

# Project Dijkstra (yes, we spelt it correctly)

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# **Content Page**

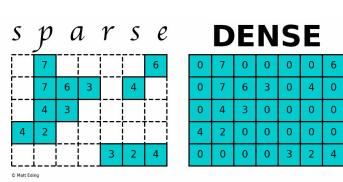
- Adjacency Matrix + Array (Time Complexity)
- Adjacency List + MinHeap (Time Complexity)
- Our Implementation
- Sparse vs Dense Graph (Theoretical)
- Empirical Trends
- Array + AdjMatrix vs MinHeap + AdjList
- Conclusion

# **Sparse & Dense Graph Definition**

- Sparse graph is a graph in which the number of edges is close to the minimal number of edges - sparsely connected
  - |E| = |**V**|
  - Binary trees
  - Can exist as a disconnected graph

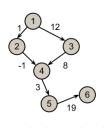


- Dense graph is a graph in which the number of edges is close to the maximal number of edges - densely connected
  - |E| = |V| \* |V-1|  $= |V|^2$
  - Complete graph



# **Time Complexity: Adjacency Matrix + Array**

	Time Complexity
Extract cheapest vertices for processing	Number of Vertices * (Extract next cheapest node + Relaxation of nodes) = O( V ) * [O( V ) + O( V )] = O V  <sup>2</sup>
Update Shortest Distance	Number of Edges * Update array = O( E ) * O(1) = O( E )
Overall	$O( V ^2 +  E )$ = $O( V ^2)$



Weighted Directed Graph

1	2	3	4	(5)	6
0	1	12	0	0	C
-1	0	0	-1	0	O
-12	0	0	8	0	С
0	1	-8	0	3	C
0	0	0	-3	0	19
0	0	0	0	-19	С
	-1	0 1 -1 0 -12 0 0 1 0 0	0 1 12 -1 0 0 -12 0 0 0 1 -8 0 0 0	0 1 12 0 -1 0 0 -1 -12 0 0 8 0 1 -8 0 0 0 0 -3	0 1 12 0 0 -1 0 0 -1 0 -12 0 0 8 0 0 1 -8 0 3 0 0 0 -3 0

Adjacency Matrix

# **Time Complexity: Adjacency List + MinHeap**

	Time Complexity
Heapify	O(log V )
Extract Vertex from Heap	Number of vertices * Cost of extracting root node = O( V ) * [O(log V ) * O(1)] = O( V  * log V )
Updating Path Cost	Number of edges * Cost of updating = O( E ) * O(log V ) = O( E  * log V )
Overall	O( E  og V  +  V  og V  +  og V ) = O([ E  +  V ] *log V )

# **Theoretical Best Case**

Sparse Graph  $\rightarrow$  |**E**| = |**V**| - **1** 

	Adjacency Matrix + Array	Adjacency List + MinHeap
Time Complexity (Formulae)	V  <sup>2</sup>	E  log  V
Vertices	1024	1024
Edges	1023	1023
Time Complexity	1,047,552	3079

# **Theoretical Worse Case**

Dense Graph  $\rightarrow$  E = V x (V - 1)

	Adjacency Matrix + Array	Adjacency List + MinHeap
Size of Priority Queue	V  <sup>2</sup>	( E + V )*log  V
Vertices	1024	1024
Edges	1,047,552	1,047,552
Time Complexity	1,048,576	3,156,528

# Our Implementation: PriorityQueue() using Array

```
class PriorityQueue(object):
    def __init__(self):
        self.queue = []
    def __str__(self):
        return ' '.join([str(i) for i in self.queue])
    def isEmpty(self):
        return len(self.queue) == 0
    # vertex is stored with distance
    # vertex 2 with distance 20: (2, 20)
    def insert(self, vertex):
        self.queue.append(vertex)
    def get smallest(self):
        min val = sys.maxsize
        min index = 0
        for i in range(len(self.queue)):
            if self.queue[i][1]<min_val:</pre>
                min_val = self.queue[i][1]
                min_index = i
        smallest = self.queue[min_index]
        del(self.queue[min index])
        return smallest
    def remove_vertex(self, vertex):
        for i in range(len(self.queue)):
            if self.queue[i][0] == vertex:
                item = self.queue[i]
                del(self.queue[i])
                return item
```



# Our Implementation: Heap()

```
def removeVertex(self, vertex):
   for i in range(self.size):
        # print(self.storage[i][0])
       if self.storage[i][0] == vertex:
           #print("vertex: ", vertex, " storage: ", self.storage)
            self.swap(i, self.size-1)
            del self.storage[self.size-1]
            self.size -= 1
            self.heapifyDown(i)
           #print("after heapifyDown: ", self.storage)
           break
def heapifyDown(self, index):
   while(self.hasLeftChild(index)):
        smallerChildIndex = self.getLeftChildIndex(index)
        self.comparisons += 1
       if(self.hasRightChild(index) and self.rightChild(index)[1] < self.leftChild(index)[1]);</pre>
            smallerChildIndex = self.getRightChildIndex(index)
        if (self.storage[index][1] < self.storage[smallerChildIndex][1]):</pre>
            break
            self.swap(index, smallerChildIndex)
        index = smallerChildIndex
```



```
def swap(self, i1, i2):
    self.storage[i1] colf storage[i2] - colf.storage[i2], self.storage[i1]
                  (parameter) vertex: Any
def insert(self, vertex):
    if(self.isFull()):
        raise("Heap is full")
    self.storage.append(vertex)
    self.size += 1
    self.heapifyUp()
def heapifyUp(self):
    # print("heapifyUp curr size", self.size)
    index = self.size-1
    while(self.hasParent(index) and self.parent(index)[1] > self.storage[index][1]);
        self.comparisons += 1
        self.swap(self.getParentIndex(index), index)
        index = self.getParentIndex(index)
    # print("after heapifyUp", self.storage)
def removeMin(self):
    if(self.size==0):
        raise("Empty Heap")
    node = self.storage[0]
    # print("removeMin Node", node)
    self.storage[0] = self.storage[self.size-1]
    del self.storage[self.size-1]
    self.size -=1
    self.heapifyDown(0)
    return node
```

# Our Implementation: Graph()

```
def init (self, v):
    self.graph = [[0 for column in range(v)]for row in range(v)]
    self.adiL = {}
    self.d = [sys.maxsize for x in range(v)]
    self.pi =[None for x in range(v)]
   self.comparisonsMHTotal, self.comparisonsDijkstraMH = 0, 0
   self.comparisonsArrTotal, self.comparisonsDijkstraArr = 0, 0
def getSize(self):
    return self.V
def adjList(self):
    for i in range(self.V):
       adjNodes = []
       for j in range(self.V):
            if self.graph[i][j]:
                adjNodes.append((j,self.graph[i][j]))
        self.adjL[i] = adjNodes
```

while(pq.isEmpty()==False): u = pq.get\_smallest() # u = (node, weight) self.S[u[0]] = 1

> # for each v adjacent to u for i in range(self.V):

> > self.pi[i] = u[0]

```
def dijkstra(self, source):
    self.d[source] = 0
    pq = PriorityQueue()
                                For when using Priority
   for i in range(self.V):
                                Queue (Array)
       pq.insert((i,self.d[i]))
```

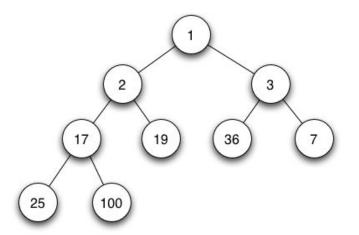
```
self.S[u[0]] = 1
                                                                        for v in self.adjL[u[0]]:
                                                                                pg2.removeVertex(v[0])
                                                                               self.pi[v[0]] = u[0]
                                                                                pq2.insert([v[0], self.d[v[0]]])
if self.graph[u[0]][i] > 0 and self.S[i] != 1 and self.d[i] > self.d[u[0]] + self.graph[u[0]][i]:
   pq.remove_vertex(i)
   self.d[i] = self.d[u[0]] + self.graph[u[0]][i]
   pq.insert((i,self.d[i]))
```

```
def dijkstraHQ(self, source):
   self.d[source] = 0
                                       For when using Heap
   pq2 = MinHeap(self.V)
   for i in range(self.V):
       pg2.insert([i, self.d[i]])
   while(pq2.isEmpty() == False):
       u = pq2.removeMin()
           if self.S[v[0]] != 1 and self.d[v[0]] > self.d[u[0]] + v[1]:
               self.d[v[0]] = self.d[u[0]] + v[1]
```

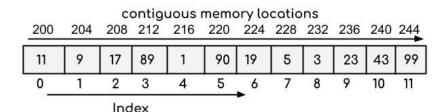
# **Our Methods: Important Functions**

✓ 0.2s

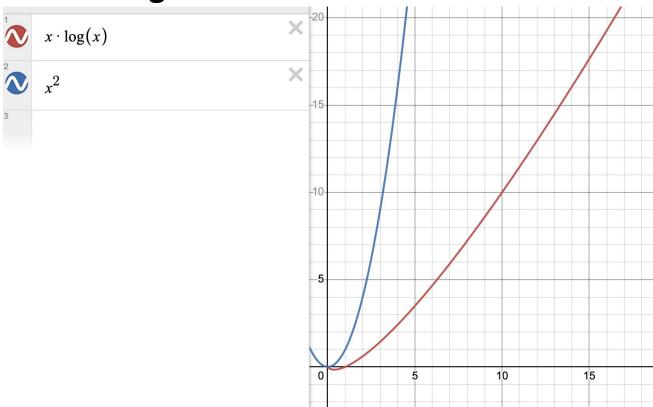
```
params : n == the number of nodes, density == the number of ed
                                                                                Generate Connected Graphs
generateConnectedGraph(n, density):
                                                                                        This function allows you to change the
mat = [[0 \text{ for } i \text{ in } range(n)] \text{ for } j \text{ in } range(n)]
                                                      (n, howMany, useMinHeap, density):
 setOfConnectedNodes = []
                                                                                             sity of graph, such that each node can be
 i = 0
                                                      .n range(howMany):
while (i < n):
                                                                                              hected to at most a certain number
                                                      it = generateConnectedGraph(n, density)
    # weight = randint(1,10)
                                                                                              isity) of other nodes.
    setOfConnectedNodes.append(i)
                                                      : Graph(n)
    if (i <= 1):
                                                      |raph| = gMat
                                                                                             e that the density < number of nodes,
        weight = randint(1,n*2)
        if (i == 1):
                                                       (useMinHeap):
                                                                                             ause one node can have at most V-1
           mat[0][1] = weight
                                                        time.append(runDijkstraHQ(g, 0))
           mat[1][0] = weight
                                                                                             es!
        i+=1
                                                        time.append(runDijkstra(g, 0))
                                                                                Average Time Calculation
                                                       sum(time)/len(time)
    for j in range(density+1):
        weight = randint(1,n*2)
                                                                                        Important to obtain averages
        adjI = randint(0, i-1)
                                                                                        of the same case, but
        adj = setOfConnectedNodes[adjI]
        mat[i][adj] = weight
                                                                                        different graphs.
        mat[adj][i] = weight
    i+=1
 return mat
```



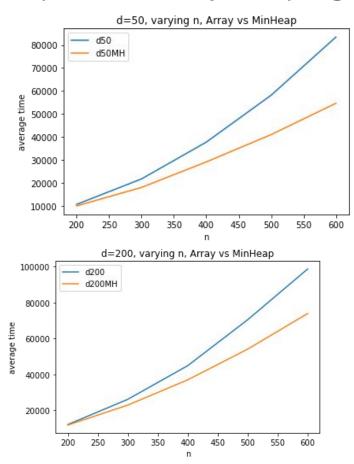
# Array vs MinHeap

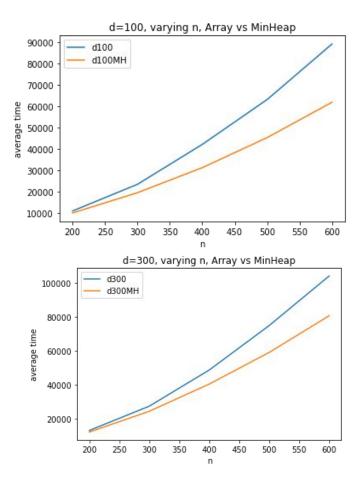


# It follows the general trend



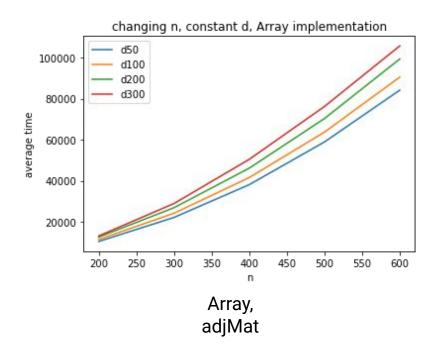
# Array vs MinHeap, varying n

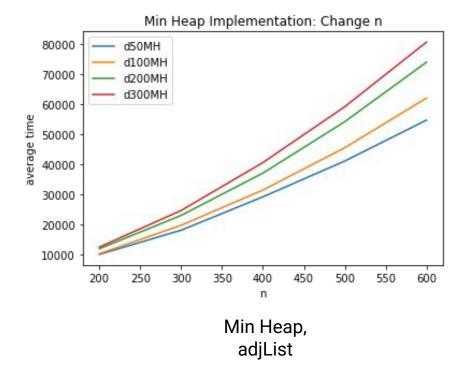




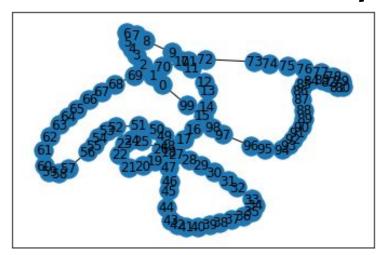
# **Empirical Trends: Changing n, constant densities**

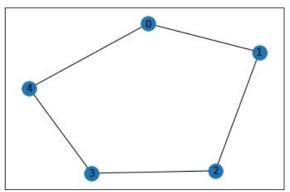
d = 50, 100, 200, 300

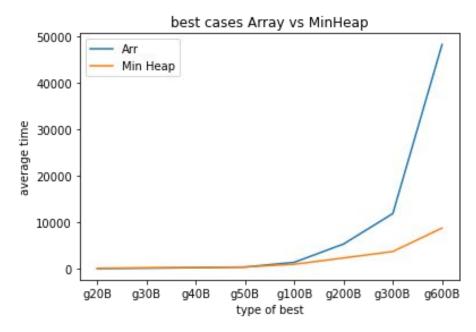




# The best case for MinHeap?





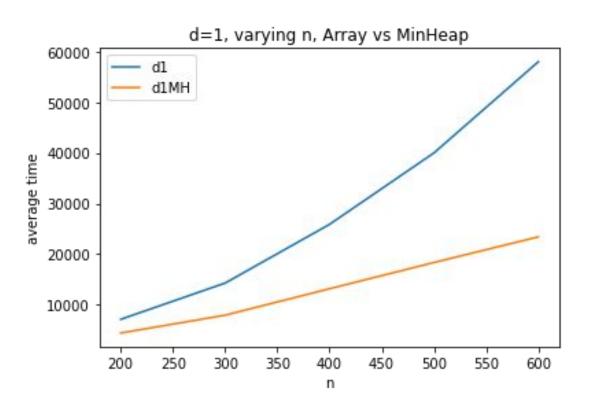


Rate of growth in average time much much **lower** using Minimum Heap for sparse graph

Reasoning: Using adjacency list, we only need to loop through the adjacent nodes, not all the nodes.

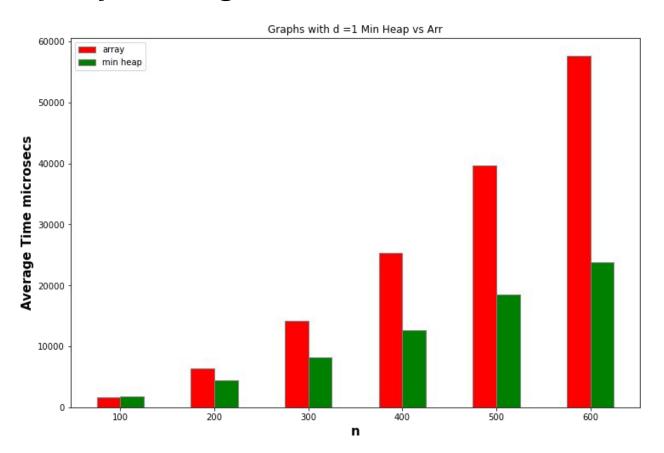
### **The case of d = 1:**

Sparse connected graph

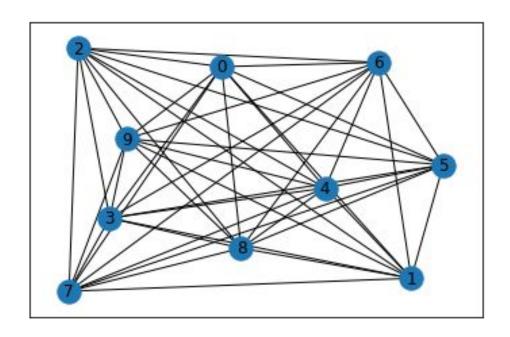


We can observe that MinHeap performs better when the graph is sparsely connected

# What if it was sparse in general?

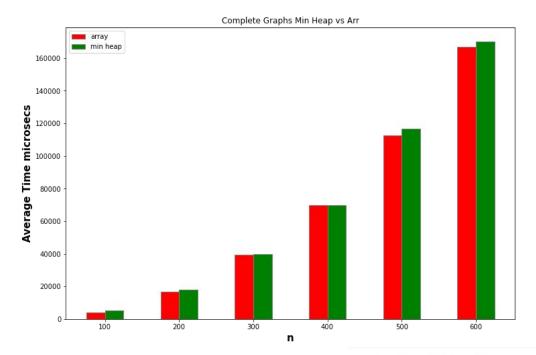


# The best case for Array?



We would expect that complete graphs will be the best cases for adjacency matrix (& using Array)

# **Using Array Performs Better: Complete Graphs**

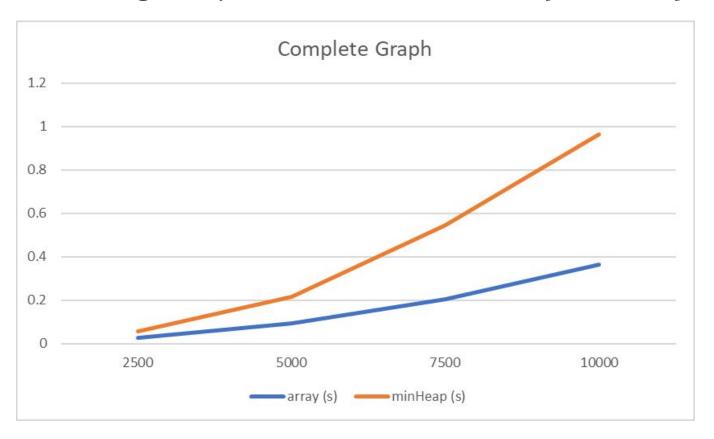


Because array implementation uses AdjMatrix, and Matrices have better cache performance.

(according to Stack Overflow)

@realUser404 Exactly, scanning a whole matrix row is an O(n) operation. Adjacency lists are better for sparse graphs when you need to traverse all outgoing edges, they can do that in O(d) (d: degree of the node). Matrices have better cache performance than adjacency lists though, because of sequential access, so for a somewhat dense graphs, scanning a matrices can make more sense. – Jochem Kuijpers Oct 15, 2018 at 11:50

# Using Array Performs Better: Complete Graphs (in C)



C implementation

## **Conclusion**

If the graph is dense and compact → Complete graph

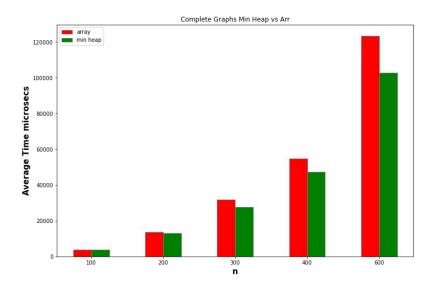
Use Adjacency Matrix with Array as Priority Queue

If the graph is sparse and less compact → Incomplete graph

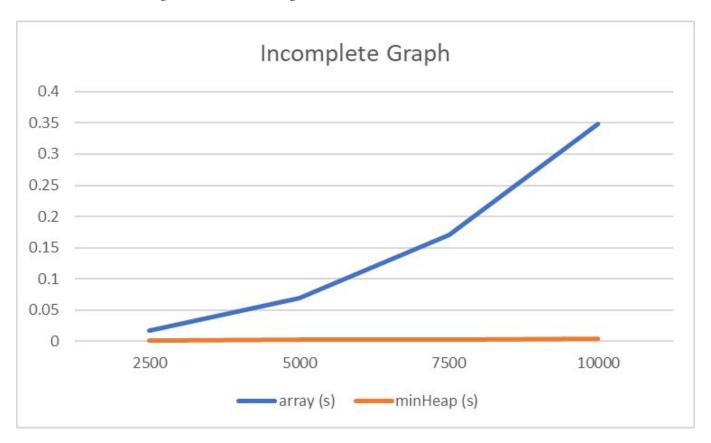
Use Adjacency List with MinHeap as Priority Queue

# Some other findings and thoughts

- Using numpy matrix to represent our AdjMatrix may make operations faster (in the context of Python)
- The variation in weights also affects performance.
  - This is because by mistake, we randomly generated **weights only from [1,10]**
  - This may suggest that the dijkstra takes longer to find the shortest path because the difference between values may be very small and therefore, when you pick from the queue, there are high chances that you have to explore more nodes.
  - Our array implementation showed worse performance (weights [1,10]) highly because the advantage in better cache performance was masked by the better O(ElogV) of the MinHeap Implementation.
- CPython!



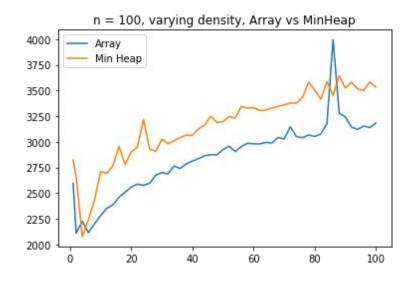
# Incomplete Graphs (in C)

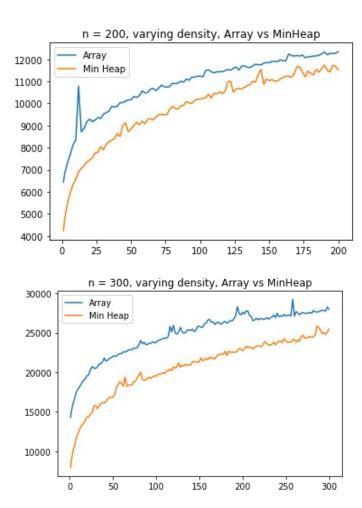


C implementation

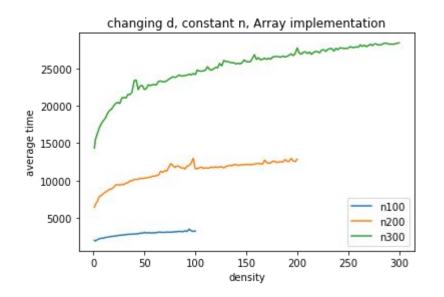
Thank you:)

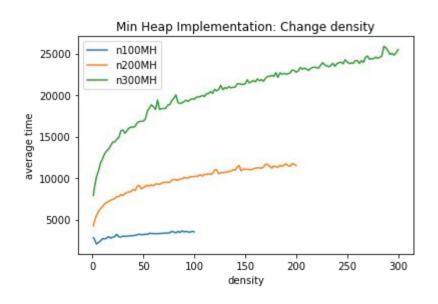
# Array vs MinHeap, varying density





# **Changing Density, Constant n for n = 100,200,300**





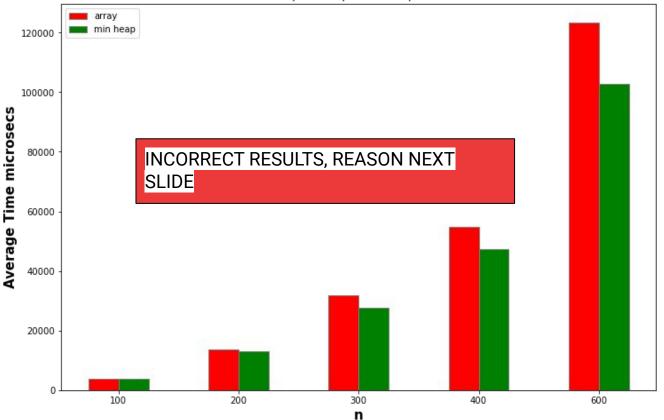
Array, using adjMatrix

MinHeap, using adjList



Initially, we got our results as this:

- This seems incorrect, because Complete graphs theoretically favours Array Implementation



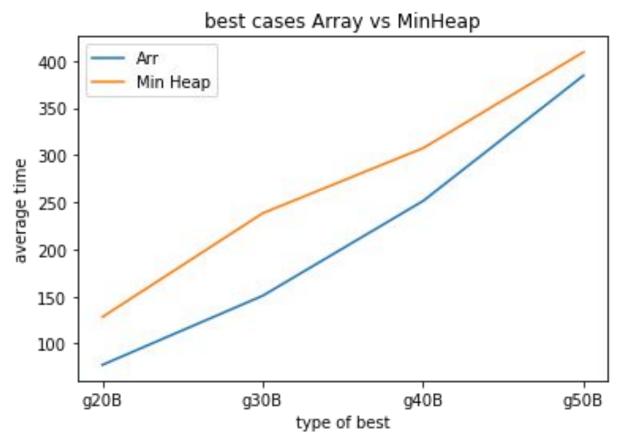
# Found the problem! Range of Weights too small!

```
# params : n == the number of nodes, density == the number of edges that o
def generateConnectedGraph(n, density):
   mat = [[0 for i in range(n)] for j in range (n)]
    setOfConnectedNodes = []
    i = 0
   while (i < n):
        # weight = randint(1,10)
        setOfConnectedNodes.append(i)
        if (i \leftarrow 1):
           weight = randint(1,10)
            if (i == 1):
                mat[0][1] = weight
                mat[1][0] = weight
            i+=1
            continue
        for j in range(density+1):
            weight = randint(1,10)
            adjI = randint(0, i-1)
            adj = setOfConnectedNodes[adjI]
            mat[i][adj] = weight
            mat[adj][i] = weight
        i+=1
```

The range of random integers too small.

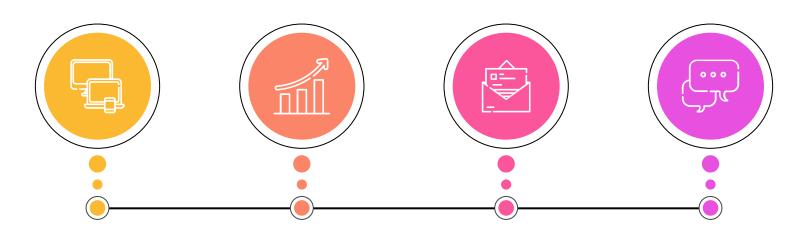
- Therefore, there are many repeats of the same weight
- This case may favour min heap implementation more, because it's likely to make the search

## BUT if we zoom in



We can observe that the Array performs slightly better.

This may suggest that the



Mars

Despite being red, Mars is a cold place

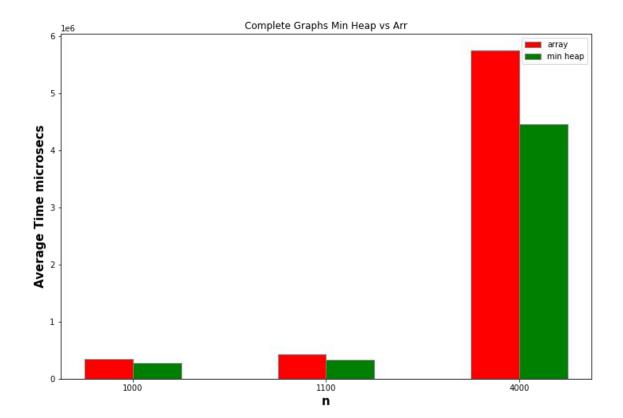
**Jupiter** 

Jupiter is a gas giant and the biggest planet

Saturn

It's composed of hydrogen and helium **Neptune** 

Neptune is the farthest planet from the Sun



#### **Mercury**

Mercury is the closest planet to the Sun and the smallest one

# Earth Earth

#### **Neptune**

Neptune is the farthest planet from the Sun and the fourth-largest one

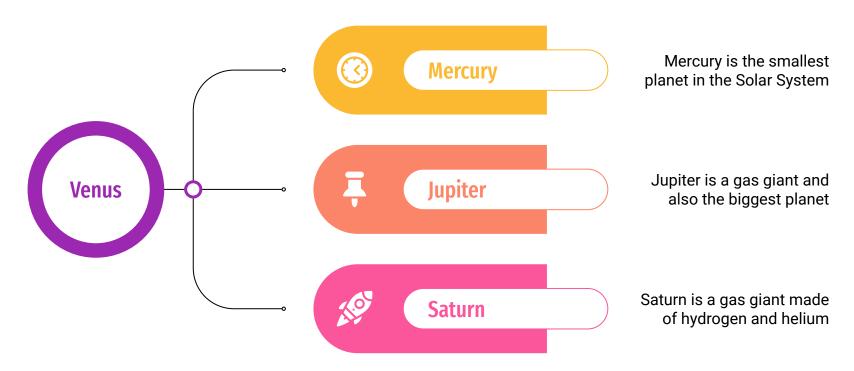
#### Mars

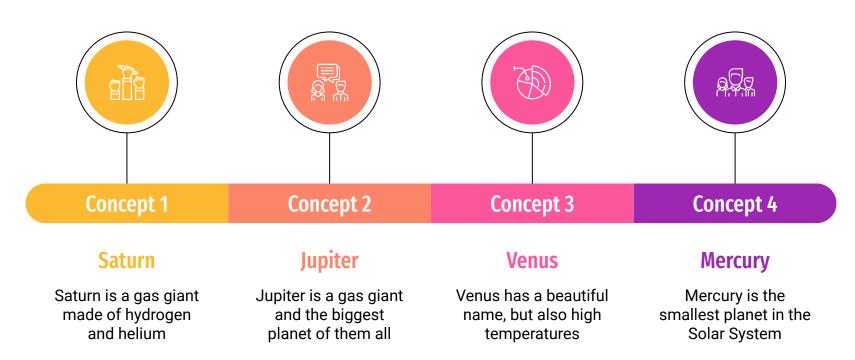
Despite being red, Mars is a cold place full of iron oxide dust

#### **Earth**

Earth is the third planet from the Sun and the only one that harbors life







**STRENGTHS** 

**WEAKNESSES** 

**OPPORTUNITIES** 

**THREATS** 



#### Venus

Venus has a beautiful name and high temperatures



#### Mars

Despite being red, Mars is a cold place full of iron oxide dust



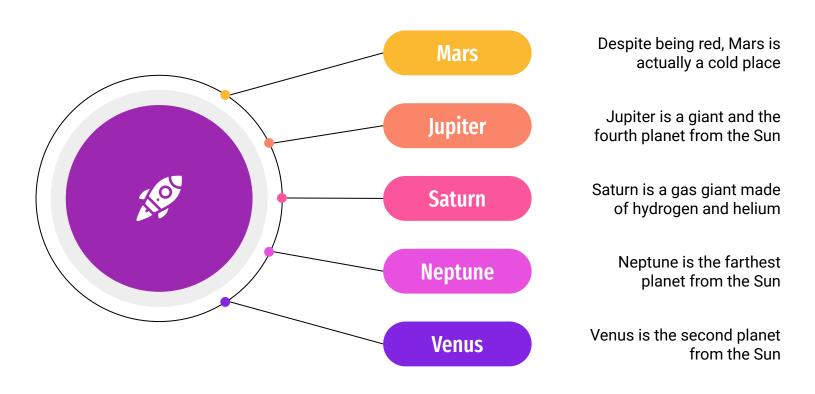
### Jupiter

Jupiter is the fourth and the biggest planet



#### Saturn

Saturn is composed of hydrogen and also helium





Mercury is the closest planet to the Sun



### Step 02

Despite being red, Mars is a cold place



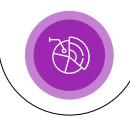
### Step 03

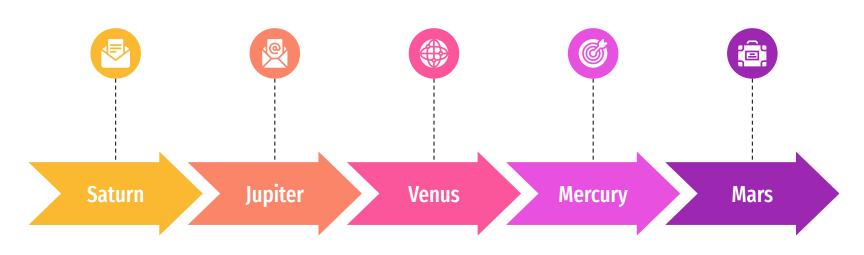
Jupiter is a gas giant and the biggest planet



### Step 04

Neptune is the farthest planet from the Sun





Saturn is a gas giant made of hydrogen and helium Jupiter is a gas giant and the biggest planet

Venus is the second planet from the Sun

Mercury is the smallest planet in the Solar System

Despite being red, Mars is actually a cold place

#### Saturn

Saturn is a gas giant composed mostly of hydrogen and helium



#### Mars

Despite being red, Mars is a cold place full of iron oxide dust

### **Jupiter**

Jupiter is a gas giant and the biggest planet in the Solar System

#### Venus

Venus has a beautiful name, but it is terribly hot there

### Mercury

Mercury is the smallest planet in the Solar System



#### Saturn

Saturn is a gas giant made of hydrogen and helium



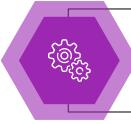
### Mercury

Mercury is the smallest planet in the Solar System



### Jupiter

Jupiter is a gas giant and the biggest planet



### Neptune

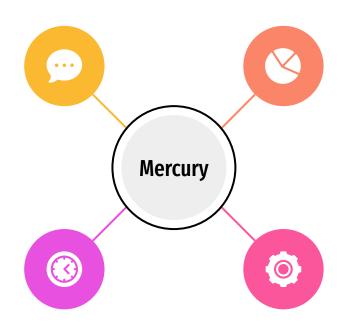
Neptune is the farthest planet from the Sun

#### Mercury

Mercury is the closest planet to the Sun and the smallest one

#### Saturn

Despite being red, Mars is a cold place full of iron oxide dust



### Neptune

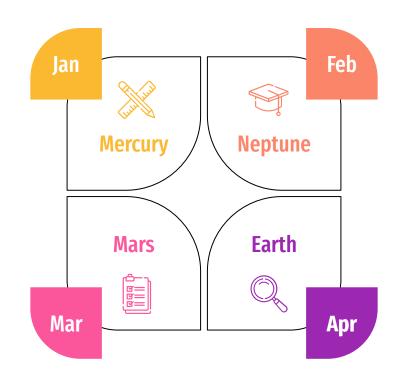
Neptune is the farthest planet from the Sun and the fourth-largest

#### **Earth**

Earth is the third planet from the Sun and the only one that harbors life

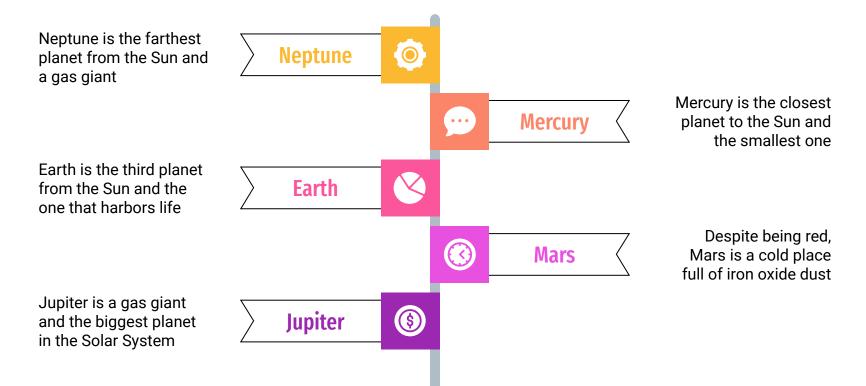
Mercury is the closest planet to the Sun and the smallest one

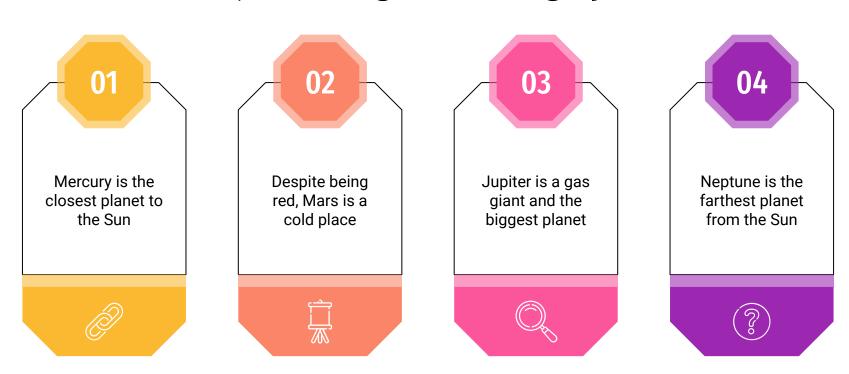
Despite being red, Mars is a cold place full of iron oxide dust



Neptune is the farthest planet from the Sun and the fourth-largest one

Earth is the third planet from the Sun and the only one that harbors life





#### **Neptune**

Neptune is the farthest planet from the Sun and a gas giant

## Item 2 Item 1 2023 Item 3 Item 4

#### Mercury

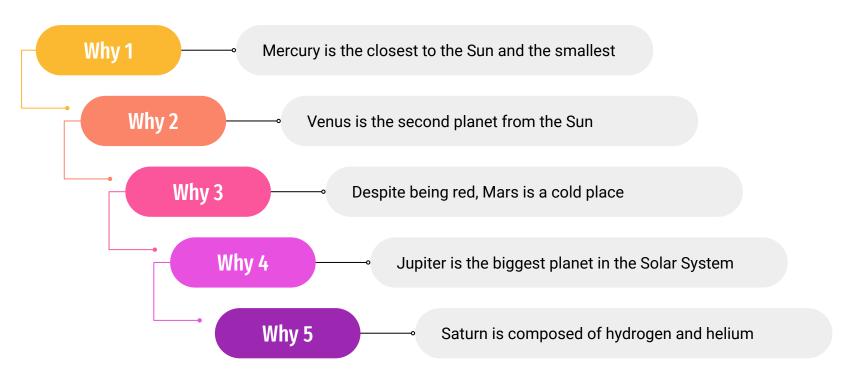
Mercury is the closest planet to the Sun and the smallest

#### **Earth**

Earth is the third planet from the Sun

#### Mars

Despite being red, Mars is actually a cold place



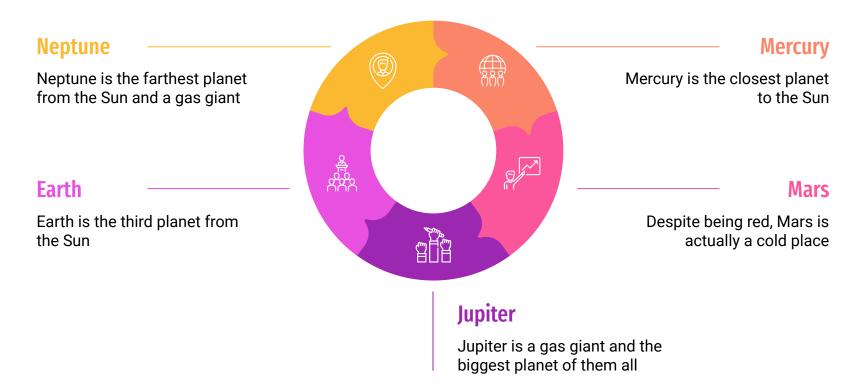
Neptune is the farthest planet from the Sun and a gas giant

Earth is the third planet from the Sun and the only one that harbors life



Despite being red, Mars is a very cold place full of iron oxide dust

Jupiter is a gas giant and the biggest planet in the Solar System

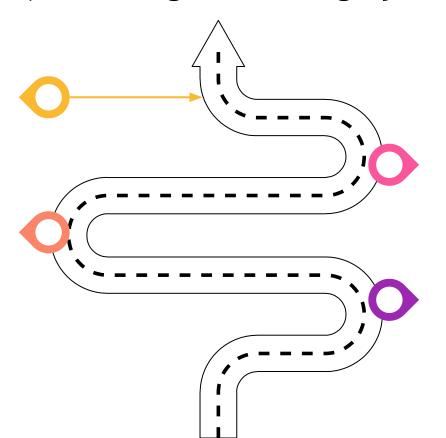


### Neptune

Neptune is the farthest planet from the Sun

### Saturn

Saturn is composed of hydrogen and helium



### Mars

Despite being red, Mars is a very cold place

### Mercury

Mercury is the closest planet to the Sun

#### Saturn

Saturn is a gas giant made of hydrogen and helium

### **Jupiter**

Jupiter is a gas giant and the biggest planet

#### Venus

Venus is the second planet from the Sun



#### Mercury

Mercury is the smallest planet in the Solar System

#### Neptune

Neptune is the farthest planet from the Sun

#### Mars

Despite being red, Mars is actually a cold place

Planet Jupiter is a gas giant and also the biggest one in the Solar System

Task 1

Mercury is the closest to the Sun and the smallest one in the Solar System

Task 2

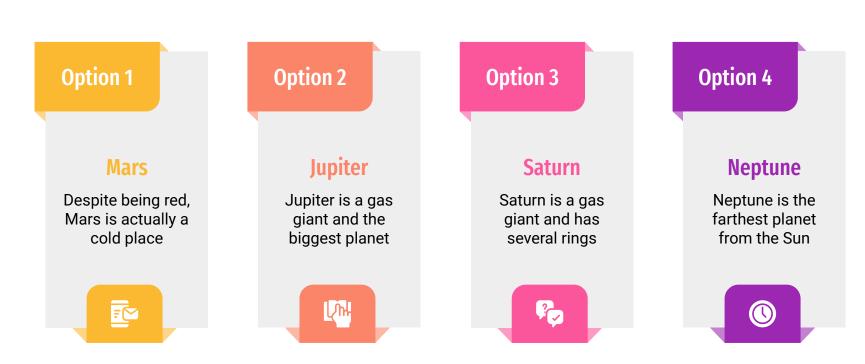
Despite being red, Mars is a very cold place full of iron oxide dust

Task 3

Earth is the third planet from the Sun and the only one that harbors life

# **Project Management Infographics**

Venus has a beautiful name and is the second planet from the Sun. It's terribly hot—even hotter than Mercury—and its atmosphere is extremely poisonous. It's the second-brightest natural object in the night sky after the Moon

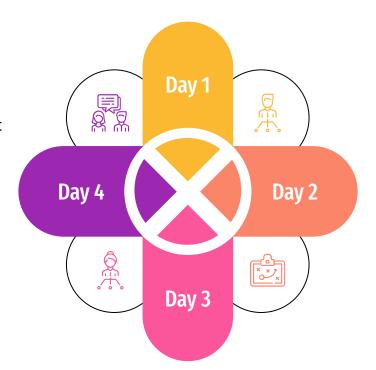


### **Neptune**

Neptune is the farthest planet from the Sun and a gas giant

#### **Earth**

Earth is the third planet from the Sun

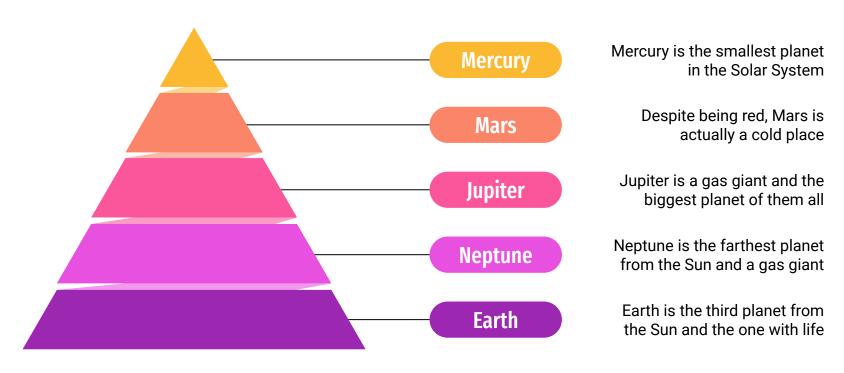


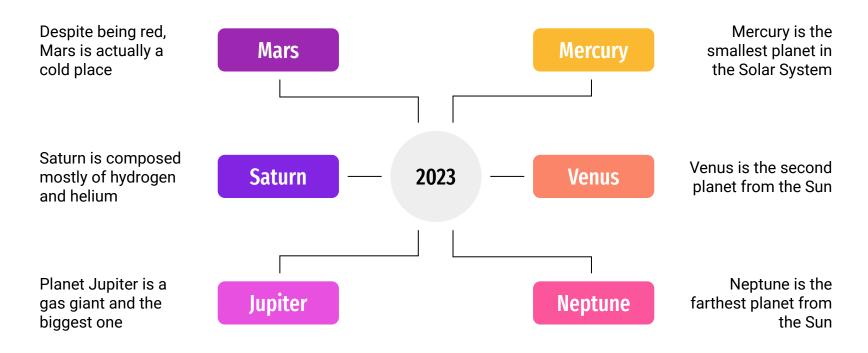
#### Mercury

Mercury is the closest planet to the Sun

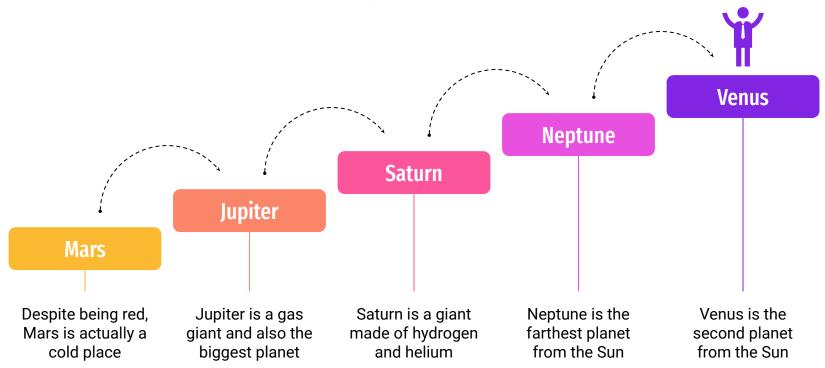
#### Mars

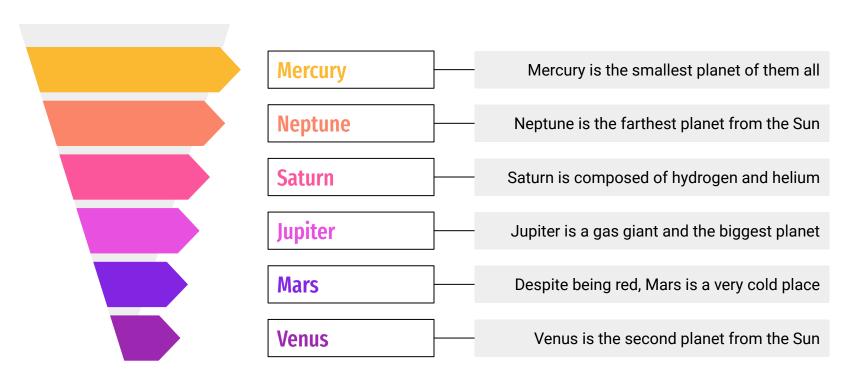
Despite being red, Mars is actually a cold place











01 Saturn

02 Mercury

03 Mars

04 Venus



Planet Saturn is a gas giant composed mostly of hydrogen and helium

Mercury is the smallest planet in the Solar System and the closest to the Sun

Despite being red, Mars is a very cold place full of iron oxide dust

Venus has a beautiful name and is the second planet from the Sun

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   + Ctrl V or Cmd C + Cmd V in Mac.
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- Change the color by clicking on the paint bucket.
- Then resize the element by clicking and dragging one of the square-shaped points of its bounding box (the cursor should look like a double-headed arrow).
   Remember to hold Shift while dragging to keep the proportions.
- Group the elements again by selecting them, right-clicking and choosing "Group".
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