#### **Process Control**

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23 April 2018



#### Control Flow



- The CPU executes one instruction after another
- Typically, they are next to each other in memory (unless jumps, branches, and returns from subroutine)
- Exceptional Control Flow, triggered by
  - hardware exception
  - software exception



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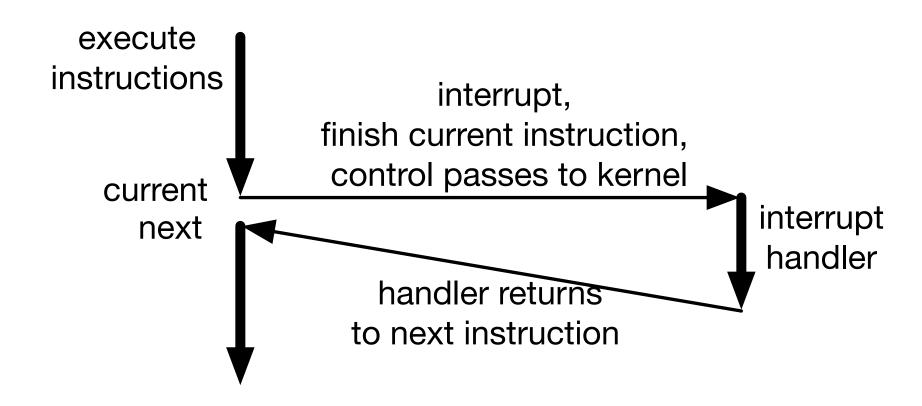
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  - if recovered, return to regular control flow
- Aborts
  - unrecoverable fatal error, e.g., memory corrupted
  - application process is terminated

## Abrupt Change in Control Flow







# processes

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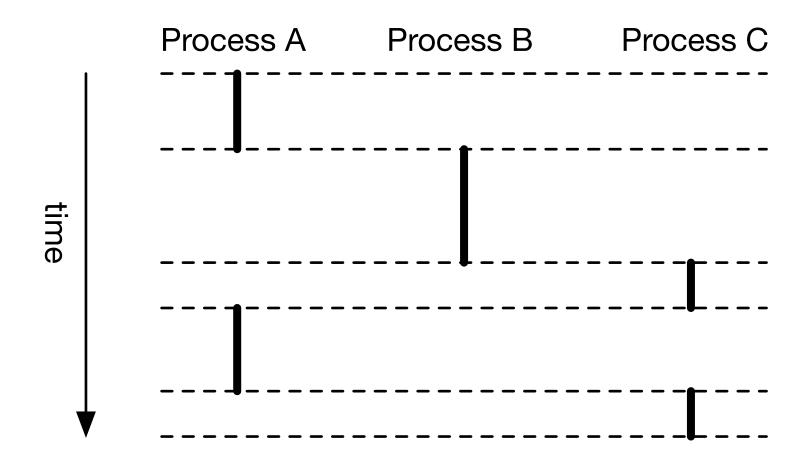
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- Multi-tasking: modern OS that allow multiple processes at once

# Logical Control Flow





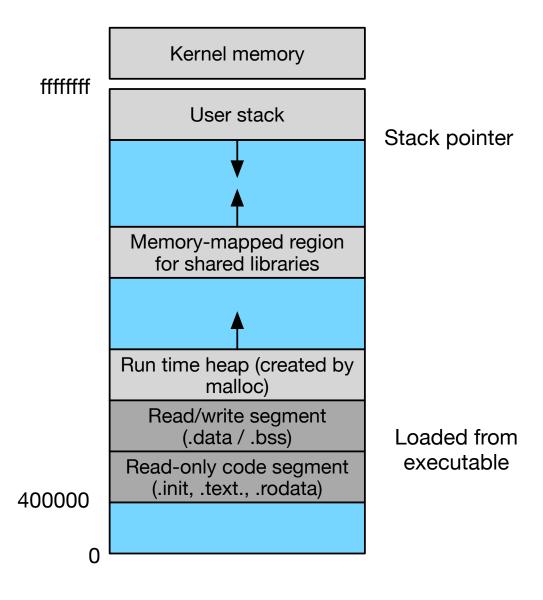
#### User and Kernel Mode



- Mode bit in control register
- Kernel mode: may execute any instruction, access any memory
- User mode: limited to private memory
- Switch from user to kernel mode
  - voluntary (sleep)
  - triggered by interrupt
  - system call

## Private Address Space





#### **Process Context**



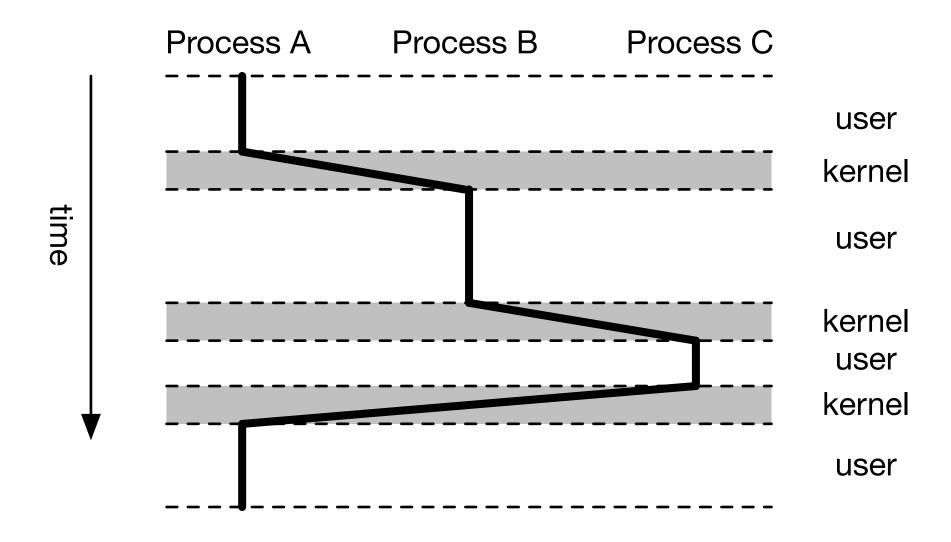
• Kernel maintains context for each process

#### • Context

- program counter
- register values
- address table (more on that next lecture)
- opened files
- various meta information (e.g., process name)
- In Linux, each process context viewable in /proc "file" system

#### **Context Switches**







# system calls

# **Examples**



Number	Name	Description
0	read	read from file
1	write	write to file
2	open	open file
3	close	close file
33	pause	suspend process until signal arrives
39	getpid	get process id
57	fork	create new process
60	exit	end process
61	wait4	wait for a process to terminate
62	kill	kill another process

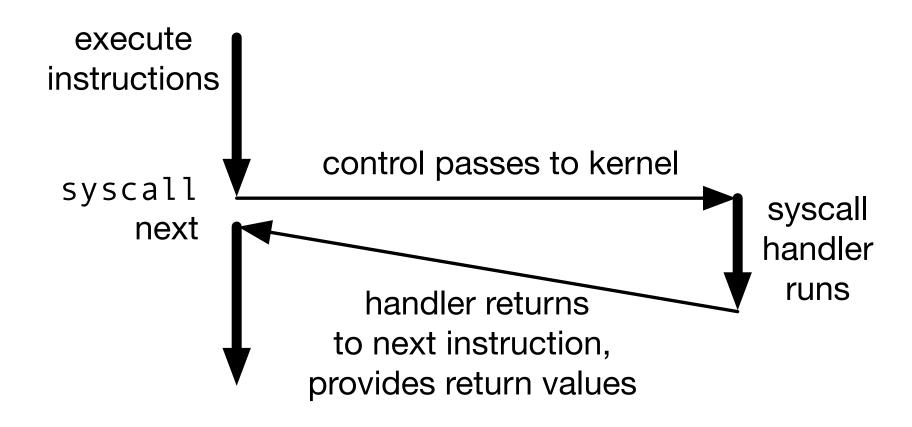
### Assembly Example



```
.section .data
string:
   .ascii "hello, world!\n"
string_end:
   .equ len, string_end - string
section text
globl main
main:
   movq $1, %rax ; write is system call 1
   movq $1, %rdi ; arg1: stdout is "file" 1
   movq string, %rsi
                       ; arg2: hello world string
   movq len, %rdx
                       ; arg3: length of string
   syscall
                       ; exit is system call 60
   movq $60, %rax
   movq $0; %rdi
                       : exit status
   syscall
```

#### System Call Control







# process control

#### **Creating New Processes**



• C code than spawns a child process

```
int main() {
  int x = 1;
  pid_t pid = fork();

if (pid == 0) {
    printf("child x=%d", ++x);
    exit(0);
  }
  printf("parent x=%d", --x);
  exit(0);
}
```

 When run, it returns parent x=0 child x=2

## Syscall 57: Fork



- fork() creates a child process
- Call once, return twice
  - in child process: return value 0
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- Concurrent exception
  - parent and child processes run concurrently
  - no guarantee which proceeds first (and for how long)
- Duplicate by separate address space
  - initially memory is identical
  - each process makes changes to its private copy

# Another Example



• Multiple forks

```
int main() {
  fork();
  fork();
  printf("hello\n");
  exit(0);
}
```

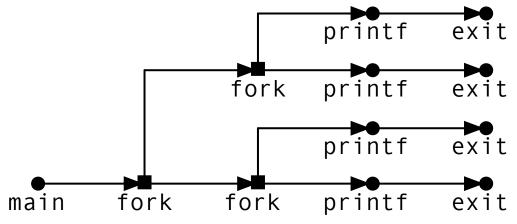
## Another Example



• Multiple forks

```
int main() {
  fork();
  fork();
  printf("hello\n");
  exit(0);
}
```

• Outputs "hello" 4 times



#### Death in the Family



- What happens when what dies when?
- Child process dies
  - process still in kernel's process table
  - waiting for parent to read exit status
  - "zombie": dead, but still active
- Parent process dies
  - children processes become orphaned
  - orphan killing: terminate all orphaned processes
  - re-parenting: make init process (pid: 1) parent
    - $(\rightarrow$  a "daemon" process)

#### Waiting for Child to Die



- 1. Parent spawns child process
- 2. Both processes running
- 3. Parent waits for child to complete
  - C: waitpid()
  - Assembly: syscall 61
- 4. Parent stalls
- 5. Child dies (zombie)
- 6. Parent receives exit status of child
- 7. Child dies completely

#### **Exec**



- Parent process may execute another program
  - C: execve(filename, argv, envp)
  - Assembly: syscall 59
- Passes environment variables (envp)
- Executed command takes over
- If both should run: fork first



# signals

# Signals



- Software-level communication between processes
- Sending the signal from one process
- Receiving the signal by another process
  - ignore
  - terminate
  - catch signal
- Handled by kernel

# **Examples**



Number	Name	Default	Corresponding Event
1	SIGHUP	terminate	Terminate line hangup
2	SIGINT	terminate	Interrupt from keyboard
3	SIGUIT	terminate	quit from keyboard
4	SIGILL	terminate	illegal instruction
5	SIGTRAP	terminate & dump core	trace trap
9	SIGKILL	terminate*	kill process
18	SIGCONT	ignore	continue process if stopped
19	SIGSTOP	stop until SIGCONT*	stop signal not from terminal
20	SIGTSTP	stop until SIGCONT	stop signal from terminal

<sup>\* =</sup> SIGKILL and SIGSTOP cannot be caught

## Sending Signals



• From shell with command

linux> /bin/kill -9 2423

• From shell with keystroke to running process

linux> start-my-process
CTRL+C

- CTRL+C: sends SIGINT

- CTRL+Z: sends SIGTSTP

• There is also a C function and an Assembly syscall

## **Receiving Signals**



- When kernel about to continue process, checks for signals
- If there is a signal, forces process to receive signal
- Each signal has a default action
  - ignore
  - terminate
  - terminate and dump core
  - stop
- Process can also set up a signal handler for customized response

#### Signal Handler



• Signal handler in C

```
#include "csapp.h"
void sigInt_handler(int sig) {
  printf("Caught SIGINT\n");
  exit(0);
}
int main() {
  signal(SIGINT, sigint_handler);
  pause();
  return 0;
}
```

• Now, process writes "Caught SIGINT" to stdout before terminating