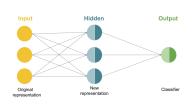
# **Deep Learning**

# Single hidden layer neural networks

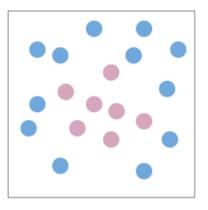


#### Learning goals

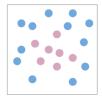
- Architecture of single hidden layer neural networks
- Representation learning/ understanding the advantage of hidden layers
- Typical (non-linear) activation functions

- The graphical way of representing simple functions/models, like logistic regression. Why is that useful?
- Because individual neurons can be used as building blocks of more complicated functions.
- Networks of neurons can represent extremely complex hypothesis spaces.
- Most importantly, it allows us to define the "right" kinds of hypothesis spaces to learn functions that are common in our universe in a data-efficient way (see Lin, Tegmark et al. 2016).

Can a single neuron perform binary classification of these points?



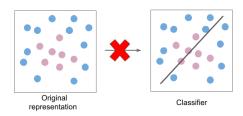
 As a single neuron is restricted to learning only linear decision boundaries, its performance on the following task is quite poor:



 However, the neuron can easily separate the classes if the original features are transformed (e.g., from Cartesian to polar coordinates):



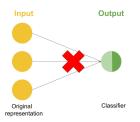
• Instead of classifying the data in the original representation,



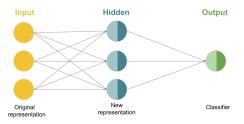
we classify it in a new feature space.



• Analogously, instead of a single neuron,



• we use more complex networks.



#### REPRESENTATION LEARNING

- It is very critical to feed a classifier the "right" features in order for it to perform well.
- Before deep learning took off, features for tasks like machine vision and speech recognition were "hand-designed" by domain experts. This step of the machine learning pipeline is called feature engineering.
- DL automates feature engineering. This is called representation learning.

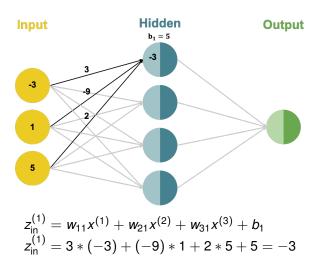
## SINGLE HIDDEN LAYER NETWORKS

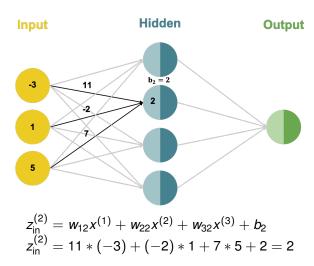
**Single neurons** perform a 2-step computation:

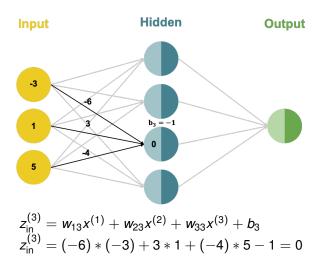
- **•** Affine Transformation: a weighted sum of inputs plus bias.
- Activation: a non-linear transformation on the weighted sum.

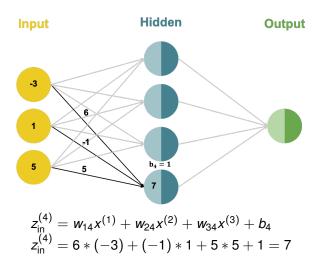
**Single hidden layer networks** consist of two layers (without input layer):

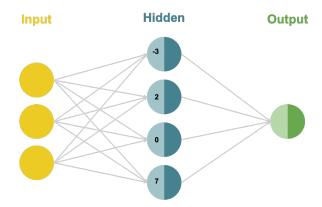
- Hidden Layer: having a set of neurons.
- 2 Output Layer: having one or more output neurons.
  - Multiple inputs are simultaneously fed to the network.
  - Each neuron in the hidden layer performs a 2-step computation.
- The final output of the network is then calculated by another 2-step computation performed by the neuron in the output layer.



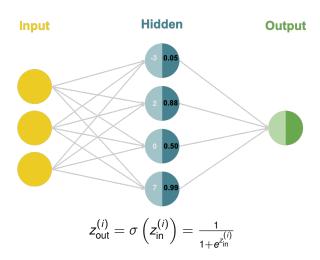




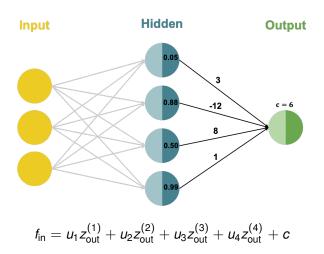




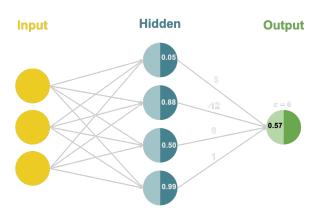
Each hidden neuron performs a non-linear **activation** transformation on the weight sum:



The output neuron performs an **affine transformation** on its inputs:

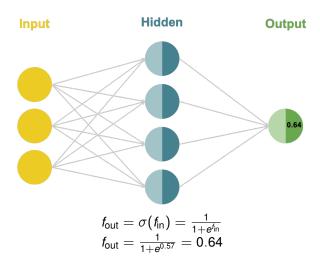


The output neuron performs an affine transformation on its inputs:



$$f_{\text{in}} = u_1 z_{\text{out}}^{(1)} + u_2 z_{\text{out}}^{(2)} + u_3 z_{\text{out}}^{(3)} + u_4 z_{\text{out}}^{(4)} + c$$
  
 $f_{\text{in}} = 3 * 0.05 + (-12) * 0.88 + 8 * 0.50 + 1 * 0.99 + 6 = 0.57$ 

The output neuron performs a non-linear **activation** transformation on the weight sum:



## **HIDDEN LAYER: ACTIVATION FUNCTION**

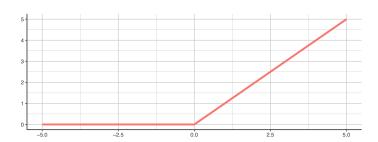
- If the hidden layer does not have a non-linear activation, the network can only learn linear decision boundaries.
- A lot of different activation functions exist.

# **HIDDEN LAYER: ACTIVATION FUNCTION**

#### **ReLU Activation:**

 Currently the most popular choice is the ReLU (rectified linear unit):

$$\sigma(v) = \max(0, v)$$



# **HIDDEN LAYER: ACTIVATION FUNCTION**

#### **Sigmoid Activation Function:**

• The sigmoid function can be used even in the hidden layer:

$$\sigma(v) = \frac{1}{1 + \exp(-v)}$$

