General Information:

- [xxx] and (xp) refer to the question's topic and maximal achievable points.
- The total number of achievable points is 46.
 You must achieve at least 50%, i.e., 23 points to get a positive grade.
- You must answer the questions via hand-written notes on empty sheets of paper.
- Show the stack of empty papers at the beginning when asked.
- Clearly indicate the respective question number for each answer.
- Add page numbers to every sheet of paper.
- Write clearly using large hand-writing and generously use the available space.
- When finished, scan all the sheets of paper into a single PDF document. Double-check that the PDF contains all pages and is of reasonable quality and submit to: nssc@iue.tuwien.ac.at

Submission should be done within 5 minutes of notifying the exam supervisor.

Inform an exam supervisor when

- you are finished and want to scan and submit.
- you need more paper then initially approved by the supervisor.
- [MPI] (3p) Consider the implementation of a stencil-based Jacobi solver for a twodimensional elliptic PDE on a square two-dimensional domain.
 - a. Write a pseudocode which shows the key adaption steps required to parallelize the solver using a ghost-layer-based two-dimensional domain decomposition using MPI.
 - Include the calculation of global residual and error norms.
- [MPI] (2p) Show via pseudocode and additional explanations the difference between blocking and non-blocking point-to-point communication.
- [ODE] (2p) Name two numerical methods for ODEs (can be explicit or implicit) together
 with the respective update rules (including the truncation error) assuming a constant step
 size h.
- (ODE) (3p) Single-step and multi-step methods:
 - Explain the key difference between both methods for the numerical solution of ODEs.
 - Explain why multistep methods (compared to single-step methods) require special attention regarding the start-up and when considering a dynamic step size.

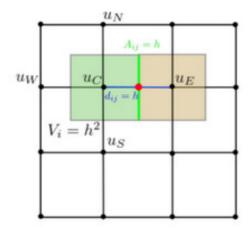
5. [FVM] (4p) Consider the discretization of the two-dimensional Poisson equation

$$u_{xx} + u_{yy} = f$$

and the integral form

$$\oint \nabla u dA = \int f dV$$

on a regular equidistant grid spacing h and box control volumes (see figure below). Show that the resulting discretization for an interior point u_C is identical for the FVM (using a central difference for ∇u) and the FDM (using second-order central differences).



- [PDE] (2p) Give an example for a second order linear parabolic operator.
- 7. [PDE] (3p) What does it mean that a second order linear operator L is elliptic?
- 8. [MD] (2p) What sets classical molecular dynamics apart from ab-initio molecular dynamics?
- [MD] (3p) Describe the minimum image convention.
 - a. When is it applicable?
 - b. If your simulation box is an axis-aligned straight rectangular prism with side lengths L_x , L_y , L_z , how would you calculate the distance between two particles with positions \boldsymbol{p} and \boldsymbol{P} under this convention?

 [MD] (4p) The following code snippet contains a naive Python implementation of the velocity Verlet integrator that uses significantly more memory than strictly necessary. Discuss why and how to fix it.

Note: For simplicity, masses are assumed to have a value of 1.

```
def next_step(pos, vel, dt):
    force = -calc gradient e pot(pos)
    pos = pos + dt * (vel + .5 * force * dt)
    newforce = -calc_gradient_e_pot (pos)
    vel = vel + (force + newforce) * .5 * dt
    return (pos, vel)
```

[FD] (2p) Consider the 1D dimensionless Diffusion Equation in cartesian coordinates

$$\frac{\partial C}{\partial t} = D \frac{\partial^2 C}{\partial x^2},$$

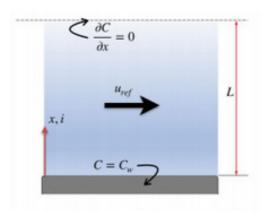
where D is the diffusion coefficient, C is the concentration field, x is the spatial coordinate, and t is the time. Derive the discretized counterpart using a 2^{nd} order implicit scheme in time using Crank-Nicolson and a 2^{nd} order central scheme in space.

12. [FD] (3p) Consider the 1D Advection-Diffusion Equation (ADE) in Cartesian coordinates:

$$\frac{\partial C^*}{\partial t^*} + u^* \frac{\partial C^*}{\partial x^*} = D \frac{\partial^2 C^*}{\partial x^{*2}},$$

where the superscript * indicates variables in dimensional form and D the diffusion coefficient. Assume the flow configuration given in the figure below.

- Derive the dimensionless counterpart of the above equation and identify the Peclet number.
- b. How does the dimensionless equation look like for (1) a diffusion-dominated and (2) for an advection-dominated phenomenon?



13. [FD] (4p) Consider the 1D pure Advection Equation in cartesian coordinates:

$$\frac{\partial C}{\partial t} + U \frac{\partial C}{\partial x} = 0,$$

where U is the (uniform and constant) advection velocity, C is the concentration field, x is the spatial coordinate and t is the time. Show that ...

- a. ... when the upwind approximation (1st order in time, 2nd order in space) is used to discretize the equation, a numerical diffusivity is introduced.
- b. ... the numerical diffusivity is null when Co = 1 (where Co indicates the Courant number).
- 14. [FEM] (2p) What is the interpretation of the determinant of the Jacobi matrix of an isoparametric element?
- 15. [FEM] (3p) The fundamental FEM equation reads: KU = F
 - Explain variables and their dimensions (in terms of lin. Algebra) in continuum solid mechanics.
 - b. Consider a plane (two-dimensional) mechanical problem with 18 elements and 16 nodes: How many equations has the system?
 - c. Consider a three-dimensional heat conduction problem with 27 elements and 64 nodes: How many equations has the system?
- 16. [FEM] (4p) Consider a FEM heat conduction problem with the global FEM equation

$$H_{ab} T_a = P_b$$

with n degrees of freedom and with the known total stiffness matrix. Dirichlet boundary conditions are given for $a=1\dots m$; Neumann boundary conditions are given for $b=m+1\dots n$.

Write the computation steps by linear algebra manipulations to solve the system, i.e., the unknown T- and P- entries.

Hint: Start by writing down the FEM equations by using sub-matrices and sub-vectors.