

Formal Verification for A Buddy Allocation Model Specification ^{*}

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Abstract. Buddy allocation algorithms are widely adopted by memory management systems to manage the address space accessed by applications. However, errors in any stage of the development process of the memory management component, from the specification to the implementation, may lead to critical issues in other components using it. We apply formal methods to ensure the absence of any misbehavior. Rigorous mathematical proofs provide strong assurance to the development process. In this paper, we firstly present a specification for the buddy allocation algorithm. And thence we validate enough properties to guarantee functional correctness of this algorithm. Finally, we construct execution traces to verify the integrity for security. Through these efforts, we propose a buddy allocation model that provides both functional correctness and security. Also, we use interactive theorem prover Isabelle/HOL to carry out the verification work.

Keywords: Memory Specification · Formal Verification · Functional Correctness · Security.

1 Introduction

In the past several decades, buddy allocation algorithms have been applied in the memory management systems. Errors in any stage of the development process of the memory management component may lead to critical issues in other components who invoke it. To improve confidence on the reliability of the development process, verification of functional correctness and security properties is applied into each stage, from the specification level to the implementation level, even the machine code level. Formal methods have been successfully applied in the verification of many critical systems due to these methods provide strong assurance by rigorous mathematical proofs. Therefore, we apply formal methods

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to ensure the absence of any misbehavior during the development process of the buddy allocation model.

here is related work.

In this paper, we propose a buddy allocation model, which supports both functional correctness and security. To achieve this goal, we develop a specification for buddy allocation algorithms by functional programming in Isabelle/HOL proof assistant. Our specification must consists of algorithm details as specific as possible for the sake of capturing any feature in the algorithms. Then we design a series of properties for functional correctness of the algorithm. After that, we apply theorem-proving method to prove these properties. To verify integrity for security, we construct execution traces based on event, and then prove that the operation of one domain on memory does not affect any other domains. So far, we have completed the construction and verification of the buddy allocation algorithm.

The following section briefly introduces the Isabelle/HOL verification environment. The next section is about the formalization of buddy allocation model including representation of our specification and proofs to properties for functional correctness. The verification of integrity for security is arranged in the following section. The last section is about the conclusions and future work.

2 Isabelle/HOL Verification Environment

Our specification and verification work is based on the interactive theorem prover Isabelle/HOL. HOL represents the Higher-Order Logical and Isabelle is its generic interactive theorem prover. In Isabelle/HOL, it is usual to employ functional programming method to define a function and to adopt theorem proving technique to reason a lemma or a theorem. For a gentle introduction to Isabelle/HOL see [1].

Apart from commonly used types like *bool* and *nat*, Isabelle offers notion *datatype* to create a distinguished element to some existing types. Projection functions *fst* and *snd* comes with the tuple $(t_1 \times t_2)$. Notions *list* and *set* are used as constructors to create a collection of same type. Operation 'cons' denoted by '#' on a list means that adding an element to the head of list. The *i*th component of a list *xs* is written as *xs*!*i*. *SOME* *x* and *THE* *x* in the *set* *A* represent choosing an element arbitrarily, existing and unique element respectively. Furthermore, λ -abstractions are also contained in terms like $\lambda(x, y). f\ x\ y$.

Non-recursive definition can be made with the **definition** command and the **primrec** function definition is used for primitive recursions. The notation $[A_1; \dots; A_n] \implies A$ represents an implication with assumptions $A_1; \dots; A_n$ and conclusion *A*. Isabelle mainly employs backward deduction, which means to prove the main goal, we must firstly prove subgoals which are decomposed from the main goal. It uses the rules of the reasoning like introduction, elimination, destruction rules, etc., as well as automatic provers such as *SMT*.

3 Formalization of Buddy Allocation Model

The formalization of buddy allocation models consists of a specification for algorithms and proofs to properties for functional correctness. The challenge is that we apply quartering from Zephyr OS for buddy allocation operations, which brings complexity to proofs.

3.1 Memory Model Specification

The specification begins with the structure of a quad-tree.

$$\begin{aligned}
 (set : 'a) \text{ tree} = & Leaf (L : 'a) \mid \\
 & Node (LL : 'a \text{ tree}) (LR : 'a \text{ tree}) (RL : 'a \text{ tree}) (RR : 'a \text{ tree}) \\
 & \text{for } map : \text{tree_map}
 \end{aligned}$$

The quad-tree constructed by induction contains two pieces of information: the memory block type (indicated as *ALLOC* and *FREE* respectively); a address tag occupied by a memory block (indicated as *ID*). The mapping function **tree.set** assists to collect the leaves from a tree. With the help of the block **type** and the function **get_level** in a quad-tree, allocated leaves or free leaves from different levels can be gathered by **allocsets**, **freesets** and **freesets_level**. To create a new leaf, we have to pick up a new *ID* to this new leaf by the strategy of *SOME* $p. p \notin idset$. Later, we will prove that with this strategy, all leaves have different *IDs*.

Based on the above quad-tree structure, next we specify two operations with the buddy algorithms: **alloc** and **free**. For *rsize* (the size of requested memory block) in allocation operation, there is a definition that maps it to the level of the quad-tree and gives the most suitable level *rlv*. The concept of *most suitable level* will be proved in the next subsection. For the specification, we only use level for both the memory blocks of the quad-tree and requested memory block. And the smaller the level, the larger size the memory block.

Definition 1. *exists_freelevel*

exists_freelevel blo_set lv $\equiv \exists l. l \leq lv \wedge \exists b \in blo_set. \text{freesets_level } b \ l \neq \emptyset$

Definition 2. *freesets_maxlevel*

freesets_maxlevel blo_set lv \equiv

THE lmax. lmax $\leq lv \wedge$

$\exists b \in blo_set. \text{freesets_level } b \ lmax \neq \emptyset \wedge$

$\forall l \leq lv. \exists b \in blo_set. \text{freesets_level } b \ l \neq \emptyset \longrightarrow l \leq lmax$

Definition 3. *Allocation Operation*

alloc blo_set rlv \equiv

if exists_freelevel blo_set rlv then

lmax = freesets_maxlevel blo_set rlv

if lmax = rlv then

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    btree = SOME b. b ∈ blo_set ∧ freesets_level b rlv ≠ ∅
    l = SOME l. l ∈ freesets_level btree rlv
else
    btree = SOME b. b ∈ blo_set ∧ freesets_level b lmax ≠ ∅
    l = split (SOME l. l ∈ freesets_level btree lmax) (rlv - lmax)
else False

```

The first step of allocation is to check whether there is a quad-tree in *blo_set* (the memory pool tree collection), that has such free memory blocks whose level is less than or equal to *rlv*. This step is done by **exists.freelevel**, and if it returns *False* then the allocation progress stops. Otherwise, the next step conducted by **freesets.maxlevel** is to return the maximum level among all levels with free memory blocks. If the maximum level is equal to *rlv*, then any free memory block in *rlv* is to be allocated. If not, any free memory block in the maximum level is to be conducted by **split** showed in Fig. 1 until free memory block in *rlv* appears and then be allocated. The type of the assigned leaf is set to *ALLOC*.

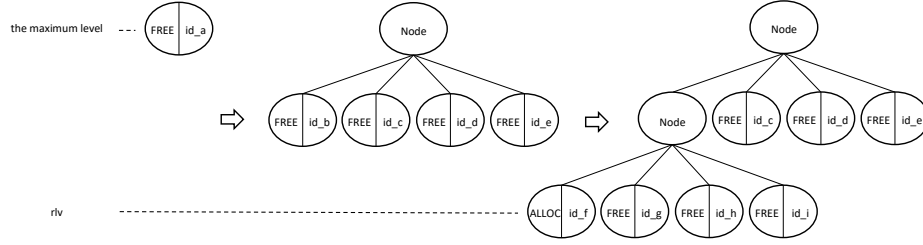


Fig. 1. The progress of dividing a free memory block

Definition 4. *Deallocation Operation*

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free blo_set b ≡
  if ∃ btree ∈ blo_set. b ∈ tree.set btree then
    if type b = FREE then False
    else btree = THE t. t ∈ blo_set ∧ b ∈ tree.set t
      merge (reset btree b FREE)
  else False

```

The deallocation progress firstly checks whether there is a quad-tree in *blo_set* that the occupied memory block to be released belongs to this tree. If there is no such tree, the procedure returns *False*. Next, if the type of the occupied memory block is *FREE*, the progress also returns *False*. When all conditions are met, the memory block is returned to the tree it belongs to, thereafter merging operation is executed. The merging operation is to combine all free memory blocks that belong to the same parent tree showed in Fig. 2.

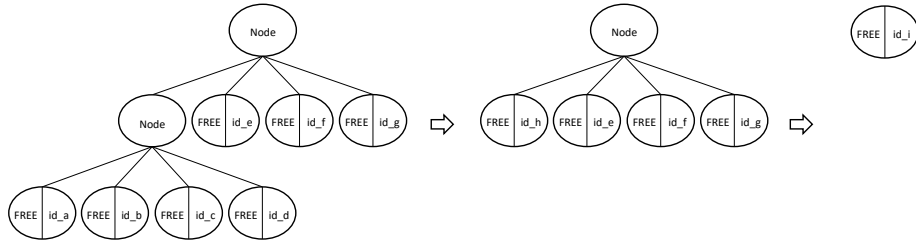


Fig. 2. The progress of merging all free memory blocks

At this point, we have done the specification for the buddy memory algorithm. Next, we are going to verify some properties to guarantee the functional correctness of this specification.

3.2 Memory Model Properties

Once the specification is finished, the preconditions & postconditions for functions as well as the invariants are to be raised up to ensure the functional correctness of the specification. We try to answer these questions: Does the algorithm pick out the most suitable block from all the available blocks? Does the algorithm correctly adjust the type of the relevant memory block after allocation and deallocation? How does the algorithm make sure to execute the merging operation after deallocation? How does the specification ensure the correctness of the quad-tree structure? What invariants does the specification preserve? Does the algorithm satisfy some security properties? Answering these questions contributes to the construction of a reliability system. We give preconditions and postconditions in the first place.

Definition 5. *Allocation Failure*

$$\neg \text{exists_freelevel } \text{blo_set } \text{rlv} \longrightarrow \text{fst } (\text{alloc } \text{blo_set } \text{rlv}) = \text{blo_set}$$

Definition 6. *Freesets for Direct Allocation*

$$\begin{aligned} &\text{exists_freelevel } \text{blo_set } \text{rlv} \wedge \text{freesets_maxlevel } \text{blo_set } \text{rlv} = \text{rlv} \longrightarrow \\ &\quad \exists l. l \in \text{freesets } \text{blo_set} \wedge l \notin \text{freesets } \text{fst } (\text{alloc } \text{blo_set } \text{rlv}) \wedge \\ &\quad \text{freesets } \text{blo_set} = \text{freesets } \text{fst } (\text{alloc } \text{blo_set } \text{rlv}) \cup \{l\} \end{aligned}$$

Definition 7. *Allocsets for Direct Allocation*

$$\begin{aligned} &\text{exists_freelevel } \text{blo_set } \text{rlv} \wedge \text{freesets_maxlevel } \text{blo_set } \text{rlv} = \text{rlv} \longrightarrow \\ &\quad \exists l. l \notin \text{allocsets } \text{blo_set} \wedge l \in \text{allocsets } \text{fst } (\text{alloc } \text{blo_set } \text{rlv}) \wedge \\ &\quad \text{allocsets } \text{fst } (\text{alloc } \text{blo_set } \text{rlv}) = \text{allocsets } \text{blo_set} \cup \{l\} \end{aligned}$$

Definition 8. *Allocsets for Indirect Allocation*

$$\begin{aligned} &\text{exists_freelevel } \text{blo_set } \text{rlv} \wedge \text{freesets_maxlevel } \text{blo_set } \text{rlv} \neq \text{rlv} \longrightarrow \\ &\quad \exists l. l \notin \text{allocsets } \text{blo_set} \wedge l \in \text{allocsets } \text{fst } (\text{alloc } \text{blo_set } \text{rlv}) \wedge \\ &\quad \text{allocsets } \text{fst } (\text{alloc } \text{blo_set } \text{rlv}) = \text{allocsets } \text{blo_set} \cup \{l\} \end{aligned}$$

Definition 9. *Deallocation failure 1*

$$\nexists btree \in blo_set. b \in tree.set \ btree \longrightarrow fst \ (free \ blo_set \ b) = blo_set$$
Definition 10. *Deallocation failure 2*

$$\exists btree \in blo_set. b \in tree.set \ btree \wedge type \ b = FREE \longrightarrow$$

$$fst \ (free \ blo_set \ b) = blo_set$$
Definition 11. *Allocsets for Deallocation Success*

$$\exists btree \in blo_set. b \in tree.set \ btree \wedge type \ b \neq FREE \longrightarrow$$

$$allocsets \ blo_set = allocsets \ fst \ (free \ blo_set \ b) \cup \{b\}$$

Theorem 1. *The buddy allocation specification satisfies all the preconditions and postconditions above.*

Proof. Apply preconditions into the definitions of allocation and deallocation, then the certain result of executions can be calculated according to the branches in the functions. The variables that change can be traced through block type changes.

To guarantee that the algorithm picks out the most suitable block, two properties have to be proved: 1. the correctness of the mapping from the request memory block size to the level of the quad-tree. 2. the correctness of the quad-tree hierarchical structure. Next are these two properties.

Definition 12. *Mapping Request Sizes & Allocation Levels*

$$output_level \ blo_list \ rsize \equiv THE \ l. \ l < L \ blo_list \wedge rsize \leq blo_list \ ! \ l \wedge$$

$$(L \ blo_list > 1 \wedge l < L \ blo_list - 1) \longrightarrow rsize > L \ blo_list \ ! \ (l+1)$$

Static linked list *blo_list* is used to store the size of block for each level in a quad-tree. And *blo_list* is a strictly decreasing list. Function *L* is used to get the length of a list. As mentioned above, the smaller the level, the larger size the memory block. The most suitable block means that its size has to be greater than or equal to the size of request block, and there is no smaller block that meets this condition. Through this definition, the most suitable block is picked up from *blo_list*, and then mapped to the correct level of the quad-tree. Some lemmas ensure the correctness of this definition.

Lemma 1. $L \ blo_list > 0 \wedge rsize \leq blo_list \ ! \ (L \ blo_list - 1) \longrightarrow output_level \ blo_list \ rsize = L \ blo_list - 1$

Lemma 2. $L \ blo_list > 1 \wedge l < L \ blo_list - 1 \wedge rsize \leq blo_list \ ! \ l \wedge rsize > blo_list \ ! \ (l + 1) \longrightarrow output_level \ blo_list \ rsize = l$

Proof. To prove these two lemmas, the existence of such a level should be prove firstly by the predicates of *rsize*. Then with the assistance of the strictly decreasing *blo_list*, the exact level can be located.

Next, we introduce a lemma alone to prove the correctness of a quad-tree structure from the aspect of its level. The **root** checks whether the tree is a root tree and **child** gives us all immediate child nodes.

Lemma 3. $(\text{root } btree \longrightarrow \text{get_level } btree = 0) \wedge (\text{get_level } btree = l \wedge l \geq 0 \wedge \text{chtree} \in \text{child } btree \longrightarrow \text{get_level } chtree = l + 1)$

Proof. Induction can prove this because of the recursive structure of the quad-tree.

With the correctness of the mapping operation and the hierarchical structure of a quad-tree, we have the following theorem.

Theorem 2. *The buddy allocation specification picks out the most suitable memory block and operates on the correct level in a quad-tree.*

To avoid the fragmentation, merging operation is asked in the progress of deallocation. The following property is put forward to ensure the merging operation being correctly executed. The **leaf** is to check whether the tree is a leaf.

Definition 13. *Four Free Leaves Belong to The Same Node*
 $\text{is_FFL } btree \equiv \forall \text{chtree} \in \text{child } btree. \text{leaf } chtree \wedge \text{type } chtree = \text{FREE}$

Fig. 2 can explain this definition well. Just like the subtree in the lower left corner of the first picture, four child nodes are all leaves and their types are *FREE*. Therefore, merging operation is necessary during the progress of deallocation to handle this situation. The following are the lemmas that ensure the non-existence of such *FFL* trees after allocation and deallocation operations if non-existence of such trees in preconditions.

Lemma 4. $\forall b \in \text{blo_set}. \neg \text{is_FFL } b \longrightarrow \forall b \in \text{fst } (\text{alloc } \text{blo_set } \text{rlv}). \neg \text{is_FFL } b$

Lemma 5. $\forall b \in \text{blo_set}. \neg \text{is_FFL } b \longrightarrow \forall b \in \text{fst } (\text{free } \text{blo_set } b). \neg \text{is_FFL } b$

Proof. Due to the operations being conducted on the recursive structure of the quad-tree, induction can solve the proofs with the assistants of the execution branches.

Theorem 3. *The buddy allocation specification guarantees non-existence of the FFL trees among all quad-trees.*

In the end, we prove two significant properties: memory isolation and non-leakage. The first one is to prove non-existence of the overlap in the address spaces. Isolation in address spaces makes sure domains' memory blocks are not maliciously overwritten. Memory leakage means that available memory blocks (including occupied and free blocks) are getting less and less. Then non-leakage is to protect the address spaces.

For the specification level, we provisionally use *ID* to present a contiguous addresses for a memory block. The mapping between a *ID* and a true range of address and the one-to-one uniqueness guarantee will be introduced in the future work. Therefore, in this specification, isolation in address spaces means that all *IDs* that leaves bring are different. The strategy of creating a new leaf has been already introduced in the previous subsection.

Definition 14. *Different IDs*

$is_different\ blo_set \equiv \forall b \in blo_set. \forall l \in tree.set\ b. (\nexists l'. l' \in tree.set\ (SOME\ b. b \in blo_set) \wedge l' \neq l \wedge ID\ l' = ID\ l)$

The above definition tells that there are no two leaves with the same id. The *ID* gives the id the leaf brings. Below are two lemmas that ensure the property holds during the procedures of allocation and deallocation.

Lemma 6. $is_different\ blo_set \longrightarrow is_different\ fst\ (alloc\ blo_set\ rlv)$

Lemma 7. $is_different\ blo_set \longrightarrow is_different\ fst\ (free\ blo_set\ b)$

Proof. Induction method can solve these lemmas with the assistants of the execution branches, because the operations are conducted on the recursive structure of the quad-tree.

Theorem 4. *The buddy allocation specification ensures all IDs of leaves are different.*

Because we use the quad-tree structure and map all the memory blocks into the leaves of the tree, then the memory non-leakage means that all the leaves (including occupied and free leaves) are in use. Thus once the certain relationship between the number of nodes and leaves has been proved, we can infer that the quad-tree always maintains correct structure. Hence, we can prove that all the leaves are in use and none leaf is forgotten.

The first step is to prove the relationship between the number of nodes and leaves in a quad-tree.

Lemma 8. $q_tree\ b: Num\ (Leaf\ b) = Num\ (Node\ b) \times 3 + 1$

Proof. We use induction to prove this lemma because of the recursive structure of the quad-tree.

Then we use the following two lemmas to guarantee all the quad-trees during the procedures maintain this relationship in numbers of leaves and nodes.

Lemma 9. $\forall b \in blo_set. q_tree\ b \longrightarrow \forall b \in fst\ (alloc\ blo_set\ rlv). q_tree\ b$

Lemma 10. $\forall b \in blo_set. q_tree\ b \longrightarrow \forall b \in fst\ (free\ blo_set\ b). q_tree\ b$

Proof. We still apply induction to solve the proofs through the execution branches, due to the operations being conducted on the recursive structure of the quad-tree.

Theorem 5. *The buddy allocation specification guarantees any tree is a q-tree.*

To sum up, in this section we introduce the quad-tree structure to simulate memory because of the buddy allocation algorithms. Then we give a specification for the algorithms including **alloc** and **free** operations. After that, we give proofs for functional correctness including preconditions and postconditions, the most suitable memory block, non-existence of the *FFL* trees, memory isolation and non-leakage. Through these efforts, we give a functionally correct buddy memory model.

4 Security of Buddy Allocation Model

Integrity is the assurance that the information is trustworthy and accurate. To achieve this, data must not be changed in transit. In this section, we try to prove the integrity property for buddy memory model. For this purpose, we firstly design a security model which consists of a nondeterministic state machine and the integrity property conditions. Next, we introduce interfaces into the buddy memory model, and package it into an event specification. We think of this event specification as an instantiated security model. The last step is to prove the instantiated model satisfy the integrity property.

4.1 A Security Model

Memory State Machine is designed to be event based. Thus, \mathcal{S} represents the state space and \mathcal{E} is the set of event labels. The state-transition function is characterized by φ , which has the form of $\varphi : \mathcal{E} \rightarrow \mathbb{P}(\mathcal{S} \times \mathcal{S})$. The state machine must execute from a initial state, therefore, $s_0 \in \mathcal{S}$ which is on behalf of the initial state must be included in this machine. The definition of this state machine is as follows.

Definition 15. *State Machine* $\mathcal{M} = \langle \mathcal{S}, \mathcal{E}, \varphi, s_0 \rangle$

Based on the state machine above, we introduce some auxiliary functions: The **execution**(\mathbf{s}, \mathbf{es}) function returns the set of final states by executing a sequence of events \mathbf{es} from a state \mathbf{s} . The **reachable**(\mathbf{s}) function (denoted as $\mathcal{R}(\mathbf{s})$) checks the reachability of a state \mathbf{s} by the *execution* function.

Next, we add the concept of partitions to represent the entities that execute the state-transition function. Therefore, partitions are the basic domains. In addition, we introduce partition scheduling as a domain **scheduler**. And we give the strict restriction that *scheduler* cannot be interfered by any other domains. Its aim is to ensure that *scheduler* does not leak information by its scheduling decisions. Therefore, the domains (\mathcal{D}) in \mathcal{M} are the configured partitions (\mathcal{P}) and the scheduler (\mathbb{S}), $\mathcal{D} = \mathcal{P} \cup \{\mathbb{S}\}$. The **dom**(\mathbf{s}, \mathbf{e}) function gives which partition is currently executing \mathbf{e} in the state \mathbf{s} by consulting the *scheduler*.

Integrity Definition is referenced to [2] which provides a formalism for the specification of security policies. The main idea in this article is that domain u is non-interfering with domain v if no action performed by u can influence the subsequence outputs seen by v . According to this, we use the concepts of state equivalence and interfering to construct integrity property.

State equivalence (denoted as \sim) means that states are identical for a domain seen by it. For example, some certain collections that accessed only by a domain are indistinguishable at two different states. We use $s \stackrel{d}{\sim} t$ to represent s and t are identical for domain d .

By the concept of state equivalence, interfering (denoted as \rightsquigarrow) means that the state equivalence of some domain is broken due to the operations by another

domain. And $\not\rightsquigarrow$ is the opposite relation of \rightsquigarrow . Since the *scheduler* can schedule other domains, it can interfere with them. However, the *scheduler* cannot be interfered by any other domains to ensure that the *scheduler* does not leak information by its scheduling decisions.

With these two concepts, we can easily define the integrity property conditions as follows.

Definition 16. *Integrity Property Conditions*

$$IPC(e) \equiv \forall d \ s \ s'. \mathcal{R}(s) \wedge dom(s, e) \not\rightsquigarrow d \wedge (s, s') \in \varphi(e) \longrightarrow (s \stackrel{d}{\sim} s')$$

From the conditions, if the domain being scheduled to run promises not to interfere other domains, then the consequences in final state seen by other domains are identical, that is to say the domain being scheduled to run has only access to its own space. The integrity property conditions do guarantee that the information is trustworthy and accurate.

Security Model is defined as follows based on the discussion above.

Definition 17. *Security Model* $\mathcal{S_M} = \langle \mathcal{M}, \mathcal{D}, dom, \rightsquigarrow, \sim \rangle$

with assumptions as follows.

1. $\forall d \in \mathcal{D}. \mathbb{S} \rightsquigarrow d$
2. $\forall d \in \mathcal{D}. d \rightsquigarrow \mathbb{S} \longrightarrow d = \mathbb{S}$
3. $\forall s \ t \ e. s \stackrel{\mathbb{S}}{\sim} t \longrightarrow dom(s, e) = dom(t, e)$
4. $\forall s \ e. \mathcal{R}(s) \longrightarrow \exists s'. (s, s') \in \varphi(e)$
5. $IPC(e)$

4.2 Instantiation

In this part, we instantiate a security model in the following ways: Setting a global state; Adding interfaces to allocation and deallocation operations and instantiating the events with scheduler; Adding state-transition function by interfaces; Instantiating the definitions of interfering and equivalence.

As a global state, it records all the information like domains and all kinds of resources. *State* mainly consists of the currently running domain (denoted by **Cur**) and the memory address spaces occupied by the partition (characterized by function **Par_Mem: partition** \rightarrow **Mem_Add**, *Mem_Add* is a set of *ID*).

For the allocation and deallocation operations, it is only necessary to update *Par_Mem* information according to the success or failure of the operations, thus forming new operations **alloc_memory** and **free_memory**. These two interfaces are defined as follows. In addition, a scheduler that arbitrarily selects partitions to execute is defined as follows.

Definition 18. *Allocate Memory*

alloc_memory $s \equiv$ if (*True alloc*) then (*update Par_Mem* s (*Cur* s)) else s

Definition 19. *Deallocate Memory*

$free_memory\ s \equiv \text{if } (True\ free) \text{ then } (update\ Par_Mem\ s\ (Cur\ s)) \text{ else } s$

Definition 20. *Scheduler*

$scheduler \equiv (Cur\ s = SOME\ p. p \in par_set)$

With these interfaces functions, we give the state-transition function **exec_event(e)** as a instantiation of φ . Thus event e represents *alloc_memory*, *free_memory* and *scheduler*.

Definition 21. *State-transition*

$exec_event\ e \equiv \{(s, s'). \text{ case } e \text{ of } alloc_memory \Rightarrow s' \in \{alloc_memory\ s\} \mid$
 $free_memory \Rightarrow s' \in \{free_memory\} \mid$
 $scheduler \Rightarrow (s' = scheduler\ s)\}$

Finally, we give the instantiation of integrity property we want to prove through the instantiations of \rightsquigarrow and \sim . In this case, our goal is to prove that if the currently running domain is not interfering other domains, then the memory address spaces other domains owns maintain identical. Then we give the instantiations of \rightsquigarrow and \sim to achieve it.

Definition 22. *Instantiation of \rightsquigarrow by Domain*

$d1 \rightsquigarrow d2 \equiv (d1 = d2) \vee is_scheduler\ d1$

Definition 23. *Instantiation of \sim by State and Domain*

$s \stackrel{d}{\sim} t \equiv (is_scheduler\ d \longrightarrow Cur\ s = Cur\ t) \wedge (is_partition\ d \longrightarrow Par_Mem\ s\ d = Par_Mem\ t\ d) \wedge True$

4.3 Security Proofs

To prove that the instantiated model is a security model, we have to prove item 1 to item 5 in \mathcal{SM} definition one by one. The first two assumptions are preserved by the interfering \rightsquigarrow definition. The assumption 3 is preserved by \sim for the scheduler. The assumption 4 of reachability is preserved with the function $exec_event(e)$ by the following lemma.

Lemma 11. $\forall s\ e. \mathcal{R}(s) \longrightarrow \exists s'. (s, s') \in exec_event(e)$

To prove the $IPC(e)$, we have to apply concrete conditions of *alloc_memory*, *free_memory* and *scheduler* to imply these events satisfy the Integrity Property Conditions. The followings are the lemmes of each concrete function and final theorem.

Lemma 12. *IPC(e) of alloc_memory*

$\forall d\ s\ s'. \mathcal{R}(s) \wedge is_partition\ (Cur\ s) \wedge (Cur\ s) \not\rightsquigarrow d \wedge s' = alloc_memory\ s \longrightarrow$
 $s \stackrel{d}{\sim} s'$

Lemma 13. *IPC(e) of free_memory*

$$\forall d \ s \ s'. \mathcal{R}(s) \wedge is_partition \ (Cur \ s) \wedge (Cur \ s) \not\rightsquigarrow d \wedge s' = free_memory \ s \longrightarrow s \stackrel{d}{\sim} s'$$

Lemma 14. *IPC(e) of scheduler*

$$\forall d \ s \ s'. is_scheduler \ (Cur \ s) \wedge (Cur \ s) \not\rightsquigarrow d \longrightarrow s \stackrel{d}{\sim} s'$$

Theorem 6. *IPC(e) Satisfaction*

$\forall e \in alloc_memory, free_memory, scheduler. IPC(e)$

In the end, we proved that the event specification based on the buddy allocation model satisfies the integrity property and is a security model. According to the instantiation of interfering, by the buddy allocation model, as long as the domain is not the scheduler, the execution of one domain will not influence the memory address spaces that other domains have. The security proofs above ensure that that memory information is trustworthy and accurate.

5 Conclusions and Future Work

To sum up, we give a specification for buddy allocation algorithm firstly.

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