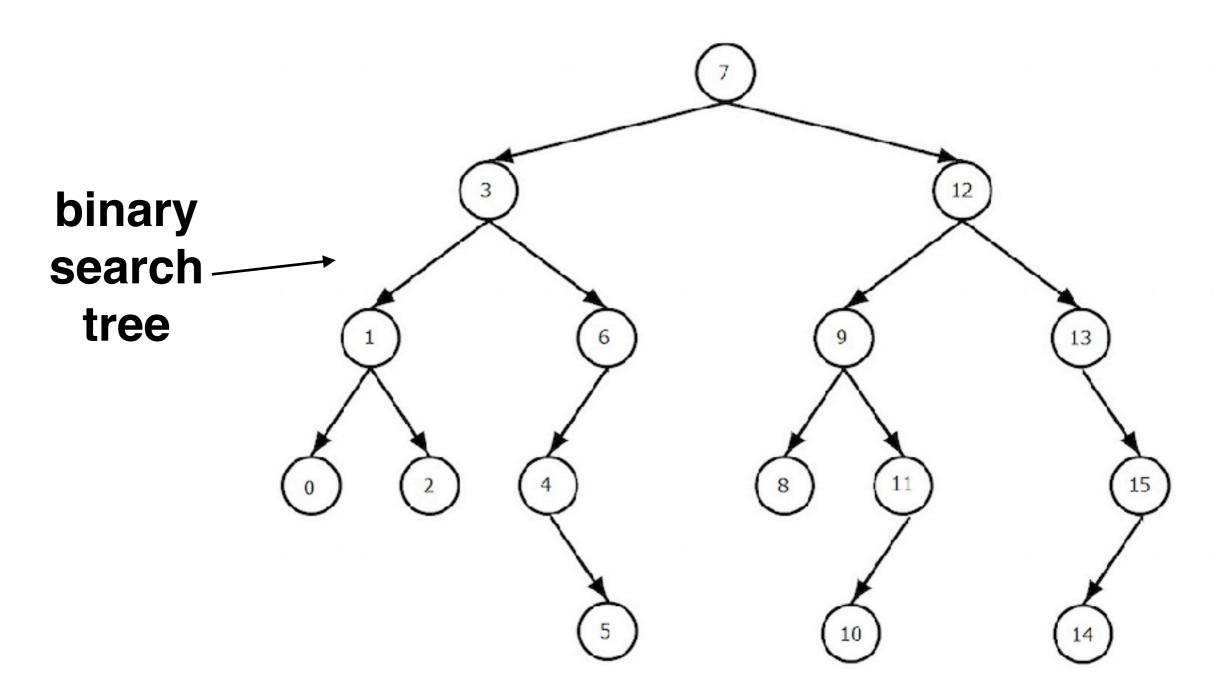
# Binary search trees and skiplists

CS 146 - Spring 2017

#### Review question (from 46B)

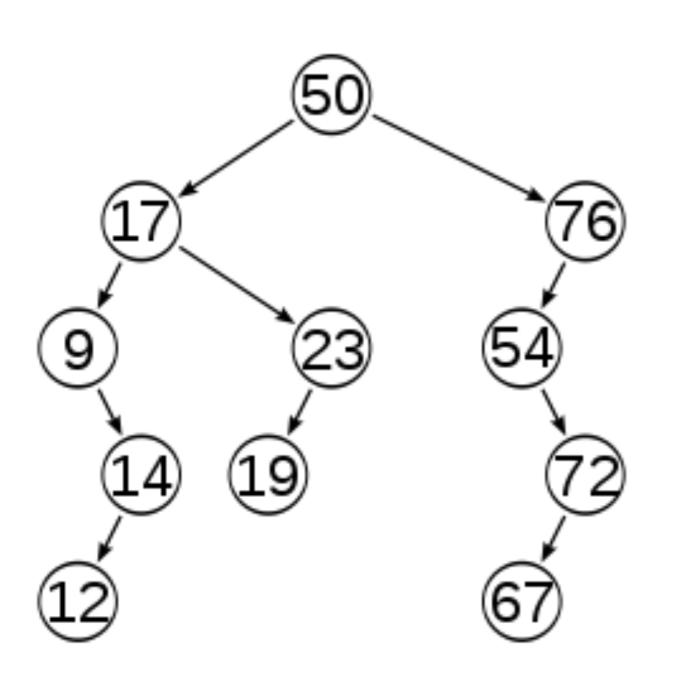


- Who is the successor of 12? 3? 8?
- What is the pattern for finding the successor?

# Today

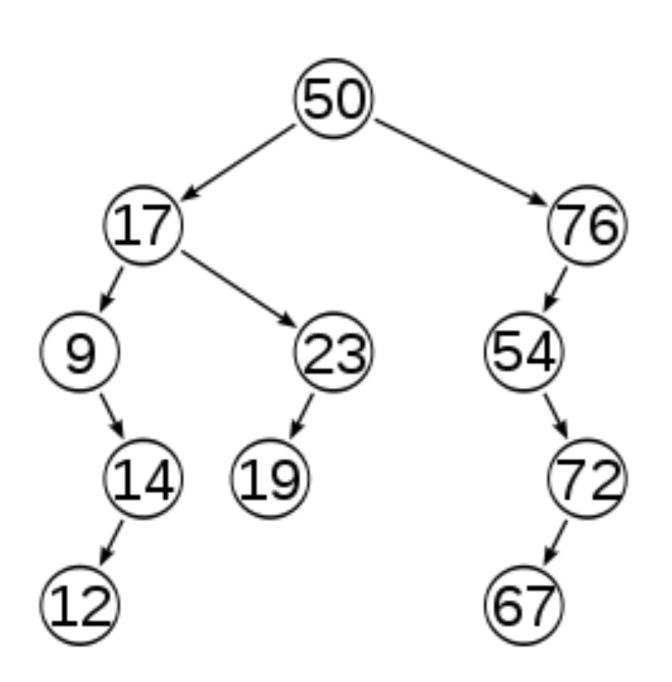
- 2 OrderedSet implementations
  - Binary search tree
  - Skiplist

## Binary search tree is



- a binary tree with...
- the binary search tree property

### To search for a key in a BST

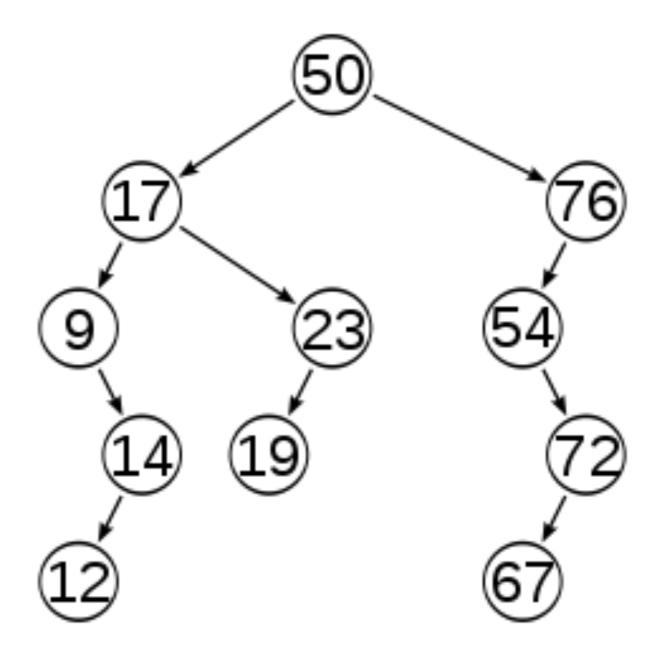


- start at root
- if key == node.key
  - (Key found!) return
- else if node.key < key</li>
  - · search left or
  - return (NOT FOUND) if no left
- else (key < node.key)</pre>
  - search right or
  - return (NOT FOUND) if no right

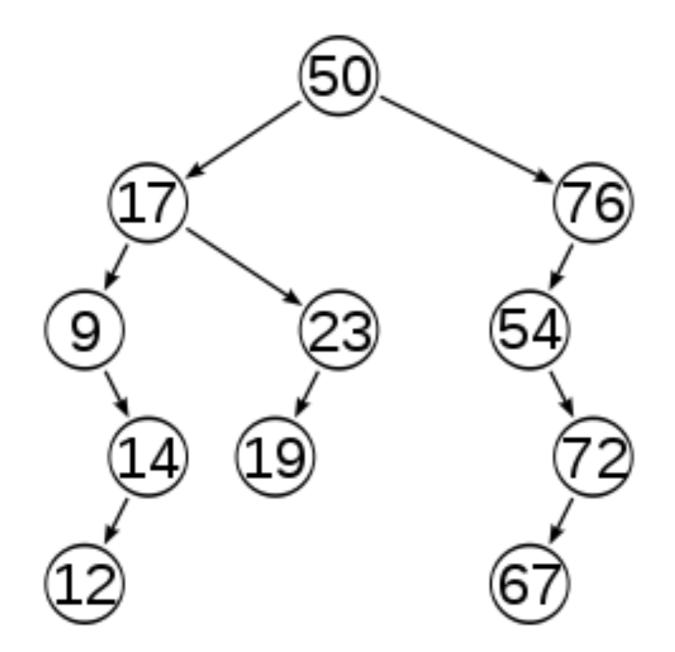
#### To insert

 perform a search until you can't keep going down

insert there



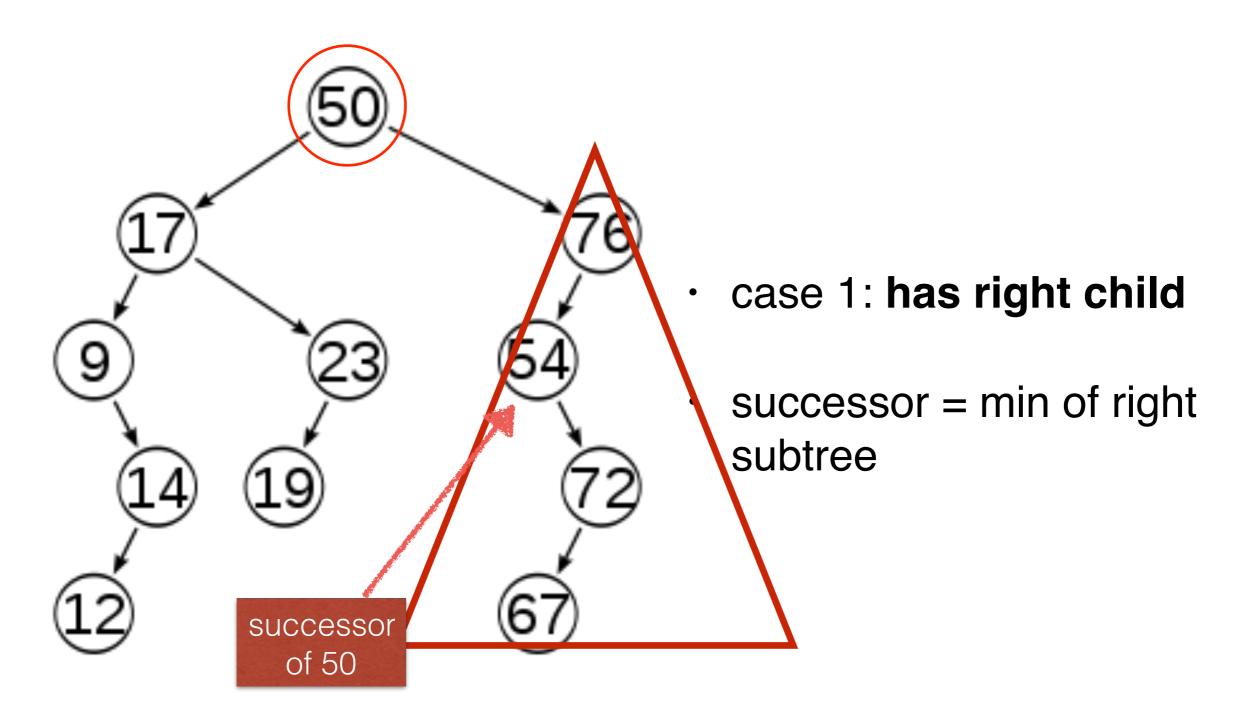
#### To find min



keep going to the left child until you can't

similar idea with finding max

#### To find successor (1/2)



similar idea with finding predecessor

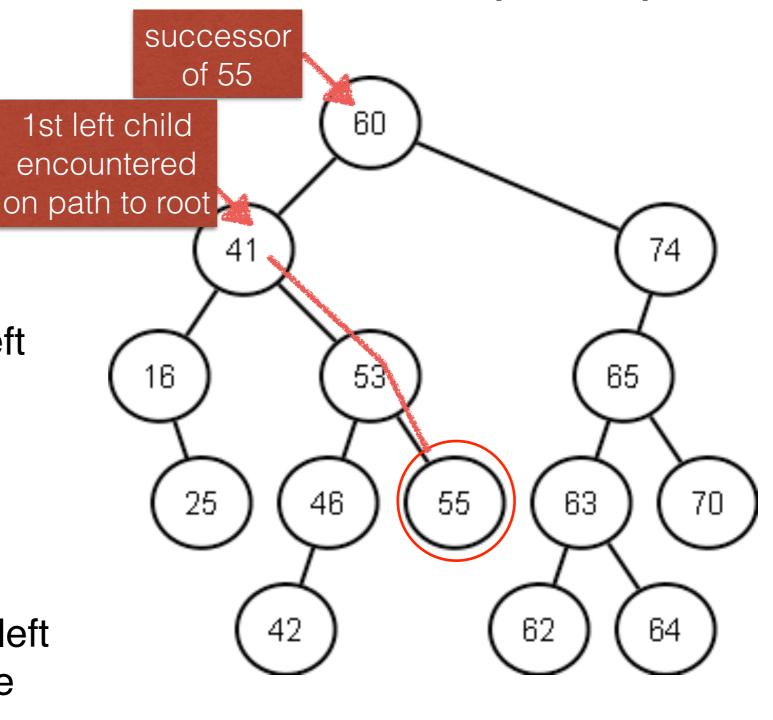
#### To find successor (2/2)



go up towards the root

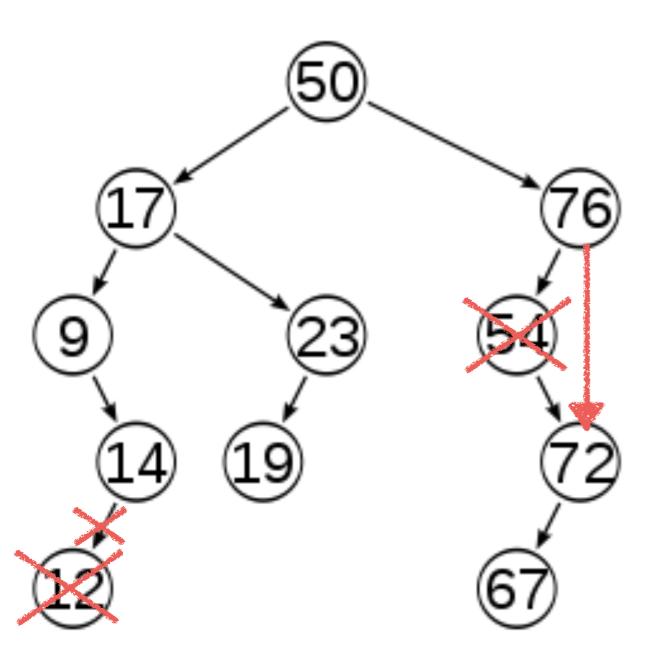
 stop when you are a left child

- your parent is the successor
- note: if you're never a left child and you reach the root, you had no successor



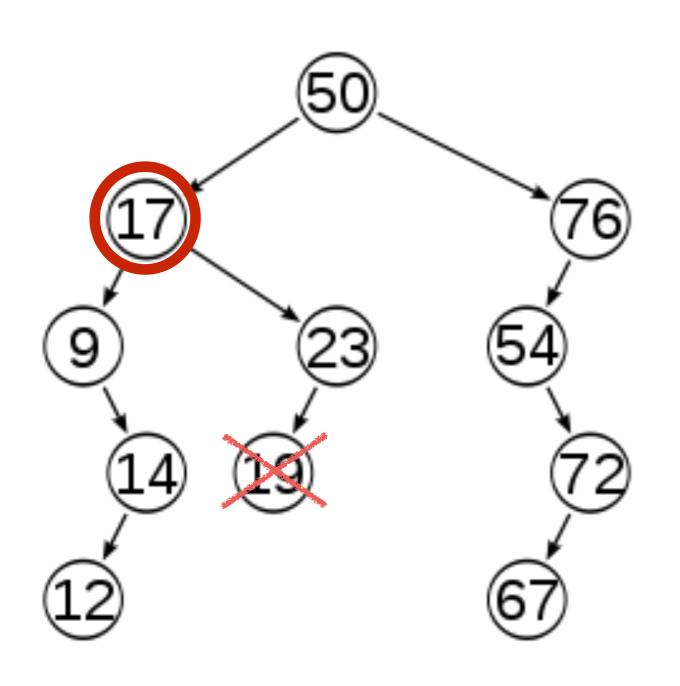
similar idea with finding predecessor

#### To delete a node (1/2)



- case 1: no children
  - delete link parent->itself
- · case 2: one child
  - relink parent and child

#### To delete a node (2/2)



- · case 3: two children
  - find the node's successor
  - swap key with successor
  - delete successor

to delete 17, swap values 17 and 19 (or 14), then delete node that used to contain 19 (but now contains 17)

# Skiplists

For slides, go to <a href="https://www.cs.umd.edu/class/spring2008/cmsc420/">https://www.cs.umd.edu/class/spring2008/cmsc420/</a>
<a href="https://www.cs.umd.edu/class/spring2008/cmsc420/">L12.SkipLists.pdf</a>

#### Recap: BST vs skiplists

	today	today	later: red- black, AVL, treaps,	today
sorted set operations	BST (h means height)	unbalanced BST (h = O(n))	balanced BST (h = O(log n))	skiplists
add/delete	O(h)	O(n)	O(log n) + time to rebalance	2 log_2 n
search	O(h)	O(n)	O(log n)	2 log_2 n
predecessor/ successor	O(h)	O(n)	O(log n)	2 log_2 n
	worst-case	worst-case	worst-case	on expectation, and with high probability