

Stacks API and finding strongly connected components

CS 146 - Spring 2017

Today

- DFS traversal
- Edge classification wrt DFS traversal
- Strongly connected components
- Tarjan's algorithm

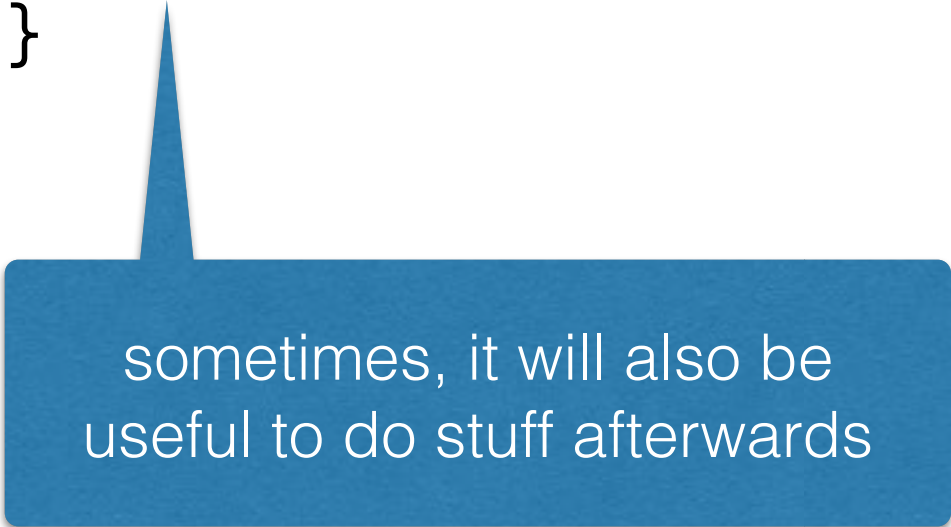
The stack API

- push()
- pop() <- **no parameter**

DFS on a tree is just a generalization of tree-traversal

```
preorder(v) {  
    // do stuff on v  
    if v has left child w  
        preorder(w)  
    if v has right child w  
        preorder(w)  
}
```

```
dfs(v) {  
    // do stuff on v  
    for every neighbor w of v  
        dfs(w)  
}
```



sometimes, it will also be useful to do stuff afterwards

DFS on a graph

```
Set visited = new Set();
```

```
dfs(v) {
```

```
    visited.add(v)
```

```
    // do stuff on v
```

```
    for every neighbor w of v
```

```
        if (!visited.contains(w))
```

```
            dfs(w)
```

```
}
```

observation: each node is “visited” (= input to a dfs call) once

Connection with textbook version

```
Set visited = new Set();
```

every vertex starts out
white (not visited)

```
dfs(v) {
```

```
    visited.add(v)
```

upon entering a recursive
call, v turns **grey (visiting)**

```
    // do stuff on v
```

```
    for every neighbor w of v
```

```
        if (!visited.contains(w))
```

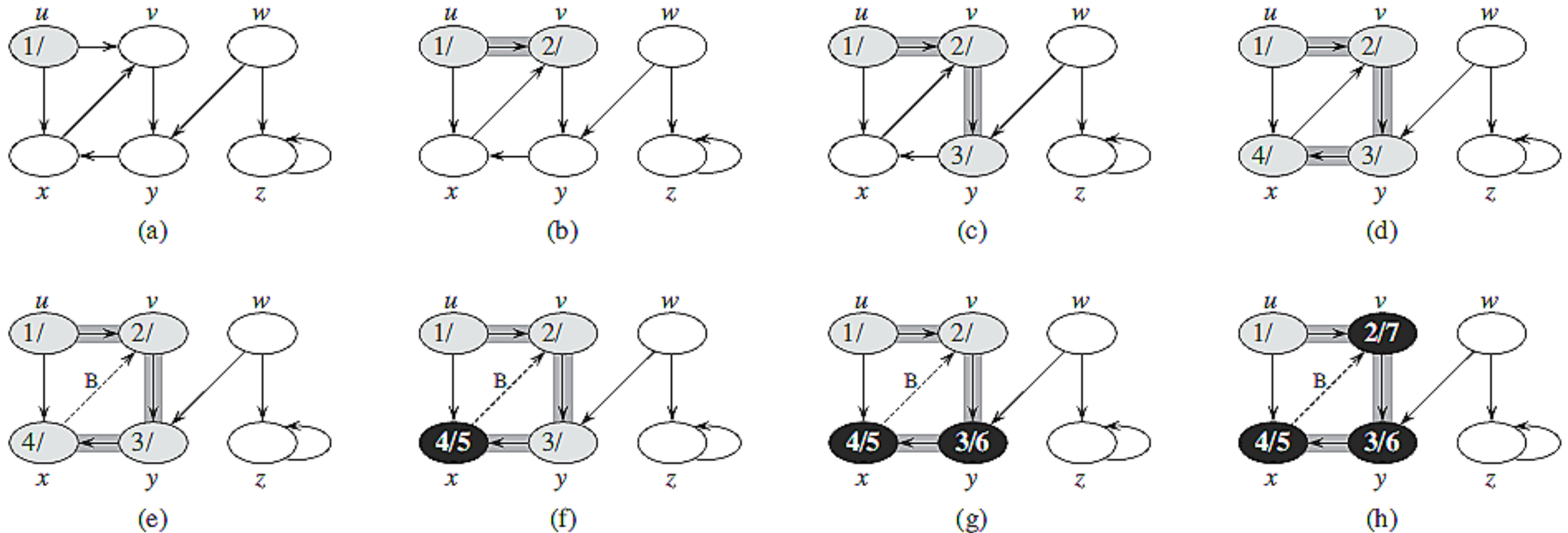
```
            dfs(w)
```

```
}
```

upon exiting the recursive call, v
turns **black (finished visiting)**

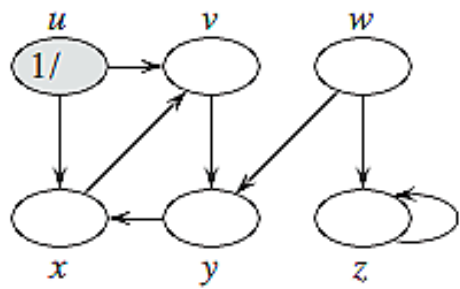
Note similarities with the lifecycle of a vertex in BFS

Example with timestamps

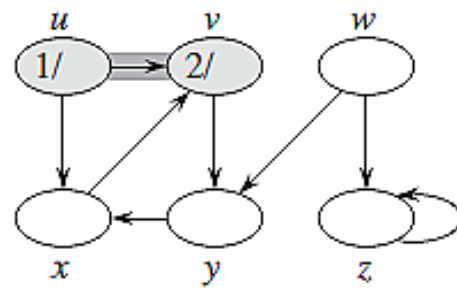


each vertex gets a “**visiting**” **timestamp** when first visited

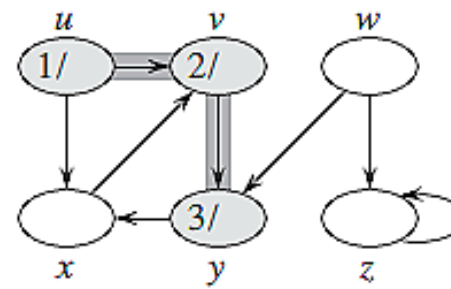
each vertex gets a “**done visiting**” **timestamp** when finished



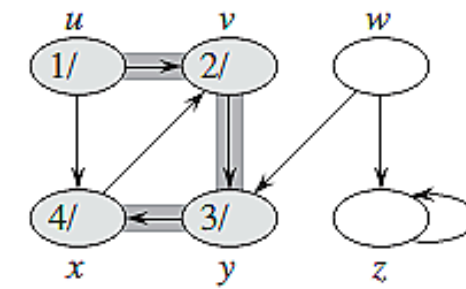
(a)



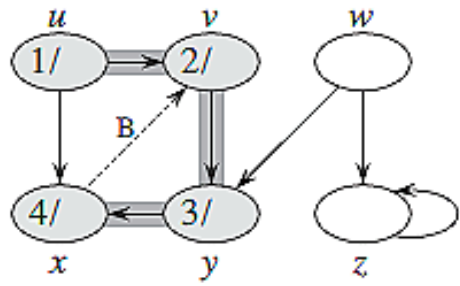
(b)



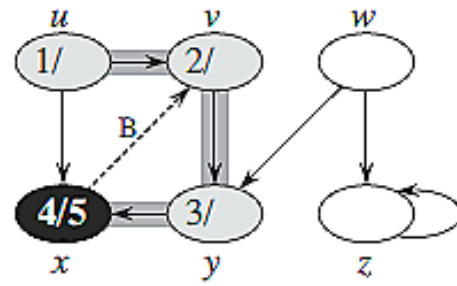
(c)



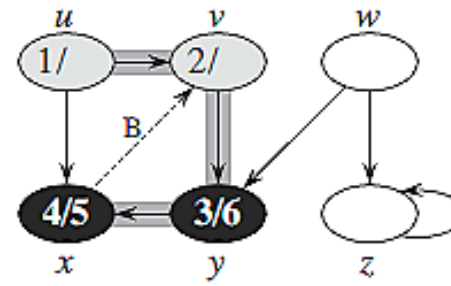
(d)



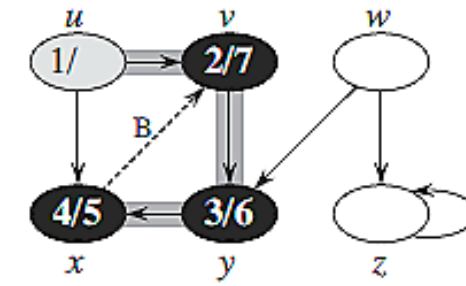
(e)



(f)



(g)



(h)

```

Set visited = new Set();
dfs(v) {
    visited.add(v)
    // do stuff on v
    for every neighbor w of v
        if (!visited.contains(w))
            dfs(w)
}

```

how would you
modify dfs() to print
timestamps...?

and ensure that
every vertex gets a
timestamp?

DFS for visit timestamp

```
Set visited = new Set();
```

```
time = 1
```

```
dfs(v) {
```

```
    visited.add(v)
```

```
    print("visiting v: " + time); time++
```

```
    for every neighbor w of v
```

```
        if (!visited.contains(w))
```

```
            dfs(w)
```

```
    print("done visiting v: " + time); time++
```

```
}
```

To ensure all vertices are visited
(and get a timestamp)

```
Set visited = new Set();
```

```
time = 1
```

```
dfs(v) {
```

```
    visited.add(v)
```

```
    print("visiting v: " + time); time++
```

```
    for every neighbor w of v
```

```
        if (!visited.contains(w))
```

```
            dfs(w)
```

```
    print("done visiting v: " + time); time++
```

```
}
```

for each vertex v

if (!visited.contains(v))

dfs(v)

Time complexity of DFS

```
Set visited = new Set();
```

```
dfs(v) {
```

```
    visited.add(v)
```

```
    // do stuff on v
```

```
    for every neighbor w of v
```

```
        if (!visited.contains(w))
```

```
            dfs(w)
```

```
}
```

each vertex is input of
at most 1 recursive call

each edge is explored
at most once overall

as long as “do stuff” is $O(1)$
DFS is $O(V + E)$

Time complexity of DFS

```
Set visited = new Set();
```

```
dfs(v) {
```

each vertex is input of
at most 1 recursive call

Note similarities with
BFS/Dijkstra analysis
despite DFS being a
recursive algorithm

```
    visited.add(v);  
    //do stuff on v  
    for every neighbor w of v
```

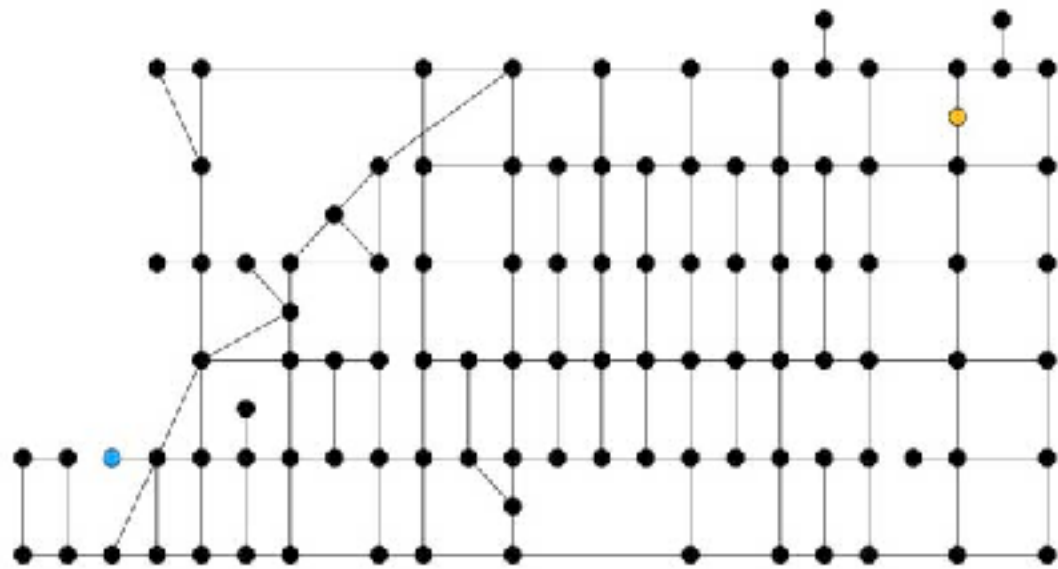
each edge is explored
at most once overall

```
        if (!visited.contains(w))
```

```
            dfs(w)
```

```
}
```

as long as “do stuff” is $O(1)$
DFS is $O(V + E)$

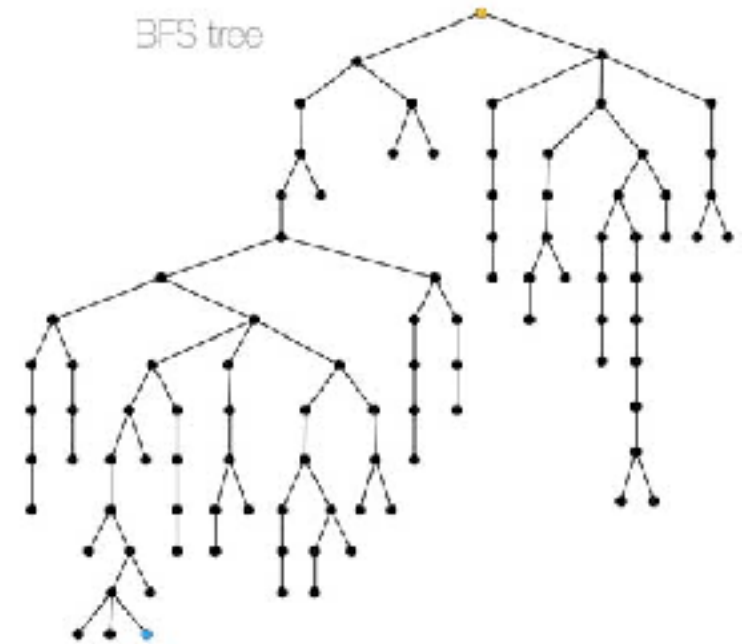


a graph to traverse

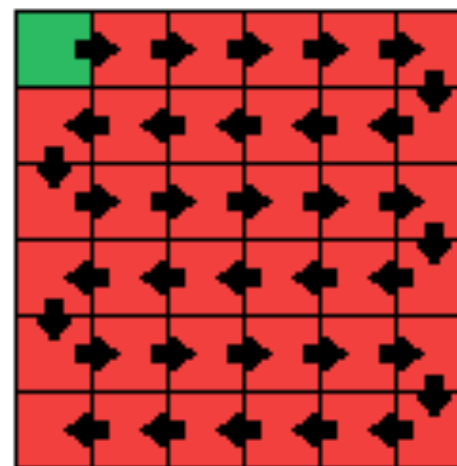
DFS tree



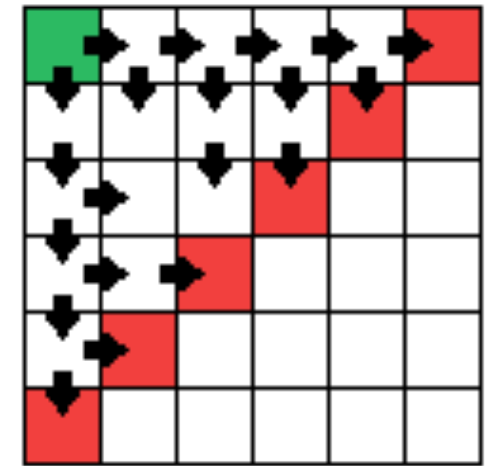
BFS tree



DFS



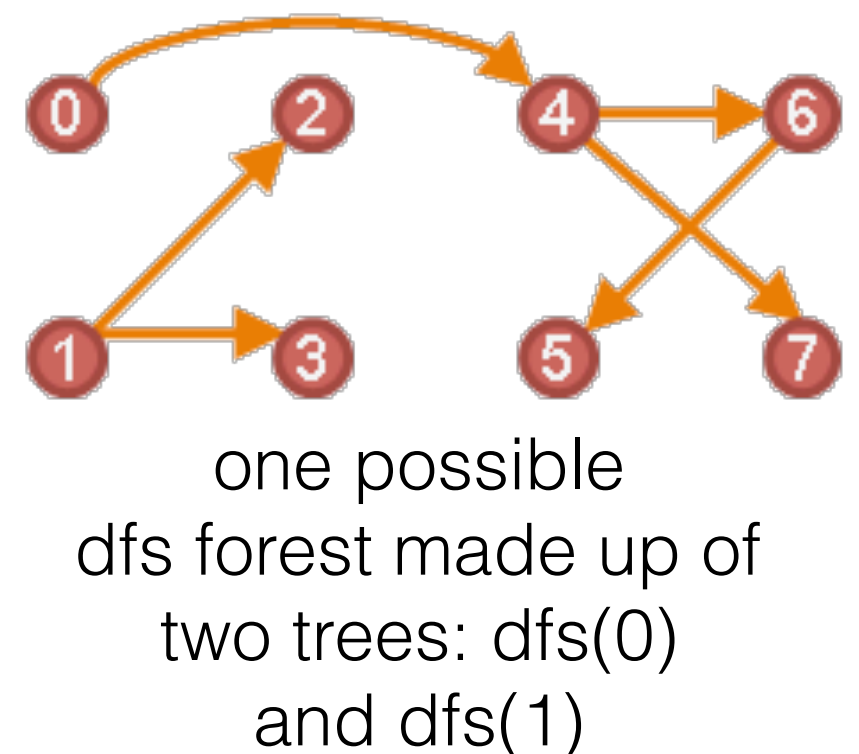
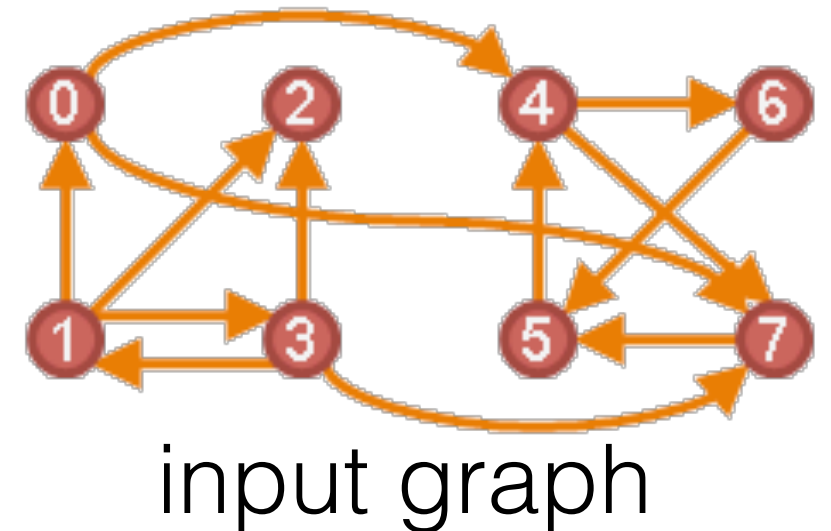
BFS

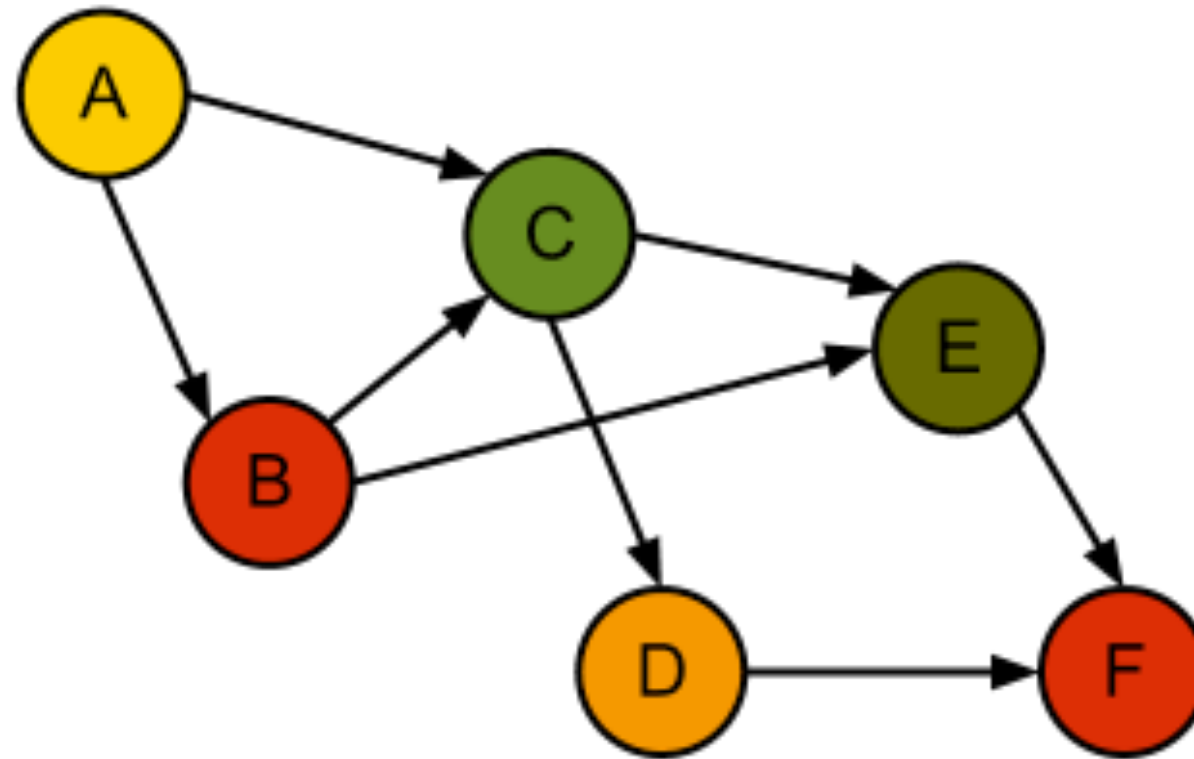


DFS forest

```
Set visited = new Set();  
for each vertex v  
    if (!visited.contains(v))  
        dfs(v) ← one DFS tree
```

```
dfs(v) {  
    visited.add(v)  
    for every neighbor w of v  
        if (!visited.contains(w))  
            dfs(w) ←  $v \rightarrow w$  is a tree edge  
                        = edge of DFS tree  
}
```

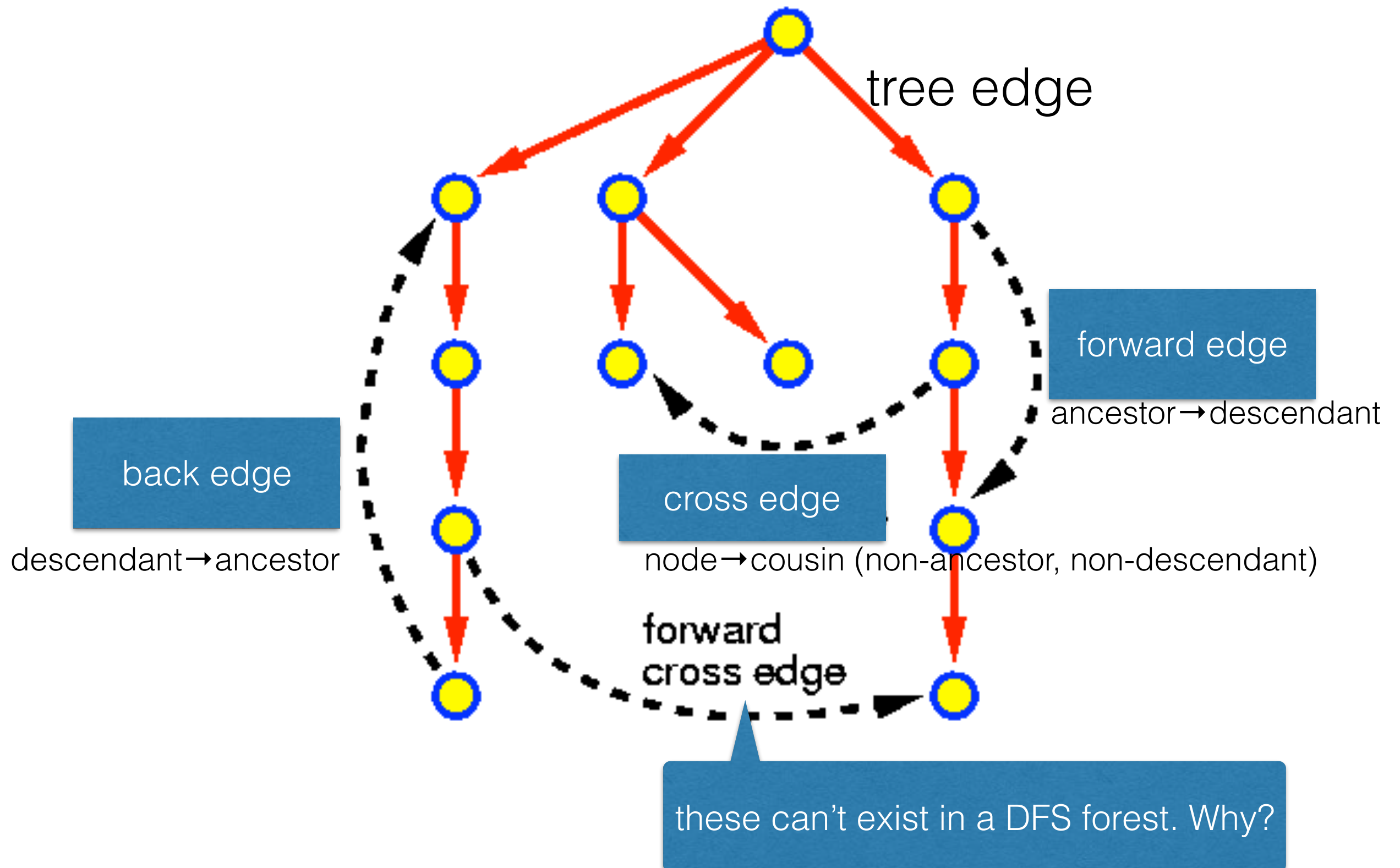




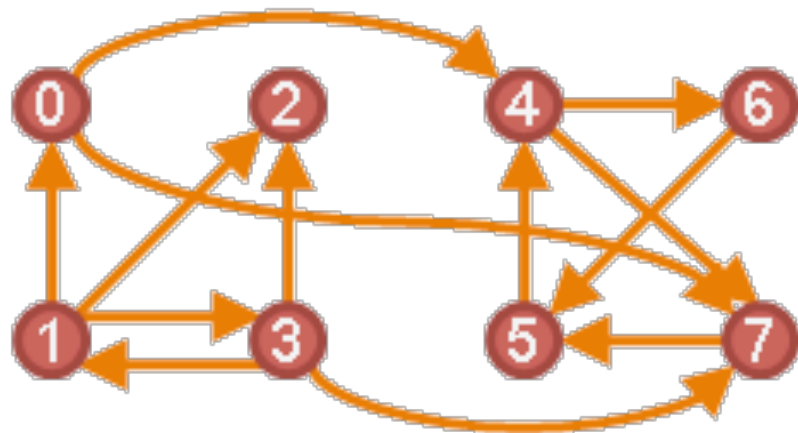
Find a DFS traversal that produces a forest with 1 tree.

Find a DFS traversal that produces a forest with 3 trees.

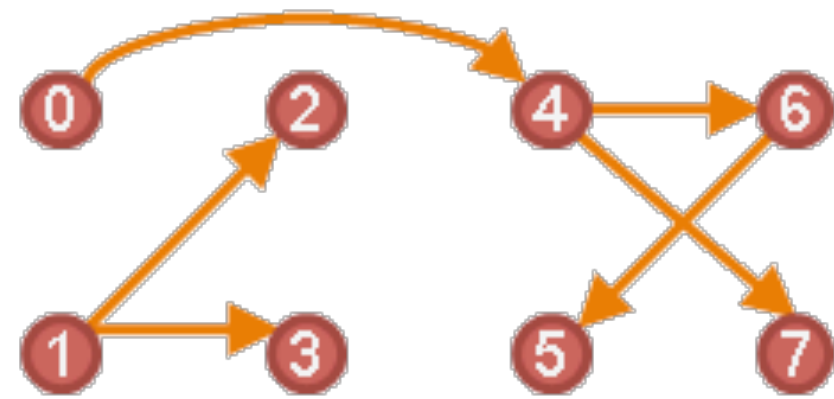
Edge classification



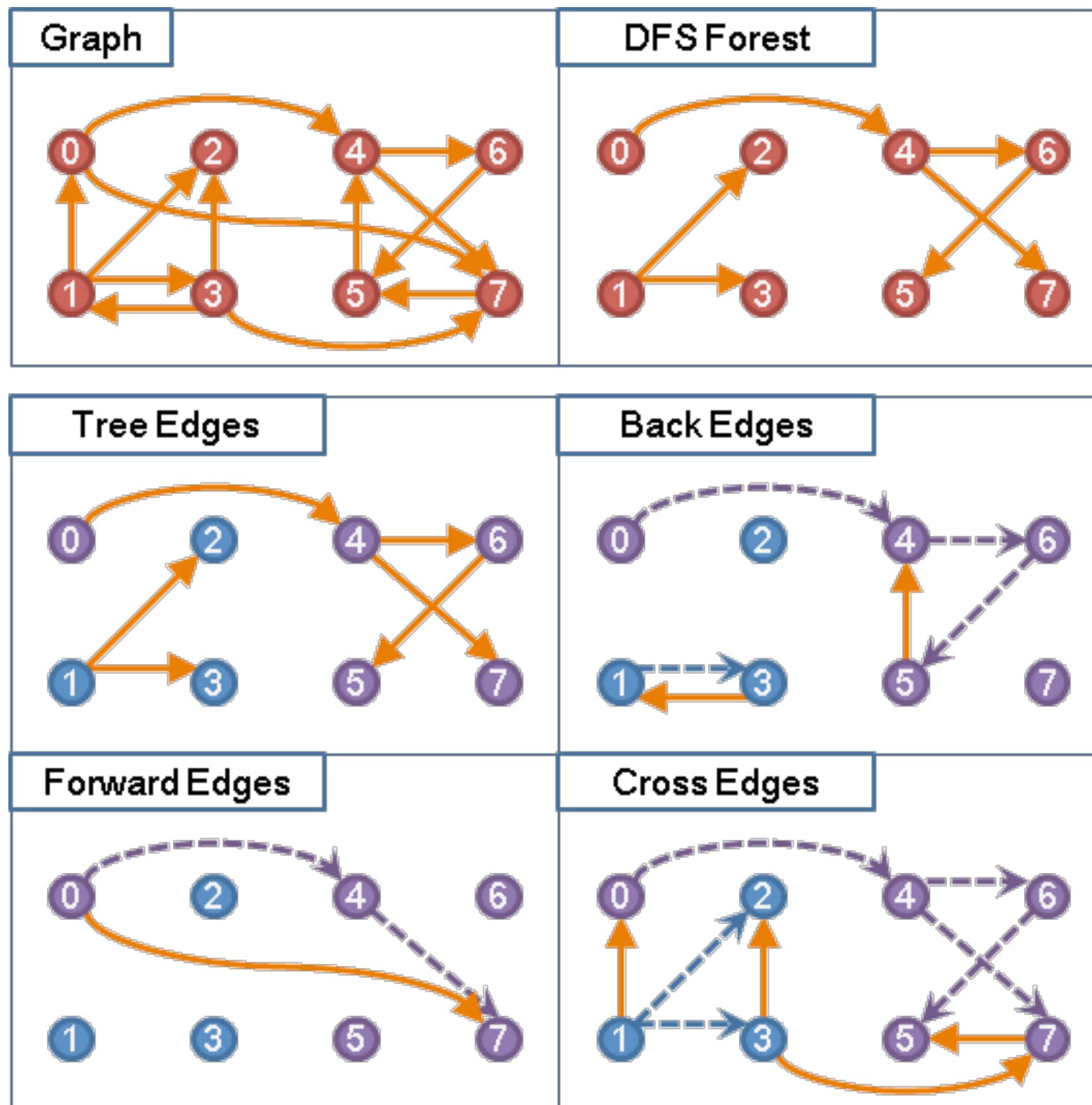
Can you classify all the other edges?



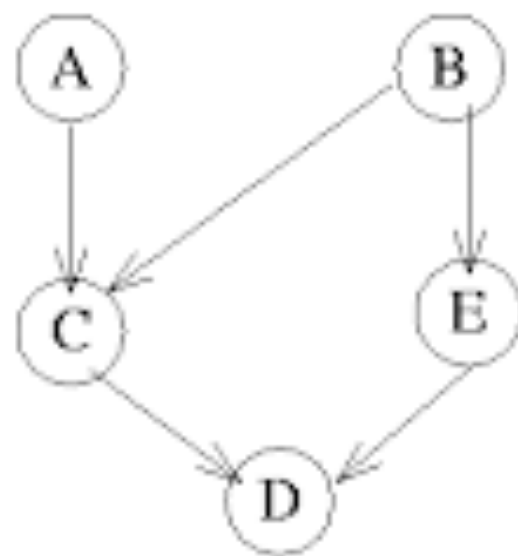
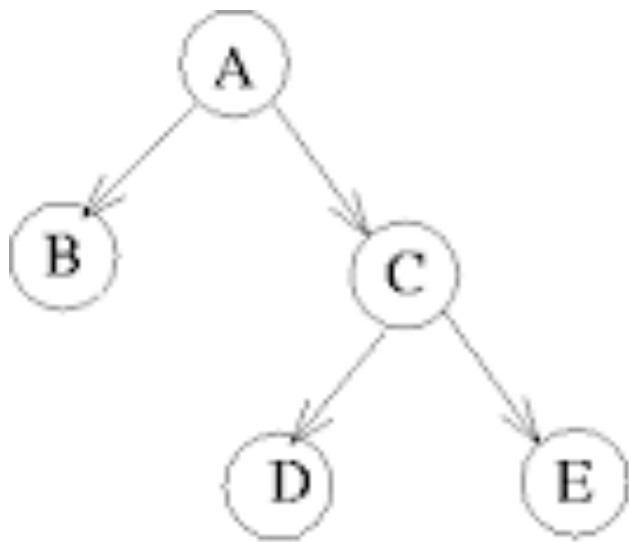
input graph



dfs forest made up of
tree edges

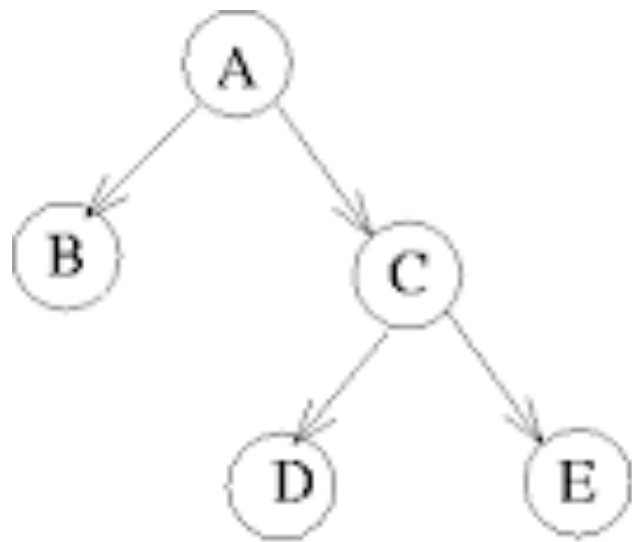


What does it mean for a **directed graph** to be connected?

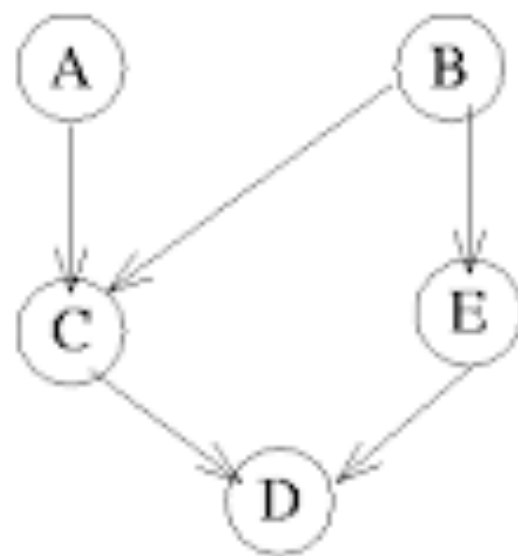


Which of these graphs would you consider to be “connected”? Why?

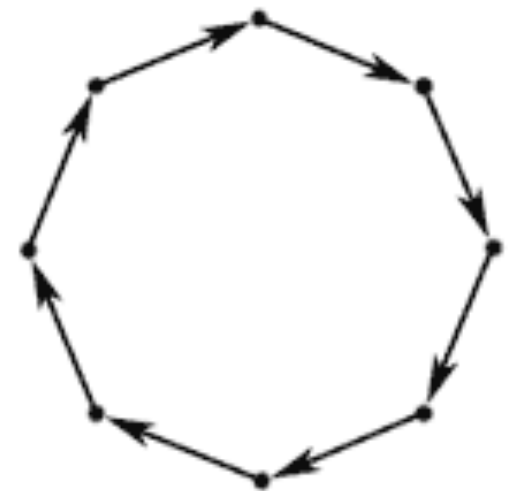
V can **reach** W if there is a directed path connecting V to W



A can reach every other vertex



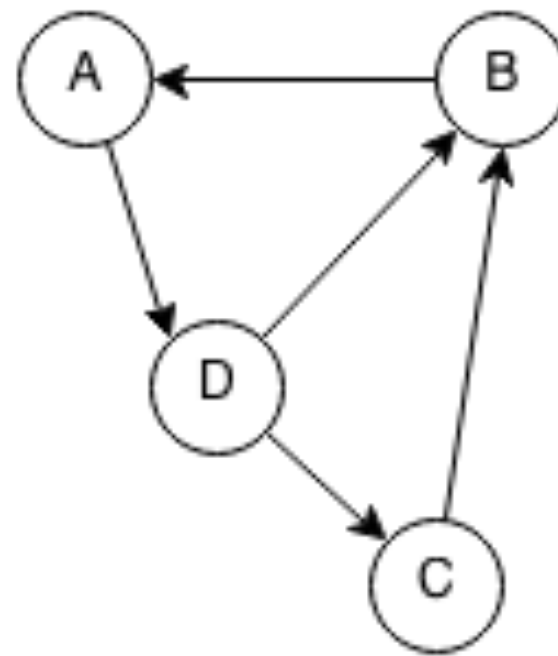
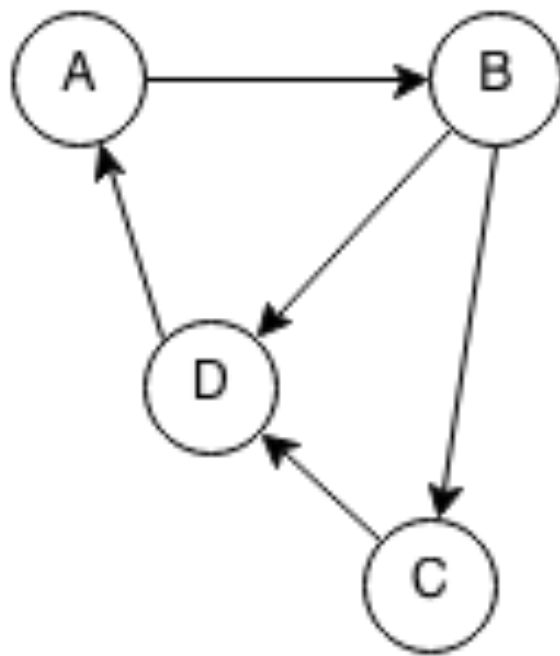
B can reach every other vertex except A



every vertex can reach every other vertex

A directed graph is said to be **strongly connected** if ...

every vertex in the graph is reachable from every other vertex in the graph



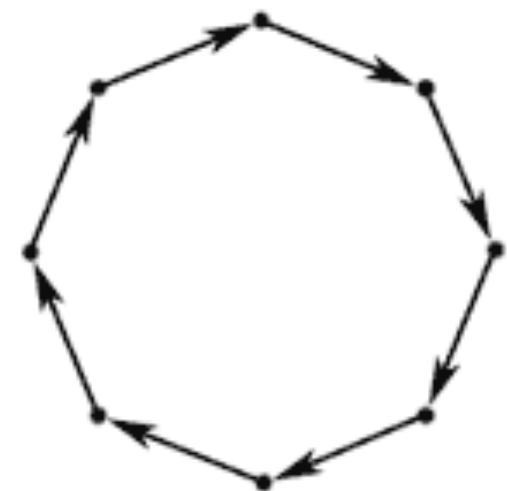
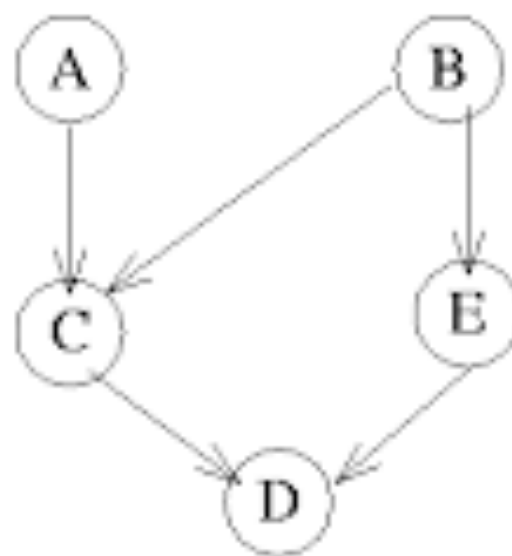
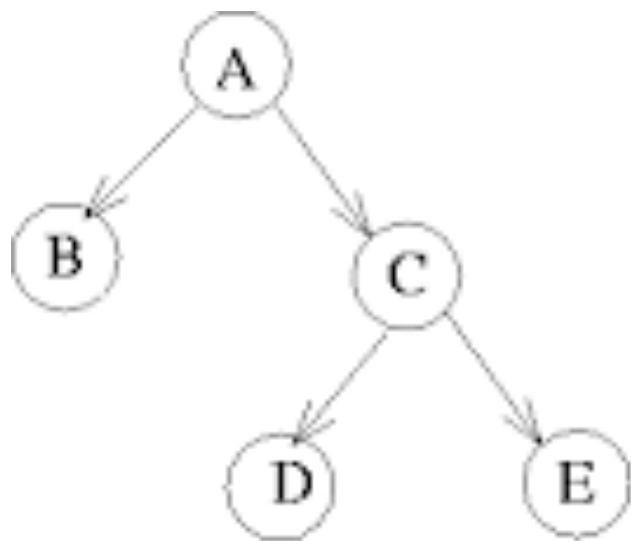
which is strongly connected?

Every directed graph can be decomposed
into a set of **strongly connected
components (SCCs)**

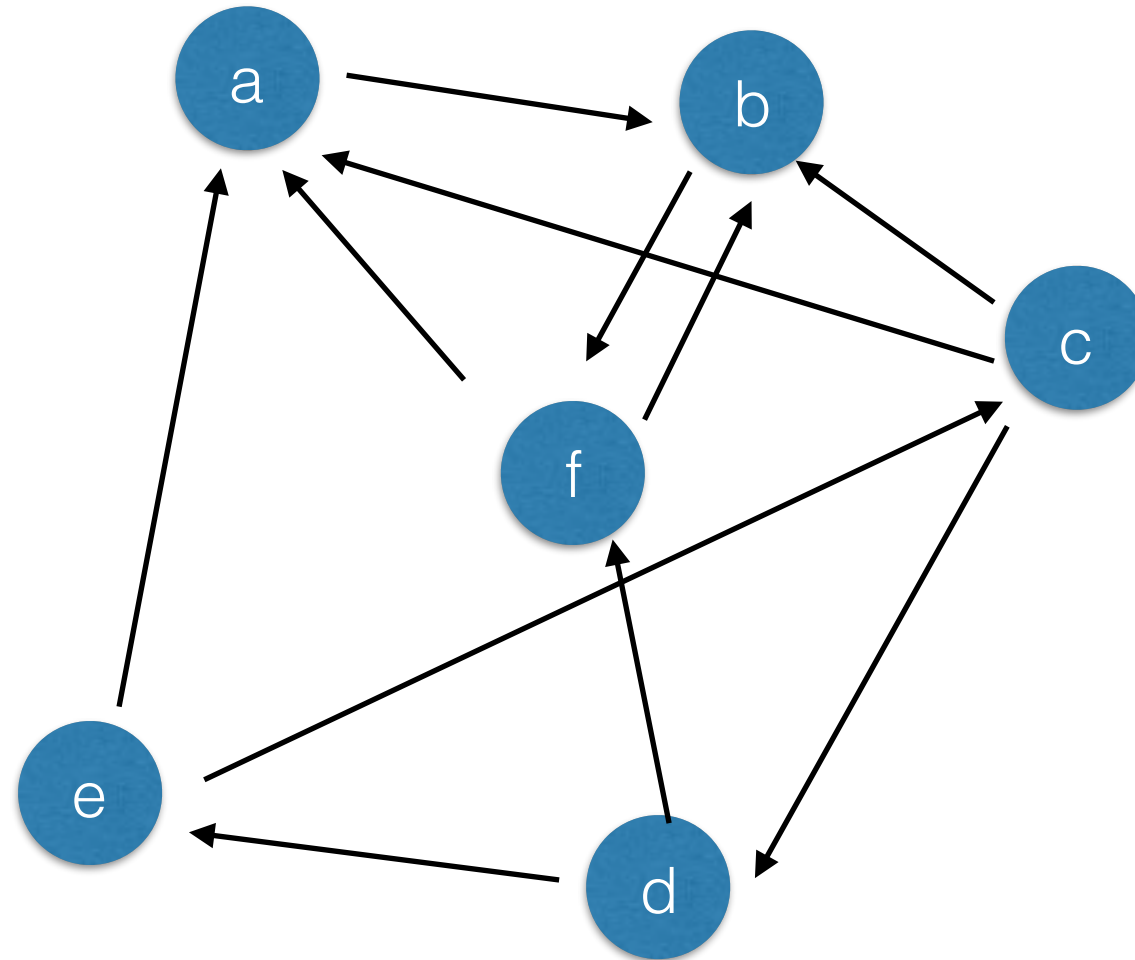
A strongly connected component is a (largest possible)
set of vertices that are mutually reachable.

Every vertex is reachable from itself.

Find the strongly connected components of each of these graphs



Find the strongly connected components of this graph



What is an algorithm for finding
all the strongly connected components
of a directed graph?

```

Stack<Vertex> stack = new Stack();
Map<Vertex, Integer> index = new Map();
Map<Vertex, Integer> lowlink = new Map();
int nextIndex = 0;
for each vertex v
    if (!index.containsKey(v))
        scc(v)

scc(v) {
    // init v
    for every neighbor w of v {
        if (!index.containsKey(w)) { // tree edge
            scc(w)
            lowlink.put(v, min(lowlink.get(v), lowlink.get(w)))
        } else if (w on stack) { // non-tree edge
            lowlink.put(v, min(lowlink.get(v), index.get(w)))
        }
    }
}

// pop current scc of v if done
}

```

```

Set visited = new Set();
for each vertex v
    if (!visited.contains(v))
        dfs(v)

dfs(v) {
    visited.add(v)
    for every neighbor w of v
        if (!visited.contains(w))
            dfs(w)
}

```

DFS

Tarjan's algorithm

```

Stack<Vertex> stack = new Stack();
Map<Vertex, Integer> index = new Map();
Map<Vertex, Integer> lowlink = new Map();
int nextIndex = 0;
for each vertex v
    if (!index.containsKey(v))
        scc(v)

scc(v) {
    // init v
    for every neighbor w of v {
        if (!index.containsKey(w)) { // tree edge
            scc(w)
            lowlink.put(v, min(lowlink.get(v), lowlink.get(w)))
        } else if (w on stack) { // non-tree edge
            lowlink.put(v, min(lowlink.get(v), index.get(w)))
        }
    }
    // pop current scc of v if done
}

```

```

stack.push(v);
index.put(v, nextIndex);
lowlink.put(v, nextIndex);
nextIndex++;

```

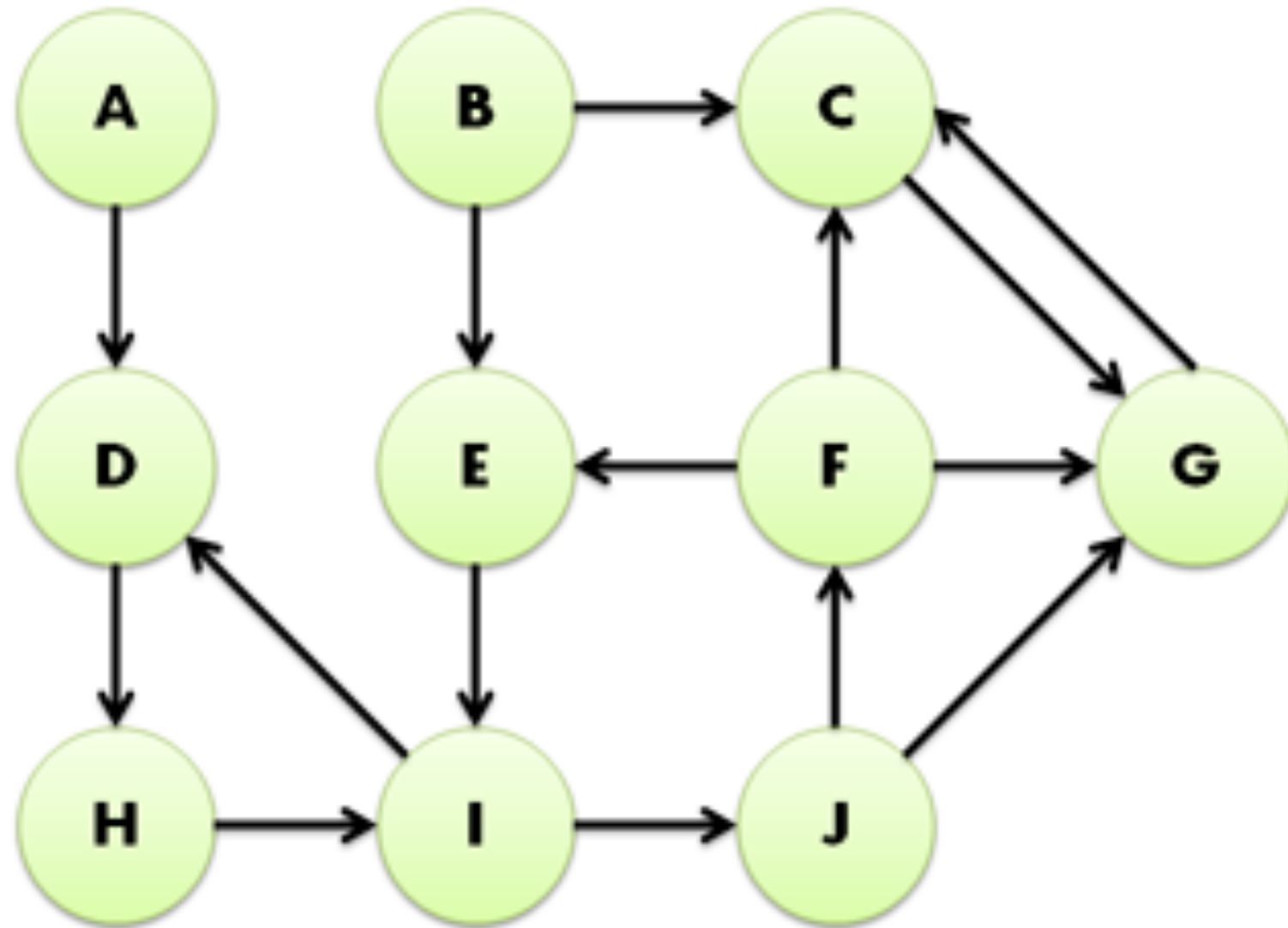
```

if (index.get(v) == lowlink.get(v)) {
    List<Vertex> component = new List();
    while (stack.peek() != v)
        component.add(stack.pop());
    component.add(stack.pop());
    print component;
}

```

Tarjan's algorithm

Tarjan's algorithm: example



```

Stack<Vertex> stack = new Stack();
Map<Vertex, Integer> index = new Map();
Map<Vertex, Integer> lowlink = new Map();
int nextIndex = 0;
for each vertex v
    if (!index.containsKey(v))
        dfs(v)

scc(v) {
    // init v
    for every neighbor w of v {
        if (!index.containsKey(w)) { // tree edge
            scc(w)
            lowlink.put(v, min(lowlink.get(v), lowlink.get(w)))
        } else if (w on stack) { // non-tree edge
            lowlink.put(v, min(lowlink.get(v), index.get(w)))
        }
    }
    // pop current scc of v if done
}

```

stack invariant:

a vertex stays on stack after it is visited if it has an edge to a vertex earlier on stack (and visited earlier)

```

stack.push(v);
index.put(v, nextIndex);
lowlink.put(v, nextIndex);
nextIndex++;

```

```

if (index.get(v) == lowlink.get(v)) {
    List<Vertex> component = new List();
    while (stack.peek() != v)
        component.add(stack.pop());
    component.add(stack.pop());
    print component;
}

```

Tarjan's algorithm

```

Stack<Vertex> stack = new Stack();
Map<Vertex, Integer> index = new Map();
Map<Vertex, Integer> lowlink = new Map();
int nextIndex = 0;
for each vertex v
    if (!index.containsKey(v))
        dfs(v)

scc(v) {
    // init v
    for every neighbor w of v {
        if (!index.containsKey(w)) { // tree edge
            scc(w)
            lowlink.put(v, min(lowlink.get(v), lowlink.get(w)))
        } else if (w on stack) { // non-tree edge
            lowlink.put(v, min(lowlink.get(v), lowlink.get(w)))
        }
    }
    // pop current scc of v if done
}

```

time complexity:

DFS with additional bookkeeping
problem: "w on stack" not constant

```

stack.push(v);
index.put(v, nextIndex);
lowlink.put(v, nextIndex);
nextIndex++;

```

```

if (index.get(v) == lowlink.get(v)) {
    List<Vertex> component = new List();
    while (stack.peek() != v)
        component.add(stack.pop());
    component.add(stack.pop());
    print component;
}

```

Tarjan's algorithm


```

Stack<Vertex> stack = new Stack();
Set<Vertex> onStack = new Map();
Map<Vertex, Integer> index = new Map();
Map<Vertex, Integer> lowlink = new Map();
int nextIndex = 0;
for each vertex v
    if (!index.containsKey(v))
        dfs(v)

scc(v) {
    // init v
    for every neighbor w of v {
        if (!index.containsKey(w)) { // tree edge
            scc(w)
            lowlink.put(v, min(lowlink.get(v), lowlink.get(w)))
        } else if (onStack.contains(w)) { // non-tree edge
            lowlink.put(v, min(lowlink.get(v), lowlink.get(w)))
        }
    }
    // pop current scc of v if done
}

Tarjan's algorithm

```

time complexity:
fix: use **set** to track what's on the stack
DFS with $O(1)$ bookkeeping is **$O(V+E)$**

```

stack.push(v); onStack.add(v);
index.put(v, nextIndex);
lowlink.put(v, nextIndex);
nextIndex++;

```

```

if (index.get(v) == lowlink.get(v)) {
    List<Vertex> component = new List();
    while (stack.peek() != v) {
        onStack.remove(stack.peek());
        component.add(stack.pop());
    }
    onStack.remove(stack.peek());
    component.add(stack.pop());
    print component;
}

```