We have seen:
$$\frac{\partial g}{\partial t} = -\left\{g,H\right\} = -\frac{\sum_{j}\left(\frac{\partial g}{\partial j},\frac{\partial H}{\partial p_{j}} - \frac{\partial g}{\partial p_{j}},\frac{\partial H}{\partial p_{j}}\right)}{\frac{\partial g}{\partial p_{j}}}$$

p(p^{3N}, q,^{3N}) is the probability that the system is found in the state p^{3N}, q^{3N}

What about quantum mechanics?

States accessible to the system $|4\rangle$ Probabilities p_i ; $\sum p_i = 1$

Operator
$$\hat{A}: \langle \hat{A} \rangle = \sum_{j} p_{j} \langle \mathcal{Y}_{j} | \hat{A} | \mathcal{Y}_{j} \rangle$$

We encode all information about the system in the density matrix operator

Then: $\langle \hat{A} \rangle = \nabla r (\hat{\rho} \hat{A}) - \sum_{n} \langle \chi_{n} | \hat{\rho} \hat{A} | \chi_{n} \rangle$ $\{ |\chi_{n} \rangle \}$ is an orthonormal basis

$$\rightarrow \langle \chi_n | \chi_m \rangle = \delta_{nm}$$

Proof
$$0 \ge |X_n| \langle X_n| = 1$$
.

Consider $|4\rangle = \sum_{m} C_m |X_m\rangle$

$$\frac{\sum_{n} |X_n| \langle X_n| \sum_{m} C_m |X_m\rangle = \sum_{n} C_n |X_n\rangle = |4\rangle}{\delta_{nm}}$$

$$\nabla r(\hat{\rho}\hat{A}) = \sum_{n} \langle Y_{n} | \sum_{j} | Y_{j} \rangle \langle Y_{j} | \hat{A} | \chi_{n} \rangle$$

$$= \sum_{j} p_{j} \sum_{j} \langle Y_{j} | \hat{A} | \chi_{n} \rangle \langle \chi_{n} | Y_{j} \rangle$$

$$= \sum_{j} p_{j} \sum_{n} \langle Y_{j} | \hat{A} | \chi_{n} \rangle \langle \chi_{n} | Y_{j} \rangle$$

of contains all the information that we may want to know about the system.

⇒ ĝ is sufficient for calculating outcomes of experiments

Time evolution:

$$\frac{\partial \hat{\rho}}{\partial t} = \sum_{j} p_{j} \left[\frac{\partial}{\partial t} \left(| \mathcal{Y}_{j} \right) \right] \langle \mathcal{Y}_{j} | + | \mathcal{Y}_{j} \rangle \frac{\partial}{\partial t} \left(\mathcal{Y}_{j} \right) \right]$$

$$i h \frac{\partial}{\partial t} | \mathcal{Y}_{i} \rangle = \hat{H} | \mathcal{Y}_{i} \rangle ; \quad -i h \frac{\partial}{\partial t} \langle \mathcal{Y}_{j} | = \langle \mathcal{Y}_{i} | \hat{H} \rangle$$

$$\frac{\partial \hat{\rho}}{\partial t} = \sum_{j} p_{j} \frac{1}{i \hbar} \left[\hat{H} | \mathcal{Y}_{j} \rangle \langle \mathcal{Y}_{j} | - | \mathcal{Y}_{j} \rangle \langle \mathcal{Y}_{j} | \hat{H} \right] = \frac{1}{i \hbar} \left(\hat{H} \hat{\rho} - \hat{\rho} \hat{H} \right) = \frac{-1}{i \hbar} \left[\hat{\rho}, \hat{H} \right].$$

$$\frac{\partial \mathcal{L}}{\partial t} \mathcal{L} = - \left\{ \mathcal{L} \mathcal{L} \right\}$$

‡

$$|0\rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \qquad |1\rangle = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

Properties of
$$\hat{g}$$
: $\forall r \hat{g} = 1$.

For a pure state:
$$P_{y} = 0$$

$$\hat{\rho} = |4\rangle\langle 4|; \quad \hat{\rho}^{z} = \hat{\rho}.$$