

$$6.1 \quad V = -mgr \cos \theta + \frac{1}{2} k (r-l)^2$$

$$\frac{\partial V}{\partial \theta} = mgr \sin \theta = 0 \quad \theta_0 = 0$$

$$\frac{\partial V}{\partial r} \Big|_{\theta=0} = -mg + k(r_0 - l) = 0$$

$$r_0 = l + \frac{mg}{k}$$

$$x = r - r_0$$

$$L = \frac{1}{2} m (\dot{r}^2 + r^2 \dot{\theta}^2) + mgr \cos \theta - mg \left( l + \frac{mg}{k} \right) - \frac{1}{2} k (r-l)^2$$

$$= \frac{1}{2} m (\dot{x}^2 + \left( l + \frac{mg}{k} \right)^2 \dot{\theta}^2) - \frac{1}{2} mg \left( l + \frac{mg}{k} \right) \theta^2 - \frac{1}{2} k x^2$$

$$a_{11} = m, \quad a_{22} = m \left( l + \frac{mg}{k} \right)^2, \quad b_{11} = -k, \quad b_{22} = mg \left( l + \frac{mg}{k} \right)$$

$$\text{本征方程} \quad \begin{vmatrix} k - m\omega^2 & 0 \\ 0 & mg \left( l + \frac{mg}{k} \right) - m \left( l + \frac{mg}{k} \right)^2 \omega^2 \end{vmatrix} = 0$$

$$\omega_1 = \sqrt{\frac{k}{m}}, \quad \omega_2 = \sqrt{\frac{g}{l + \frac{mg}{k}}}$$

$$\text{因此 } r = l + \frac{mg}{k} + A \cos \omega_1 t + B \cos \omega_2 t$$

$$4. \quad V = \frac{1}{2} k_1 x_1^2 + \frac{1}{2} k_2 x_2^2 + \frac{1}{2} k_3 x_3^2$$

$$T = \frac{1}{2} m_1 \dot{x}_1^2 + \frac{1}{2} m_2 \dot{x}_2^2 + \frac{1}{2} m_3 \dot{x}_3^2$$

代入拉格朗日方程

$$\begin{cases} m_1 \ddot{x}_1 + k_1 x_1 = 0 \\ m_2 \ddot{x}_2 + k_2 x_2 = 0 \\ m_3 \ddot{x}_3 + k_3 x_3 = 0 \end{cases}$$

$$\begin{cases} m_2 \ddot{x}_2 + k_2 x_2 = 0 \\ m_3 \ddot{x}_3 + k_3 x_3 = 0 \end{cases}$$

$$m_3 \ddot{x}_3 + k_3 x_3 = 0$$

$$k_1 - m_1 \omega^2$$

$$k_2 - m_2 \omega^2$$

$$k_3 - m_3 \omega^2$$

$$\omega = \pm \sqrt{\frac{k_1}{m_1}} \pm \sqrt{\frac{k_2}{m_2}} \pm \sqrt{\frac{k_3}{m_3}}$$

$$\begin{aligned}
 T &= \frac{1}{2} m l^2 \dot{\theta}_1^2 + \frac{1}{2} m l^2 \dot{\theta}_2^2 \\
 V &= -mgl \cos \theta_1 - mgl \cos \theta_2 + \frac{1}{2} k (\sqrt{(l \sin \theta_1 - l \sin \theta_2)^2 + (l \cos \theta_1 - l \cos \theta_2)^2} - d) \\
 &\approx \frac{1}{2} mgl (\theta_1^2 + \theta_2^2) + \frac{1}{2} k l^2 (\theta_1^2 + \theta_2^2) \\
 &= \frac{1}{2} (mgl + kl^2) (\theta_1^2 + \theta_2^2) + kl^2 \theta_1 \theta_2 \\
 \begin{vmatrix} mgl + kl^2 - m l^2 \omega^2 & kl^2 \\ kl^2 & mgl + kl^2 - m l^2 \omega^2 \end{vmatrix} &= 0 \\
 \omega &= \sqrt{\frac{g}{l} + \frac{k}{m} \pm \frac{k}{m}} \quad \omega_1 = \sqrt{\frac{g}{l}} \quad \omega_2 = \sqrt{\frac{g}{l} + \frac{2k}{m}}
 \end{aligned}$$

$$T = \frac{1}{2} m \dot{x}_1^2 + \frac{1}{2} m \dot{x}_2^2 + \frac{1}{2} m l^2 \dot{\theta}^2 \quad \frac{1}{2} m_2 [(l \dot{\theta} \cos \theta + \dot{x}_1)^2 + (\dot{\theta} \sin \theta)^2]$$

$$V = \frac{1}{2} k x_1^2 - mgl \cos \theta$$

代入拉格朗日方程

$$\begin{cases} m_1 \ddot{x}_1 + m_2 \ddot{x}_1 + k x_1 + m_2 l \ddot{\theta} = 0 \\ m_2 l^2 \ddot{\theta} + mgl \sin \theta + m_2 l \ddot{x}_1 = 0 \end{cases} \quad \begin{matrix} \cos \theta \approx 1 \\ \sin \theta \approx \theta \end{matrix}$$

$$[k - (m_1 + m_2) \omega^2] [mgl - m_2 l \omega^2] - m_2^2 \omega^2 = 0$$

$$\begin{vmatrix} k - (m_1 + m_2) \omega^2 & m_2 l \\ m_2 l & mgl - m_2 l \omega^2 \end{vmatrix} = 0$$

$$\omega = \sqrt{\frac{k l + mgl \pm \sqrt{(m_1 m_2 g^2 k^2 - 4(m_1 m_2)(k l - mgl))}}{2(m_1 + m_2)}}$$

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$$6.9 \quad T = \frac{1}{2} m \dot{x}^2 + \frac{1}{2} m \dot{y}^2$$

$$V = 2k(x^2 + y^2)$$

代入拉格朗日方程

$$m \ddot{x} + 4kx = 0$$

$$m \ddot{y} + 4ky = 0$$

$$\begin{vmatrix} 4k - m\omega^2 & 0 \\ 0 & 4k - m\omega^2 \end{vmatrix} = 0$$

$$\begin{matrix} a_{11} = m & b_{11} = 4k \\ a_{22} = m & b_{22} = 4k \end{matrix}$$

$$\omega = 2\sqrt{\frac{k}{m}}$$