

# INDIAN INSTITUTE OF INFORMATION TECHNOLOGY

SURAT



## LABORATORY MANUAL

**ELECTRONICS & COMMUNICATION ENGINEERING DEPARTMENT**

**EC: 303: COMMUNICATION ENGINEERING**

**B.TECH II-SEMESTER III**

NAME: GONDHA ANKITKUMAR GHANSHYAMBHAI

ROLL NO: UI21CS10

BRANCH: Computer science Engineering

**INDIAN INSTITUTE OF INFORMATION AND  
TECHNOLOGY**

**Certificate**



This is to certify that Mr./Ms. ANKIT GONDHA of 2<sup>nd</sup> year 3<sup>rd</sup> sem Class Roll No. UI21CS10 has Satisfactory completed the course in Communication Engineering laboratory practical during the Year 2022-2023 .

**MS. SEJAL RATHOD  
(COURSE COORDINATOR)**

**MS. SEJAL RATHOD  
MR. RAHUL PATEL  
MR. DHIRAJ PATEL**

**(LAB INSTRUCTORS)**

SL NO.	AIM
1	Introduction to MATLAB and plotting of different types of periodic signals and aperiodic signals using mathematical functions in MATLAB.
2	To study and implement the Fourier Transforms of different periodic and aperiodic signals in MATLAB.
3	To study amplitude modulation and observe the waveforms for three different modulation indices and reception of AM signals using code in MATLAB Software and simulink.
4	To study amplitude modulation and observe the waveforms for three different Modulation AM,DSB-SC,SSB-SC and its frequency spectrum in MATLAB Software.
5	To perform sampling of input sinusoidal signal using code in MATLAB software and verify the Nyquist Criteria in MATLAB and simulink.
6	To study and implement PAM (Pulse Amplitude Modulation) ,PWM (Pulse Width Modulation) and PPM (Pulse Position Modulation) of analog signal in MATLAB software and simulink.
7	To obtain frequency modulation and demodulation using equations and in-built functions in MATLAB software and simulink.
8	To study about modulation and demodulation of Pulse Code Modulation (PCM) in MATLAB software and simulink.
9	To study and implement about delta modulation in MATLAB software.
10	To study and verify the outputs of PCM and PCM-TDM system on hardware kit.

# EXPERIMENT 1

## Periodic Signal

**Aim:** Creating six different periodic signals and display it on the MATLAB application

### **Theory:**

Functions for the six different periodic signals:

- a Sine Wave: -  $\sin(x)$ , where  $x$ =input signal (x-axis)
- b Cosine Wave: -  $\cos(x)$ , where  $x$ =input signal (x-axis)
- c Tangent Wave: -  $\tan(x)$ , where  $x$ =input signal (x-axis)
- d Square Wave: -  $\text{square}(x)$ , where  $x$ =input signal (x-axis)
- e Triangular Wave: -  $\text{sawtooth}(x,0)$ , where  $x$ =input signal (x-axis)
- f Saw tooth Wave: -  $\text{sawtooth}(x,0.5)$ , where  $x$ =input signal (x-axis)

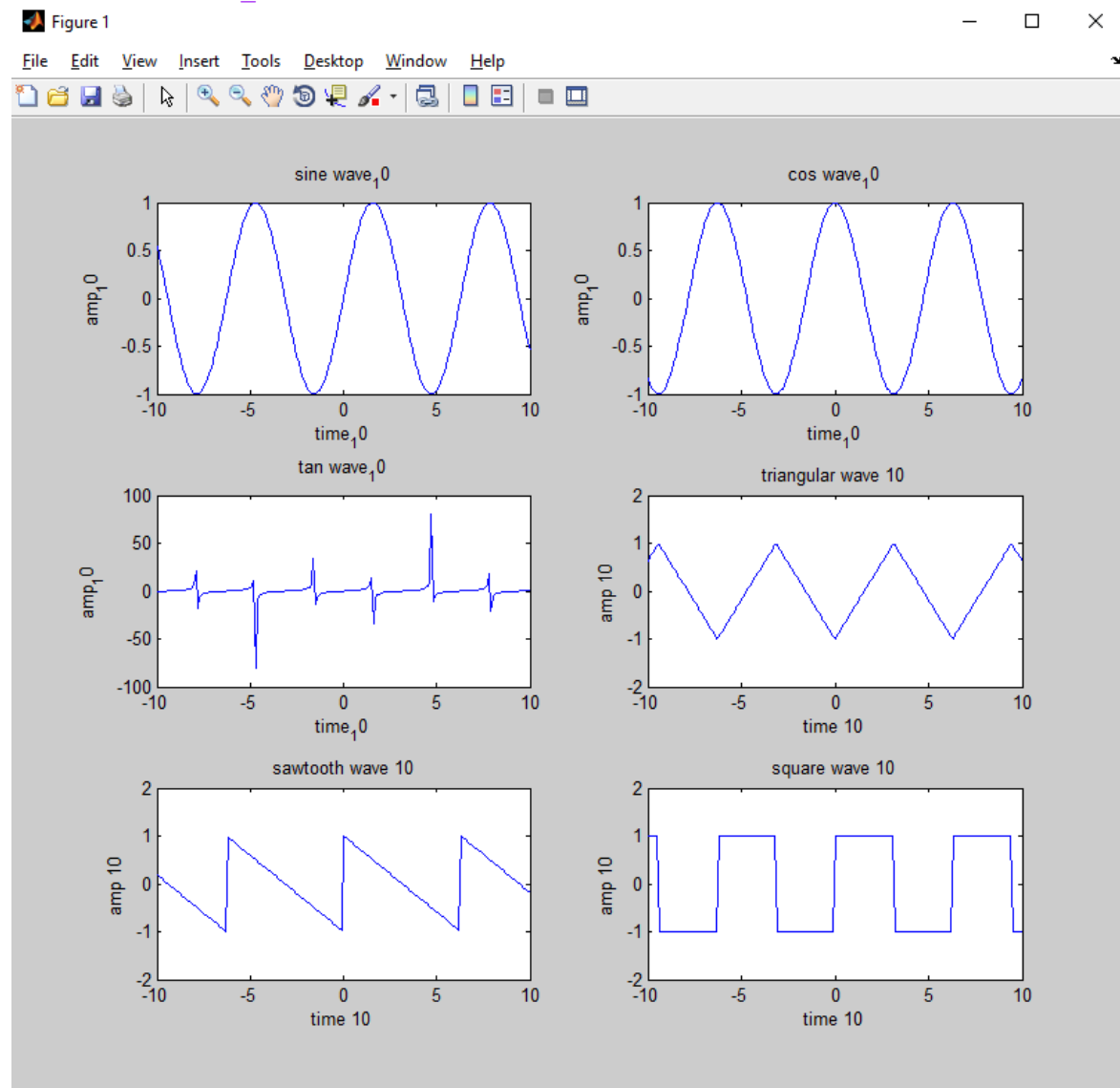
### CODE

```
clc;
clear all;
close all;
figure;
t=[-10:0.1:10];
a=(sin(t));
subplot(3,2,1);
plot(t,a);
xlabel('time_10');
ylabel('amp_10');
%axis([-10 10 -2 2]);
title('sine wave_10');

t=[-10:0.1:10];
a=cos(t);
subplot(3,2,2);
plot(t,a);
xlabel('time_10');
ylabel('amp_10');
%axis([-10 10 -2 2]);
title('cos wave_10');

t=[-10:0.1:10];
a=tan(t);
subplot(3,2,3);
plot(t,a);
xlabel('time_10');
ylabel('amp_10');
```

```
%axis([-10 10 -2 2]);  
title('tan wave_10');
```



## Aperiodic Signal

**Aim:** Creating six different Aperiodic signals and display it on the MATLAB application

## Theory:

Functions for the six different Aperiodic signals:

- Unit step function :
- Unit impulse function:
- Ramp signal:
- Signum function:
- Exponential Wave:

f rectangular Wave:

## CODE

```
clc;
clear all;
close all;
figure;
t=[-10:0.1:10];
a=(t>=0);
subplot(3,2,1);
plot(t,a);
xlabel('time_10');
ylabel('amp_10');
%axis([-10 10 -2 2]);
title('unit step function_10');
```

```
t=[-10:0.1:10];
a=(t==0);
subplot(3,2,2);
plot(t,a);
xlabel('time_10');
ylabel('amp_10');
%axis([-10 10 -2 2]);
title('unit function_10');
```

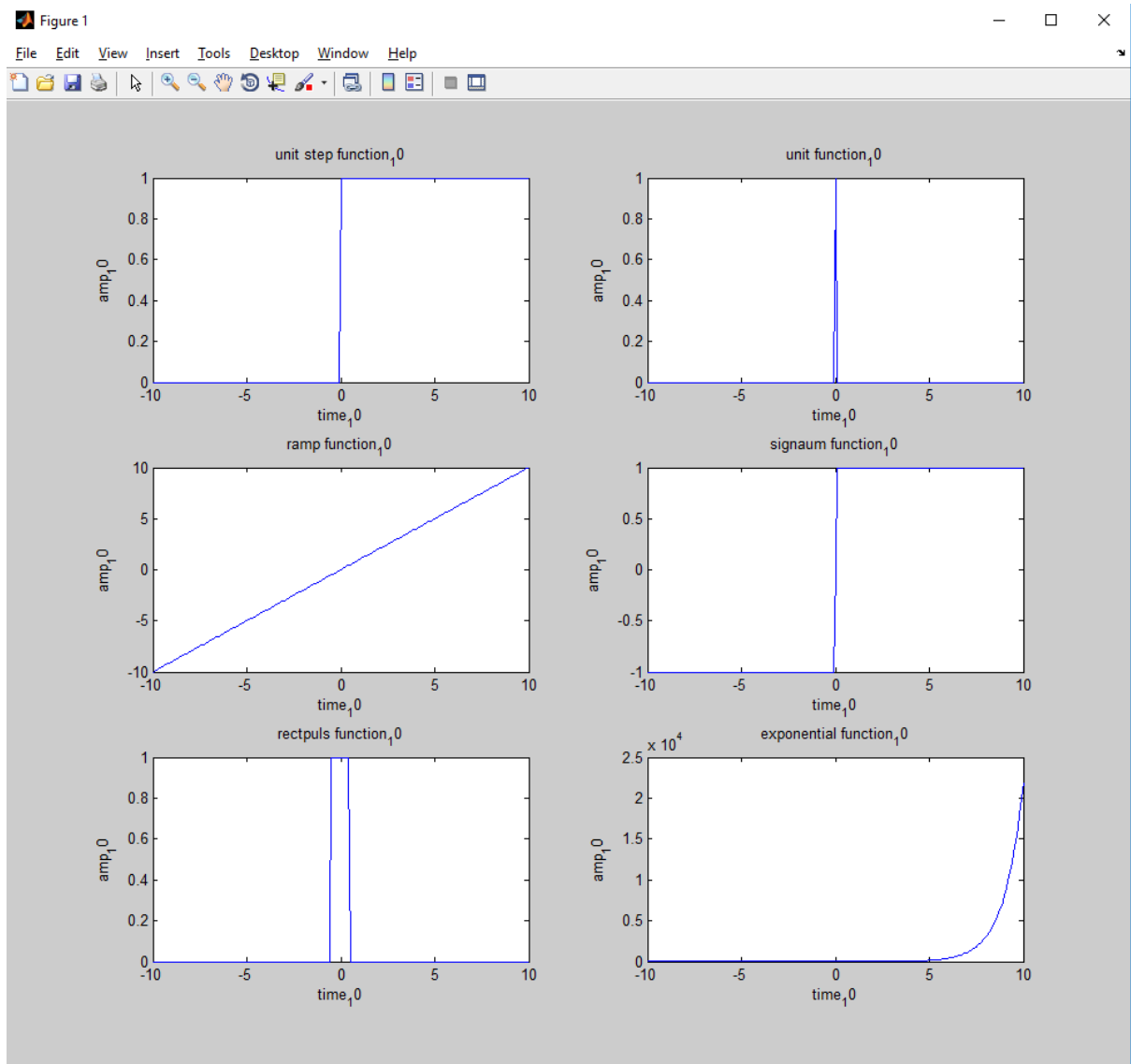
```
t=[-10:0.1:10];
a=(t);
subplot(3,2,3);
plot(t,a);
xlabel('time_10');
ylabel('amp_10');
%axis([-10 10 -2 2]);
title('ramp function_10');
```

```
t=[-10:0.1:10];
a=sign(t);
subplot(3,2,4);
plot(t,a);
xlabel('time_10');
ylabel('amp_10');
%axis([-10 10 -2 2]);
title('signaum function_10');
```

```
t=[-10:0.1:10];
a=rectpuls(t);
subplot(3,2,5);
plot(t,a);
xlabel('time_10');
ylabel('amp_10');
%axis([-10 10 -2 2]);
title('rectpuls function_10');
```

```
t=[-10:0.1:10];
a=exp(t);
subplot(3,2,6);
plot(t,a);
```

```
xlabel('time_10');
ylabel('amp_10');
%axis([-10 10 -2 2]);
title('exponential function_10');
```



# EXPERIMENT 2

**Aim:** To study and implement the Fourier Transforms of different periodic and aperiodic signals in MATLAB

## **Code :**

```
clc;
clear all;
close all;
figure;

%sine
t=[-10:0.1:10];
a=sin(t);
subplot(6,2,1);
plot(t,a);
xlabel('time UI21CS10');
ylabel('amplitude UI21CS10');
axis([-10 10 -2 2]);
title('sinwave UI21CS10');

y=fftshift(abs(fft(a)));
subplot(6,2,2);
plot(y);
xlabel('time UI21CS10');
ylabel('amplitude UI21CS10');
title('sinwave UI21CS10');

%cosine
t=[-10:0.1:10];
a=cos(t);
subplot(6,2,3);
plot(t,a);
xlabel('time UI21CS10');
ylabel('amplitude UI21CS10');
axis([-10 10 -2 2]);
title('cosine UI21CS10');

y=fftshift(abs(fft(a)));
subplot(6,2,4);
```



```
plot(y);
xlabel('time UI21CS10');
ylabel('amplitude UI21CS10');
title('cosine UI21CS10');

%exponential
t=[-10:0.1:10];
a=exp(t);

subplot(6,2,5);
plot(t,a);
xlabel('time UI21CS10');
ylabel('amplitude UI21CS10');
axis([-10 10 -2 2]);
title('exponential UI21CS10');

y=fftshift(abs(fft(a)));
subplot(6,2,6);
plot(y);
xlabel('time UI21CS10');
ylabel('amplitude UI21CS10');
title('exponential UI21CS10');

%rectagular pulse
t=[-10:0.1:10];
a=rectpuls(t);

subplot(6,2,7);
plot(t,a);
xlabel('time UI21CS10');
ylabel('amplitude UI21CS10');
axis([-10 10 -2 2]);
title('rectagular pulse UI21CS10');

y=fftshift(abs(fft(a)));
subplot(6,2,8);
plot(y);
xlabel('time UI21CS10');
ylabel('amplitude UI21CS10');
title('rectagular pulse UI21CS10');

%sinc wave
t=[-10:0.1:10];
a=sinc(t);
```

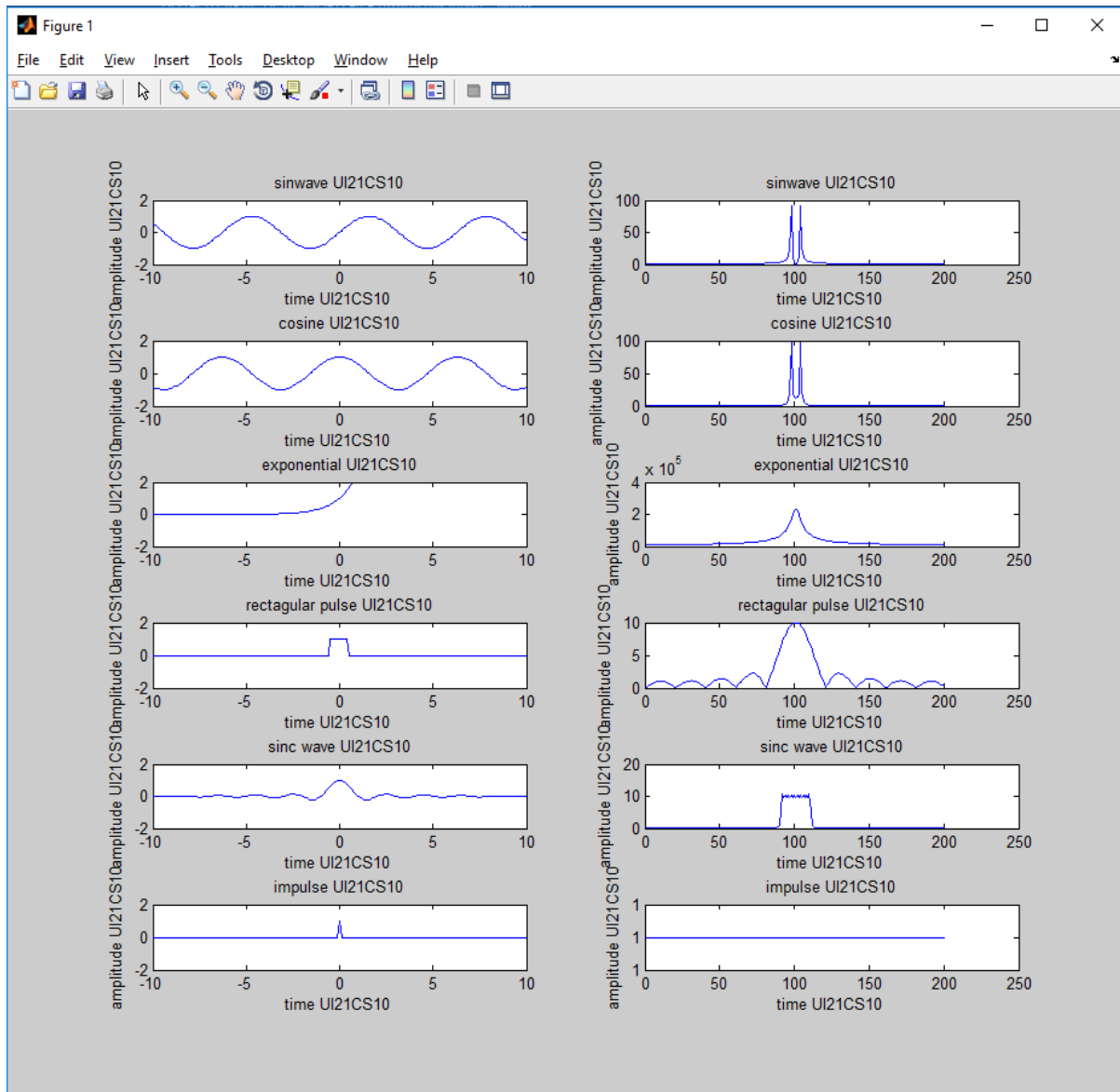
```
subplot(6,2,9);
plot(t,a);
xlabel('time UI21CS10');
ylabel('amplitude UI21CS10');
axis([-10 10 -2 2]);
title('sinc wave UI21CS10');

y=fftshift(abs(fft(a)));
subplot(6,2,10);
plot(y);
xlabel('time UI21CS10');
ylabel('amplitude UI21CS10');
title('sinc wave UI21CS10');

%impulse
t=[-10:0.1:10];
a=(t==0);

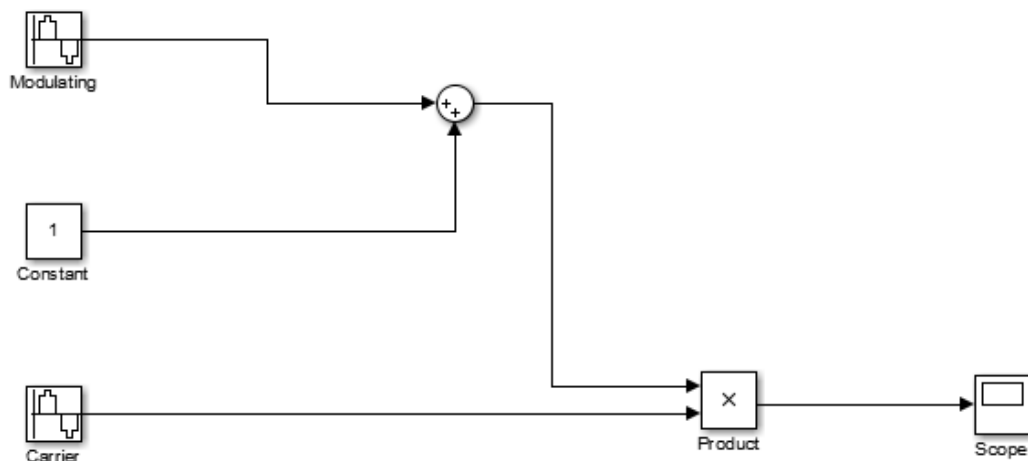
subplot(6,2,11);
plot(t,a);
xlabel('time UI21CS10');
ylabel('amplitude UI21CS10');
axis([-10 10 -2 2]);
title('impulse UI21CS10');

y=fftshift(abs(fft(a)));
subplot(6,2,12);
plot(y);
xlabel('time UI21CS10');
ylabel('amplitude UI21CS10');
title('impulse UI21CS10');
```



## EXPERIMENT 3

**Aim:** To study amplitude modulation and observe the waveforms for three different modulation indices and reception of AM signals using code in MATLAB Software and simulink.



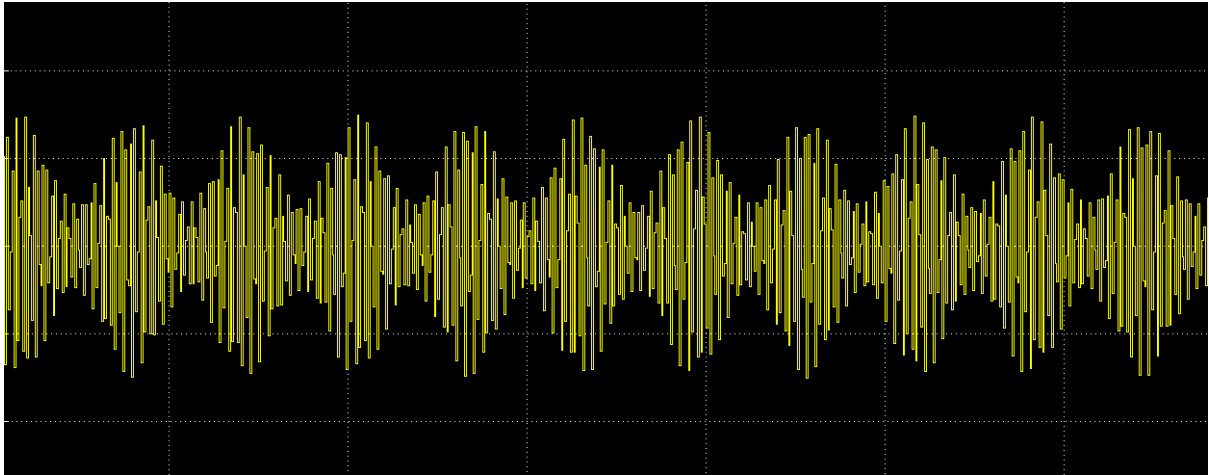
**Frequency message = 10Hz**

**Frequency carrier = 1000Hz**

**Sample time = 0.01**

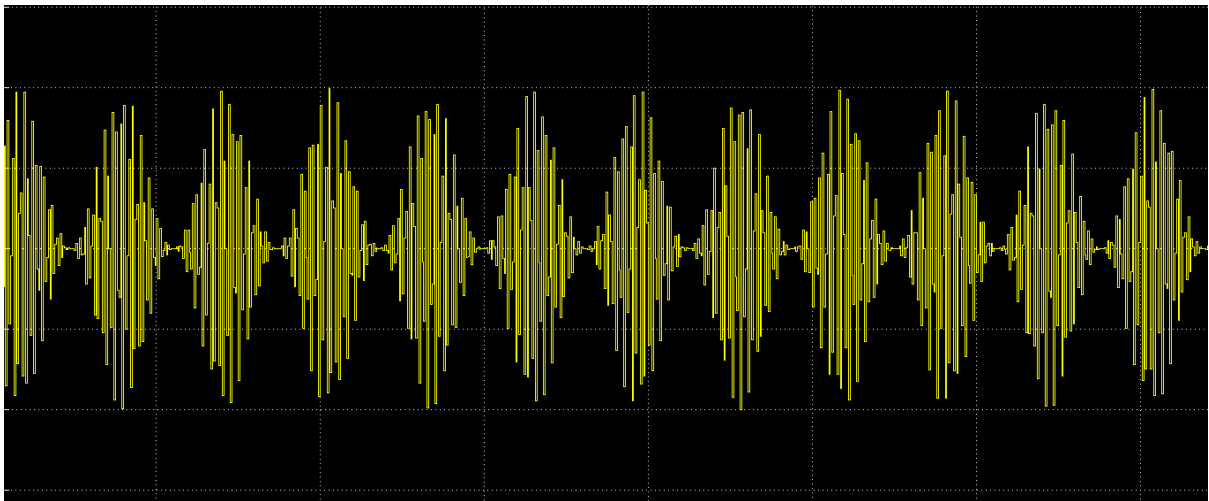
**Case 1:**

**$A_m = 0.5$   $m < 1$**



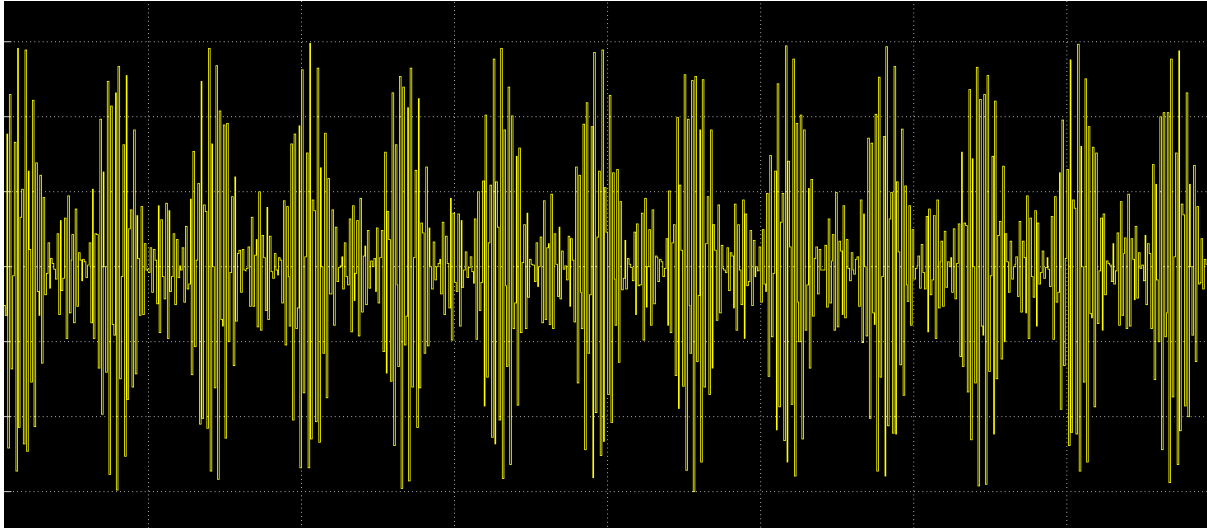
Case 2:

$A_m=1, m=1$



## Case 3:

$$A_m=2, m>1$$



CODE:

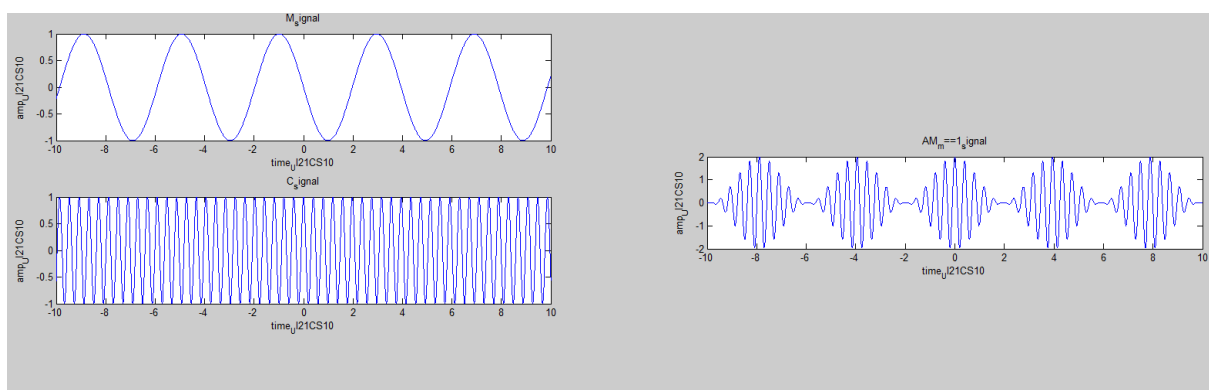
M=0

```
clc;
clear all;
close all;
t=[-10:0.01:10];
em=1;
ec=1;
p=3.14;
m=em/ec;
fc=5000;
fm=500;
%M_SIGNAL
a=sin(2*p*fm*t);
subplot(4,2,1);
plot(t,a);
xlabel('time_UI21CS10');
ylabel('amp_UI21CS10');
title('M_signal');
%c_signal
b=ec*cos(2*p*fc*t);
subplot(4,2,3);
```

```

plot(t,b);
xlabel('time_UI21CS10');
ylabel('amp_UI21CS10');
title('C_signal');
%AM
s=ec*(1+m.*cos(2*p*fm*t)).*cos(2*p*fc*t);
subplot(5,2,4);
plot(t,s);
xlabel('time_UI21CS10');
ylabel('amp_UI21CS10');
title('AM_m==1_signal');

```



$M > 1$

CODE

```

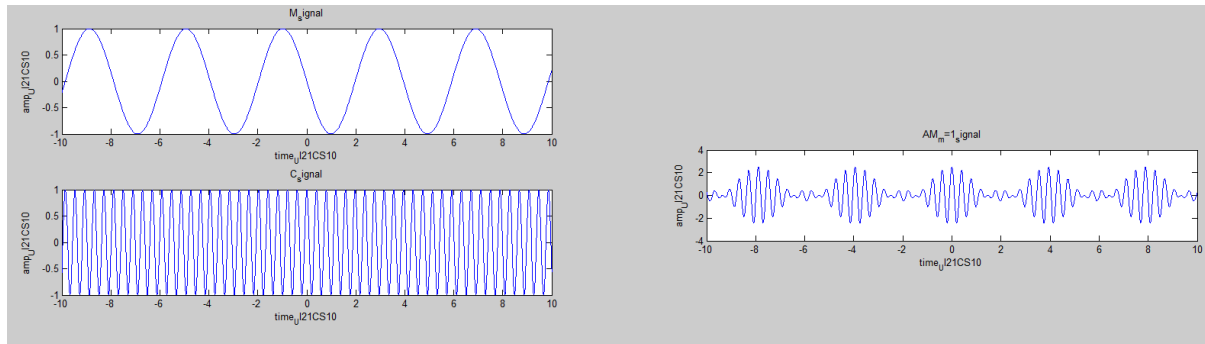
clc;
clear all;
close all;
t=[-10:0.01:10];
em=1.5;
ec=1;
p=3.14;
m=em/ec;
fc=5000;
fm=500;
%M_SIGNAL
a=sin(2*p*fm*t);
subplot(4,2,1);
plot(t,a);
xlabel('time_UI21CS10');
ylabel('amp_UI21CS10');

```

```

title('M_signal');
%c_signal
b=ec*cos(2*p*fc*t);
subplot(4,2,3);
plot(t,b);
xlabel('time_UI21CS10');
ylabel('amp_UI21CS10');
title('C_signal');
%AM
s=ec*(1+m.*cos(2*p*fm*t)).*cos(2*p*fc*t);
subplot(5,2,4);
plot(t,s);
xlabel('time_UI21CS10');
ylabel('amp_UI21CS10');
title('AM_m=1_signal');

```



## DSB SC

### CODE

```

clc;
clear all;
close all;
t=[-10:0.01:10];
em=1.5;
ec=1;
p=3.14;
m=em/ec;
fc=5000;
fm=500;
%M_SIGNAL
a=em*cos(2*p*fm*t);
subplot(5,2,1);

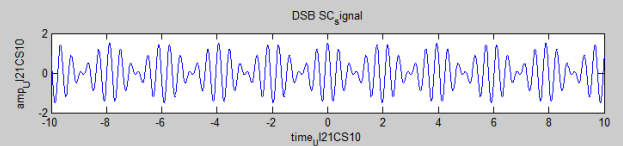
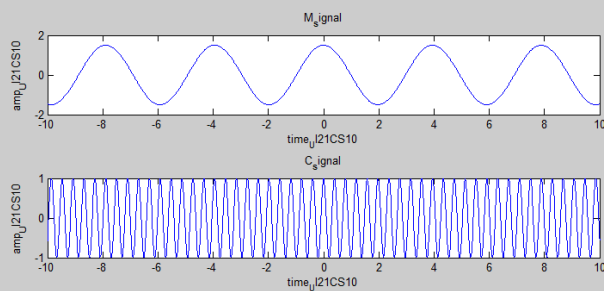
```



```

plot(t,a);
xlabel('time_UI21CS10');
ylabel('amp_UI21CS10');
title('M_signal');
%c_signal
b=ec*cos(2*p*fc*t);
subplot(5,2,3);
plot(t,b);
xlabel('time_UI21CS10');
ylabel('amp_UI21CS10');
title('C_signal');
%DSB SC
s=a.*b;
subplot(5,2,4);
plot(t,s);
xlabel('time_UI21CS10');
ylabel('amp_UI21CS10');
title('DSB SC_signal');

```



# EXPERIMENT 4

**AIM:** To study amplitude modulation and observe the waveforms for three different Modulation AM,DSB-SC,SSB-SC and its frequency spectrum in MATLAB Software.

```

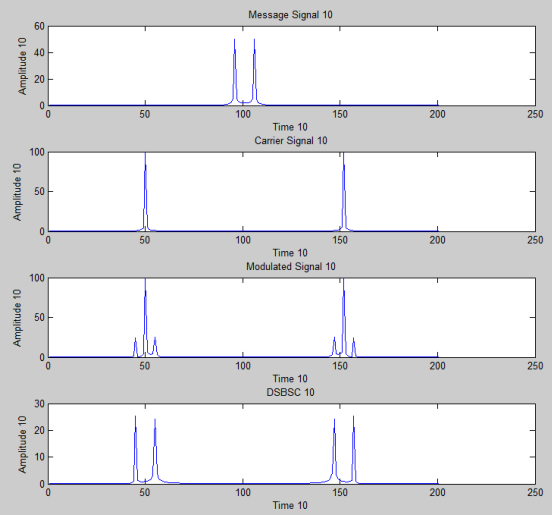
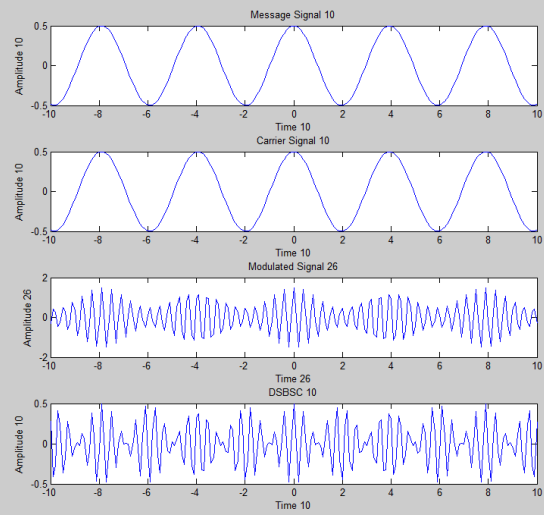
clc;
clear all;
close all;
figure;
t = [-10:0.1:10];
pi = 3.14;
Em = 0.5;
Ec = 1;
Fm = 500;
Fc = 5000;
M = Em/Ec;
%Message Signal
m = Em.*cos(2.*pi.*Fm.*t);
subplot(5,2,1);
plot(t,m);
xlabel('Time 10');
ylabel('Amplitude 10');
title('Message Signal 10');
y=fftshift(abs(fft(m)));
subplot(5,2,2);
plot(y);
xlabel('Time 10');
ylabel('Amplitude 10');
title('Message Signal 10');
%Carrier Signal
c = Ec.*cos(2.*pi.*Fc.*t);
subplot(5,2,3);
plot(t,m);
xlabel('Time 10');
ylabel('Amplitude 10');
title('Carrier Signal 10');
y=fftshift(abs(fft(c)));
subplot(5,2,4);
plot(y);

```

```

xlabel('Time 10');
ylabel('Amplitude 10');
title('Carrier Signal 10');
%Amplitude Modulation
Mod = (1 + M.*cos(2.*pi.*Fm.*t)).*c;
subplot(5,2,5);
plot(t,Mod);
xlabel('Time 10');
ylabel('Amplitude 10');
title('Modulated Signal 10');
y=fftshift(abs(fft(Mod)));
subplot(5,2,6);
plot(y);
xlabel('Time 10');
ylabel('Amplitude 10');
title('Modulated Signal 10');
%DSB-SC
dsbsc = m.*c;
subplot(5,2,7);
plot(t,dsbsc);
xlabel('Time 10');
ylabel('Amplitude 10');
title('DSBSC 10');
y=fftshift(abs(fft(dsbsc)));
subplot(5,2,8);
plot(y);
xlabel('Time 10');
ylabel('Amplitude 10');
title('DSBSC 10');
%SSB-SC
ssbsc = m.*c + m'.*c';
subplot(5,2,9);
plot(t,ssbsc);
xlabel('Time 10');
ylabel('Amplitude 10');
title('SSBSC 10');
y=fftshift(abs(fft(ssbsc)));
subplot(5,2,10);
plot(y);
xlabel('Time 10');
ylabel('Amplitude 10');
title('SSBSC 10');

```



# EXPERIMENT 5

**Aim:** To perform sampling of input sinusoidal signal using code in MATLAB software and verify the Nyquist Criteria in MATLAB and simulink.

```
clc;
clear ALL;
close all;
t= 0:0.1:10;
fm=input('enter frequency fm= ');
fs=input('enter frequency fs= ');
pi=3.14;

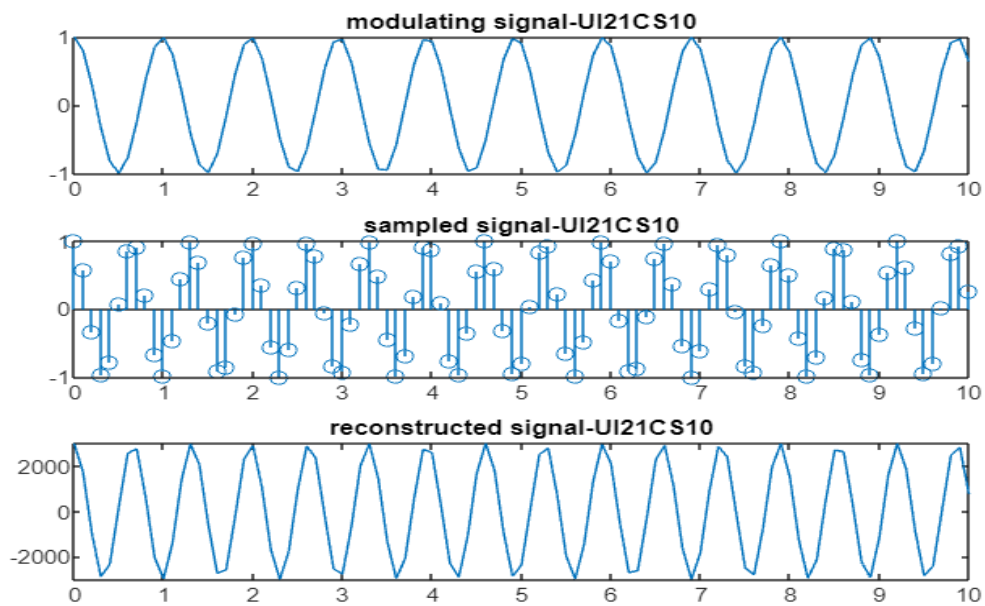
x=cos(2*fm*pi*t);
subplot(3,1,1);
plot(t,x);
title('modulating signal-UI21CS10');

y=cos(2*fs*pi*t);
subplot(3,1,2);
stem(t,y);
title('sampled signal-UI21CS10');

h=filter(fs,1,y);
subplot(3,1,3);
plot(t,h);
title('reconstructed signal-UI21CS10');
```

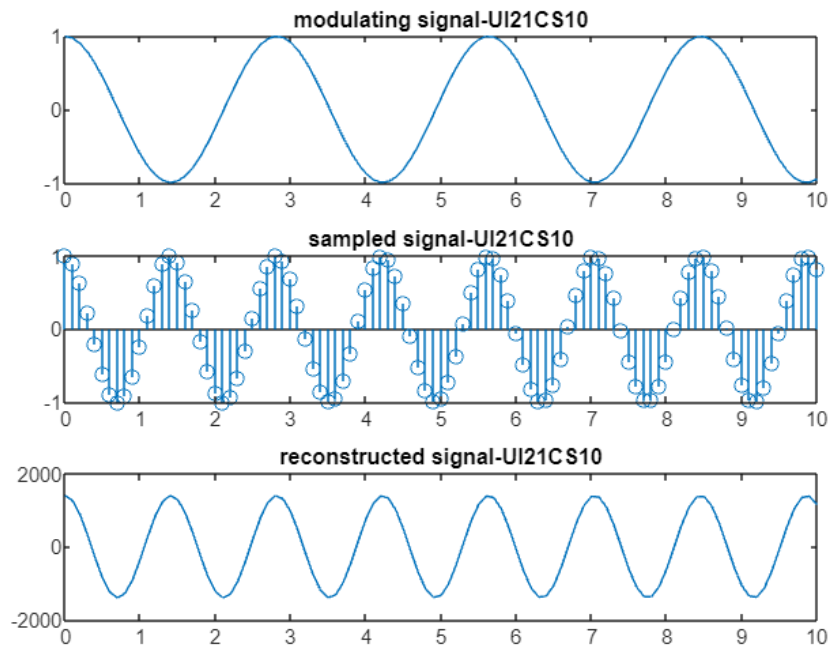
### CASE-I: Under-Sampling

- $F_s < 2 \cdot F_m$
- $F_m = 2000$
- $F_s = 3000$



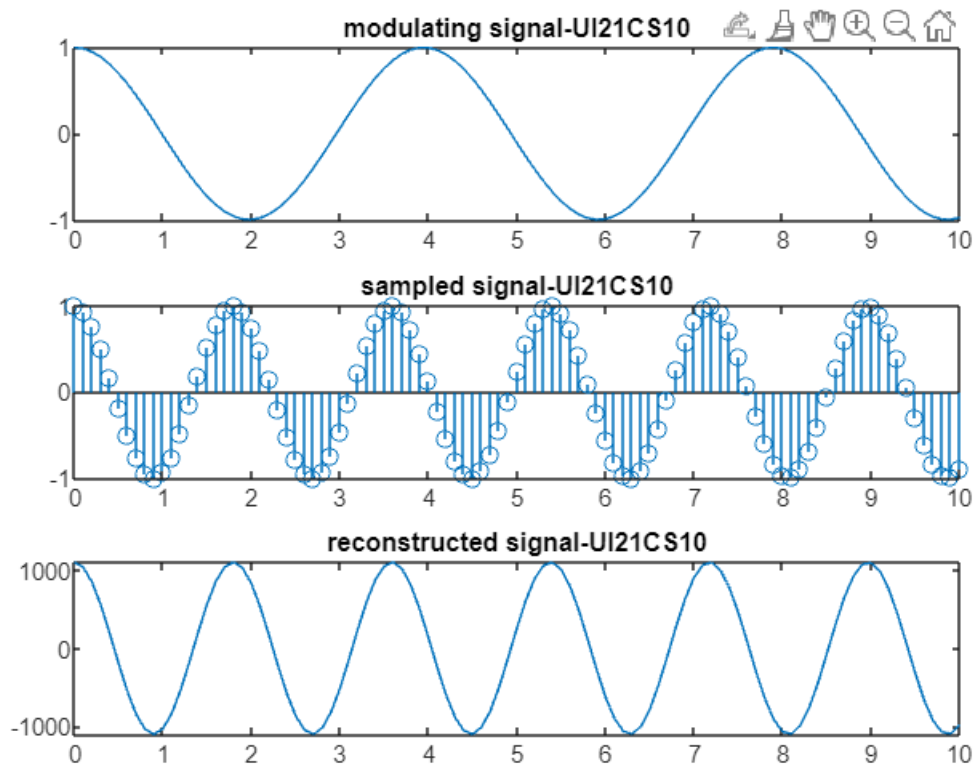
### CASE-II: Perfect Sampling

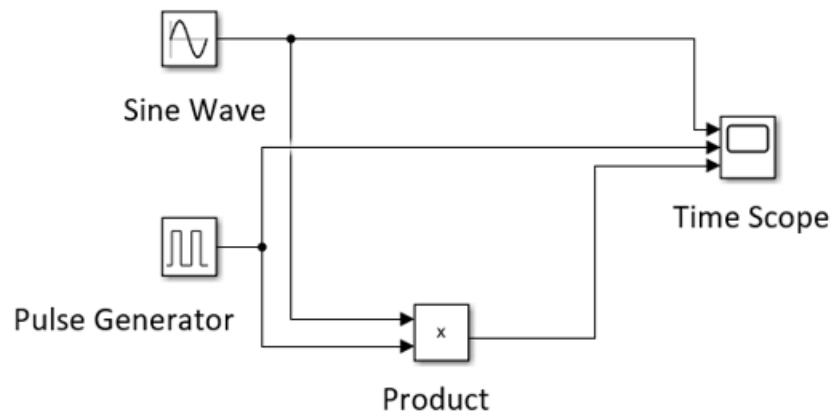
- $F_s = 2 \cdot F_m$
- $F_s = 700$
- $F_m = 1400$



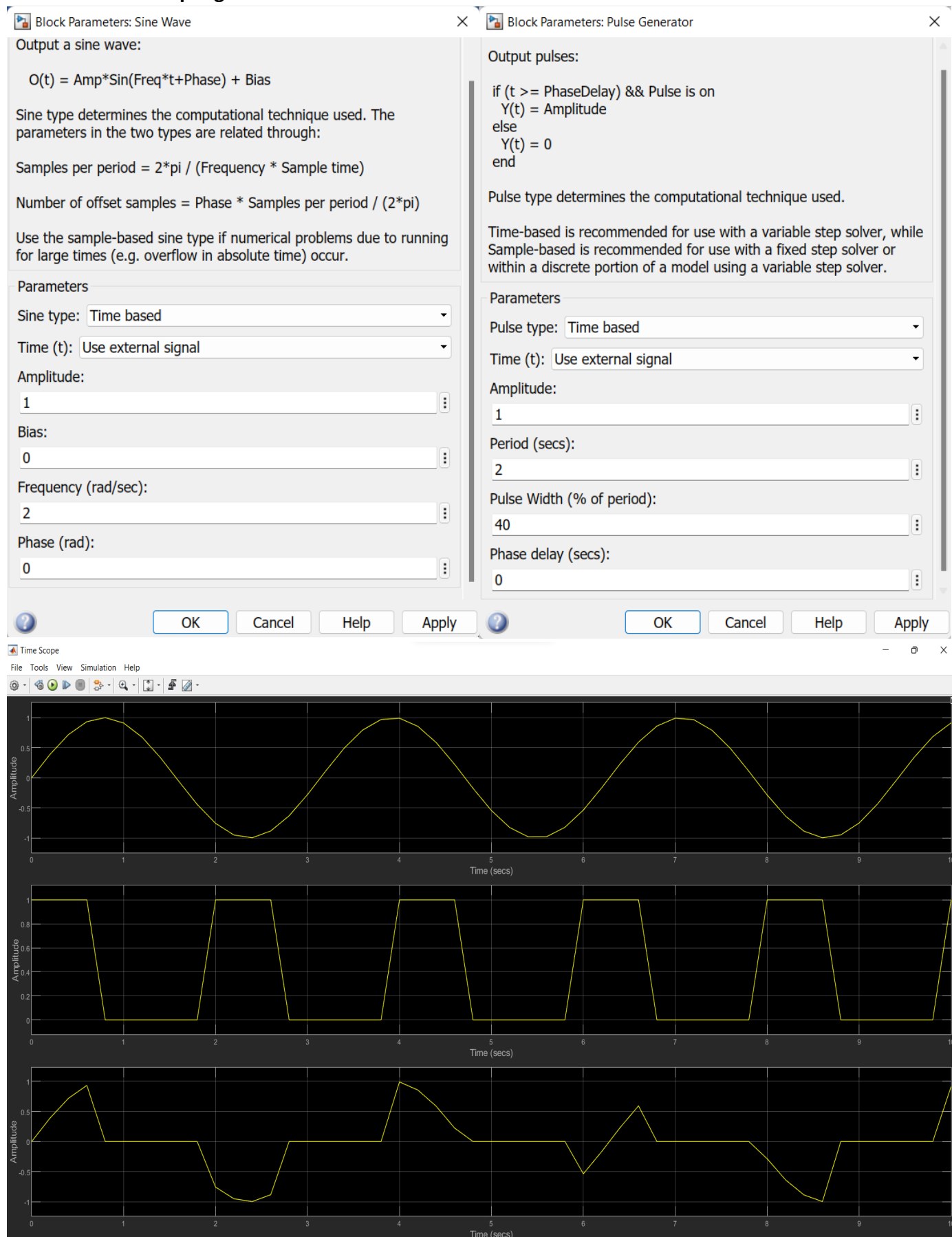
### CASE-III: Over Sampling

- $F_s > 2 \cdot F_m$
- $F_m = 500$
- $F_s = 1100$



**Figure:-**



**CASE-I: Under-Sampling**

## CASE-II: Perfect Sampling

### Block Parameters: Sine Wave

Output a sine wave:

$$O(t) = \text{Amp} * \sin(\text{Freq} * t + \text{Phase}) + \text{Bias}$$

Sine type determines the computational technique used. The parameters in the two types are related through:

$$\text{Samples per period} = 2 * \pi / (\text{Frequency} * \text{Sample time})$$

$$\text{Number of offset samples} = \text{Phase} * \text{Samples per period} / (2 * \pi)$$

Use the sample-based sine type if numerical problems due to running for large times (e.g. overflow in absolute time) occur.

**Parameters**

Sine type: Time based

Time (t): Use simulation time

Amplitude: 1

Bias: 0

Frequency (rad/sec): 2

Phase (rad): 0

Buttons: OK Cancel Help Apply

### Block Parameters: Pulse Generator

Output pulses:

```

if (t >= PhaseDelay) && Pulse is on
    Y(t) = Amplitude
else
    Y(t) = 0
end
        
```

Pulse type determines the computational technique used.

Time-based is recommended for use with a variable step solver, while Sample-based is recommended for use with a fixed step solver or within a discrete portion of a model using a variable step solver.

**Parameters**

Pulse type: Time based

Time (t): Use simulation time

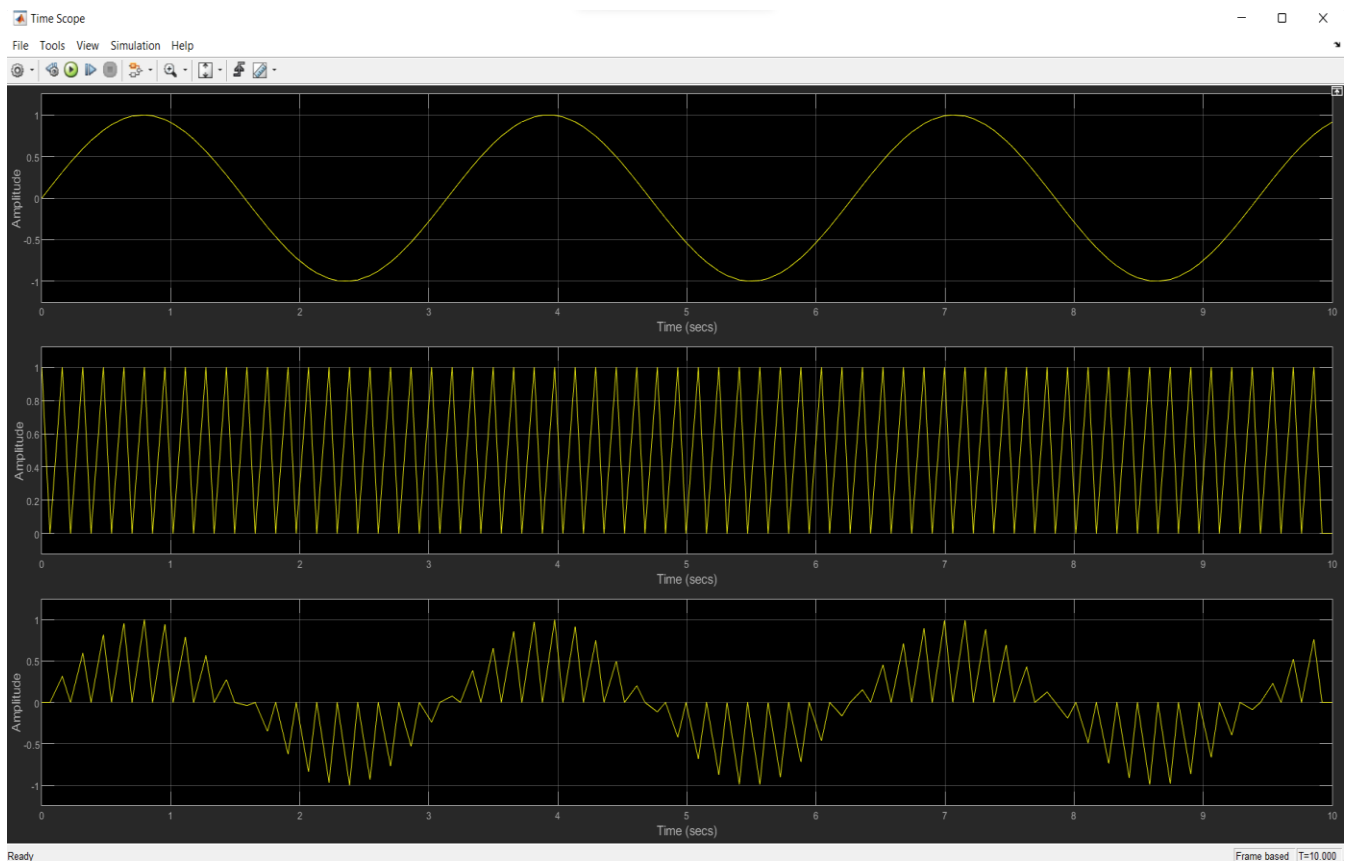
Amplitude: 1

Period (secs): 0.159

Pulse Width (% of period): 40

Phase delay (secs): 0

Buttons: OK Cancel Help Apply



### CASE-III: Over Sampling

#### Block Parameters: Sine Wave

Output a sine wave:

$$O(t) = \text{Amp} * \sin(\text{Freq} * t + \text{Phase}) + \text{Bias}$$

Sine type determines the computational technique used. The parameters in the two types are related through:

Samples per period =  $2 * \pi / (\text{Frequency} * \text{Sample time})$

Number of offset samples =  $\text{Phase} * \text{Samples per period} / (2 * \pi)$

Use the sample-based sine type if numerical problems due to running for large times (e.g. overflow in absolute time) occur.

**Parameters**

Sine type: Time based

Time (t): Use external signal

Amplitude: 1

Bias: 0

Frequency (rad/sec): 2

Phase (rad): 0

#### Block Parameters: Pulse Generator

```

if (t >= PhaseDelay) && Pulse is on
    Y(t) = Amplitude
else
    Y(t) = 0
end
        
```

Pulse type determines the computational technique used.

Time-based is recommended for use with a variable step solver, while Sample-based is recommended for use with a fixed step solver or within a discrete portion of a model using a variable step solver.

**Parameters**

Pulse type: Time based

Time (t): Use simulation time

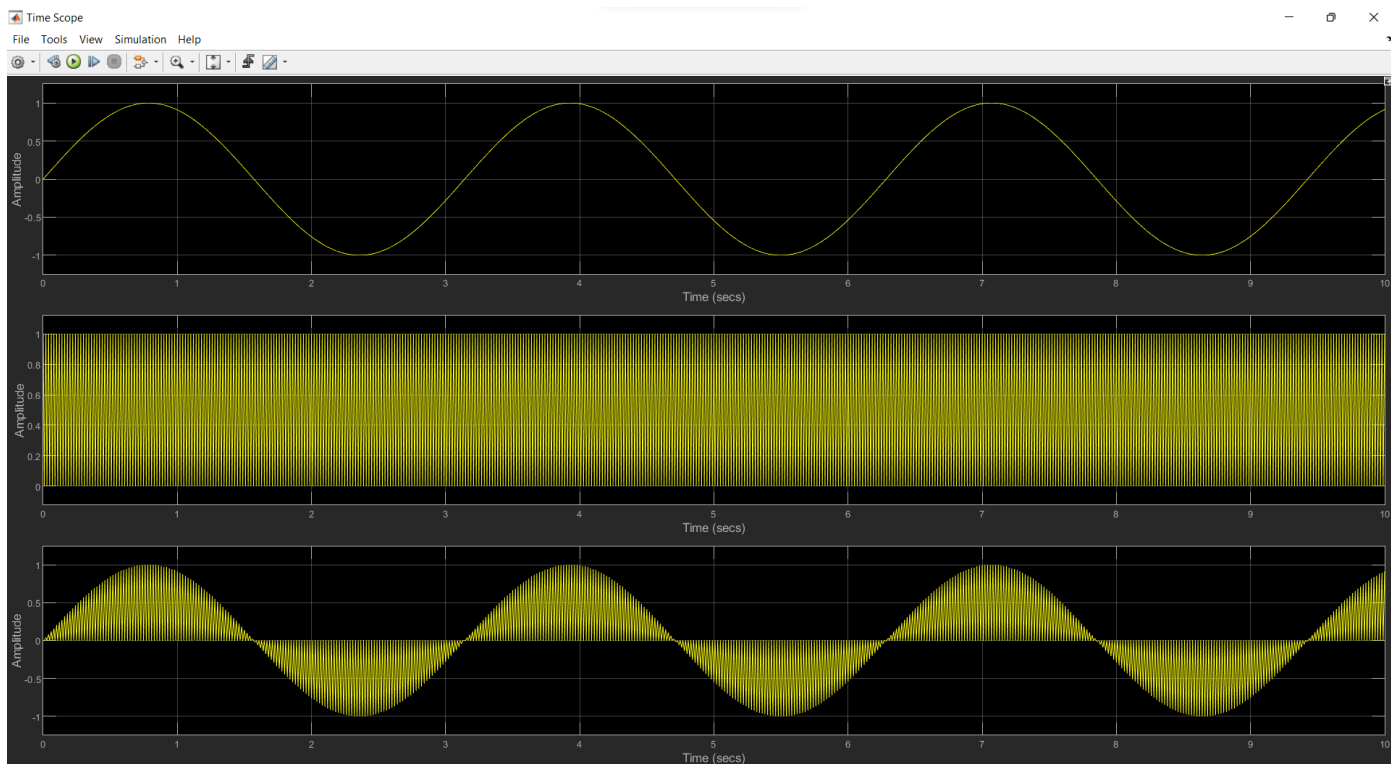
Amplitude: 1

Period (secs): 0.02

Pulse Width (% of period): 40

Phase delay (secs): 0

☒ Interpret vector parameters as 1-D



# EXPERIMENT 6

**Aim:** To study and implement PAM (Pulse Amplitude Modulation), PWM (Pulse Width Modulation) and PPM (Pulse Position Modulation) of analog signal in MATLAB software and simulink.

```

clc;
clear ALL;
close all;
%LAB 6 UI21CS10 FM SIGNAL
% MODULATING SIGNAL
figure;
fs=10000;
t = -1:1/fs:1;
pi=3.14;
fm=10;
fc=100;
Am=1;
Ac=1;
B=8;%modulation index
freqdev=B*fm;

m=Am*cos(2*pi*fm*t);
subplot(5,1,1);
plot(t,m);
xlabel('time 10');
ylabel('amp 10');
title('MODULATING SIGNAL UI21CS10');

% CARRIER SIGNAL
c=Ac*cos(2*pi*fc*t);
subplot(5,1,2);
plot(t,c);
xlabel('time 10');
ylabel('amp 10');
title('CARRIER SIGNAL UI21CS10');

% FM SIGNAL
s=Ac*cos(2*pi*fc*t+(B*sin(2*pi*fm*t)));
subplot(5,1,3);
plot(t,s);
xlabel('time 10');
ylabel('amp 10');
title('FM SIGNAL UI21CS10');

%IN-BUILT FM SIGNAL
y=fmmod(m,fc,fs,freqdev);
subplot(5,1,4);
plot(t,y);
xlabel('time 10');
ylabel('amp 10');
title('FM SIGNAL using IN-BUILT UI21CS10');

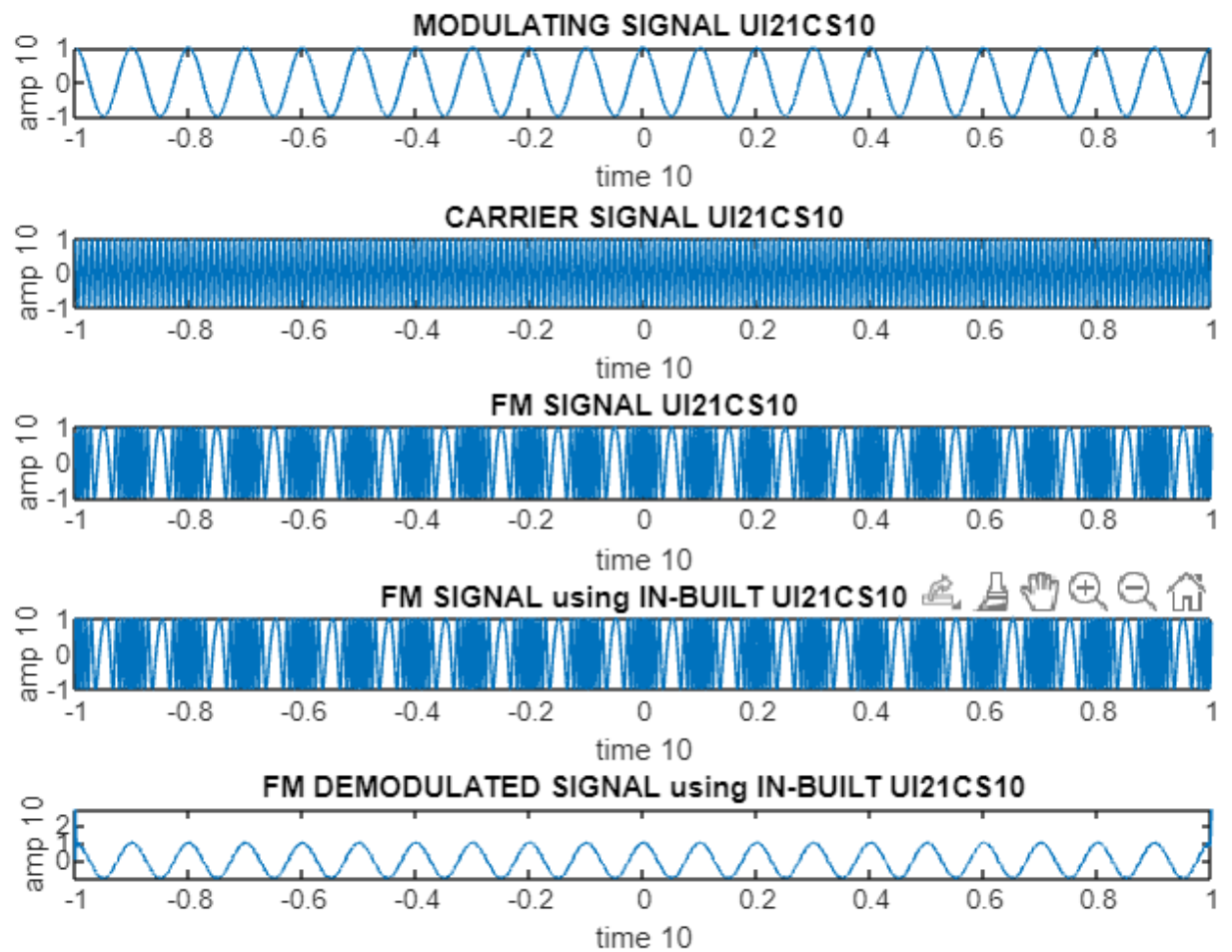
%IN-BUILT FM DEMODULATION SIGNAL

```

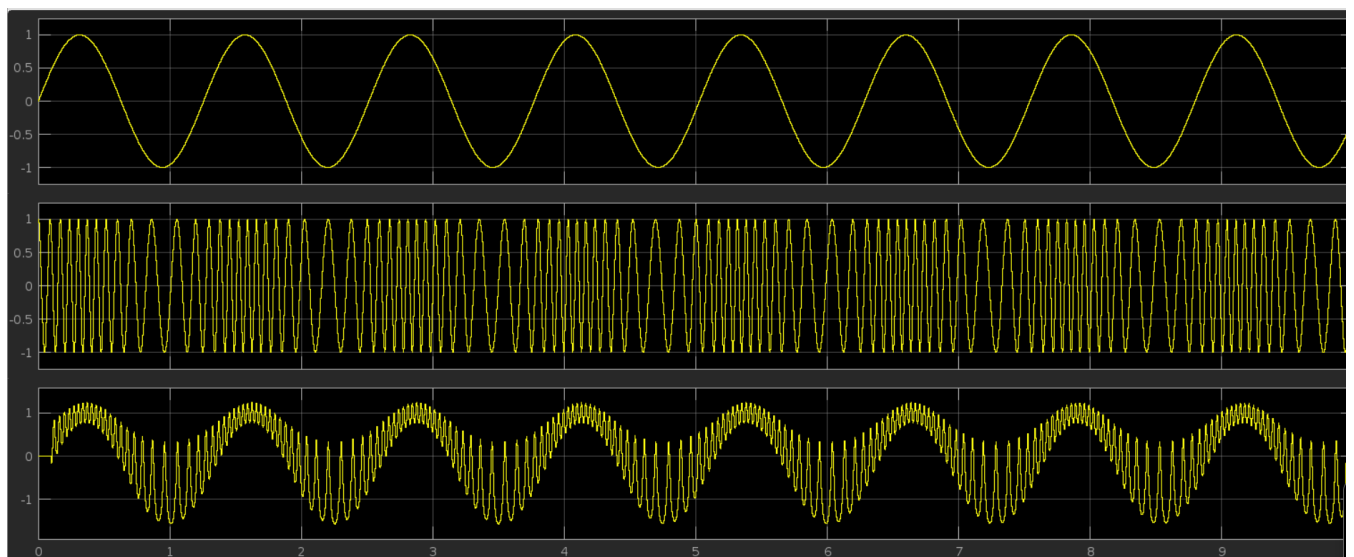
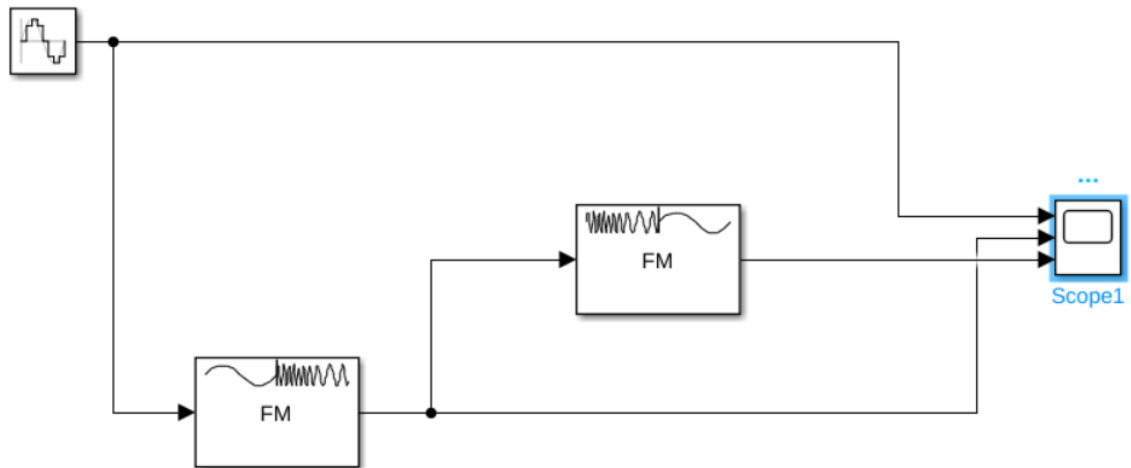
```

z=fmdemod(s,fc,fs,freqdev);
subplot(5,1,5);
plot(t,z);
xlabel('time 10');
ylabel('amp 10');
title('FM DEMODULATED SIGNAL using IN-BUILT UI21CS10');

```



## Simulink:



# EXPERIMENT 7

**Aim:** To obtain frequency modulation and demodulation using equations and in-built functions in MATLAB software and simulink.

## Code:

```

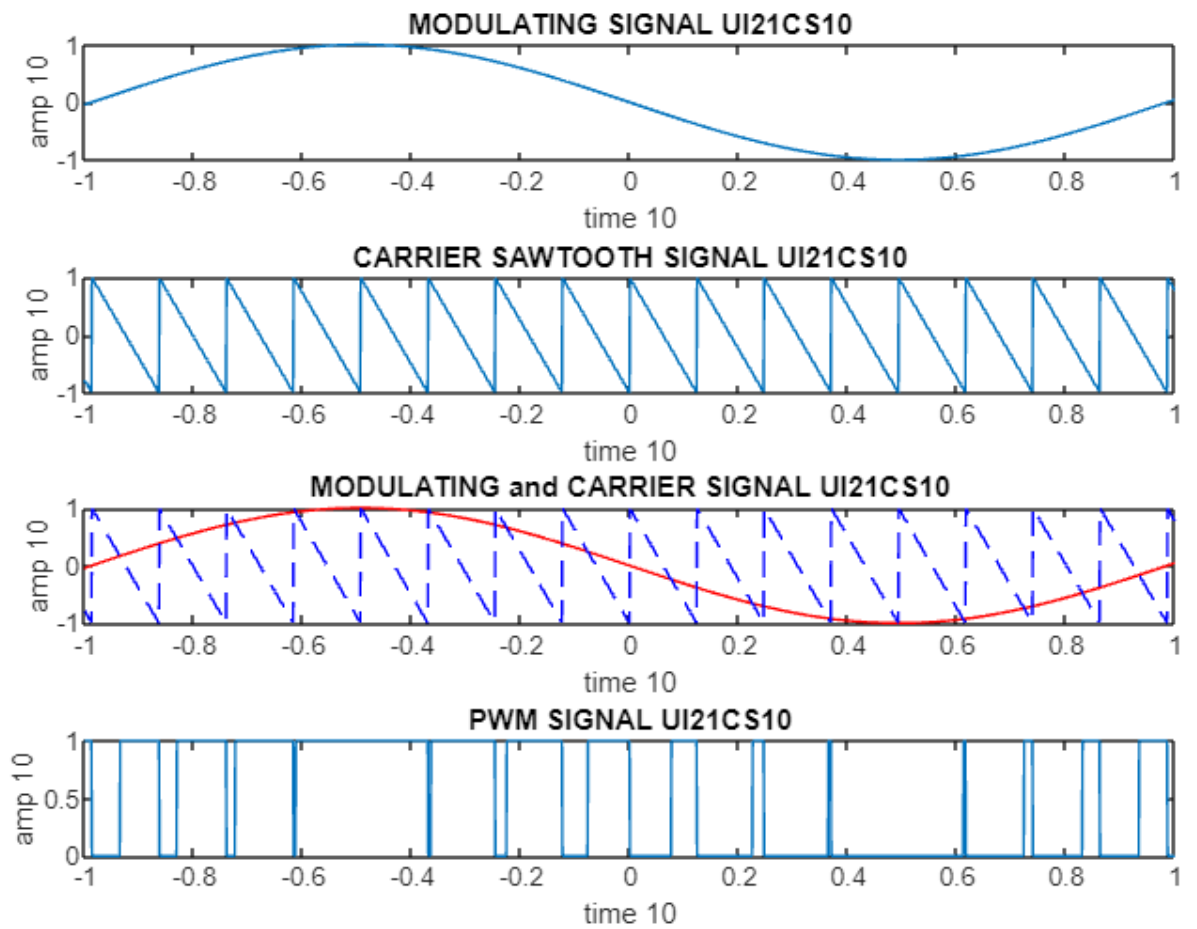
clc;
clear ALL;
close all;
%LAB 7 UI21CS10 PAM - PWM - PPM SIGNAL
% MESSAGE SIGNAL
figure;
fs=10000;
t = -1:0.001:1;
pi=3.14;
fm=1000;
fc=16000;
m=sin(2*pi*fm*t);
subplot(4,1,1);
plot(t,m);
xlabel('time 10');
ylabel('amp 10');
title('MODULATING SIGNAL UI21CS10');

% SAWTOOTH CARRIER SIGNAL
c=sawtooth(2*pi*fc*t);
subplot(4,1,2);
plot(t,c);
xlabel('time 10');
ylabel('amp 10');
title('CARRIER SAWTOOTH SIGNAL UI21CS10');

subplot(4,1,3);
plot(t,m,'r',t,c,'b--');
xlabel('time 10');
ylabel('amp 10');
title('MODULATING and CARRIER SIGNAL UI21CS10');
n=length(c);
for i = 1:n
    if m(i)>=c(i)
        pwm(i)=1;
    else
        pwm(i)=0;
    end
end
subplot(4,1,4);
plot(t,pwm);
xlabel('time 10');
ylabel('amp 10');
title('PWM SIGNAL UI21CS10');

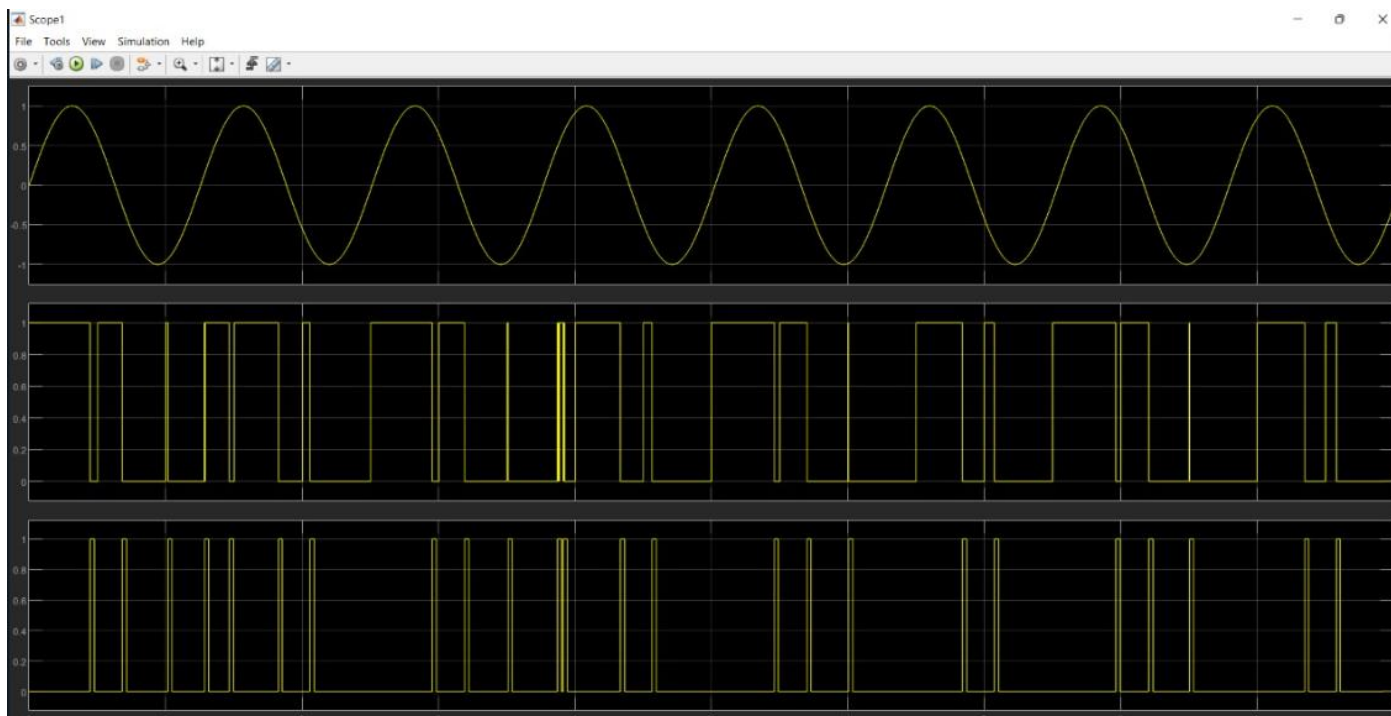
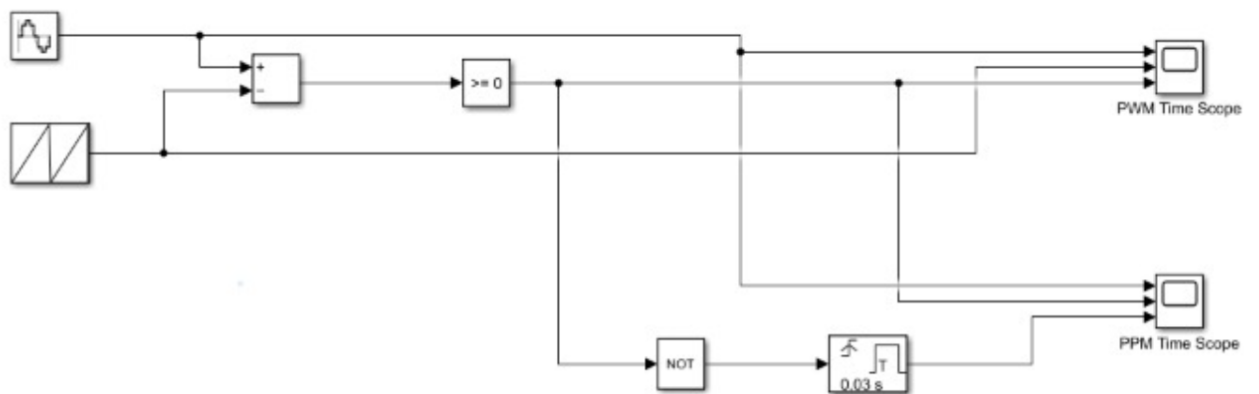
```

## Output





## Simulink:



## **EXPERIMENT 8**

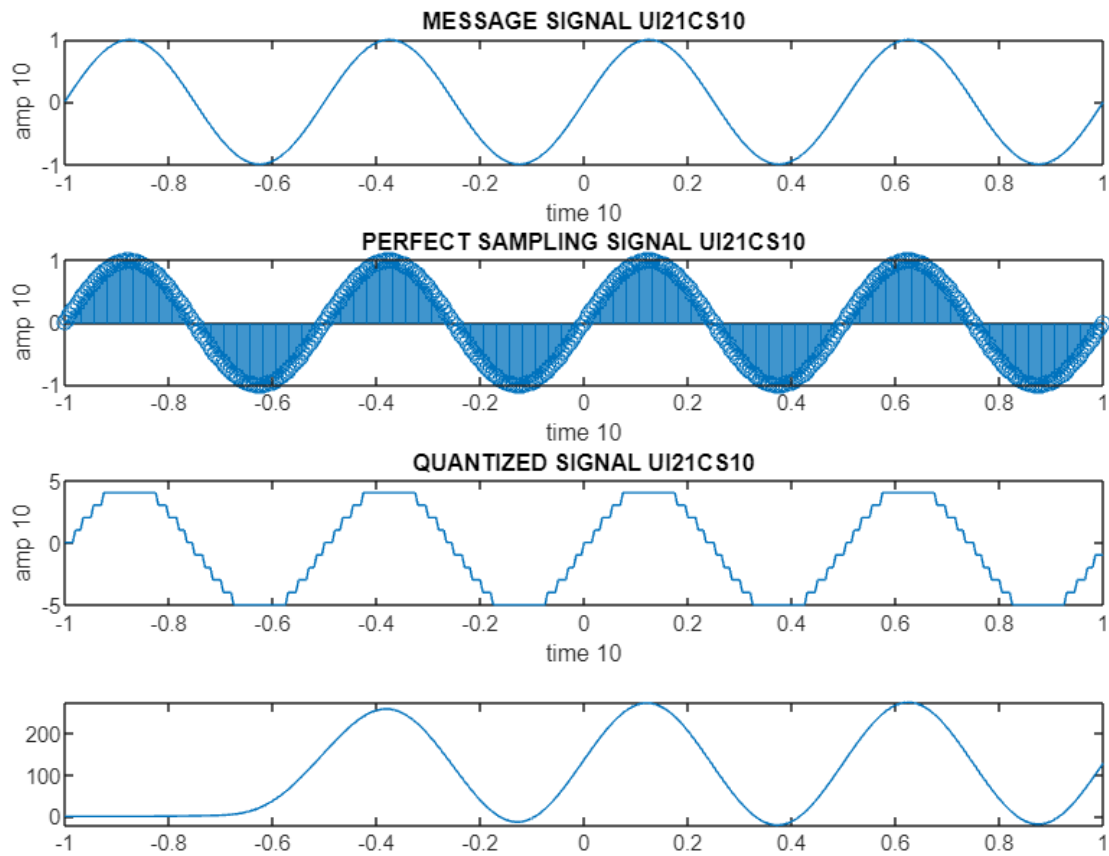
**Aim:** To study about modulation and demodulation of Pulse Code Modulation (PCM) in MATLAB software and simulink.

### **Code:**

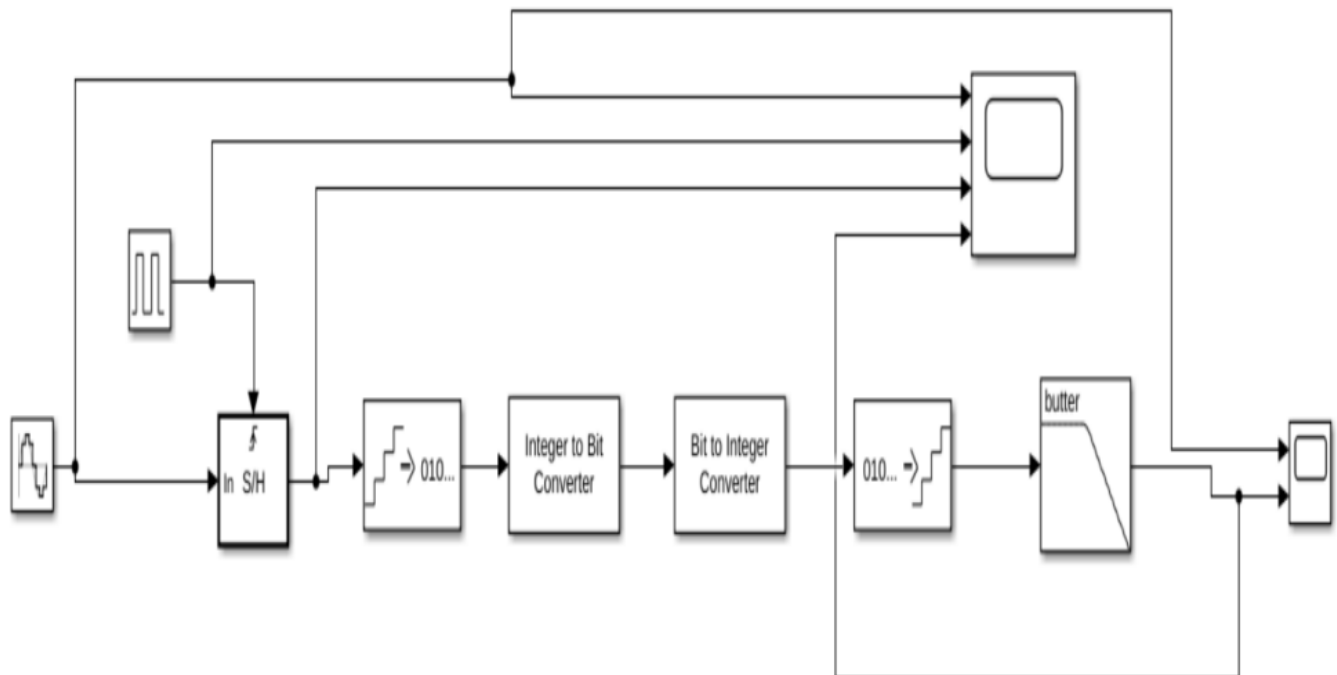
```
clc;
clear All;
close all;
%LAB 8 UI21CS10 ANALOG TO DIGITAL CONVERSION
% MESSAGE SIGNAL
figure;
t = -1:0.005:1;
pi=3.14;
fm=2;
m=sin(2*pi*fm*t);
subplot(4,1,1);
plot(t,m);
xlabel('time 10');
ylabel('amp 10');
title('MESSAGE SIGNAL UI21CS10');
% PERFECT SAMPLING
fm=1000;
subplot(4,1,2);
stem(t,m);
```

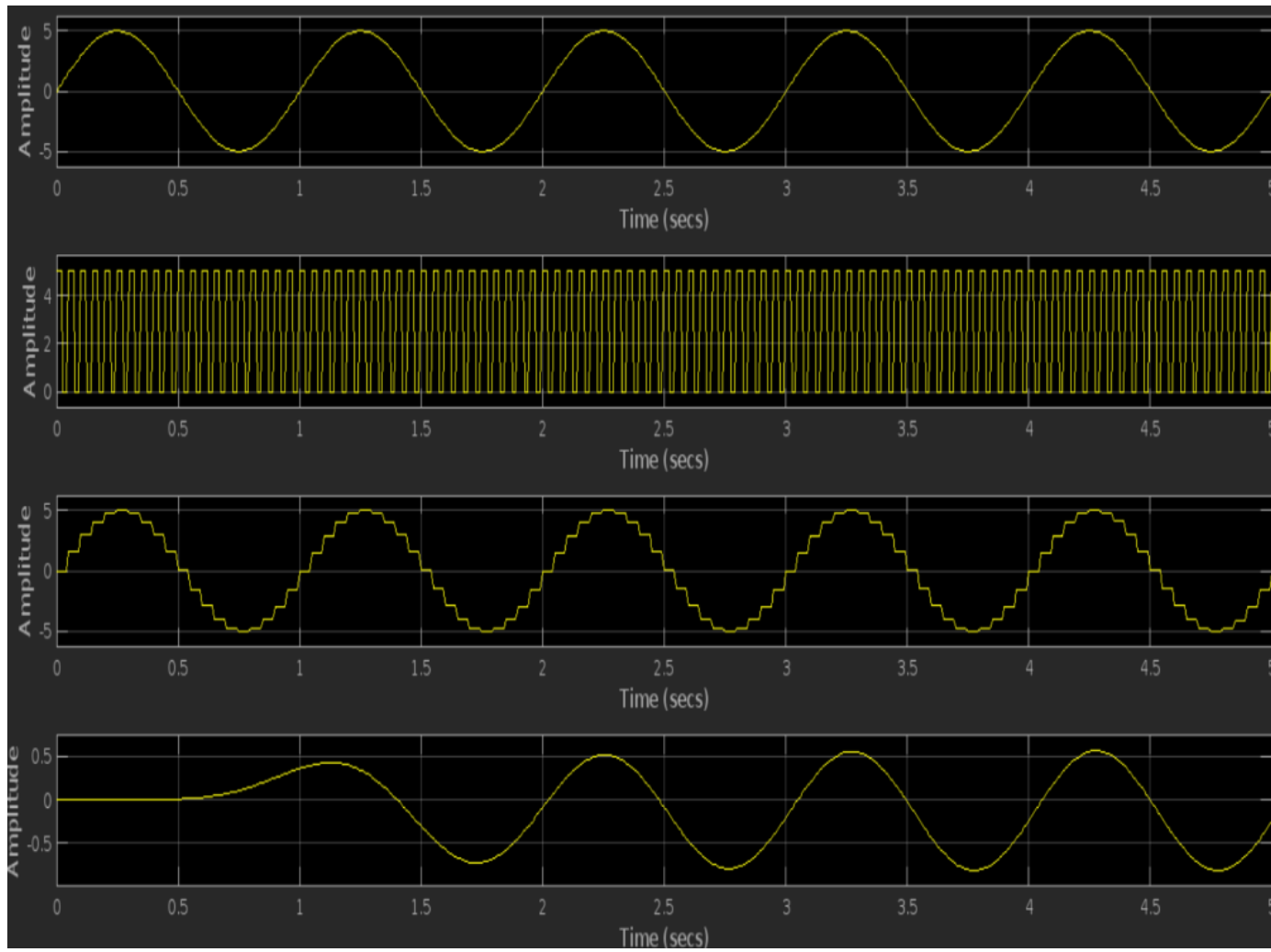
```
xlabel('time 10');  
ylabel('amp 10');  
title('PERFECT SAMPLING SIGNAL UI21CS10');  
x=floor(m/0.2);  
y=dec2bin(x);  
subplot(4,1,3);  
plot(t,x);  
xlabel('time 10');  
ylabel('amp 10');  
title('QUANTIZED SIGNAL UI21CS10');  
z=bin2dec(y);s  
disp(z);  
output1=filter(1,1,z);  
[B,A]=butter(5,1/42,'low');  
output2=filter(B,A,output1);  
subplot(4,1,4);  
plot(t,output2);
```

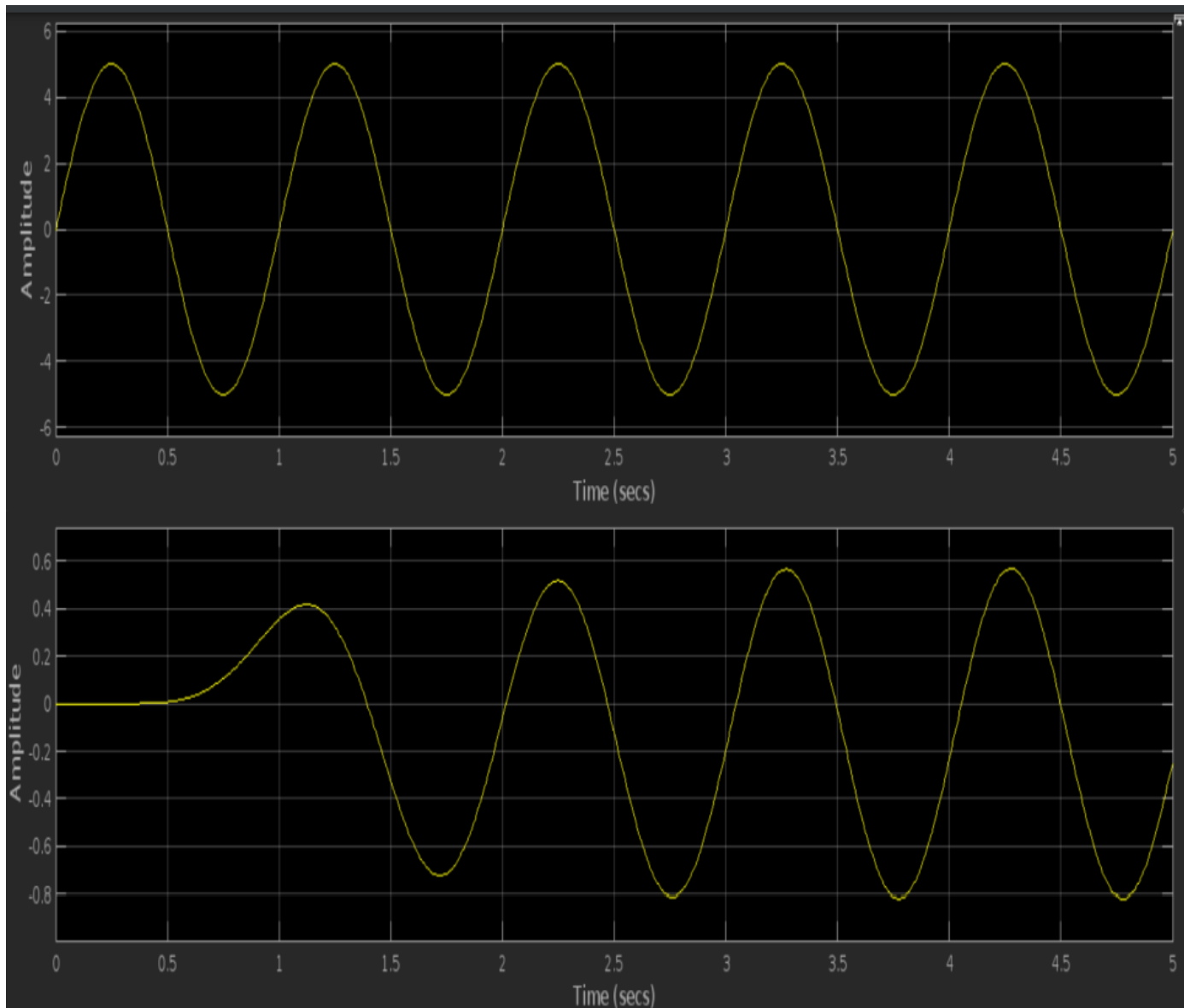
**OUTPUT:**



## SIMULINK:



**OUTPUT:**



# EXPERIMENT 9

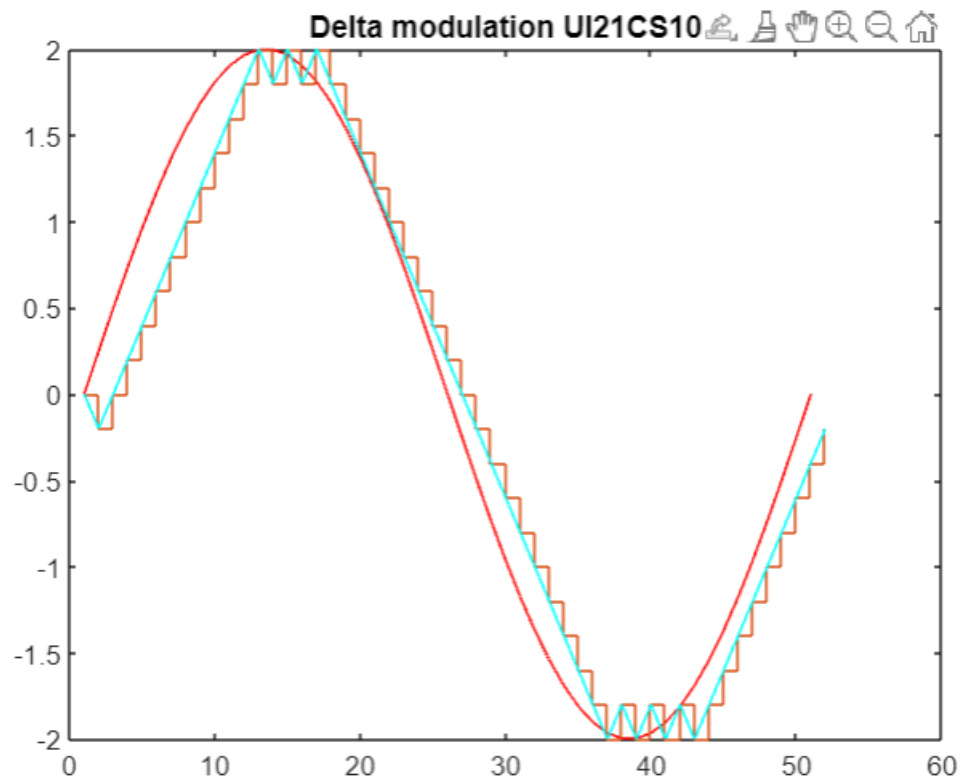
**AIM:-**The study And emplemnt the delta modulation

**CODE:**

```
clc;
clear all;
close all;
a=2;
t=0:2*pi/50:2*pi;
x = a*sin(t);
l = length(x);
plot(x,'r');
title('Delta modulation UI21CS10');
delta = 0.2;
```

```
hold on
xn = 0;
for i=1:l
if x(i)> xn(i)
d(i) = 1;
xn(i+1) = xn(i)+delta;
else
d(i) = 0;
xn(i+1)= xn(i)-delta;
end
end
stairs(xn)
hold on
for i=1:d
if d(i)>xn(i)
d(i) = 0;
xn(i+1) = xn(i)-delta;
else
d(i) = 1;
xn(i+1) = xn(i)+delta;
end
end
```

```
plot(xn,'c');
```

**OUTPUT:**

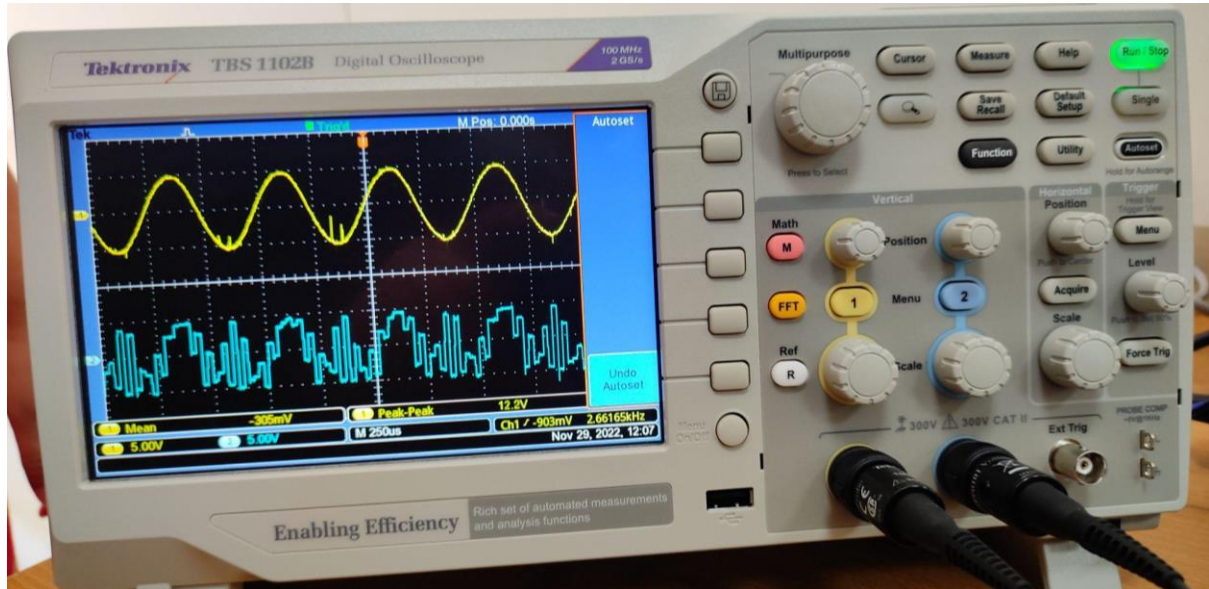


# EXPERIMENT 10

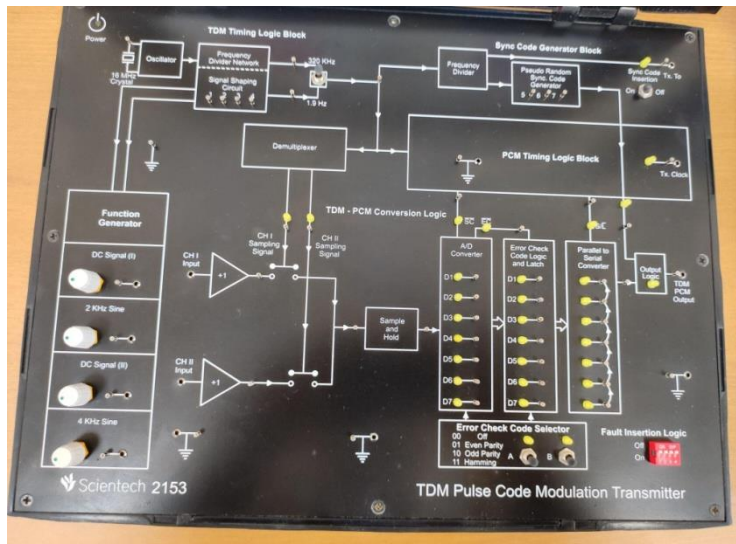
**AIM:-**The study construction and execution of PCM and PCM-TDM signals using Transmission and Receiver kit.

## APPARATUS:-

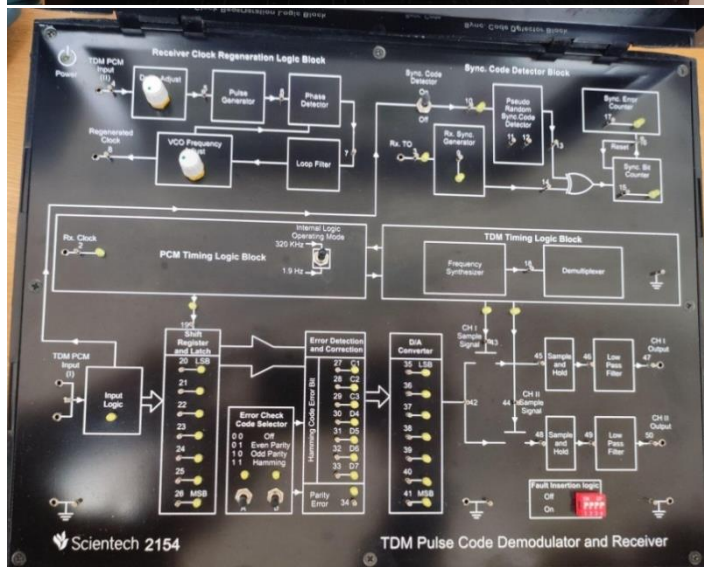
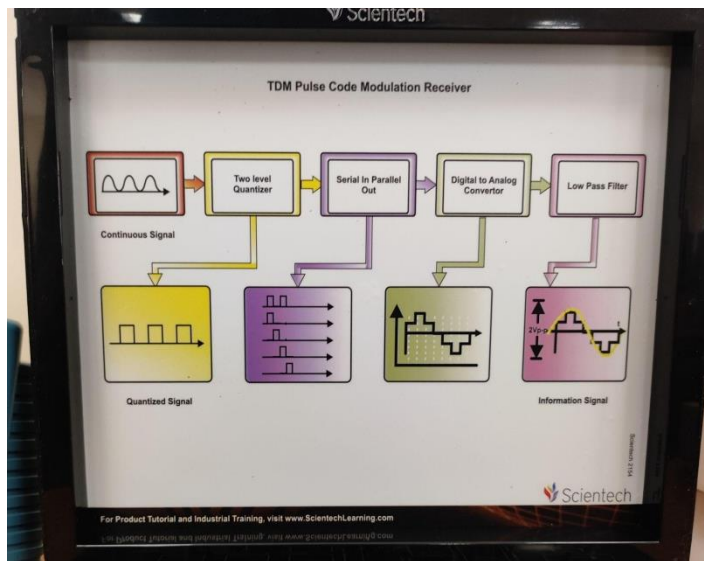
### 1. OSCILLOSCOPE



### 2. PCM-TDM TRANSMITTER:-



### 3.TDM DECODER and DEMODULATOR KIT:-

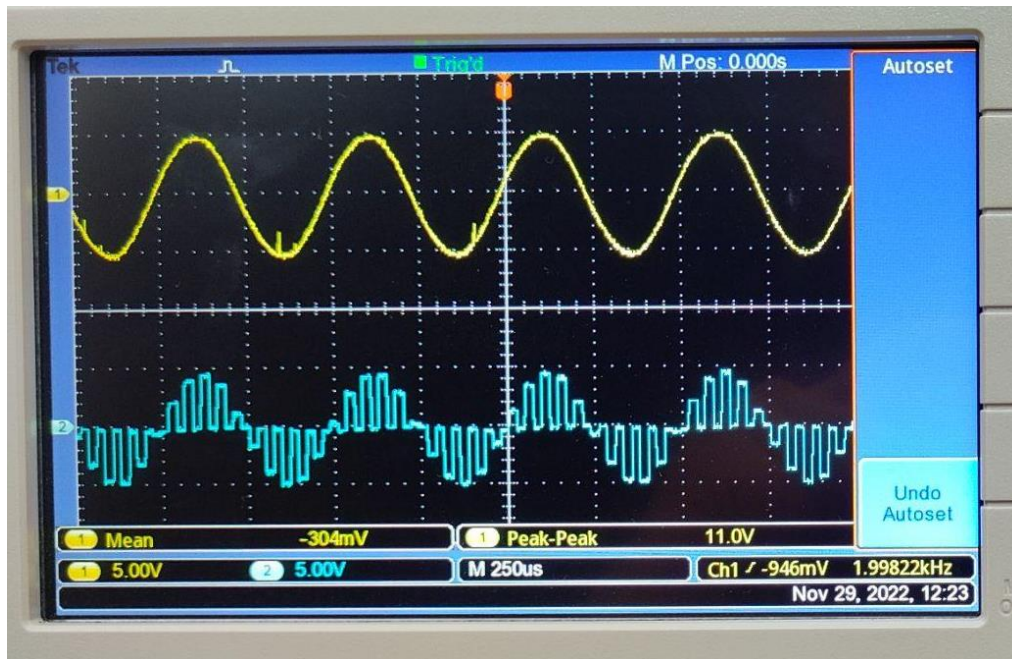




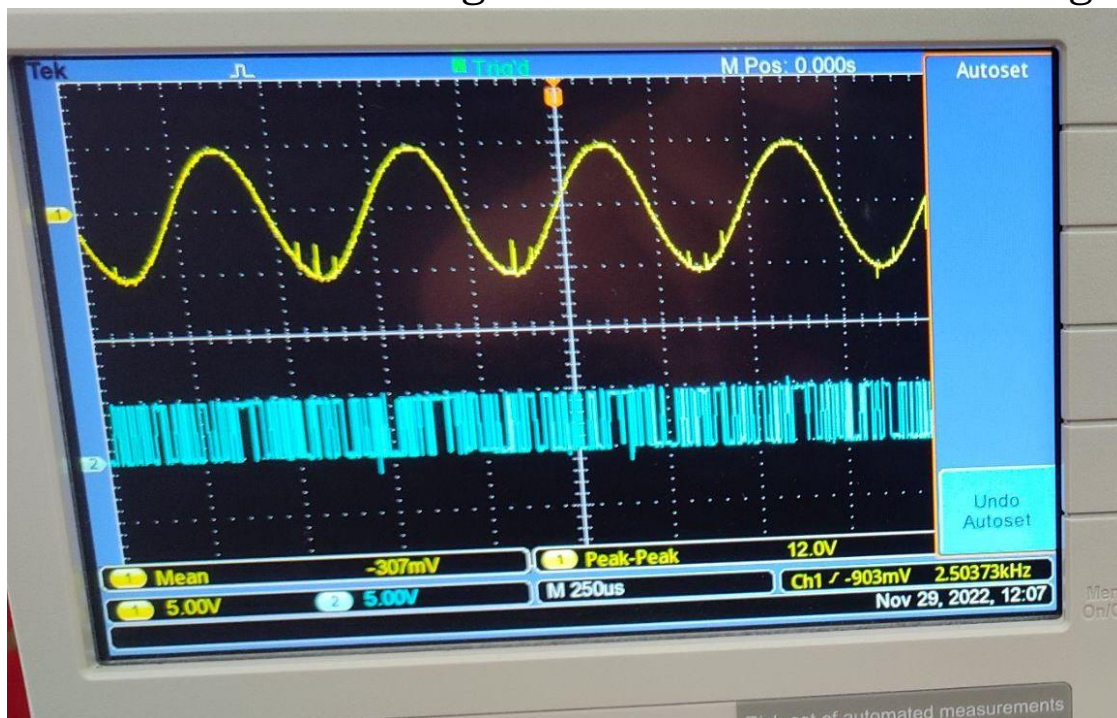
### **OBSERVATION: (PCM TX -RX)**

MESSAGE Signal(2KHz) and its SAMPLED OUTPUT  
Signal:-



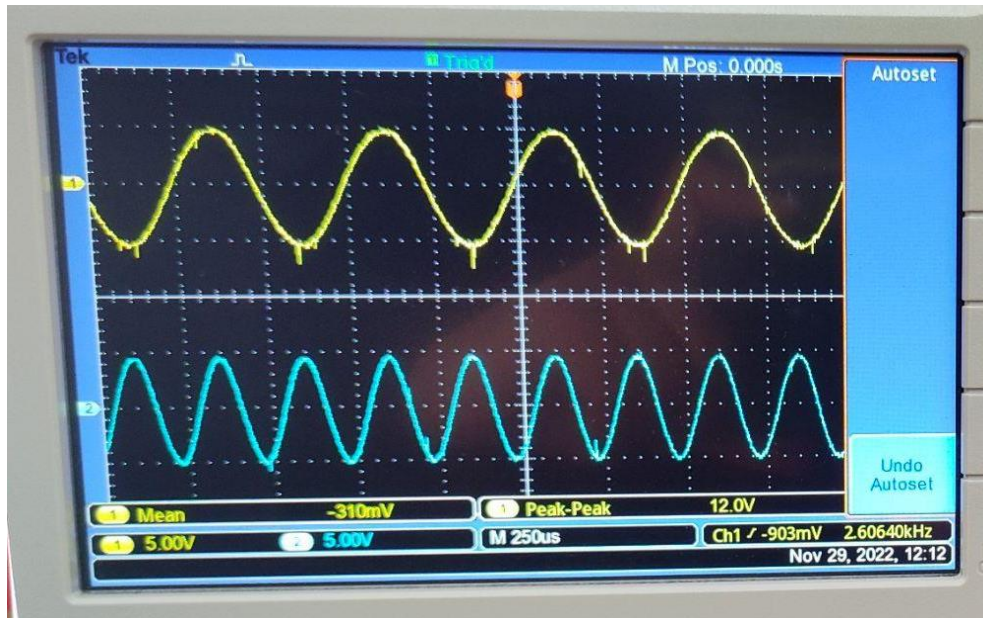


RECONSTRUCTED Signal and RECIEVED PCM Signal:-

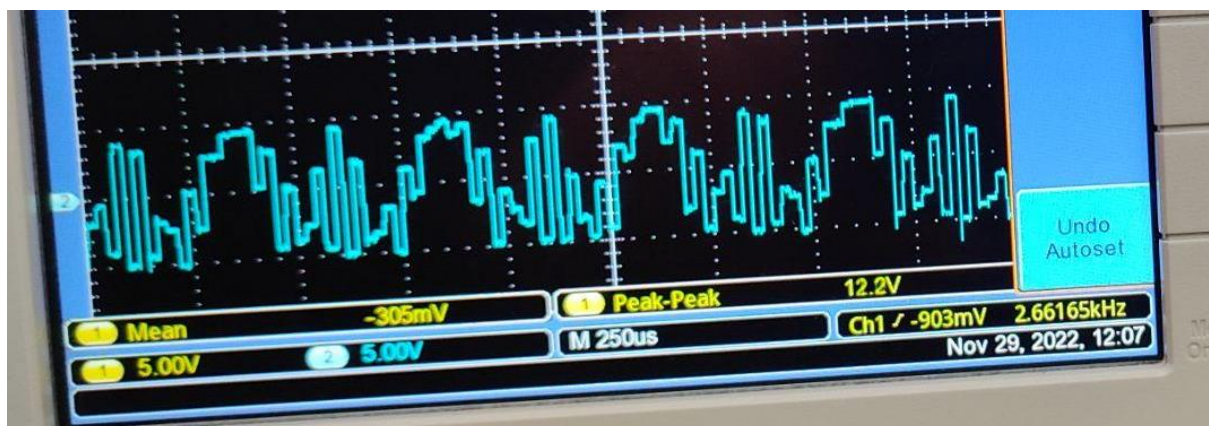


## OBSERVATION: (PCM-TDM TX -RX)

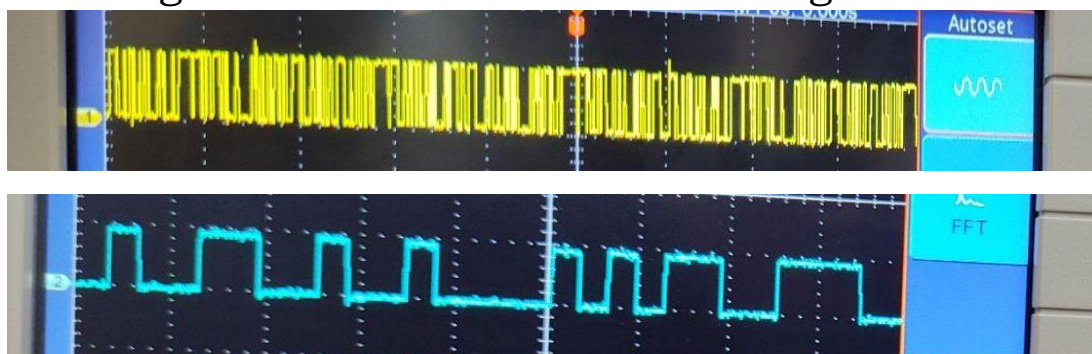
TWO MESSAGE SIGNAL (2KHz and 4KHz):-



TDM SAMPLED SIGNAL for both the SIGNALS (2KHz&4KHz):-



PCM Signal and RECONSTRUCTED Signal:-





TDM RECONSTRUCTED SIGNAL (2KHz and 4KHz):-



### **CONCLUSION:-**

We learned how to create ,transmit and recieve PCM,PCM-TDM signaal using TDM Transmission and Recieving Kit.