lin_prog_example

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```
[]: # src: https://www.kaggle.com/mchirico/linear-programming
[9]: import matplotlib.pyplot as plt
[1]: # scipy.linproq
    # https://docs.scipy.org/doc/scipy/reference/generated/scipy.optimize.linprog.
    \hookrightarrow html
[2]: # Consider the following problem:
    # Minimize: f = -1x[0] + 4x[1]
    # Subject to:
    \# -3x[0] + 1x[1] <= 6
    # 1x[0] + 2x[1] <= 4
    \# x[1] >= -3
    \# -inf \le x[0] \le +inf
    c = [-1, 4] # minimize function
    A = [ [-3, 1], [1, 2] ] # subject to 1, 2
    b = [6, 4] # subject to 1, 2 (free term)
    x0_bounds = (None, None)
    x1_bounds = (-3, None)
[7]: from scipy.optimize import linprog
    result = linprog(
        c, # coeffs of the linear objective function to be minimized
        A_ub=A, # inequality constraint matrix: coeffs of a linear inequality
        b_ub=b, # inequality constraint vector: upper bound A_ub @ x
        bounds=(x0_bounds, x1_bounds), # sequence of (min, max) pairs for each_
    \rightarrowelement in x
        options={'disp': True}
    display(result)
```

Duality Gap

Step

Primal Feasibility Dual Feasibility

Objective

Path Parameter

```
-8.0
                       0.09885158404625
                                           0.09885158404625
    0.09885158404625
                                                              0.903461537018
    0.09885158404625
                       -6.284698425658
    0.05788429348353
                       0.05788429348355
                                           0.05788429348355
                                                               0.4273037994111
    0.05788429348355
                       -7.864724729573
    0.04539867008244
                                                               0.2387091287399
    0.04539867008244 -12.78916804766
    0.00666151448168
                       0.006661514481681
                                           0.006661514481682
                                                               0.8665142913493
    0.006661514481682 -21.3520715063
    6.299626472829e-06 6.299626472597e-06 6.299626472583e-06 1.0
    6.299626472568e-06 -21.99681708159
    3.150184161152e-10 3.150192895998e-10 3.150192773305e-10 0.999949939736
    3.150193133197e-10 -21.99999984082
    Optimization terminated successfully.
             Current function value: -22.000000
             Iterations: 6
         con: array([], dtype=float64)
         fun: -21.99999984082497
     message: 'Optimization terminated successfully.'
         nit: 6
       slack: array([3.89999997e+01, 8.46872172e-08])
      status: 0
     success: True
           x: array([ 9.99999989, -2.99999999])
[14]: # Example 2
     # A trading company is looking for a way to maximize profit per transportation
     \rightarrow of their goods.
     # The company has a train available with 3 wagons.
     # When stocking the wagons they can choose between 4 types of cargo, each with
     \rightarrow its own specifications.
     # How much of each cargo type should be loaded on which wagon in order to_{\sqcup}
     →maximize profit?
    data_matrix = [['Train Wagon', 'Item Capacity', 'Space Capacity'],
                   ['w1', 10, 5000],
                    ['w2', 8, 4000],
                    ['w3', 12, 8000],]
    data_matrix 2 = [['Cargo<br>Type', '#Items Available', 'Volume', 'Profit'],
                    ['c1', 18, 400,2000],
                    ['c2', 10, 300,2500],
                    ['c3', 5, 200,5000],
                    ['c4', 20, 500,3500]]
```

1.0

1.0

1.0

1.0

```
# Objective function
# max: +2000 C1 +2500 C2 +5000 C3 +3500 C4 +2000 C5 +2500 C6 +5000 C7 +3500 C8 _{oldsymbol{\sqcup}}
→+2000 C9 +2500 C10 +5000 C11 +3500 C12;
# Flip sign above to get MIN PROBLEM
# Constraints
# +C1 +C2 +C3 +C4 <= 10;
# +C5 +C6 +C7 +C8 <= 8;
# +C9 +C10 +C11 +C12 <= 12;
# +400 C1 +300 C2 +200 C3 +500 C4 <= 5000;
# +400 C5 +300 C6 +200 C7 +500 C8 <= 4000;
# +400 C9 +300 C10 +200 C11 +500 C12 <= 8000;
# +C1 +C5 +C9 <= 18;
# +C2 +C6 +C10 <= 10;
# +C3 +C7 +C11 <= 5;
# +C4 +C8 +C12 <= 20;
# What if we get rid of item constraint?
# Change min to max
c = [-2000, -2500, -5000, -3500, -2000, -2500, -5000, -3500, -2000, -2500, -5000, -3500]
xb=[]
for i in range (0,12):
    xb.append((0, None))
A = [
     [400,300,200,500,0,0,0,0,0,0,0,0,],
     [0,0,0,0,400,300,200,500,0,0,0,0]
     [0,0,0,0,0,0,0,0,400,300,200,500],
     [1,0,0,0,1,0,0,0,1,0,0,0]
     [0,1,0,0,0,1,0,0,0,1,0,0]
     [0,0,1,0,0,0,1,0,0,0,1,0]
     [0,0,0,1,0,0,0,1,0,0,0,1],
    ]
b = [5000, 4000, 8000, 18, 10, 5, 20]
res = linprog(c, A_ub=A, b_ub=b, bounds=xb,
              options={"disp": True})
print(res)
```

Primal Feasibility	Dual Feasibility	Duality Gap	Step	
Path Parameter	Objective			
1.0	1.0	1.0	-	1.0
-39000.0				
0.01857376342384	0.01857376342407	0.01857376342394	0.9814325002781	
0.01857376342401	-41923.6805552			

```
0.00827368183376
                                                      0.6023022624057
0.008273681833793 -57685.84657308
0.001369502404791 0.001369502404933
                                    0.001369502405595 -104680.9016415
2.177560547685e-05 2.177560547873e-05 2.177560547858e-05 0.9866690285217
2.177560548592e-05 -134394.9097331
1.238954819161e-09 1.238954871486e-09 1.238954870803e-09 0.9999431604847
1.238956052819e-09 -134999.965423
6.2835484587e-14 6.259364057527e-14 6.259349674501e-14 0.9999494786712
6.202546866317e-14 -134999.9999983
Optimization terminated successfully.
        Current function value: -134999.999998
        Iterations: 6
    con: array([], dtype=float64)
    fun: -134999.99999825243
message: 'Optimization terminated successfully.'
    nit: 6
  slack: array([6.86113708e-08, 4.87984835e-08, 1.26165105e-07, 1.05000000e+01,
      1.14406262e-10, 2.61639599e-11, 3.10620862e-10])
 status: 0
success: True
      x: array([ 2.46339402, 3.24582181, 1.67878867, 5.41027623,
2.22657249,
       2.82995238, 1.64300888, 3.86356703, 2.81003349, 3.92422581,
       1.67820245, 10.72615674])
```