Decision Tree Learning

Based on "Machine Learning", T. Mitchell, McGRAW Hill, 1997, ch. 3

Acknowledgement:

The present slides are an adaptation of slides drawn by T. Mitchell

PLAN

- Concept learning: an example
- Decision tree representation
- ID3 learning algorithm
- Statistical measures in decision tree learning: Entropy, Information gain
- Issues in DT Learning:
 - 1. Inductive bias in ID3
 - 2. Avoiding overfitting of data
 - 3. Incorporating continuous-valued attributes
 - 4. Alternative measures for selecting attributes
 - 5. Handling training examples with missing attributes values
 - 6. Handling attributes with different costs

1. Concept learning: an example

Given the data:

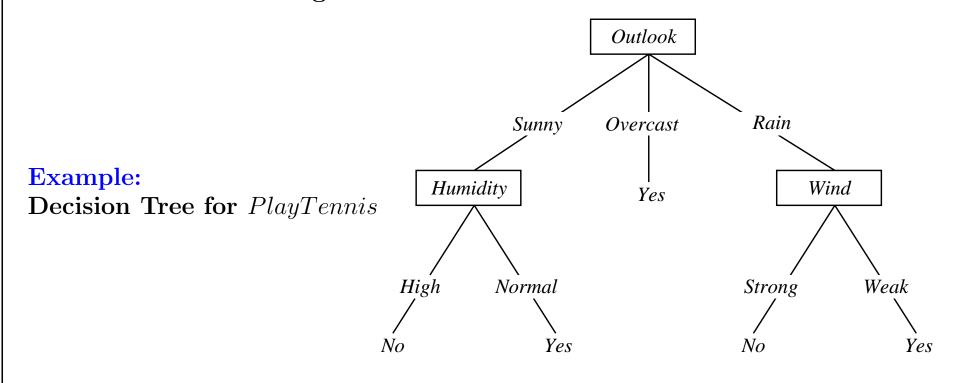
Day	Outlook	Temperature	Humidity	Wind	PlayTennis
D1	Sunny	Hot	High	Weak	No
$\mathbf{D2}$	Sunny	\mathbf{Hot}	${f High}$	\mathbf{Strong}	\mathbf{No}
$\mathbf{D3}$	Overcast	\mathbf{Hot}	${f High}$	\mathbf{Weak}	Yes
$\mathbf{D4}$	Rain	\mathbf{Mild}	${f High}$	\mathbf{Weak}	Yes
$\mathbf{D5}$	Rain	\mathbf{Cool}	Normal	\mathbf{Weak}	Yes
D6	Rain	\mathbf{Cool}	Normal	\mathbf{Strong}	No
D7	Overcast	\mathbf{Cool}	Normal	\mathbf{Strong}	Yes
$\mathbf{D8}$	Sunny	\mathbf{Mild}	${f High}$	\mathbf{Weak}	No
D9	Sunny	\mathbf{Cool}	Normal	\mathbf{Weak}	Yes
D10	Rain	\mathbf{Mild}	Normal	Weak	Yes
D11	Sunny	\mathbf{Mild}	Normal	\mathbf{Strong}	Yes
D12	Overcast	\mathbf{Mild}	${f High}$	\mathbf{Strong}	Yes
D13	Overcast	\mathbf{Hot}	Normal	Weak	Yes
D14	Rain	Mild	High	Strong	No

predict the value of PlayTennis for

 $\langle Outlook = sunny, Temp = cool, Humidity = high, Wind = strong \rangle$

2. Decision tree representation

- Each internal node tests an attribute
- Each branch corresponds to attribute value
- Each leaf node assigns a classification



Another example:

A Tree to Predict C-Section Risk

Learned from medical records of 1000 women

Negative examples are C-sections

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[833+,167-] .83+ .17-
Fetal_Presentation = 1: [822+,116-] .88+ .12-
| Previous_Csection = 0: [767+,81-] .90+ .10-
| | Primiparous = 0: [399+,13-] .97+ .03-
| | Primiparous = 1: [368+,68-] .84+ .16-
| | | Fetal_Distress = 0: [334+,47-] .88+ .12-
| | | Birth_Weight < 3349: [201+,10.6-] .95+ .05-
| | | Birth_Weight >= 3349: [133+,36.4-] .78+ .22-
| | Fetal_Distress = 1: [34+,21-] .62+ .38-
| Previous_Csection = 1: [55+,35-] .61+ .39-
Fetal_Presentation = 2: [3+,29-] .11+ .89-
Fetal_Presentation = 3: [8+,22-] .27+ .73-
```

When to Consider Decision Trees

- Instances describable by attribute–value pairs
- Target function is discrete valued
- Disjunctive hypothesis may be required
- Possibly noisy training data

Examples:

- Equipment or medical diagnosis
- Credit risk analysis
- Modeling calendar scheduling preferences

3. ID3 Algorithm: Top-Down Induction of Decision Trees

START

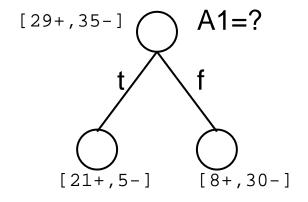
create the root *node*; assign all examples to root;

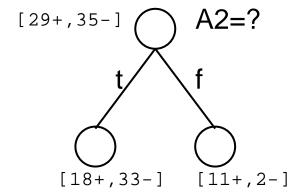
Main loop:

- 1. $A \leftarrow$ the "best" decision attribute for next node;
- 2. for each value of A, create a new descendant of node;
- 3. sort training examples to leaf nodes;
- 4. if training examples perfectly classified, then STOP; else iterate over new leaf nodes

4. Statistical measures in DT leraning: Entropy, Information Gain

Which attribute is best?





Entropy

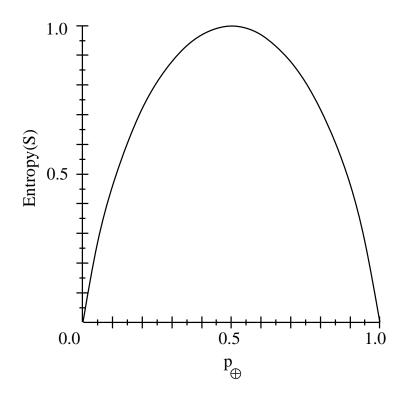
- Let S be a sample of training examples p_{\oplus} is the proportion of positive examples in S p_{\ominus} is the proportion of negative examples in S
- Entropy measures the impurity of S
- Information theory:

Entropy(S) =expected number of bits needed to encode \oplus or \ominus for a randomly drawn member of S (under the optimal, shortest-length code)

The optimal length code for a message having the probability p is $-\log_2 p$ bits. So:

$$Entropy(S) \equiv p_{\oplus}(-\log_2 p_{\oplus}) + p_{\ominus}(-\log_2 p_{\ominus}) = -p_{\oplus}\log_2 p_{\oplus} - p_{\ominus}\log_2 p_{\ominus}$$

Entropy

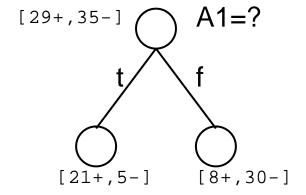


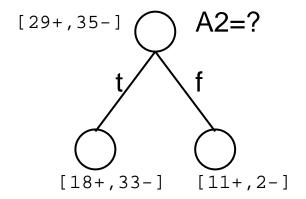
 $Entropy(S) \equiv -p_{\oplus} \log_2 p_{\oplus} - p_{\ominus} \log_2 p_{\ominus}$

Information Gain:

expected reduction in entropy due to sorting on A

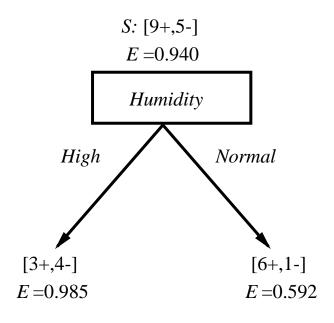
$$Gain(S, A) \equiv Entropy(S) - \sum_{v \in Values(A)} \frac{|S_v|}{|S|} Entropy(S_v)$$

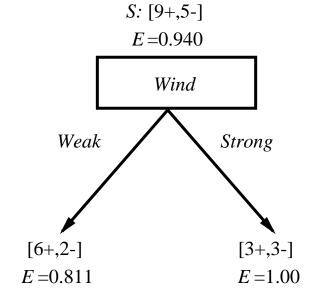




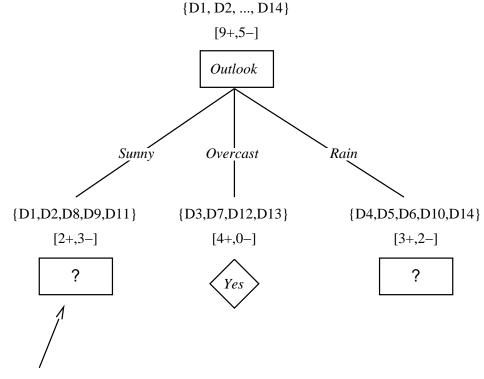
Selecting the Next Attribute

Which attribute is the best classifier?





Partially learned tree



Which attribute should be tested here?

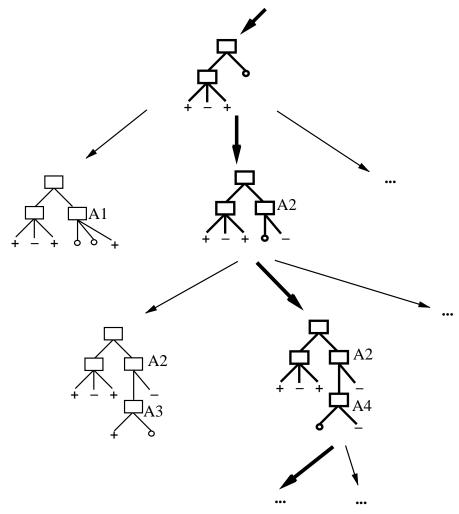
$$S_{sunny} = \{D1,D2,D8,D9,D11\}$$

$$Gain (S_{sunny}, Humidity) = .970 - (3/5) 0.0 - (2/5) 0.0 = .970$$

$$Gain (S_{sunny}, Temperature) = .970 - (2/5) 0.0 - (2/5) 1.0 - (1/5) 0.0 = .570$$

$$Gain (S_{sunny}, Wind) = .970 - (2/5) 1.0 - (3/5) .918 = .019$$

Hypothesis Space Search by ID3



Hypothesis Space Search by ID3

- Hypothesis space is complete!
 - Target function surely in there...
- Outputs a single hypothesis
 - Which one?
- Inductive bias: approximate "prefer shortest tree"
- No back tracking
 - Local minima...
- Statistically-based search choices
 - Robust to noisy data...

5. Issues in DT Learning

5.1 Inductive Bias in ID3

Note: H is the power set of instances X

 \rightarrow Unbiased?

Not really...

- Preference for short trees, and for those with high information gain attributes near the root
- Bias is a *preference* for some hypotheses, rather than a *restriction* of hypothesis space *H*
- Occam's razor: prefer the shortest hypothesis that fits the data

Occam's Razor

Why prefer short hypotheses?

Argument in favor:

- Fewer short hypotheses than long hypsotheses
 - → a short hypothesis that fits data unlikely to be coincidence
 - \rightarrow a long hypothesis that fits data might be coincidence

Argument opposed:

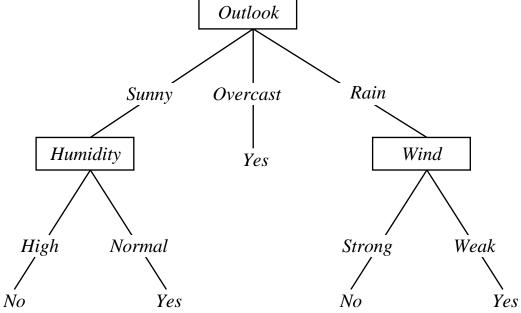
- There are many ways to define small sets of hypotheses (E.g., all trees with a prime number of nodes that use attributes beginning with "Z".)
- What's so special about small sets based on *size* of hypothesis??

5.2 Overfitting in Decision Trees

Consider adding noisy training example #15:

(Sunny, Hot, Normal, Strong, PlayTennis = No)

What effect does it produce on the earlier tree?



Overfitting: Definition

Consider error of hypothesis h over

- training data: $error_{train}(h)$
- entire distribution \mathcal{D} of data: $error_{\mathcal{D}}(h)$

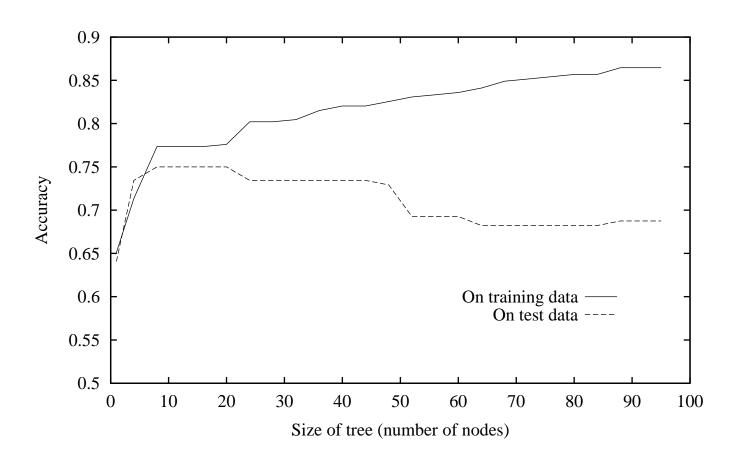
Hypothesis $h \in H$ overfits training data if there is an alternative hypothesis $h' \in H$ such that

$$error_{train}(h) < error_{train}(h')$$

and

$$error_{\mathcal{D}}(h) > error_{\mathcal{D}}(h')$$

Overfitting in Decision Tree Learning



Avoiding Overfitting

How can we avoid overfitting?

- stop growing when the data split is not anymore statistically significant
- grow full tree, then post-prune

How to select "best" tree:

- Measure performance over training data
- Measure performance over a separate validation data set
- MDL: minimize size(tree) + size(misclassifications(tree))

Reduced-Error Pruning

Split data into training set and validation set

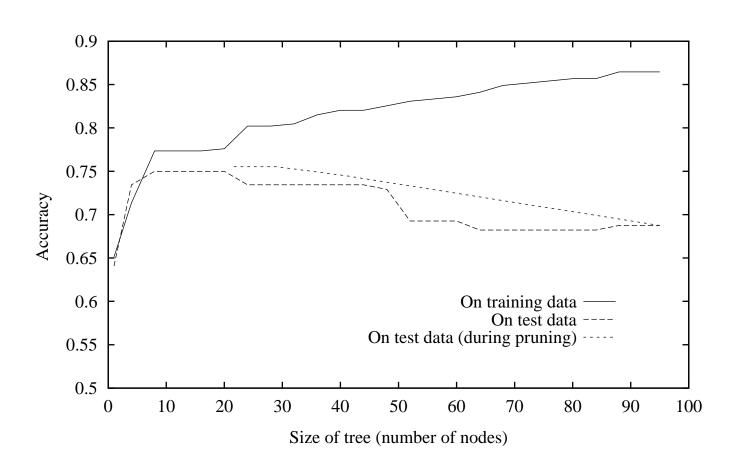
Do until further pruning is harmful:

- 1. Evaluate impact on validation set of pruning each possible node (plus those below it)
- 2. Greedily remove the one that most improves validation set accuracy

Efect: Produces the smallest version of most accurate subtree

Question: What if data is limited?

Effect of Reduced-Error Pruning

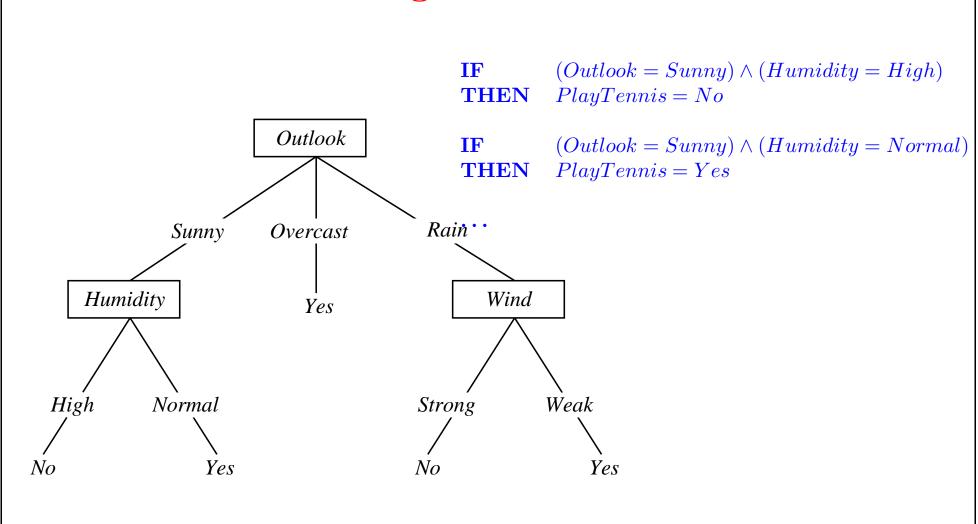


Rule Post-Pruning

- 1. Convert tree to equivalent set of rules
- 2. Prune each rule independently of others
- 3. Sort final rules into desired sequence for use

It is perhaps most frequently used method (e.g., C4.5)

Converting A Tree to Rules



5.3 Continuous Valued Attributes

Create a discrete attribute to test continuous

- \bullet Temperature = 82.5
- (Temperature > 72.3) = t, f

Temperature: 40 48 60 72 80 90 PlayTennis: No No Yes Yes Yes No

5.4 Attributes with Many Values

Problem:

- If attribute has many values, Gain will select it
- Imagine using $Date = Jun_3_1996$ as attribute

One approach: use GainRatio instead

$$GainRatio(S, A) \equiv \frac{Gain(S, A)}{SplitInformation(S, A)}$$

$$SplitInformation(S, A) \equiv -\sum_{i=1}^{c} \frac{|S_i|}{|S|} \log_2 \frac{|S_i|}{|S|}$$

where S_i is the subset of S for which A has the value v_i

5.5 Attributes with Costs

Consider

- medical diagnosis, BloodTest has cost \$150
- robotics, Width_from_1ft has cost 23 sec.

Question: How to learn a consistent tree with low expected cost?

One approach: replace gain by

- $ullet rac{Gain^2(S,A)}{Cost(A)}$ (Tan and Schlimmer, 1990)
- $\bullet \ \frac{2^{Gain(S,A)}-1}{(Cost(A)+1)^w} \qquad \text{(Nunez, 1988)}$

where $w \in [0,1]$ determines importance of cost

5.6 Unknown Attribute Values

Question: What if an example is missing the value of an attribute A?

Use the training example anyway, sort through tree

- If node n tests A, assign the most common value of A among the other examples sorted to node n
- assign the most common value of A among the other examples with same target value
- assign probability p_i to each possible value v_i of A
 - assign the fraction p_i of the example to each descendant in the tree

Classify new examples in same fashion.