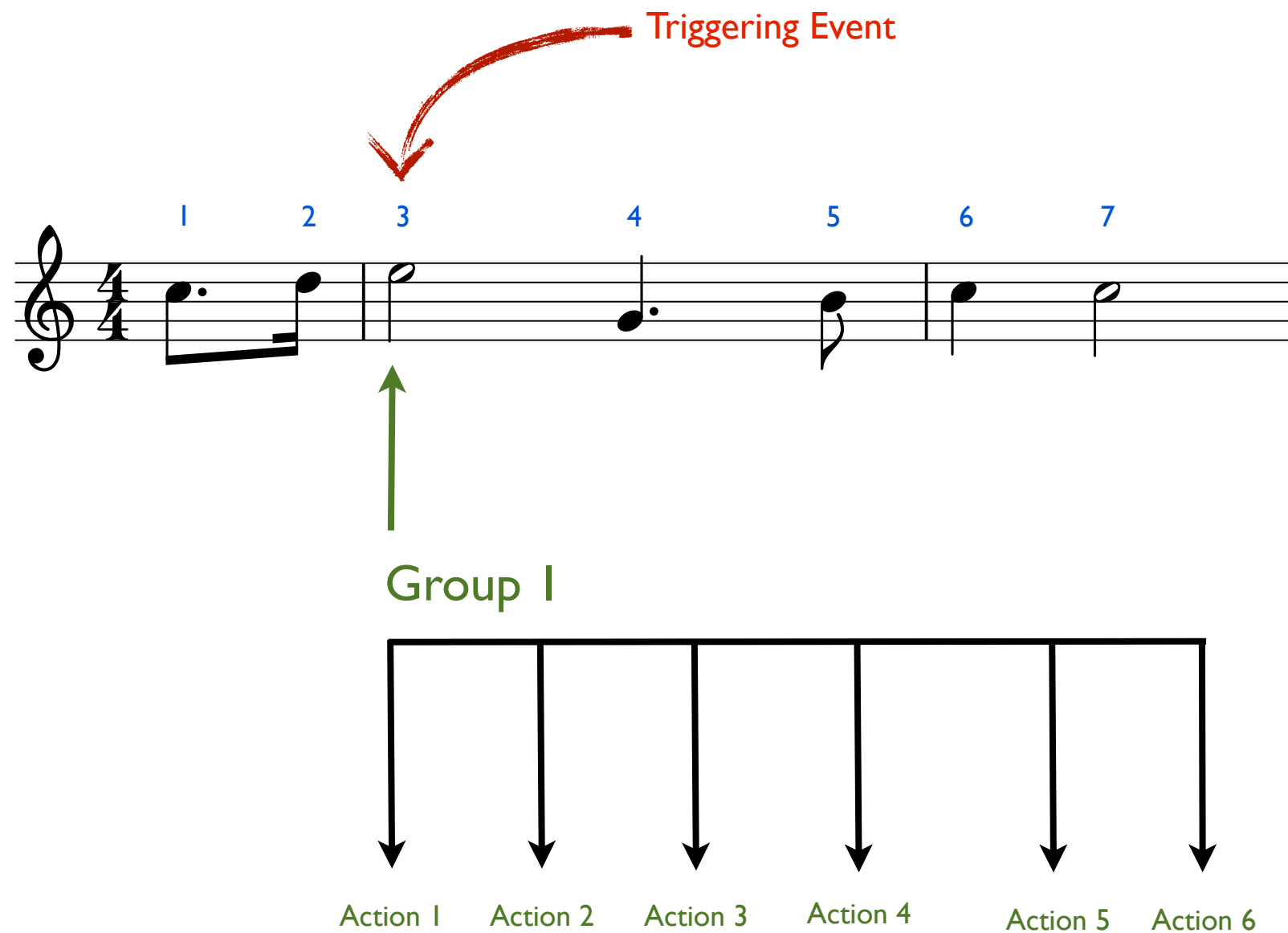
Language Characteristics

- A global logical time relative to the tempo
- Specify electronic actions with:
 - synchronization strategies
 - error handling strategies
- Composer friendly

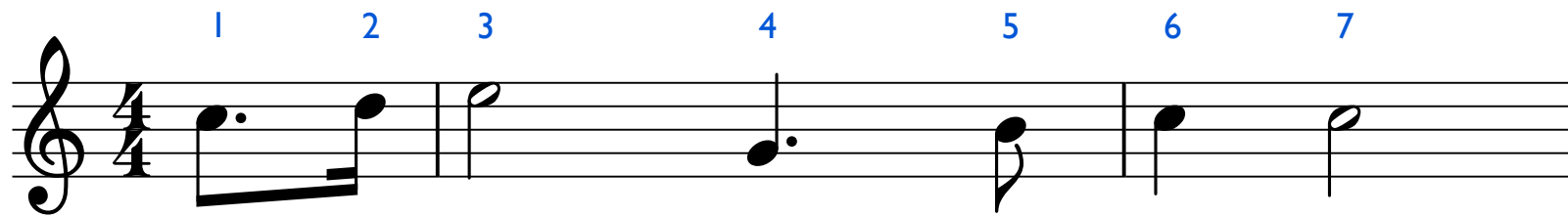
Synchronization Strategies



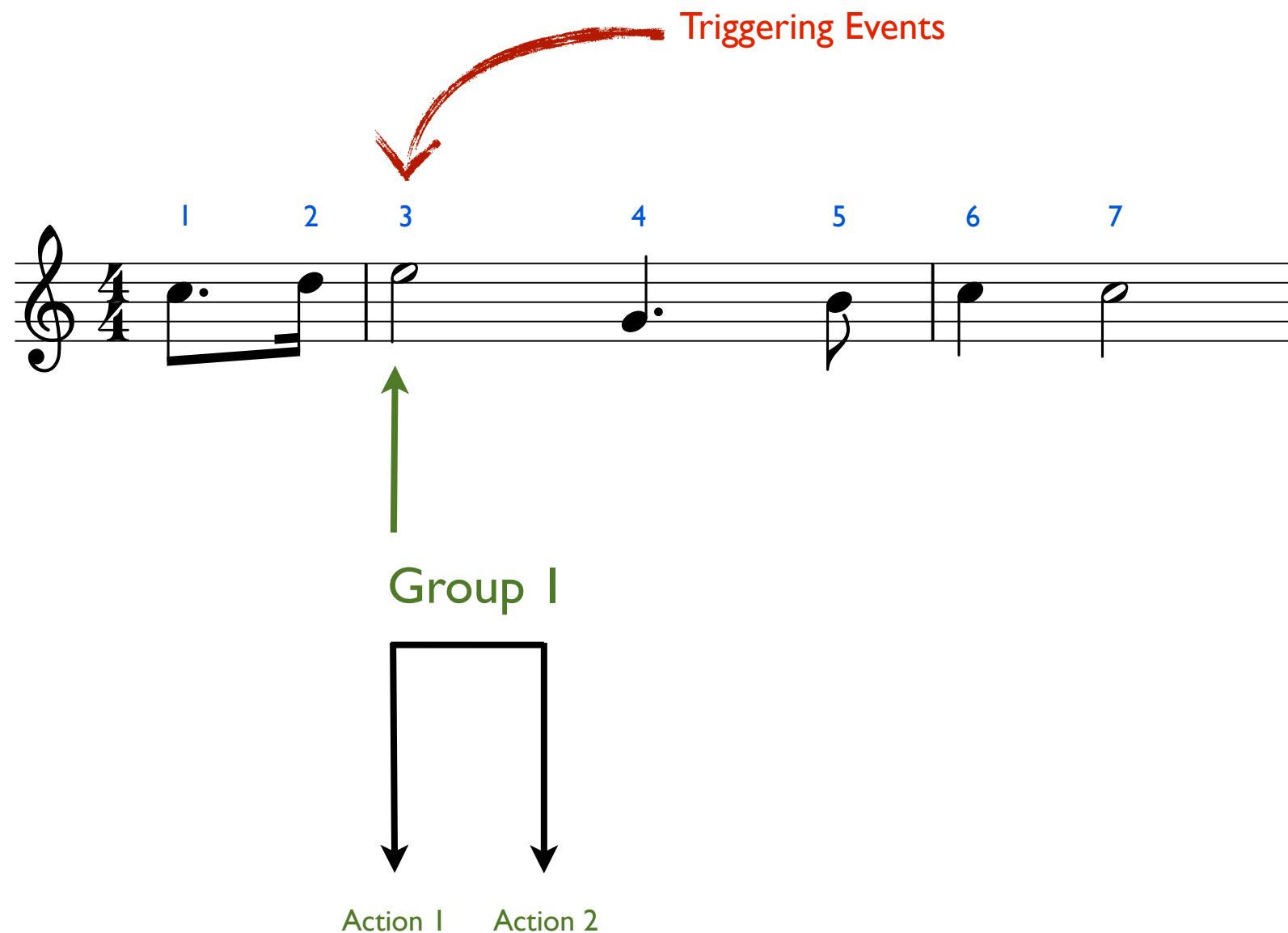
Loose: Synchronization
with the tempo stream.



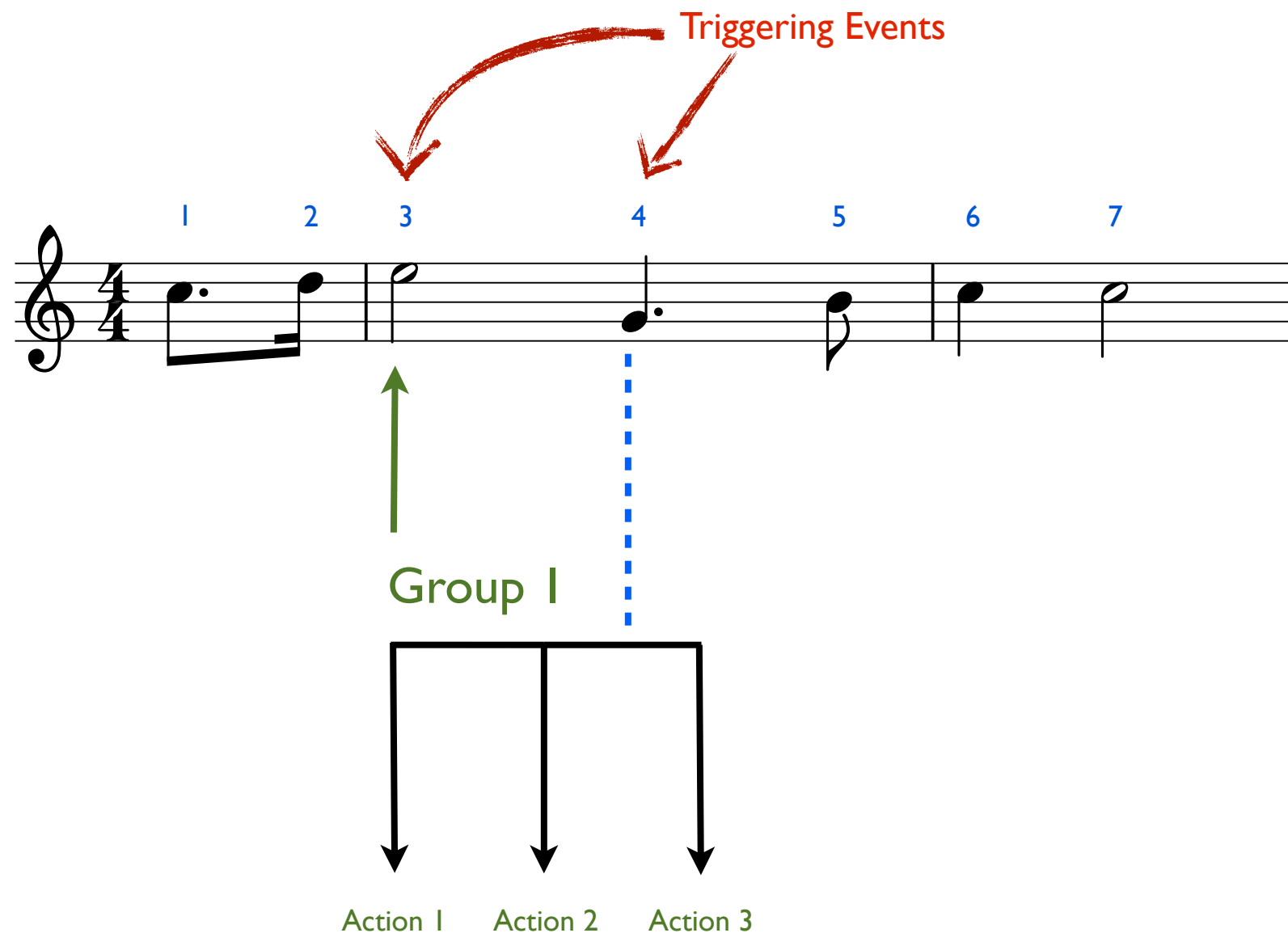
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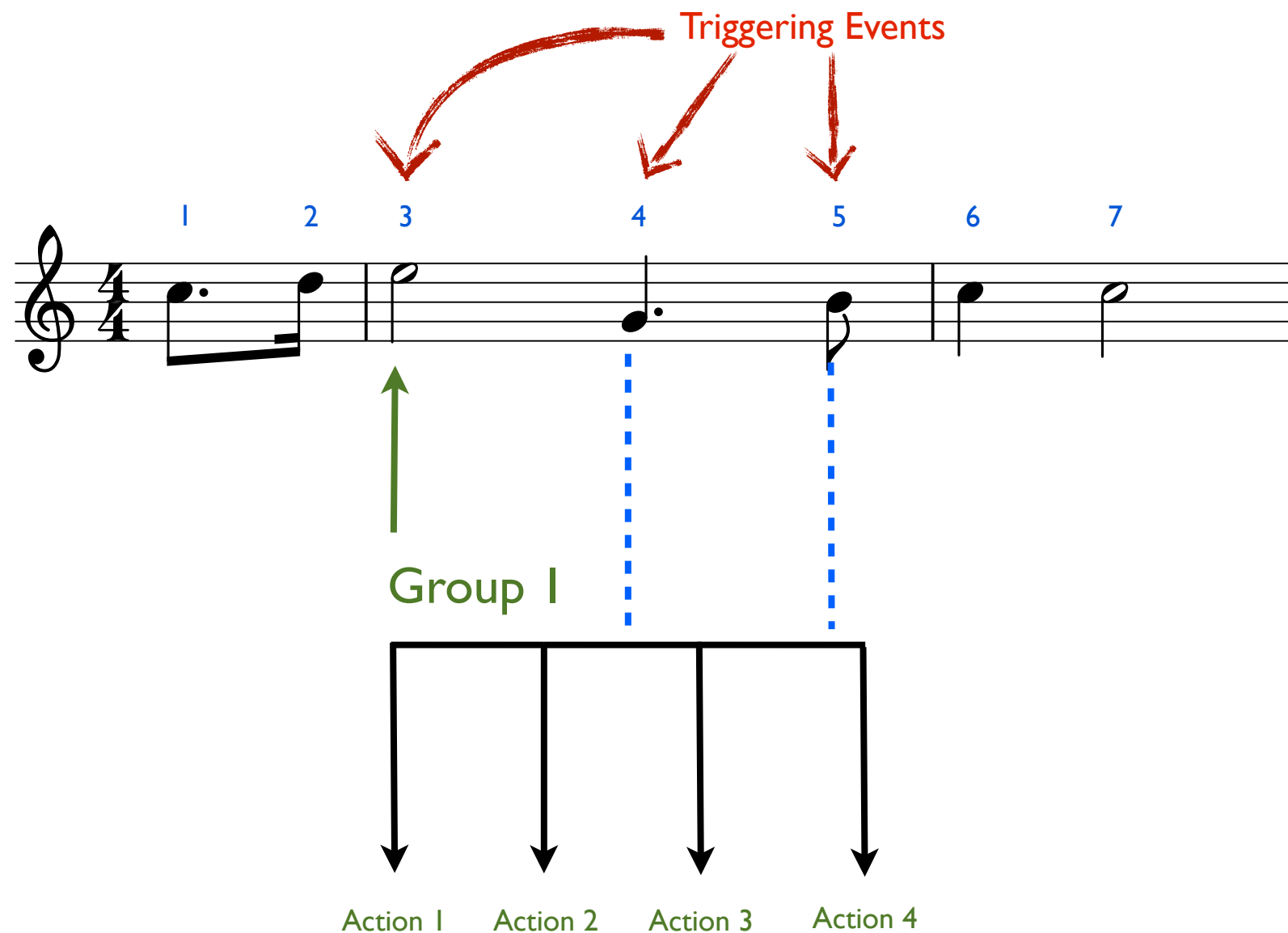
Tight: Synchronization
with tempo and events stream.



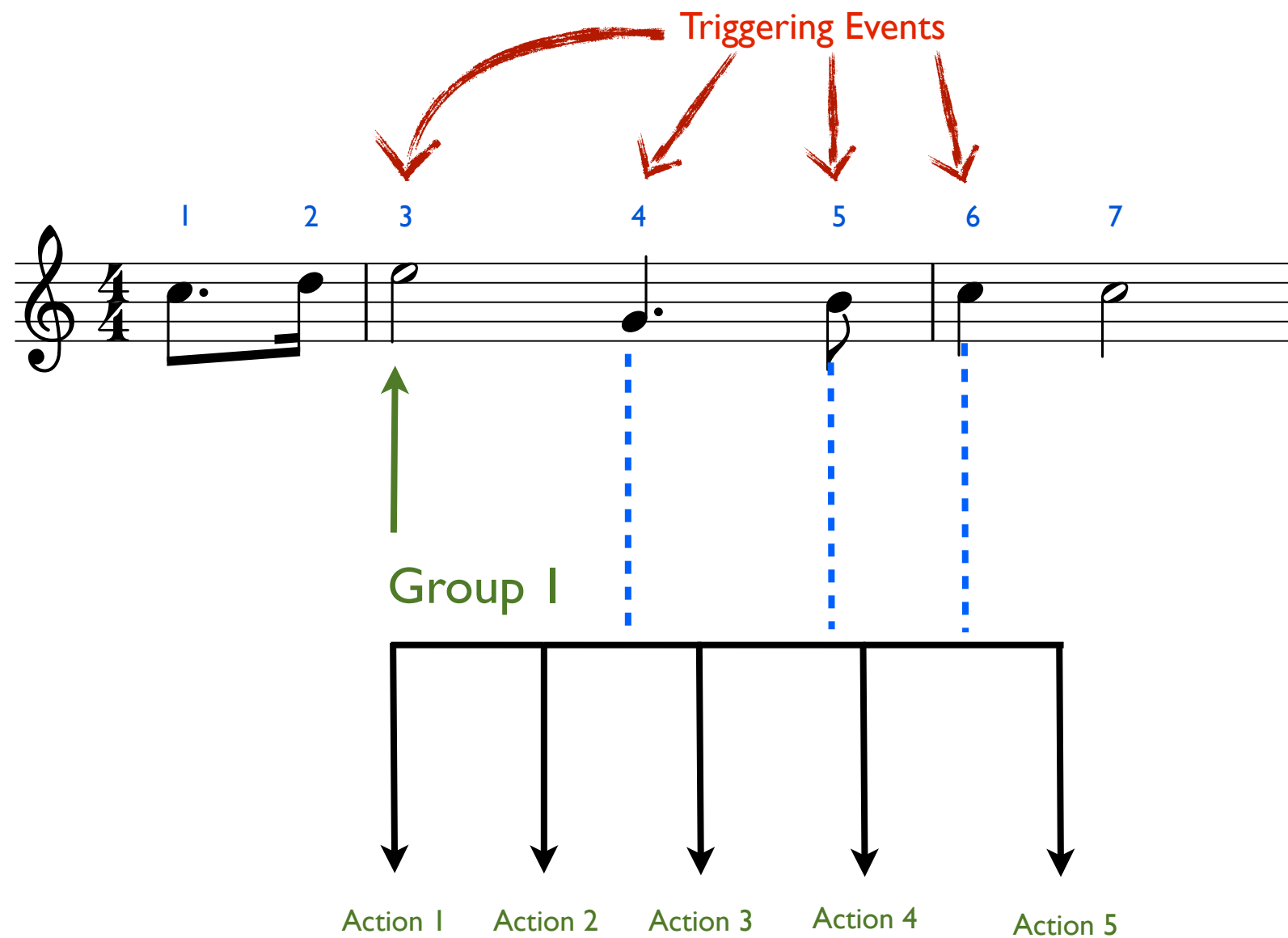
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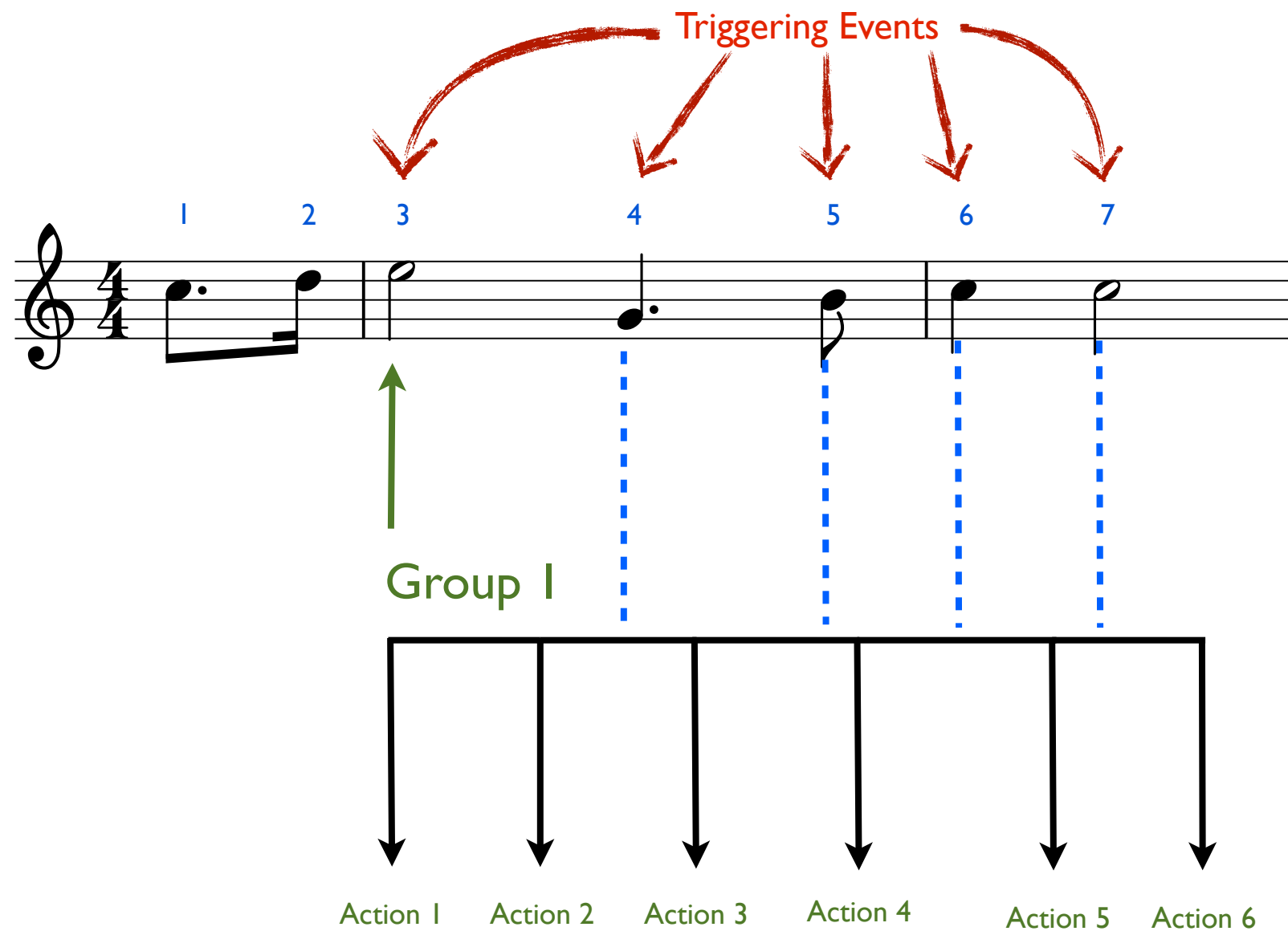
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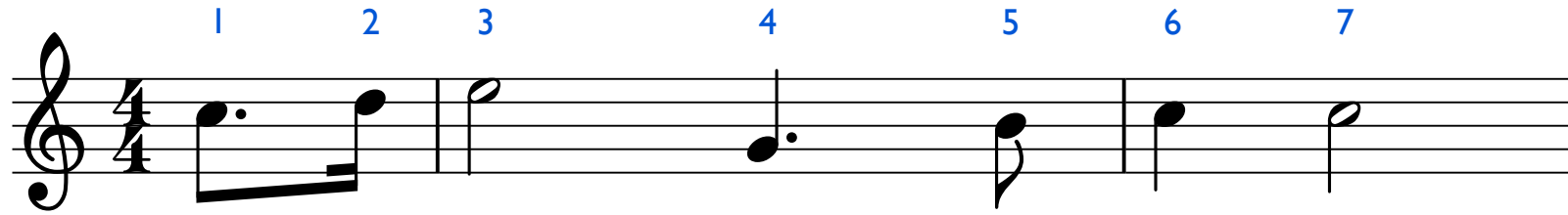


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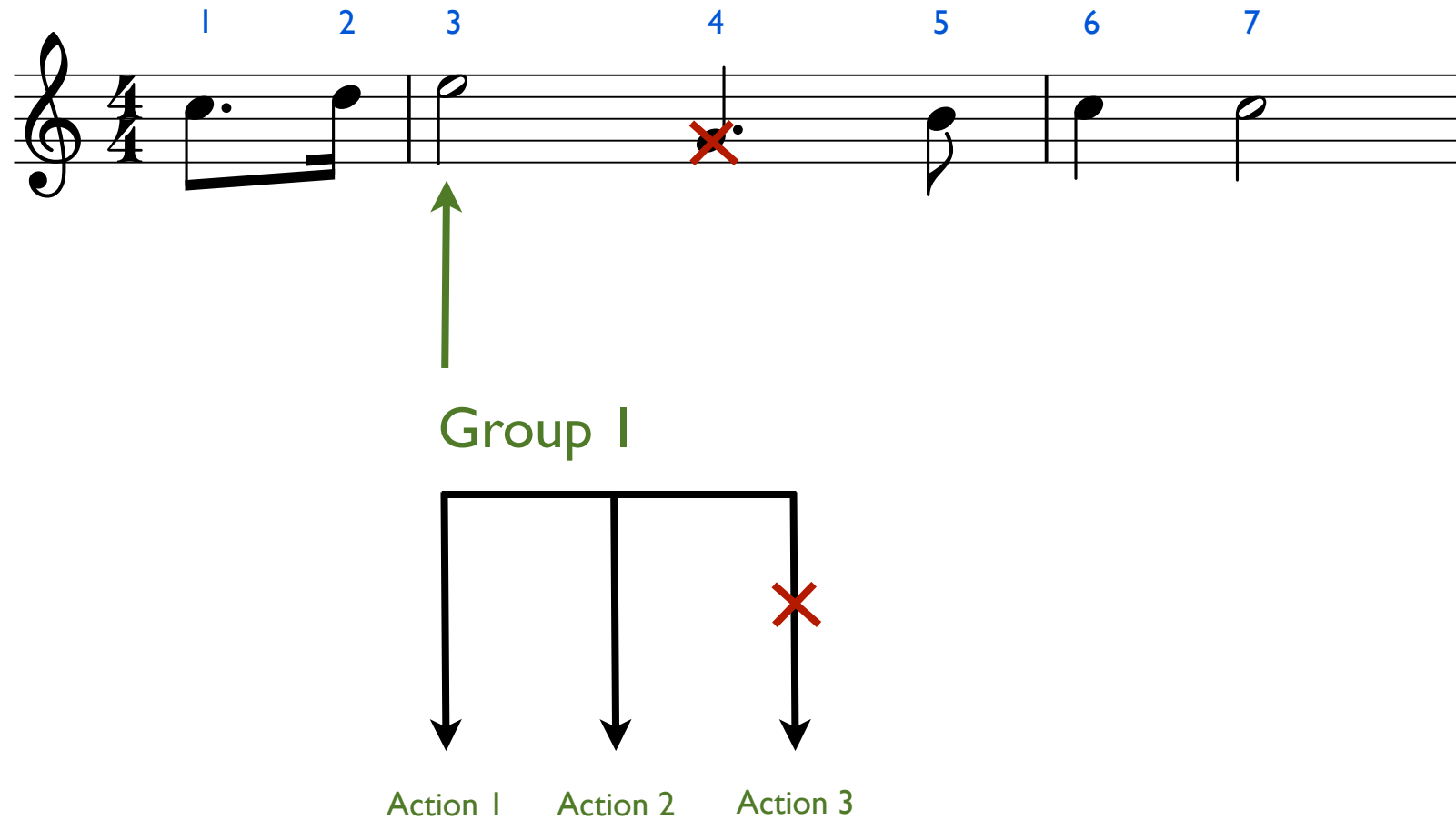


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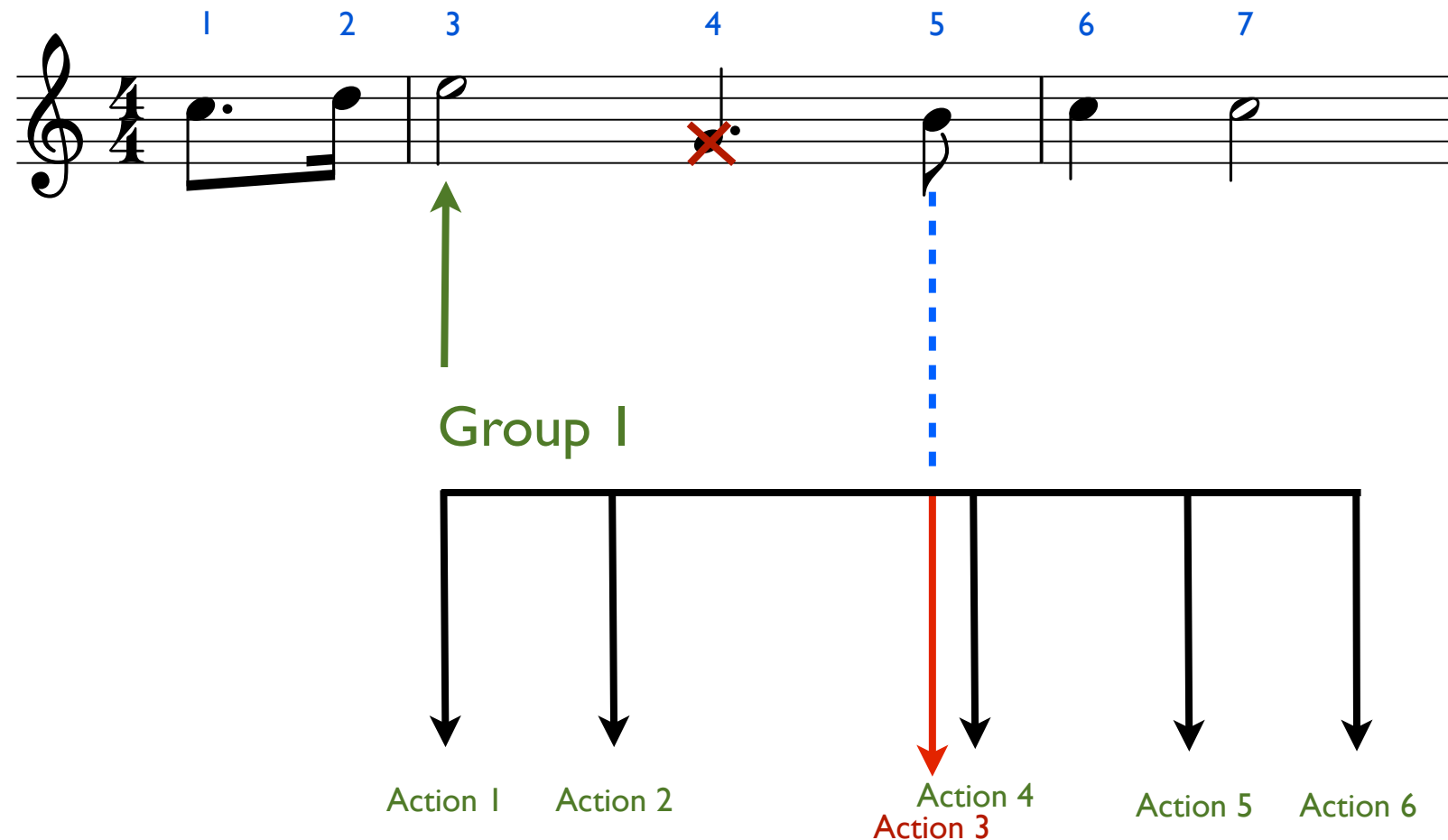
Error Handling Strategies



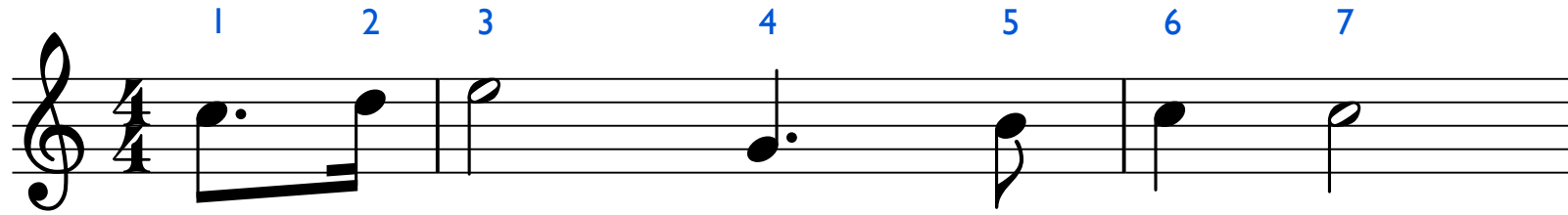
Causal: Actions should be launched immediately when the system recognizes the absence of the triggering event



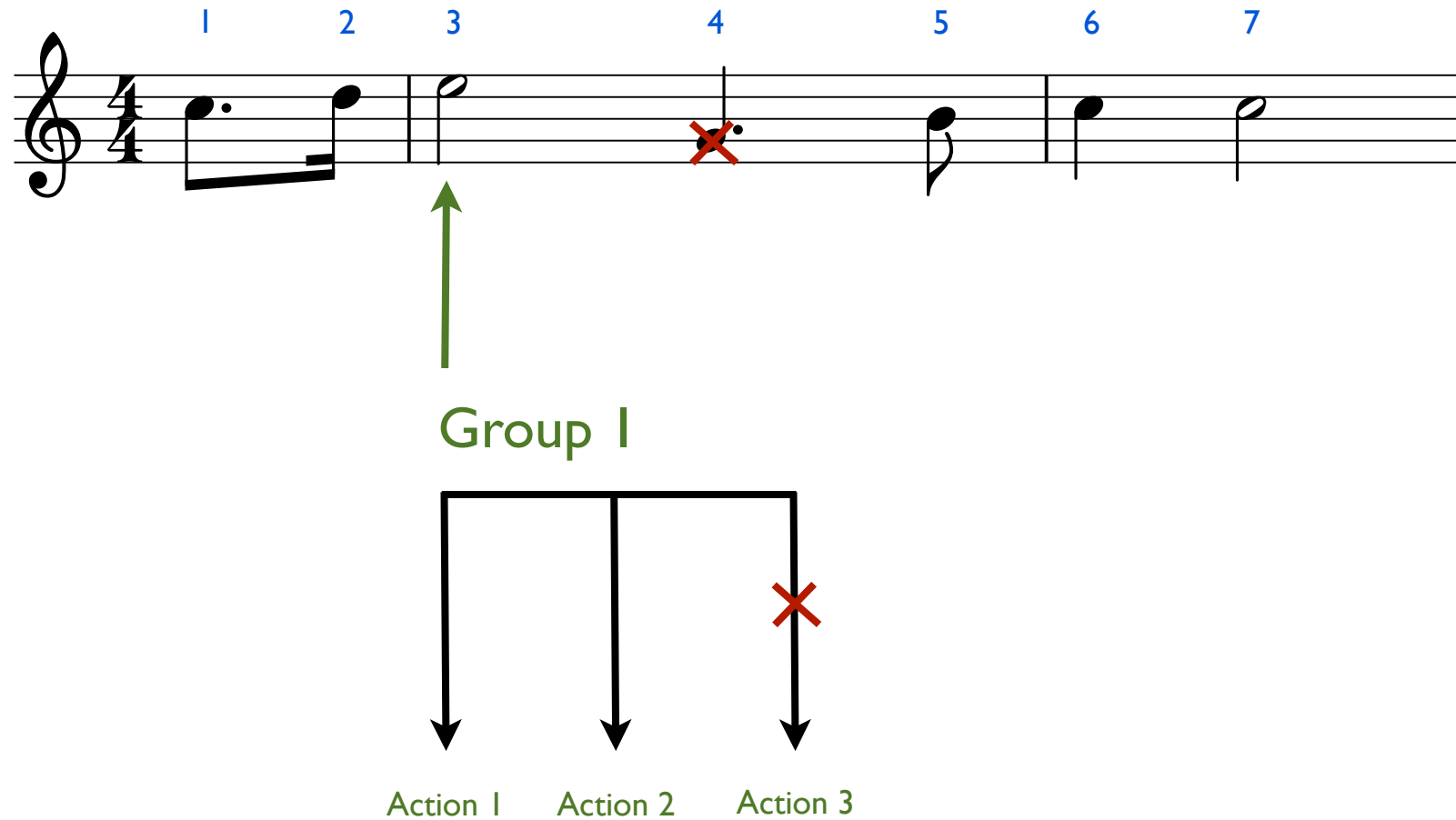
Causal: Actions should be launched immediately when the system recognizes the absence of the triggering event



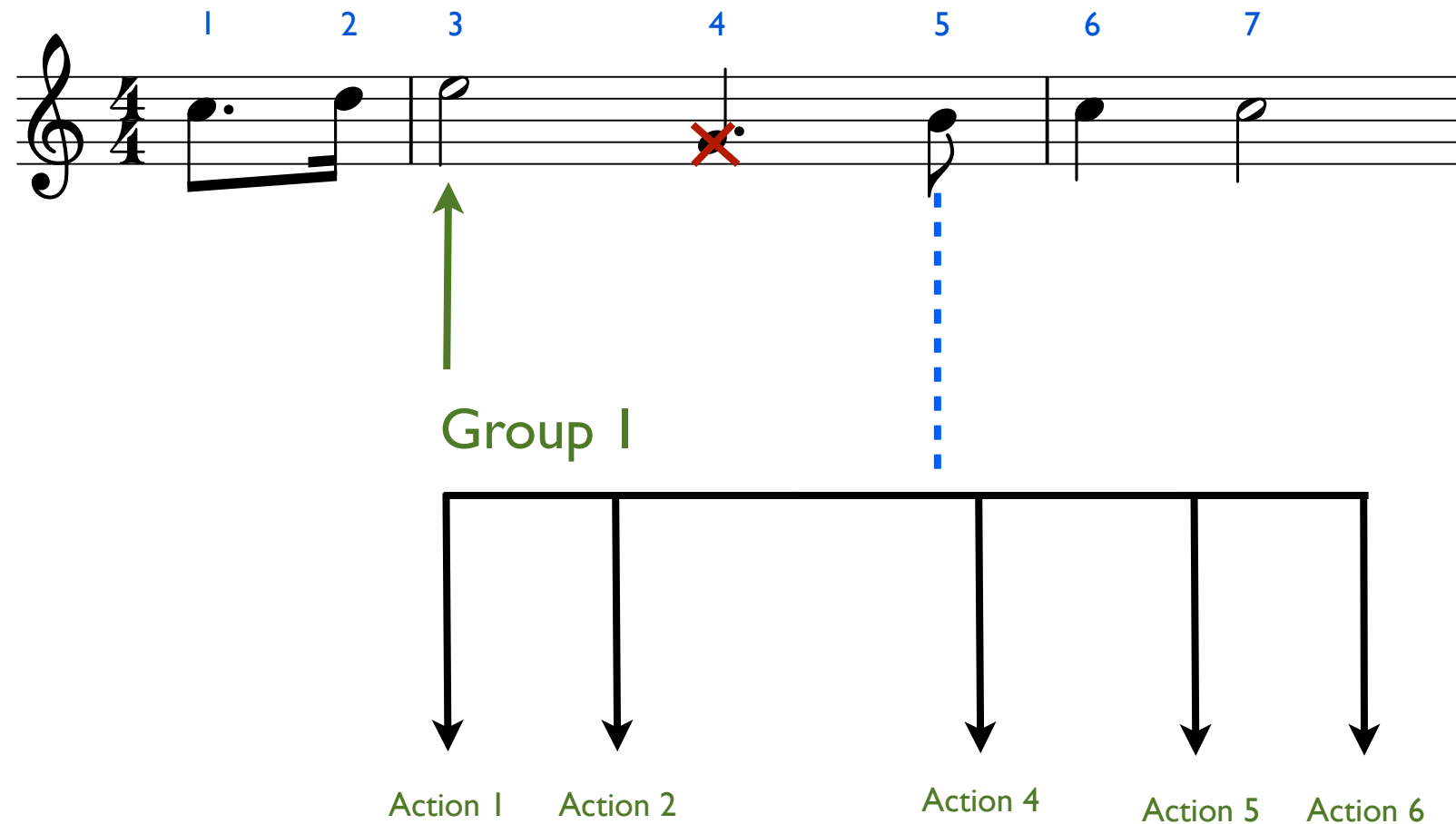
Causal: Actions should be launched immediately when the system recognizes the absence of the triggering event



Partial: Actions should be dismissed in the absence of the triggering event



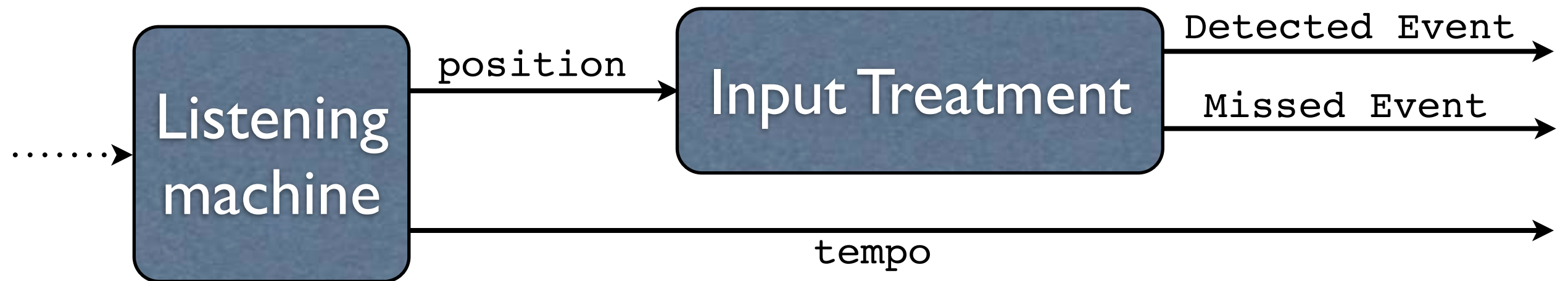
Partial: Actions should be dismissed in the absence of the triggering event



Partial: Actions should be dismissed in the absence of the triggering event

Semantics

Detected and Missed Event

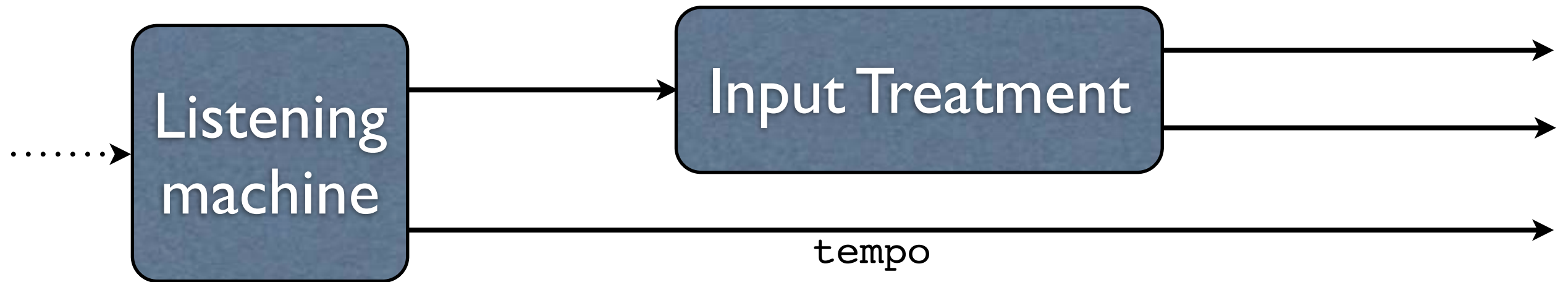


$\mathcal{E}(i)$: date of event i

For each missed event i we associate
the next detected event

$$\mathcal{M}(i) = \min\{j \in D \mid \mathcal{E}(j) > \mathcal{E}(i)\}$$

Detected and Missed Event

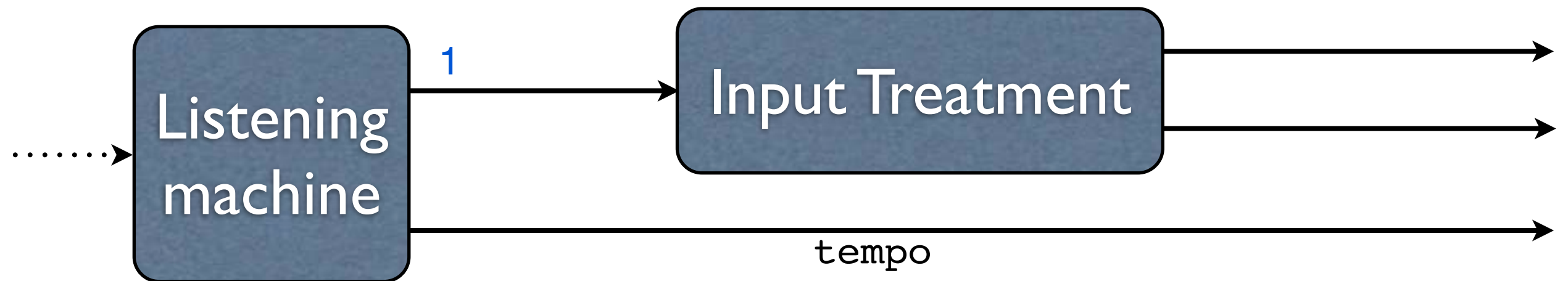


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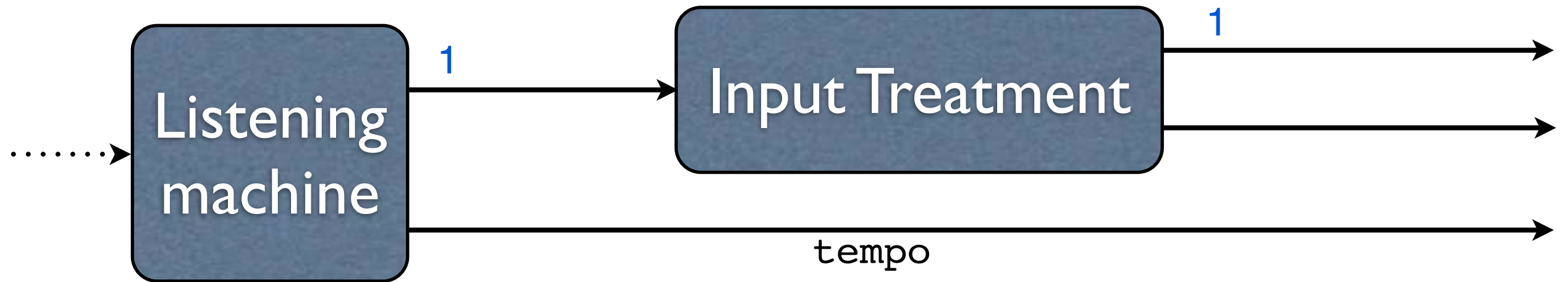


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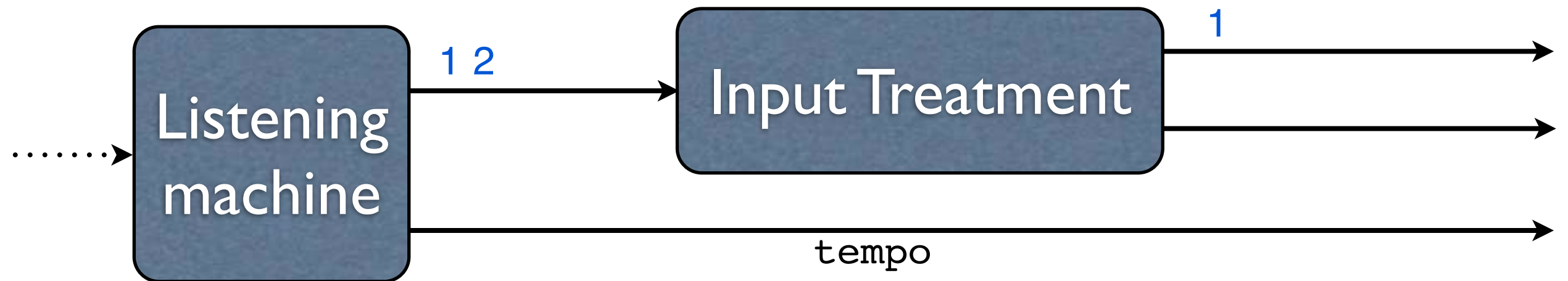


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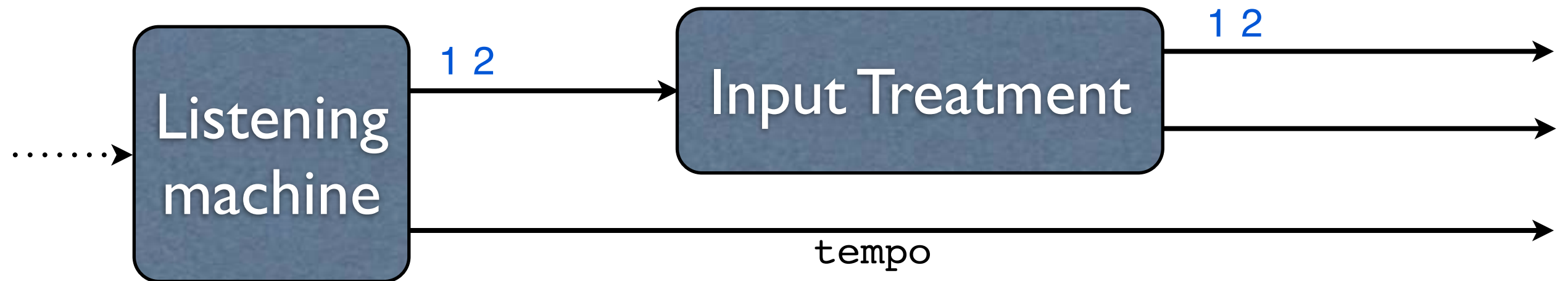


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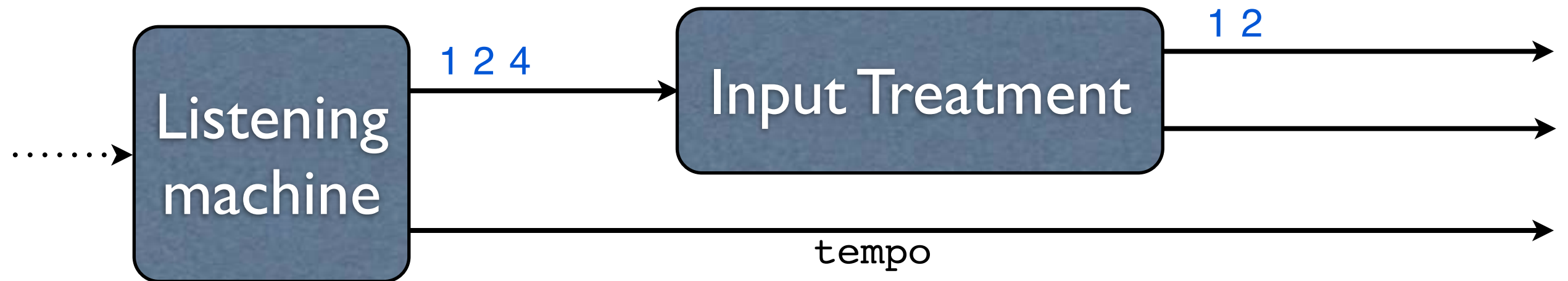


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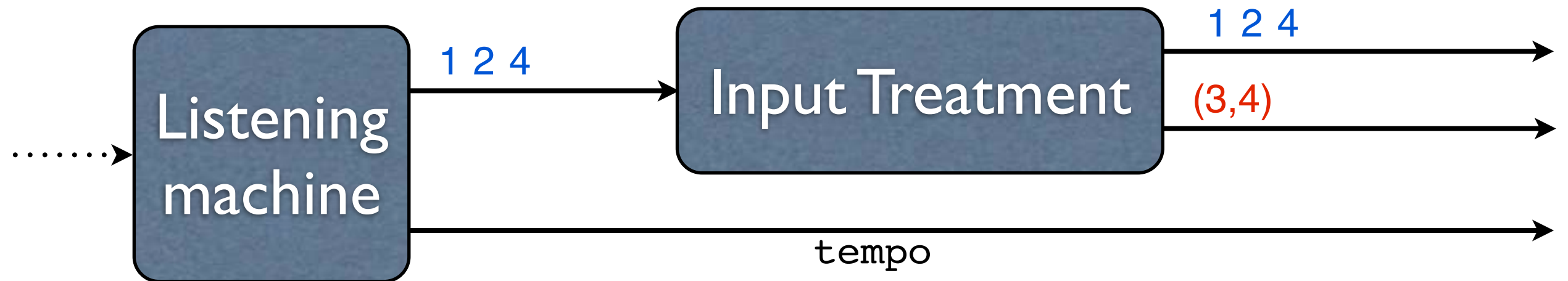


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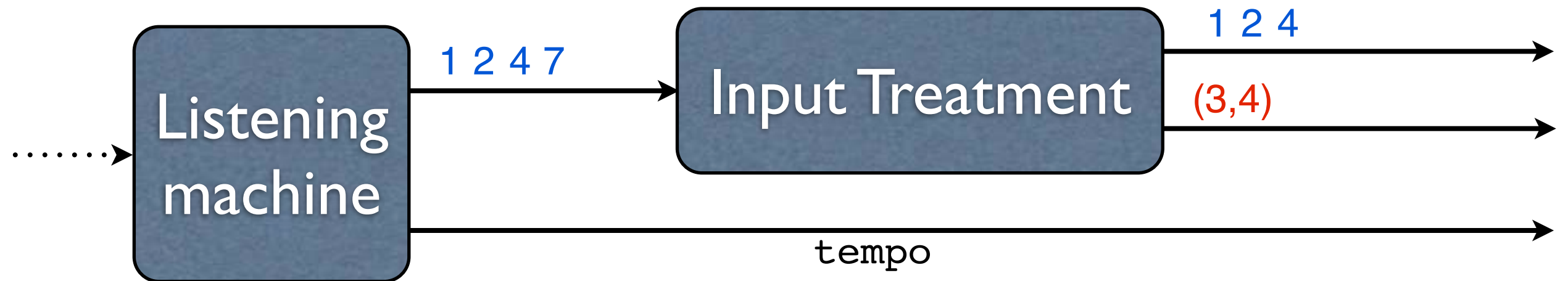


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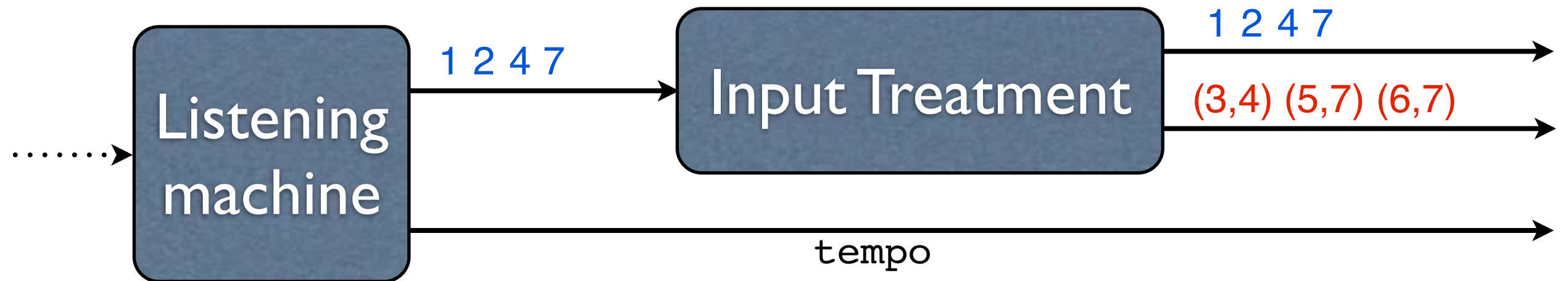


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Detected and Missed Event



$\mathcal{E}(i)$: date of event i

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Formalization

<i>score</i>	$::=$	$\varepsilon \mid (event : seq) score$		
<i>event</i>	$::=$	<code>event</code> i t	$t \in \mathbb{Q}$	Duration
<i>seq</i>	$::=$	$\varepsilon \mid (\delta ae) seq$	$\delta \in \mathbb{Q}$	Delay
<i>ae</i>	$::=$	<i>action</i> \mid <i>group</i>	$i \in \mathbb{N}$	Label
<i>group</i>	$::=$	<code>group</code> <i>synchro</i> <i>error</i> <i>seq</i>	$a \in \mathcal{A}$	Action
<i>synchro</i>	$::=$	<code>tight</code> \mid <code>loose</code>		
<i>error</i>	$::=$	<code>local</code> \mid <code>global</code> \mid <code>partial</code> \mid <code>causal</code>		

A performance *perf* is a set of triplets (i, δ, a)
D is the set of detected instrumental event

Semantics

$$D \mid \frac{exec}{\quad} score \Rightarrow perf$$

The Three Predicates

$$D \mid \frac{exec}{sc} \Rightarrow p$$

Execute a score

$$D, i, \delta \mid \frac{detected}{seq} \Rightarrow p$$

Execute a sequence of actions
bound to a detected event i
with a delay δ

$$D, i, \delta \mid \frac{missed}{seq} \Rightarrow p$$

Execute a sequence of actions
bound to a missed event i
with a delay δ

Execution of a score

$$\text{(Empty Score)} \quad \frac{}{D \mid_{exec} \varepsilon \Rightarrow \emptyset}$$

$$\text{(Exec Score)} \quad \frac{D \mid_{exec} (\text{event } i \ t : seq) \rightarrow p_1 \quad D \mid_{exec} sc \Rightarrow p_2}{D \mid_{exec} (\text{event } i \ t : seq) \ sc \Rightarrow p_1 \cup p_2}$$

Triggering

$$\text{(Detect)} \quad \frac{i \in D \quad D, i, 0.0 \mid \frac{\text{detected}}{\quad} seq \Rightarrow p}{D \mid \frac{\text{exec}}{\quad} (\text{event } i \text{ } t : seq) \rightarrow p}$$

$$\text{(Miss)} \quad \frac{i \notin D \quad D, i, 0.0 \mid \frac{\text{missed}}{\quad} seq \Rightarrow p}{D \mid \frac{\text{exec}}{\quad} (\text{event } i \text{ } t : seq) \rightarrow p}$$

Execution: Atomic Actions

$$\text{(Detected Action)} \quad \frac{}{D, i, \delta \mid \frac{\text{detected}}{} a \rightarrow (i, \delta, a)}$$

$$\text{(Missed Action)} \quad \frac{\mathcal{M}(i) = j}{D, i, \delta \mid \frac{\text{missed}}{} a \rightarrow (j, \max(0.0, \mathcal{E}(i) + \delta - \mathcal{E}(j)), a)}$$

$\mathcal{E}(i)$: Position of event i

$$\mathcal{M}(i) = \min\{j \in D \mid \mathcal{E}(j) > \mathcal{E}(i)\}$$

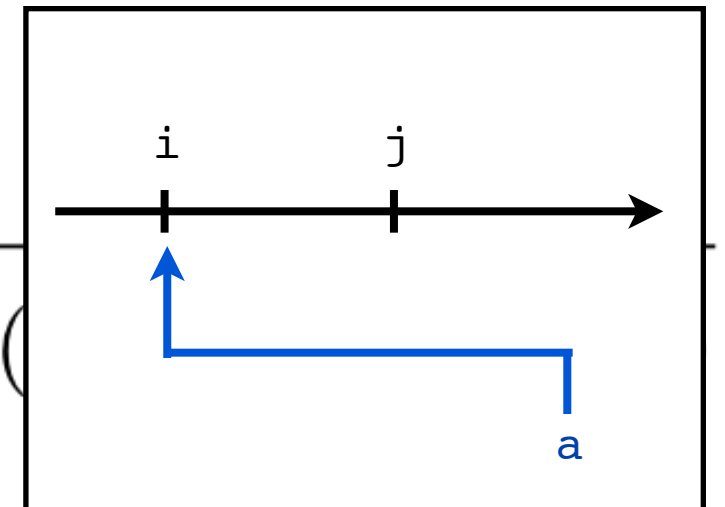
Error detection: i is missed

j is the first detection after i

Execution: Atomic Actions

$$\text{(Detected Action)} \quad \frac{}{D, i, \delta \mid \frac{\text{detected}}{} a \rightarrow (i, \delta, a)}$$

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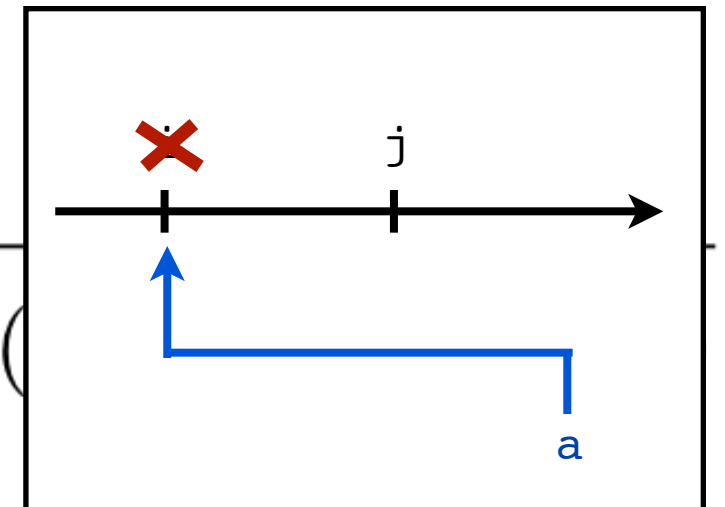
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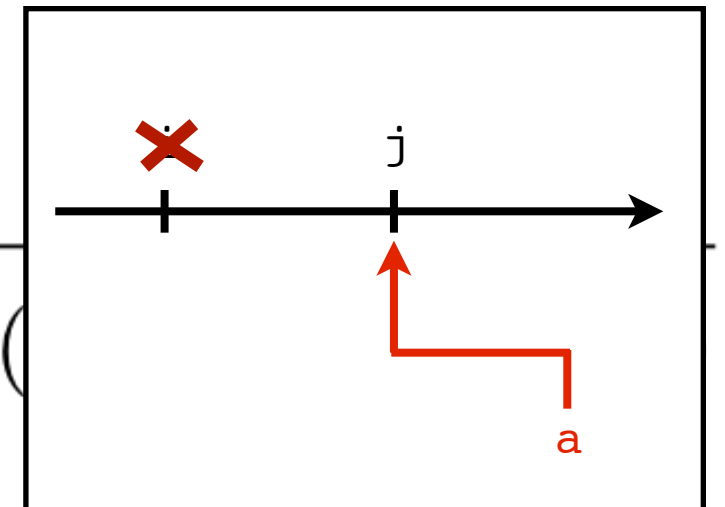
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Execution: Atomic Actions

(Detected Action)
$$\frac{}{D, i, \delta \mid \frac{detected}{a \rightarrow (i, \delta, a)}}$$

(Missed Action)
$$\frac{\mathcal{M}(i) = j}{D, i, \delta \mid \frac{missed}{a \rightarrow (j, \max(0.0, \mathcal{E}(i)), a)}}$$



$\mathcal{E}(i)$: Position of event i

$$\mathcal{M}(i) = \min\{j \in D \mid \mathcal{E}(j) > \mathcal{E}(i)\}$$

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$\mathcal{E}(i)$: Position of event i

$$\mathcal{M}(i) = \min\{j \in D \mid \mathcal{E}(j) > \mathcal{E}(i)\}$$

Error detection: i is missed

j is the first detection after i

Implementation

ReactiveML

OCaml extended with synchronous features à la Esterel

[Mandel Pouzet 2005]

Process

```
let process <id> {<pattern>} = <expr>
```

*State machines, executed through several instants.
Simple OCaml functions are considered to be instantaneous.*

Basics

Synchronization: `pause`

Execution: `run <expr>`

Composition

Sequence: `<expr> ; <expr>`

Parallelism: `<expr> || <expr>`

Signals

Definition: `signal <id>`

Emission: `emit <id>`

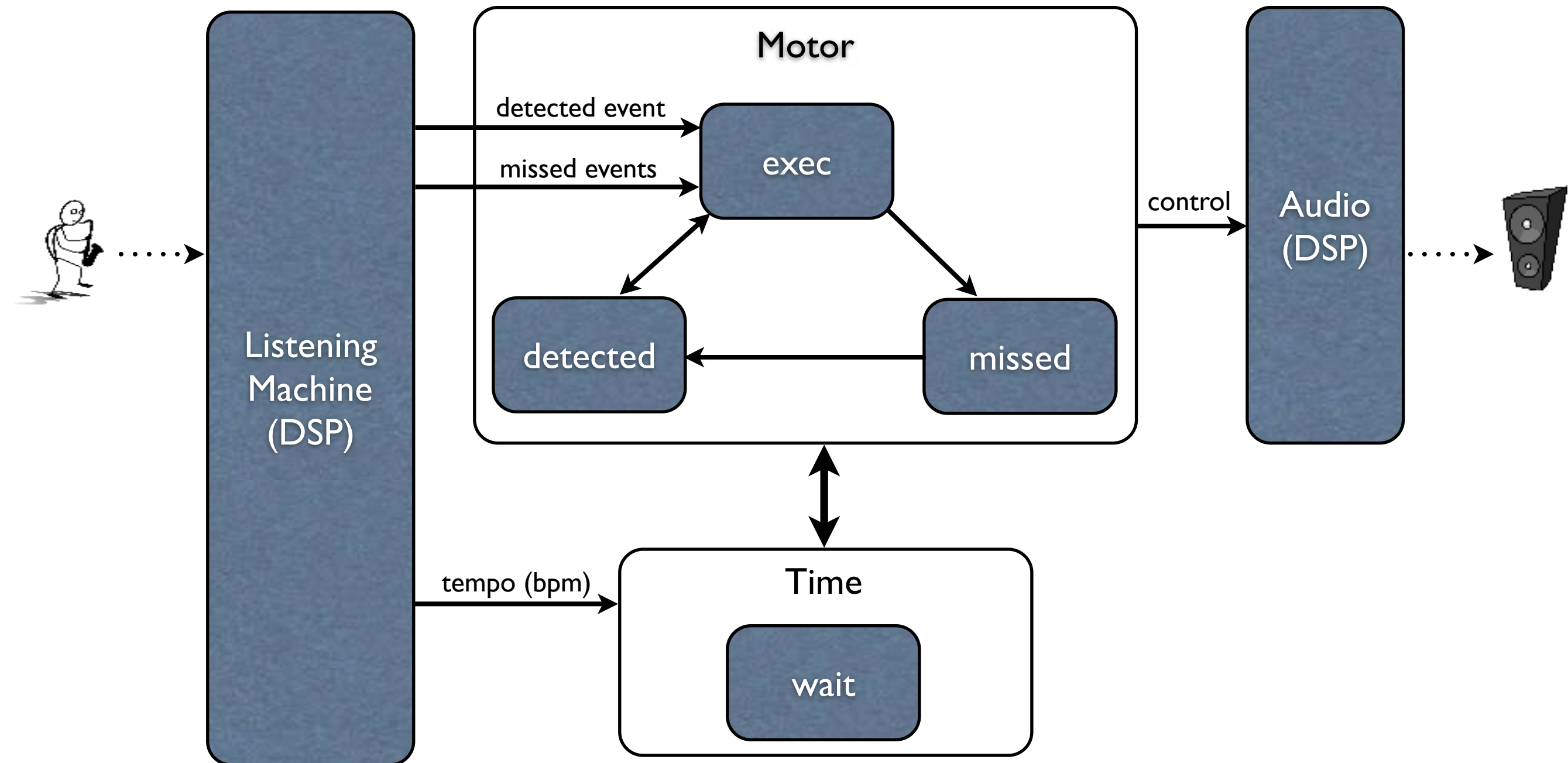
Waiting: `await <id>`

*Broadcast communication
between processes*

Why ReactiveML?

- **A synchronous language**
expressiveness for time and events
- **Functional, typed language, on top of OCaml**
recursion and higher order processes
- **Efficient implementation**
no busy waiting
- **Dynamical features**
new interactions, live coding

Architecture



Execution of a score

$$\text{(Exec Score)} \quad \frac{D \mid \frac{exec}{\quad} (\text{event } i \ t : seq) \rightarrow p_1 \quad D \mid \frac{exec}{\quad} sc \Rightarrow p_2}{D \mid \frac{exec}{\quad} (\text{event } i \ t : seq) \ sc \Rightarrow p_1 \cup p_2}$$

```
let rec process exec score =  
  match score with  
  | [] -> (* rule (Empty Score) *) ()  
  | se::sc ->  
    (* rule (Exec Score) *)  
    run (exec_score_event se) ||  
    run (exec sc)
```

Triggering

$$\text{(Detect)} \quad \frac{i \in D \quad D, i, 0.0 \mid \frac{\text{detected}}{\quad} seq \Rightarrow p}{D \mid \frac{\text{exec}}{\quad} (\text{event } i \text{ } t : seq) \rightarrow p}$$

$$\text{(Miss)} \quad \frac{i \notin D \quad D, i, 0.0 \mid \frac{\text{missed}}{\quad} seq \Rightarrow p}{D \mid \frac{\text{exec}}{\quad} (\text{event } i \text{ } t : seq) \text{ } sc \rightarrow p}$$

Triggering

$$\text{(Detect)} \quad \frac{i \in D \quad D, i, 0.0 \mid \frac{\text{detected}}{\text{seq}} \Rightarrow p}{D \mid \frac{\text{exec}}{(\text{event } i \text{ } t : \text{seq})} \rightarrow p}$$

$$\text{(Miss)} \quad \frac{i \notin D \quad D, i, 0.0 \mid \frac{\text{missed}}{\text{seq}} \Rightarrow p}{D \mid \frac{\text{exec}}{(\text{event } i \text{ } t : \text{seq})} \text{sc} \rightarrow p}$$

```
let rec process exec_score_event se =  
  let i = se.event in  
  await events.(i)(status) in  
  match status with  
  | Detected ->  
    (* rule (Detect) *)  
    run (exec_seq (detect i) 0.0 se.seq)  
  | Missed(j) ->  
    (* rule (Miss) *)  
    run (exec_seq (missed i j) 0.0 se.seq)
```

- **Contributions**

- a new semantics for Antescofo
- a sequencer efficient enough to compare well with the actual one
- prototyping new features:
new attributes, reactive behaviors, live coding, ...

- **Next?**

- interaction with other system: gesture follower, voice recognition, ...
- link with synthesis tool or other media

To continue...

www.reactiveml.org/emsoft | 3

References

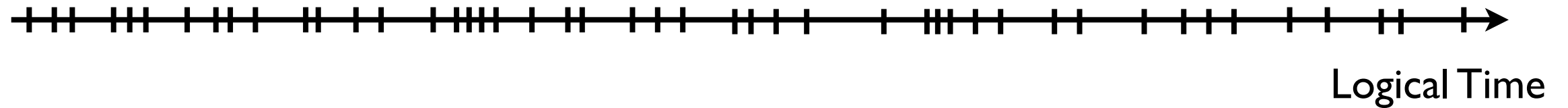
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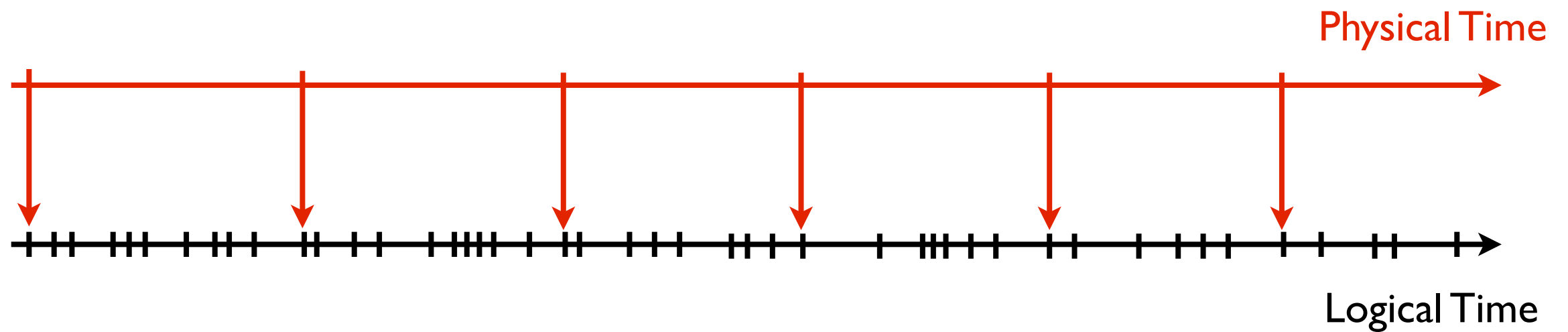
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From Logical Time to Physical Time



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From Logical Time to Physical Time

```
let process tick period clock =  
  let next = ref (Unix.gettimeofday () +. period) in  
  loop  
    let current = Unix.gettimeofday () in  
    if (current >= !next)  
    then (emit clock (); next := !next +. period);  
    pause;  
end
```

```
val tick : float -> (unit, 'a) event -> unit process
```

Wait !

```
let process wait dur period clock =  
  let d = int_of_float (dur /. period) in  
  do  
    for i=1 to d do pause done  
  when clock done
```

```
val wait : float -> float -> ('a, 'b) event -> unit process
```

Detection

$$\begin{array}{c}
 \text{(Detected Action)} \quad \frac{}{D, i, \delta \mid \frac{\text{detected}}{} a \rightarrow (i, \delta, a)} \\
 \text{(Detected Loose Group)} \quad \frac{D, i, \delta \mid \frac{\text{detected}}{} seq \Rightarrow p}{D, i, \delta \mid \frac{\text{detected}}{} \text{group loose err seq} \rightarrow p}
 \end{array}$$

$$\text{(Detected Tight Group)} \quad \frac{D \mid \frac{\text{exec}}{} \text{Slice}(i, \delta, (\text{group tight err seq})) \rightarrow p}{D, i, \delta \mid \frac{\text{detected}}{} \text{group tight err seq} \rightarrow p}$$

```

and process detected i delta ae =
  match ae with
  | Action(a) ->
    (* rule (Detected Action) *)
    run (wait date delta);
    emit perf (i,delta,a)
  | Group(g) ->
    begin match g.group_synchro with
    | Loose ->
      (* rule (Detected Loose Group) *)
      let bg = g.group_seq in
      run (exec_seq (detected i) delta bg)
    | Tight ->
      (* rule (Detected Tight Group) *)
      let gs = slice i delta g in
      run (exec gs)
    end
end
  
```