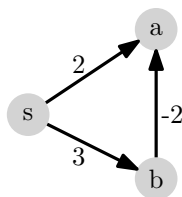


C-14.2 Give an example of an weighted directed graph, G , with negative-weight edges but no negative-weight cycle, such that Dijkstra's algorithm incorrectly computes the shortest-path distances from some start vertex v .

Solution. In this example, $s \rightarrow a$ and $s \rightarrow b$ will be relaxed first (these two can be relaxed in any order). Then a , having the lower distance estimate to s , will be pulled off the priority queue, with no outgoing edges to relax. Finally, b will be pulled off, again with no edges to relax since its only outgoing edge is to a vertex that has already been examined. This implies that Dijkstra's algorithm will determine a 's shortest path to be $s \rightarrow a$ rather than $s \rightarrow b \rightarrow a$.

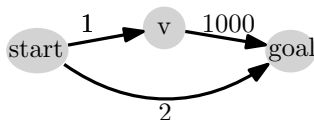


C-14.4 Consider the following greedy strategy for finding a shortest path from vertex *start* to vertex *goal* in a given connected graph.

- Initialize *path* to *start*.
- Initialize *VisitedVertices* to $\{\text{start}\}$.
- If $\text{start} = \text{goal}$, return *path* and exit. Otherwise, continue.
- Find the edge (start, v) of minimum weight such that v is adjacent to *start* and v is not in *VisitedVertices*.
- Add v to *path*.
- Add v to *VisitedVertices*.
- Set *start* equal to v and go to Step 3.

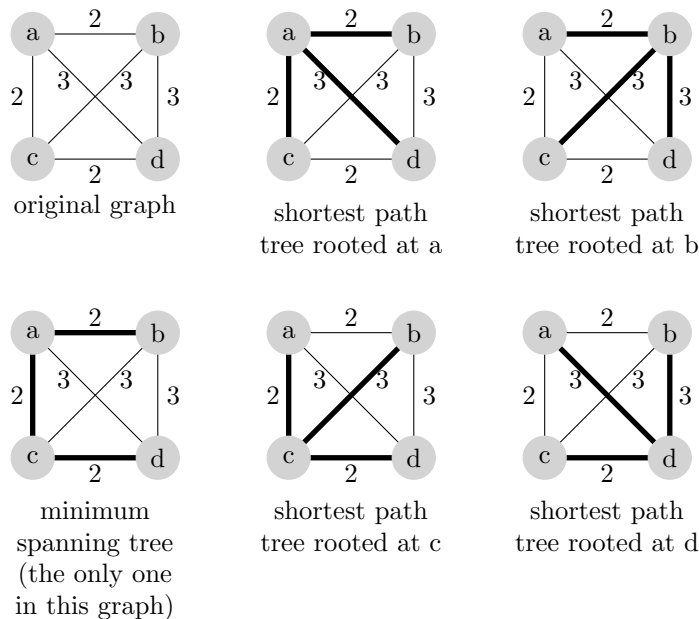
Does this greedy strategy always find a shortest path from *start* to *goal*? Either explain intuitively why it works, or give a counter example.

Solution. In the following example, the greedy algorithm will return path $\text{start} \rightarrow v \rightarrow \text{goal}$, which has length 1001 and is not the shortest path, which is actually the direct path $\text{start} \rightarrow \text{goal}$ with length 2.



R-15.9 Give an example of weighted, connected, undirected graph, G , such that the minimum spanning tree for G is different from every shortest-path tree rooted at a vertex of G .

Solution. Here is an example.



R-15.10 Let G be a weighted, connected, undirected graph, and let V_1 and V_2 be a partition of the vertices of G into two disjoint nonempty sets. Furthermore, let e be an edge in the minimum spanning tree for G such that e has one endpoint in V_1 and the other in V_2 . Give an example that shows that e is not necessarily the smallest-weight edge that has one endpoint in V_1 and the other in V_2 .

Solution. Here are two valid examples in which the edge of weight 2 is the edge e required by the problem. The edges of the minimum spanning tree are bold and the vertex partitioning is represented by the vertex colors. (Notice that the minimum spanning tree of a tree is the tree itself.)

