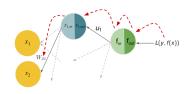
Deep Learning

Basic Backpropagation 1



Learning goals

- Forward and backward passes
- Chain rule
- Details of backprop

BACKPROPAGATION: BASIC IDEA

We would like to run ERM by GD on:

$$\mathcal{R}_{\mathsf{emp}}(\boldsymbol{ heta}) = rac{1}{n} \sum_{i=1}^{n} L\left(y^{(i)}, f\left(\mathbf{x}^{(i)} \mid \boldsymbol{ heta}
ight)
ight)$$

Backprop training of NNs runs in 2 alternating steps, for one x:

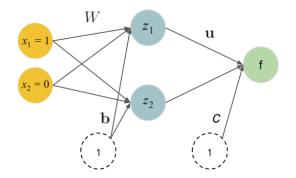
- Forward pass: Inputs flow through model to outputs. We then compute the observation loss. We covered that.
- Backward pass: Loss flows backwards to update weights so error is reduced, as in GD.

We will see: This is simply (S)GD in disguise, cleverly using the chain rule, so we can reuse a lot of intermediate results.

Bernd Bischl Deep Learning - 1 / 19

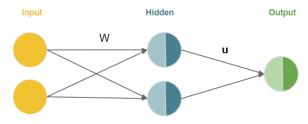
XOR EXAMPLE

- As activations (hidden and outputs) we use the logistic.
- We run one FP and BP on $\mathbf{x} = (1,0)^T$ with y = 1.
- We use L2 loss between 0-1 labels and the predicted probabilities.
 This is a bit uncommon, but computations become simpler.

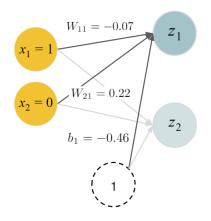


Note: We will only show rounded decimals.

- We will divide the FP into four steps:
 - the inputs of z_i : $z_{i,in}$
 - the activations of z_i : $z_{i,out}$
 - the input of f: fin
 - and finally the activation of f: fout



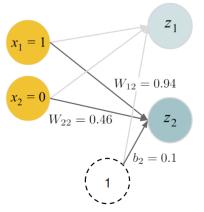
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$$z_{1,in} = \mathbf{W}_1^T \mathbf{x} + b_1 = 1 \cdot (-0.07) + 0 \cdot 0.22 + 1 \cdot (-0.46) = -0.53$$

 $z_{1,out} = \sigma(z_{1,in}) = \frac{1}{1 + \exp(-(-0.53))} = 0.3705$

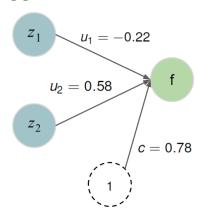
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$$z_{2,in} = \mathbf{W}_{2}^{T} \mathbf{x} + b_{2} = 1 \cdot 0.94 + 0 \cdot 0.46 + 1 \cdot 0.1 = 1.04$$

 $z_{2,out} = \sigma(z_{2,in}) = \frac{1}{1 + \exp(-1.04)} = 0.7389$

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$$f_{in} = \mathbf{u}^T \mathbf{z} + c = 0.3705 \cdot (-0.22) + 0.7389 \cdot 0.58 + 1 \cdot 0.78 = 1.1122$$

 $f_{out} = \tau (f_{in}) = \frac{1}{1 + \exp(-1.1122)} = 0.7525$

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- The FP predicted $f_{out} = 0.7525$
- Now, we compare the prediction $f_{out} = 0.7525$ and the true label y = 1 using the L2-loss:

$$L(y, f(\mathbf{x})) = \frac{1}{2} (y - f(\mathbf{x}^{(i)} \mid \theta))^2 = \frac{1}{2} (y - f_{out})^2$$
$$= \frac{1}{2} (1 - 0.7525)^2 = 0.0306$$

 The calculation of the gradient is performed backwards (starting from the output layer), so that results can be reused.

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The main ingredients of the backward pass are:

- to reuse the results of the forward pass (here: $z_{i,in}$, $z_{i,out}$, f_{in} , f_{out})
- reuse the intermediate results from the chain rule
- the derivative of the activations and some affine functions

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• Let's start to update u_1 . We recursively apply the chain rule:

$$\frac{\partial L(y, f(\mathbf{x}))}{\partial u_1} = \frac{\partial L(y, f(\mathbf{x}))}{\partial f_{out}} \cdot \frac{\partial f_{out}}{\partial f_{in}} \cdot \frac{\partial f_{in}}{\partial u_1}$$

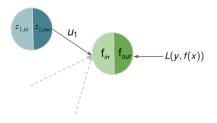
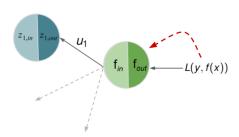


Figure: Snippet from our NN, with backward path for u_1 .

• 1st step: The derivative of L2 is easy; we know fout from FP.

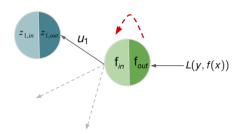
$$\frac{\partial L(y, f(\mathbf{x}))}{\partial f_{out}} = \frac{d}{\partial f_{out}} \frac{1}{2} (y - f_{out})^2 = \underbrace{(y - f_{out})}_{\hat{=} \text{residual}}$$
$$= -(1 - 0.7525) = -0.2475$$



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• 2nd step. $f_{out} = \sigma(f_{in})$, use rule for σ' , use f_{in} from FP.

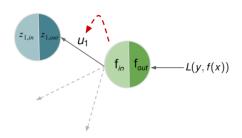
$$\frac{\partial f_{out}}{\partial f_{in}} = \sigma(f_{in}) \cdot (1 - \sigma(f_{in}))$$
= 0.7525 \cdot (1 - 0.7525) = 0.1862



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• 3rd step. Derivative of the linear input is easy; use $z_{1,out}$ from FP.

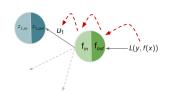
$$\frac{\partial f_{in}}{\partial u_1} = \frac{\partial (u_1 \cdot z_{1,out} + u_2 \cdot z_{2,out} + c \cdot 1)}{\partial u_1} = z_{1,out} = 0.3705$$



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• Plug it together:

$$\frac{\partial L(y, f(\mathbf{x}))}{\partial u_1} = \frac{\partial L(y, f(\mathbf{x}))}{\partial f_{out}} \cdot \frac{\partial f_{out}}{\partial f_{in}} \cdot \frac{\partial f_{in}}{\partial u_1} \\
= -0.2475 \cdot 0.1862 \cdot 0.3705 = -0.0171$$



• With LR $\alpha = 0.5$:

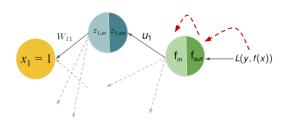
$$u_1^{[new]} = u_1^{[old]} - \alpha \cdot \frac{\partial L(y, f(\mathbf{x}))}{\partial u_1}$$

= $-0.22 - 0.5 \cdot (-0.0171) = -0.2115$

• Now for W_{11} :

$$\frac{\partial L(y, f(\mathbf{x}))}{\partial W_{11}} = \frac{\partial L(y, f(\mathbf{x}))}{\partial f_{out}} \cdot \frac{\partial f_{out}}{\partial f_{in}} \cdot \frac{\partial f_{in}}{\partial z_{1,out}} \cdot \frac{\partial z_{1,out}}{\partial z_{1,in}} \cdot \frac{\partial z_{1,in}}{\partial W_{11}}$$

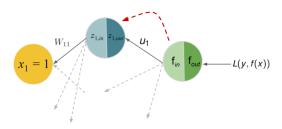
• We know $\frac{\partial L(y,f(\mathbf{x}))}{\partial f_{out}}$ and $\frac{\partial f_{out}}{\partial f_{in}}$ from BP for u_1 .



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• $f_{in} = u_1 \cdot z_{1,out} + u_2 \cdot z_{2,out} + c \cdot 1$ is linear, easy and we know u_1 :

$$\frac{\partial f_{in}}{\partial z_{1,out}} = u_1 = -0.22$$

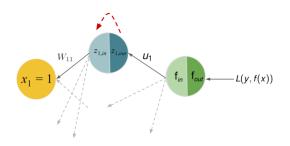


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• Next. Use rule for σ' and FP results:

$$\frac{\partial z_{1,out}}{\partial z_{1,in}} = \sigma(z_{1,in}) \cdot (1 - \sigma(z_{1,in}))$$

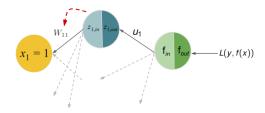
$$= 0.3705 \cdot (1 - 0.3705) = 0.2332$$



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• $z_{1,in} = x_1 \cdot W_{11} + x_2 \cdot W_{21} + b_1 \cdot 1$ is linear and depends on inputs:

$$\frac{\partial z_{1,in}}{\partial W_{11}} = x_1 = 1$$



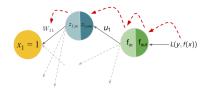
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• Plugging together:

$$\frac{\partial L(y, f(\mathbf{x}))}{\partial W_{11}} = \frac{\partial L(y, f(\mathbf{x}))}{\partial f_{out}} \cdot \frac{\partial f_{out}}{\partial f_{in}} \cdot \frac{\partial f_{in}}{\partial z_{1,out}} \cdot \frac{\partial z_{1,out}}{\partial z_{1,in}} \cdot \frac{\partial z_{1,in}}{\partial W_{11}}$$

$$= (-0.2475) \cdot 0.1862 \cdot (-0.22) \cdot 0.2332 \cdot 1$$

$$= 0.0024$$



Full SGD update:

$$W_{11}^{[new]} = W_{11}^{[old]} - \alpha \cdot \frac{\partial L(y, f(\mathbf{x}))}{\partial W_{11}}$$

= -0.07 - 0.5 \cdot 0.0024 = -0.0712

RESULT

• We can do this for all weights:

$$W = \begin{pmatrix} -0.0712 & 0.9426 \\ 0.22 & 0.46 \end{pmatrix}, b = \begin{pmatrix} -0.4612 \\ 0.1026 \end{pmatrix},$$

$$u = \begin{pmatrix} -0.2115 \\ 0.5970 \end{pmatrix}$$
 and $c = 0.8030$.

- Yields $f(\mathbf{x} \mid \boldsymbol{\theta}^{[new]}) = 0.7615$ and loss $\frac{1}{2}(1 0.7615)^2 = 0.0284$.
- Before, we had $f(\mathbf{x} \mid \boldsymbol{\theta}^{[old]}) = 0.7525$ and higher loss 0.0306.

Now rinse and repeat. This was one training iter, we do thousands.

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