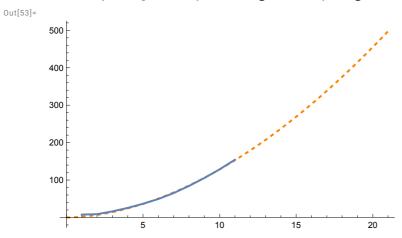
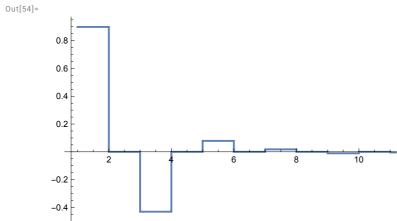
```
In[43]:= SetOptions[SelectedNotebook[],
           PrintingStyleEnvironment → "Printout", ShowSyntaxStyles → True]
 In[44]:= V_0 = 10.; a = 0.5; L = 1.;
         n = 11;
         \phi[k_{-}]? NumericQ] := If \left[ \text{OddQ}[k], \text{Cos}\left[ \frac{k \pi x}{2 I} \right], \text{Sin}\left[ \frac{k \pi x}{2 I} \right] \right]
 In[47]:= H = Quiet@ParallelTable[If[k_1 == k_2, \frac{k_1^2 \pi^2}{8}, 0] +
                  V_0 Quiet@NIntegrate[\phi[k_1] \times \phi[k_2], {x, -a, a}, AccuracyGoal \rightarrow 4], {k_1,
                  1, n}, {k_2, 1, n}];
 In[48]:= H // MatrixForm;
         \{\lambda, \psi\} = Eigensystem[H];
         Reverse@Take[\lambda, -4]
Out[50]=
         {7.76594, 8.75999, 16.1812, 25.6011}
 ln[51]:= \xi = NonlinearModelFit[Reverse@\lambda, k x^b, \{k, b\}, x];
         ξ["ParameterTable"]
Out[52]=
            | Estimate Standard Error t-Statistic P-Value
         k 1.91432 0.18677 10.2496 2.91328 ×10<sup>-6</sup>
b 1.82647 0.0436527 41.8411 1.26863 ×10<sup>-11</sup>
```





$$In[67]:= \Psi = \#.Table[\phi[k], \{k, 1, n\}] \& /@\psi;$$
 With[$\{\xi = Take[\Psi, -5]\}, Plot[\xi, \{x, -L, L\}]]$

