

RS Control Suite — Provisional Patent Package

Magnetic Controller — ICF φ -Pulse Shaper — φ -Scheduler Module

Purpose. A single, self-contained specification that packages three related inventions with quick figures and short *Best Mode* sections suitable for provisional filings.

Global notation (used throughout). Golden ratio $\varphi = \frac{1 + \sqrt{5}}{2}$. Recognition ratios $r_i := y_i/y_i^*$ with declared targets $y_i^* > 0$. Ledger cost

$$J(x) = \frac{1}{2} \left(x + \frac{1}{x} \right) - 1, \quad x > 0, \quad J(1) = 0, \quad J''(1) = 1.$$

A control period of length T is partitioned into L phase windows W_0, \dots, W_{L-1} with durations Δt_ℓ s.t. $\sum_\ell \Delta t_\ell = T$ and $\Delta t_{\ell+1}/\Delta t_\ell \in \{\varphi, \varphi^{-1}\}$ (φ -commensurate).

SPEC I — Magnetic Confinement Controller

Summary

A controller for magnetically confined plasma that minimizes a convex ledger over dimensionless recognition ratios, enforces φ -timed multi-actuator updates on an eight-phase schedule, and deploys actions only if a certificate (audit surface) passes. Implementations include periodic MPC and RL with a safety filter that guarantees φ -gating and certificate compliance.

Quick figure: control pipeline

Key definitions

Recognition ratios: $r_i = y_i/y_i^*$ over declared targets (T_e, T_i, n_e , q -profile metrics, shear proxy $\gamma_{E \times B}/\gamma^*$, turbulence bands, impurity/radiated fractions).

φ -timed schedule: $L=8$ windows; actuator class assignment $\Pi(a) \subset \{0, \dots, 7\}$.

Audit surface (certificate): fixed thresholds on disruptivity risk, impurity/radiation fractions, transport proxies, and tracking error; non-passing policies are auto-rejected/filtered.

Best Mode (preferred embodiment)

- **Actuators:** NBI (two phases for torque/shear), ECRH (two phases for core/edge), ICRH (single phase), RMP (single phase), pellets (single phase), gas puffing (single phase), shaping/Vs (fast loop; updates gated).
- **Diagnostics:** Thomson, ECE, reflectometry, BES, SXR/bolometry, neutron rate, magnetic probes, loop voltage, equilibrium reconstructions.
- **Window map:** $\Pi(\text{pellet}) = \{0\}$, $\Pi(\text{RMP}) = \{2\}$, $\Pi(\text{ECRH}) = \{1, 5\}$, $\Pi(\text{ICRH}) = \{3\}$, $\Pi(\text{NBI}) = \{4, 7\}$, $\Pi(\text{Gas}) = \{6\}$.
- **Objective:** $\sum_i w_i J(r_i)$ with w_i set from sensitivity of a certified transport surrogate at $r = 1$.
- **Controller:** periodic MPC ($N=10\text{--}30$ steps, terminal set/cost 8-phase periodic); fallback RL with safety filter that solves the same constrained ledger problem online.
- **Certificate thresholds:** declare fixed θ for risk, impurities, radiated fraction, and tracking error; deployment only if $\mathcal{A} \leq \theta$ for M consecutive windows.

Quick figure: eight-phase φ schedule

$$\Delta t_{\ell+1}/\Delta t_{\ell} \in \{\varphi, \varphi^{-1}\}, \quad \sum \Delta t_{\ell} = T$$

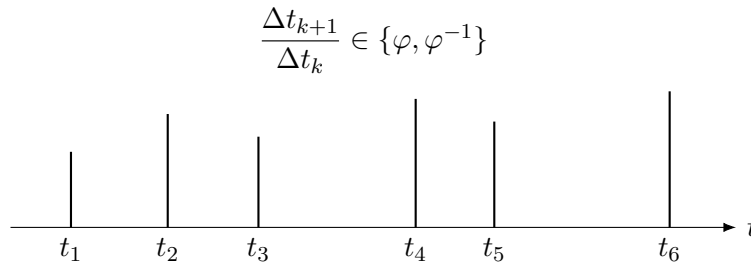


SPEC II — ICF φ -Pulse Shaping

Summary

An ICF pulse-shaping method that constructs φ -spaced sub-pulses and minimizes a *symmetry ledger* over normalized spherical-harmonic mode magnitudes $r_{\ell m} = |a_{\ell m}|/a_{\ell}^*$ subject to energy/facility constraints. Deployment is certificate-gated. Residual asymmetry decreases at least geometrically with sub-pulse count within the admissible regime.

Quick figure: φ -spaced sub-pulse train



Key definitions

Symmetry coefficients: $a_{\ell m}$ from x-ray self-emission, radiography, or backlighter.

Symmetry ledger: $\mathcal{L}_{\text{sym}} = \sum_{\ell \in \mathcal{S}} w_{\ell} \sum_{m=-\ell}^{\ell} J(|a_{\ell m}|/a_{\ell}^*)$, with declared \mathcal{S} (e.g. $\{2, 4, 6\}$), targets $a_{\ell}^* > 0$, and weights $w_{\ell} > 0$.

Certificate: thresholds on \mathcal{L}_{sym} , mode caps (e.g. $|a_{20}| \leq \tau_2$, $|a_{4m}| \leq \tau_4$), shock timing/bang-time windows, adiabat and preheat limits.

Best Mode (preferred embodiment)

- **Sub-pulses:** $K = 5\text{--}8$ pickets/ramps with raised-cosine template $s(\cdot)$; amplitudes A_k bounded by facility cone/ring allocations; total energy E_{tot} fixed.
- **Timing:** enforce $\Delta t_{k+1}/\Delta t_k \in \{\varphi, \varphi^{-1}\}$ within a declared drive window; per-ring micro-delays allowed if φ -commensurability preserved.
- **Mode set:** $\mathcal{S} = \{2, 4, 6\}$ with a_{ℓ}^* set from prior symmetry campaigns; w_{ℓ} proportional to capsule-yield sensitivity.
- **Optimizer:** hydrodynamics surrogate with declared error bounds; optionally Bayesian update from low-energy surrogate shots; keep ledger, φ -spacing, and certificate fixed.
- **On-shot gating:** online symmetry proxies checked; certificate violation aborts remaining sub-pulses.

SPEC III — φ -Scheduler Module

Summary

A reusable scheduling module that partitions control periods into φ -commensurate windows, assigns actuators to phase sets, enforces update admissibility within windows, guarantees periodic invariance with bounded jitter, provides a qualitative interference bound, and exposes a controller-agnostic *Compliance API* with signed logs. Useful across domains (fusion, lasers, robotics, beamlines, power electronics).

Quick figure: scheduler architecture & API

Key definitions

φ -windows: $L=8$ default; optional superframe ST with φ -relations preserved inside each T .

Interference bound (qualitative): For band-limited cross-coupling, time-averaged bilinear cross-terms are reduced by a strict factor $\kappa \in (0, 1)$ relative to co-phased/equal-spaced baselines (window smoothness controls κ).

Compliance API: `BeginWindow(ℓ)`, `EndWindow(ℓ)`, `WindowIndex()`, `Allowed(a)`, `RequestUpdate(a , pay)` (admit/reject), `GetComplianceReport()` (cryptographically signed).

Best Mode (preferred embodiment)

- **Timing:** T linked to plant reference τ_{ref} ; $L=8$; raised-cosine window edges; jitter $\leq 100 \mu\text{s}$ (magnetic) / 100 ps (ICF triggers).
- **Phase sets:** disjoint or minimally overlapping $\Pi(a)$ for actuators with strong cross-coupling; mandatory dwell δ_a enforced.
- **Compliance:** hardware timer/FPGA for edges; secure element for signature of logs; per-period attestation of φ -ratios and window adherence.
- **Integration:** controller-agnostic; third-party stacks must call API; noncompliant requests are rejected and logged.

Claims (outline — each spec provides an independent set)

- **Spec I (Magnetic Controller):** Method, System, and Non-transitory Medium claims covering ledger-objective over recognition ratios, φ -timed eight-phase actuation with assignments $\Pi(a)$, certificate-gated deployment, periodic MPC or RL with safety filter; dependent claims on actuators, diagnostics, specific ratios (critical gradients, shear), periodic terminal ingredients, robustness bounds.

- **Spec II (ICF φ -Pulse Shaper):** Method, System, and Medium claims covering φ -spaced sub-pulses, symmetry-ledger minimization over $|a_{\ell m}|/a_{\ell}^*$, certificate thresholds, and a geometric convergence feature ($0 < \eta < 1$ qualitative); dependent claims on pulse templates, mode sets, facility constraints, online gating.
- **Spec III (φ -Scheduler):** Method, System, and Medium claims covering φ -commensurate windows, periodic invariance and interference bounds, and the Compliance API with signed logs; dependent claims on jitter bounds, superframes, window smoothness, hardware realization.

Enablement & best-mode checklist (for counsel)

- Equations/algorithms present (ledger J , ratios r , φ -windowing; symmetry ledger).
- Concrete mappings (actuator phase sets; pulse timing; API calls).
- Figures showing pipeline, schedule, pulse train, and module blocks.
- Best Mode sections for each spec: actuators/diagnostics & thresholds; K sub-pulses & mode set; timing/jitter & API/signing.