



Communication Sensor-Core

- Handshake:
 - Sensor sends string with the name of the location
 - Core replies with an OK (or with a KO if something goes wrong)
- Data:
 - Sensor sends directly an array with the components

Communication Core-Robot

- Handshake:
 - Core sends Hello message
 - Robot sends ack
- Data:
 - String or int with the event detected*