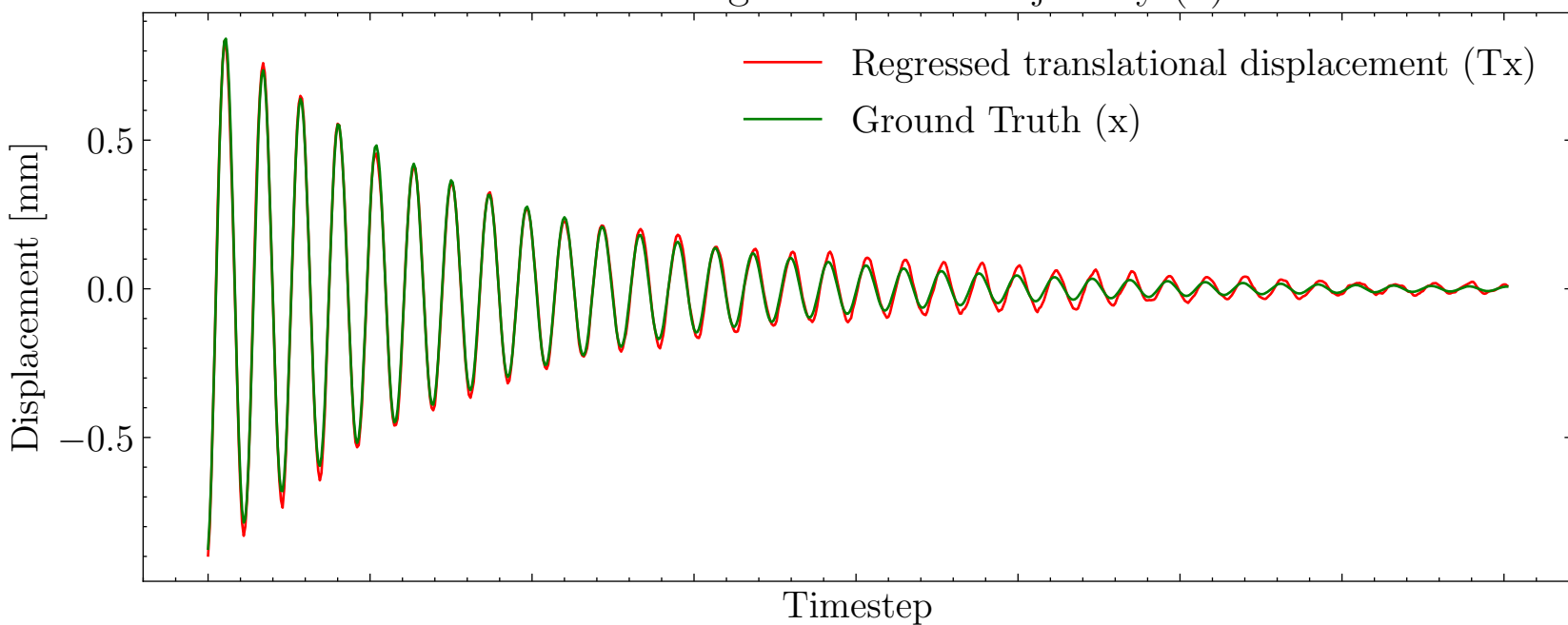
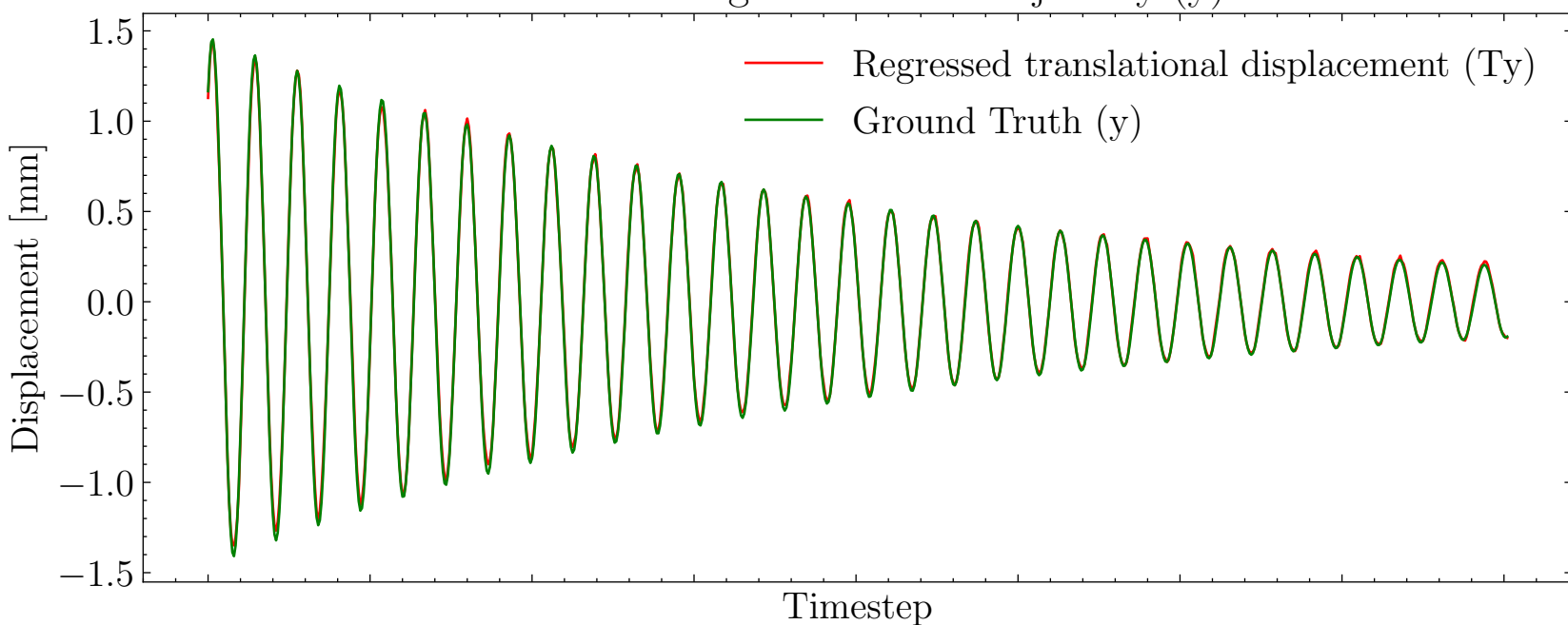


Predicted vs ground truth trajectory (x)



Predicted vs ground truth trajectory (y)



Predicted vs ground truth trajectory (z)

