Lecture 21: Signals

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Example code

Example code for today is on course website in signals.zip

Signals

Signals

- ► Software-level communication between processes
- ► Sending the signal from one process
- ► Receiving the signal by another process
 - ignore
 - terminate
 - catch signal
- ► Handled by kernel

Examples

Number	Name	Default	Corresponding Event
1	SIGHUP	terminate	terminal line hangup
2	SIGINT	terminate	interrupt from keyboard
3	SIGQUIT	terminate	quit from keyboard
4	SIGILL	terminate	illegal instruction
5	SIGTRAP	terminate & dump core	trace trap
9	SIGKILL	terminate*	kill process
18	SIGCONT	ignore	continue process if stopped
19	SIGSTOP	stop until SIGCONT*	stop signal not from terminal
20	SIGTSTP	stop until SIGCONT	stop signal from terminal

^{* =} SIGKILL and SIGSTOP cannot be caught



Sending Signals

- ► From shell with command
 - \$ /bin/kill -9 2423
- ► From shell with keystroke to running process
 - \$ start-my-process
 CTRL+C
 - ► CTRL+C: sends SIGINT
 - ► CTRL+Z: sends SIGTSTP
- ▶ There is also a C function and an Assembly syscall

Receiving Signals

- ▶ When kernel about to continue process, checks for signals
- ▶ If there is a signal, forces process to receive signal
- ► Each signal has a default action
 - ignore
 - terminate
 - terminate and dump core
 - ► stop
- ▶ Process can also set up a signal handler for customized response

Signal Handler

Signal handler in C #include "csapp.h" void sigint handler(int sig) { printf("Caught SIGINT\n"); exit(0); int main() { signal(SIGINT, sigint handler); pause(); return 0;

▶ Now, process writes "Caught SIGINT" to stdout before terminating

Signal delivery, signal masks

Signal delivery

- ▶ In general, the OS kernel could deliver a signal to a process at any time
- ▶ Delivering a signal:
 - Pushing a special return address of code to restore the CPU state (so that process can continue normal execution when signal handler returns)
 - Creating stack frame for signal handler
 - Setting argument registers for signal handler
 - ► Jumping to signal handler
- Signals are normally delivered on the process's call stack
 - ► Really a *thread*'s call stack, more about threads later on
- Process may designate a special area of memory to serve as a stack for received signals

Signals and asynchrony

- ► Signal delivery could occur before or after *any* instruction
- ► That means that signals are asynchronous
- "Asynchronous" means "could happen at any time" or "ordering is unpredictable"
- ▶ Signal handlers are asynchronous with respect to the rest of the program
- ▶ This can cause strange behavior!

A C program

```
#include "csapp.h"

#define NCOUNT 100000000

volatile int count = 0;

int main(void) {
    // count up
    for (int i = 0; i < NCOUNT; i++) { count++; }
    printf("count=%d\n", count);
    return 0;
}</pre>
```

Note that "volatile" tells the compiler not to optimize away accesses to the count variable

Compiling and executing the program

```
$ gcc -0 -Wall -c count.c
$ gcc -o count count.o
$ ./count
count=100000000
```

Nothing surprising happened

Interval timers

- ► An *interval timer* is a means for notifying the process than an interval of time has elapsed
- ► Can be "one shot" or repeating
- ▶ The setitimer system call allows the process to create an interval timer
- When the timer elapses, OS kernel sends SIGALRM signal to process
- ► Let's change the program so that the handler for SIGALRM is also incrementing the global counter

Modified version of program

```
#include "csapp.h"
#define NCOUNT 100000000
volatile int stop = 0, nsigs = 0, count = 0;
void sigalrm_handler(int signo) {
  if (!stop) { nsigs++; count++; }
int main(void) {
  // handle SIGALRM signal
  code to set up signal handler for SIGALRM
  // arrange for SIGALRM to be delivered once every millisecond
  code to set up interval timer
  // count up
  for (int i = 0; i < NCOUNT; i++) { count++; }</pre>
  code to check final counts
  return 0;
```

Code to set up signal handler

```
// code to set up signal handler for SIGALRM
struct sigaction sa;
sigemptyset(&sa.sa_mask);
sa.sa_flags = 0;
sa.sa_handler = sigalrm_handler;
sigaction(SIGALRM, &sa, NULL);
```

Note that to install a signal handler, sigaction is recommended over signal, for reasons we'll discuss soon

Topic

```
// code to set up interval timer
struct itimerval itv;
itv.it_interval.tv_sec = 0;
itv.it_interval.tv_usec = 1000; // 1000 microseconds = 1 millisecond
itv.it_value = itv.it_interval;
setitimer(ITIMER_REAL, &itv, NULL);
```

ITIMER_REAL means that the intervals are "real time" (not relative to CPU time used by the process)

Topic

In theory, the final value of count should be <code>NCOUNT</code> + <code>nsigs</code>

- ▶ NCOUNT is the number of increments (to count) in main
- nsigs is the number of calls to the signal handler (which also increments count)

Running the modified program

```
$ gcc -0 -Wall -c alarm1.c
$ gcc -o alarm1 alarm1.o
$ ./alarm1
count=100000028, NCOUNT=100000000, nsigs=174
anomaly detected!
```

What just happened?

Asynchrony and atomicity

- ▶ When a program
 - ▶ has code paths which execute asynchronously, and
 - ► the asynchronous paths update shared data then anomalous behavior can be observed if either process executes code which is not *atomic*
- ► "Atomic" means "happens in its entirety, or not at all"
- ► Incrementing a variable is not (necessarily) atomic

Why increment is not atomic

▶ The statement count++; really means

```
1: tmp = count;

2: tmp = tmp + 1;

3: count = tmp;

where tmp is a register
```

- ► If count is updated by code executing asynchronously, the updated value could be overwritten by step 3
- ► The anomaly in our program execution shows this happening (the final value of count doesn't reflect all of the increments)

Zoom poll!

Assume:

- count is a global variable whose initial value is 0
- ▶ tmp and tmp2 are registers

Also, assume the following two sequences of operations are executed asynchronously:

```
// sequence 1 // sequence 2
tmp = count; tmp2 = count;
tmp = tmp + 1; tmp2 = tmp2 + 1;
count = tmp; count = tmp2;
```

After both sequence 1 and sequence 2 complete, what are the possible final values of count?

- A. 0
- B. 1
- C. 2
- D. Either 1 or 2
- E. Either 0, 1, or 2

Synchronization, signal masks

- "Synchronization" means coordinating asynchronous accesses to shared data to avoid anomalous results
- ► For programs using signals we can use *signal masks* to synchronize signal handlers with the main program
- ► Signal mask = set of signals that are temporarily blocked
 - OS kernel will only deliver a signal if it isn't blocked
 - Note that not all signals may be blocked
 - ► For our example program, we can block SIGALRM to avoid the signal handler from executing at the wrong time

Modified main loop

```
sigset_t mask;
sigemptyset(&mask);
sigaddset(&mask, SIGALRM);

// count up
for (int i = 0; i < NCOUNT; i++) {
   sigprocmask(SIG_BLOCK, &mask, NULL);
   count++;
   sigprocmask(SIG_UNBLOCK, &mask, NULL);
}</pre>
```

Running the modified program

```
$ gcc -0 -Wall -c alarm2.c
$ gcc -o alarm2 alarm2.o
$ ./alarm2
count=100070462, NCOUNT=100000000, nsigs=70462
  count makes sense
```

No anomaly! However, note that the program took a very long time to run (more than 70 seconds) due to the overhead of calling sigprocmask in the main loop.

signal vs. sigaction

- ► Historically, the signal system call was used to register a signal handler on Unix systems
- ► New code should use sigaction
- ► Why?
 - ► Handlers registered using signal may get "unregistered" when the signal arrives
 - signal doesn't provide any mechanism for preventing signal handlers from being interrupted by other signals