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# A low-rank high-precision solver for semidefinite programming

Joint work with Daniel Brosch and Angelika Wiegele

Jan Schwidessen

OR 2024, Munich



UNIVERSITÄT  
KLAGENFURT



# Semidefinite programming

## SDP in standard form

$$\begin{array}{ll} \min & \langle C, X \rangle \\ \text{s. t.} & \mathcal{A}(X) = b \\ & X \in \mathcal{S}_n^+ \end{array} \quad (\text{SDP})$$

►  $C, A_1, \dots, A_m \in \mathcal{S}_n$ ,  $b \in \mathbb{R}^m$ , linear operator  $\mathcal{A}: \mathcal{S}_n \rightarrow \mathbb{R}^m$

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- adjoint operator  $\mathcal{A}^\top: \mathbb{R}^m \rightarrow \mathcal{S}_n$  with  $\mathcal{A}^\top(y) = \sum_{i=1}^m y_i A_i$

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- **assumption:** strong duality holds

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- ▶ project name: The Augmented Mixing Method

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**Idea:** combine both approaches (**Augmented Mixing Method**)

- ▶ tackle **general** SDPs
- ▶ solve small subproblems with **high** precision
- ▶ **ADMM-style** method

# Burer-Monteiro factorization (Burer & Monteiro, 2003)

## Theorem (Barvinok, 1995; Pataki, 1998)

*If  $\bar{X}$  is an extreme point of (SDP), then  $\text{rank}(\bar{X}) \leq k_m$ , where  $k_m := \max \{k \in \mathbb{N} : k(k+1)/2 \leq m\}$ .*

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► Barvinok-Pataki bound:  $k \geq \sqrt{2m}$

# Non-convex reformulation

## Reformulation

$$\begin{aligned} \min \quad & \langle C, V^T V \rangle \\ \text{s. t.} \quad & \mathcal{A}(V^T V) = b \\ & V \in \mathbb{R}^{k \times n} \end{aligned} \quad (*)$$

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## Proposition (Burer & Monteiro, 2005)

*Suppose  $X = V^\top V$  is feasible for (LR-SDP). Then  $X$  is a local minimum of (LR-SDP) if and only if  $V$  is a local minimum of  $(*)$ .*

# Augmented Lagrangian approach

## Augmented Lagrangian

$$\mathcal{L}(V, y; \mu) := \langle C, V^\top V \rangle + \frac{\mu}{2} \|b - \mathcal{A}(V^\top V)\|^2 + \langle y, b - \mathcal{A}(V^\top V) \rangle$$

- ▶ penalty parameter  $\mu > 0$
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## Derivative w.r.t $V$

$$\nabla_V \mathcal{L}(V, y; \mu) = 2V\tilde{S}$$

where

$$\tilde{S} = C - \sum_{i=1}^m \tilde{y}_i A_i$$

$$\tilde{y} = y - \mu(\mathcal{A}(V^\top V) - b)$$

# Implementation of augmented Lagrangian approach

---

**Algorithm 1** SDPLR (Burer & Monteiro, 2003)

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- ➊ Choose starting values  $V^0, y^0, \mu^0$ , and set  $p := 0$ .
  - ➋ While  $\|b - \mathcal{A}(V^p{}^\top V^p)\|$  too large:
    - ▶ Compute  $V^{p+1} := \arg \min_{V \in \mathbb{R}^{k \times n}} \mathcal{L}(V^p, y^p; \mu^p)$ .
    - ▶ If  $\|b - \mathcal{A}(V^{p+1}{}^\top V^{p+1})\|$  has sufficiently decreased:
      - ▶ Update  $y^{p+1} := y^p - \mu^p(\mathcal{A}(V^{p+1}{}^\top V^{p+1}) - b)$ .
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    - Otherwise:
      - ▶ Set  $y^{p+1} := y^p$ .
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- ▶ primal method in  $kn$  variables
  - ▶ quasi-Newton method used
  - ▶ no eigenvalue computations, exploits sparsity



# Theoretical results

## Max-Cut relaxation

$$\begin{array}{ll} \max & \langle C, X \rangle \\ \text{s. t.} & X_{ii} = 1, \quad i = 1, \dots, n \\ & X \in \mathcal{S}_n^+ \end{array} \quad (\text{MC-SDP})$$

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**However:** strong practical performance with smaller values of  $k$

**Issue:** cannot achieve very high accuracy in many cases

# Burer-Monteiro factorization for Max-Cut

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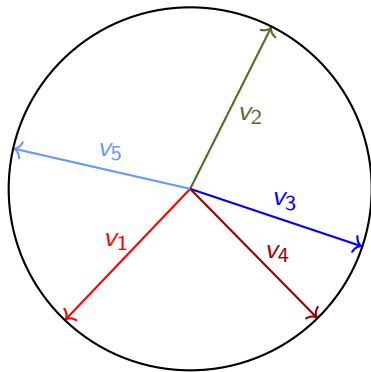
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► Barvinok-Pataki bound:  $(\text{MC-SDP}) \Leftrightarrow (\text{MC-vec})$  for  $k \geq \sqrt{2n}$

# Geometric interpretation

## Optimization problem (MC-vec)

$$\begin{aligned} \max \quad & \langle C, V^T V \rangle = \sum_{i,j=1}^n C_{ij} v_i^T v_j \\ \text{s. t.} \quad & \|v_i\| = 1, \quad i = 1, \dots, n \end{aligned} \quad (\text{MC-vec})$$



$$\begin{aligned} v_i^T v_j &= \|v_i\| \cdot \|v_j\| \cdot \cos \angle(v_i, v_j) \\ &= \cos \angle(v_i, v_j) \end{aligned}$$

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► closed-form solution:  $v_i = \frac{g}{\|g\|}$  if  $g \neq 0$

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**Algorithm 2** Mixing Method (Wang et al., 2018)

---

**Input:**  $C \in \mathbb{R}^{n \times n}$  with  $\text{diag}(C) = 0$ ,  $k \in \mathbb{N}_{\geq 1}$

**Output:** approximate solution  $V = (v_1 | \dots | v_n) \in \mathbb{R}^{k \times n}$  of (SDP-vec)

**for**  $i \leftarrow 1$  **to**  $n$  **do**

$v_i \leftarrow$  **random vector** on the unit sphere  $\mathcal{S}^{k-1}$

**end**

**while** *not yet converged* **do**

**for**  $i \leftarrow 1$  **to**  $n$  **do**

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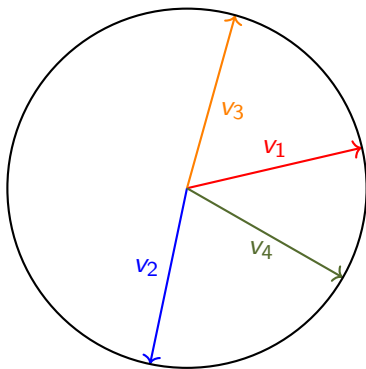
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**Theorem:** local linear convergence (Wang et al., 2018)

Let  $k > \sqrt{2n}$ . If the iterates do not degenerate, then the Mixing Method **converges** locally to the global **optimum** of (SDP-vec) at a linear rate.

Example with  $n = 4$  and  $k = 2$

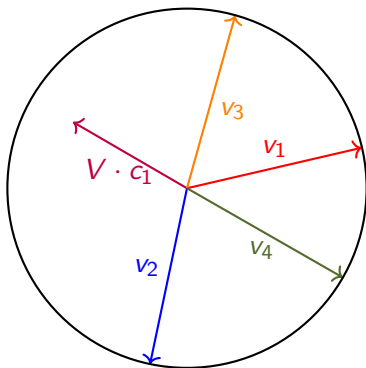
$$C = \frac{1}{4} \begin{pmatrix} 1 & 1 & 1 & -3 \\ 1 & -1 & 1 & -1 \\ 1 & 1 & -4 & 2 \\ -3 & -1 & 2 & 2 \end{pmatrix}$$



$$\langle C, V^T V \rangle = -2.469151715641014$$

Example with  $n = 4$  and  $k = 2$

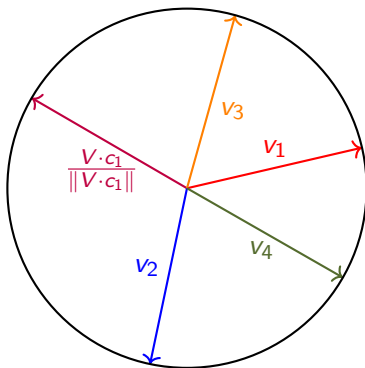
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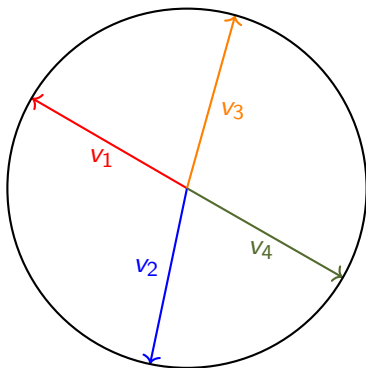
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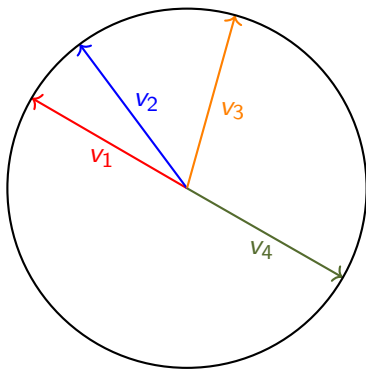
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$$\langle C, V^T V \rangle = 0.0701836938398076$$

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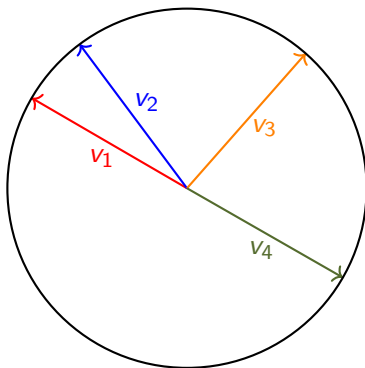


$$\langle C, V^T V \rangle = 2.1042821481042009$$



Example with  $n = 4$  and  $k = 2$

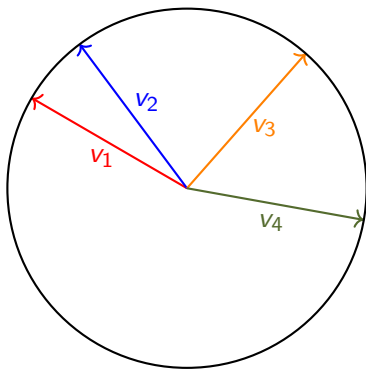
$$C = \frac{1}{4} \begin{pmatrix} 1 & 1 & 1 & -3 \\ 1 & -1 & 1 & -1 \\ 1 & 1 & -4 & 2 \\ -3 & -1 & 2 & 2 \end{pmatrix}$$



$$\langle C, V^T V \rangle = 2.1248497956082537$$

Example with  $n = 4$  and  $k = 2$

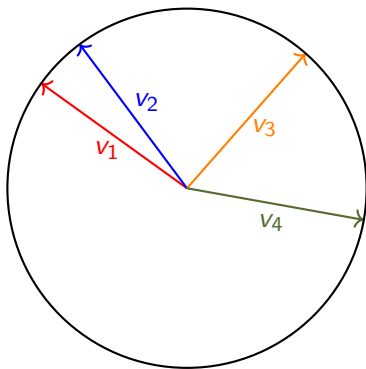
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$$\langle C, V^T V \rangle = 2.2584781813631301$$

Example with  $n = 4$  and  $k = 2$

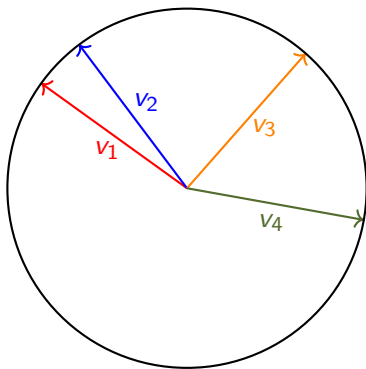
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$$\langle C, V^T V \rangle = 2.2669613535505473$$

Example with  $n = 4$  and  $k = 2$

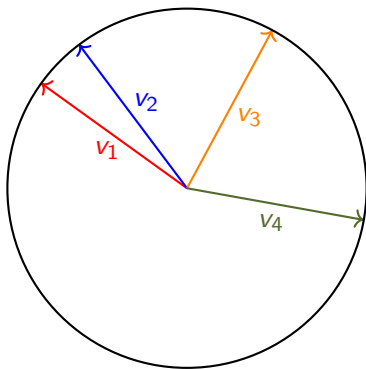
$$C = \frac{1}{4} \begin{pmatrix} 1 & 1 & 1 & -3 \\ 1 & -1 & 1 & -1 \\ 1 & 1 & -4 & 2 \\ -3 & -1 & 2 & 2 \end{pmatrix}$$



$$\langle C, V^T V \rangle = 2.2669669930002718$$

Example with  $n = 4$  and  $k = 2$

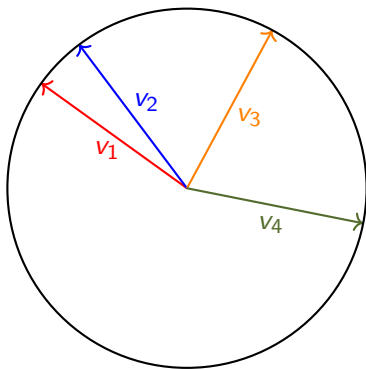
$$C = \frac{1}{4} \begin{pmatrix} 1 & 1 & 1 & -3 \\ 1 & -1 & 1 & -1 \\ 1 & 1 & -4 & 2 \\ -3 & -1 & 2 & 2 \end{pmatrix}$$



$$\langle C, V^T V \rangle = 2.2820426702215686$$

Example with  $n = 4$  and  $k = 2$

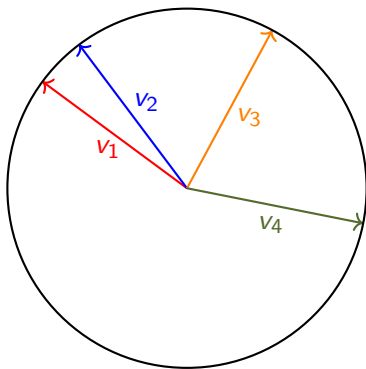
$$C = \frac{1}{4} \begin{pmatrix} 1 & 1 & 1 & -3 \\ 1 & -1 & 1 & -1 \\ 1 & 1 & -4 & 2 \\ -3 & -1 & 2 & 2 \end{pmatrix}$$



$$\langle C, V^T V \rangle = 2.2824146853764495$$

Example with  $n = 4$  and  $k = 2$

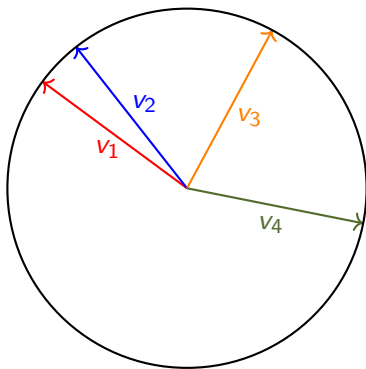
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$$\langle C, V^T V \rangle = 2.2825485984904232$$

Example with  $n = 4$  and  $k = 2$

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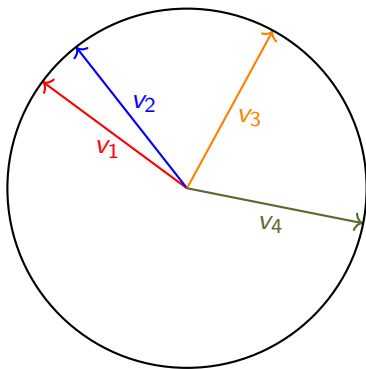


$$\langle C, V^T V \rangle = 2.2827921992397187$$



Example with  $n = 4$  and  $k = 2$

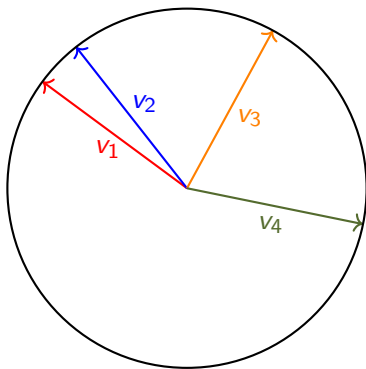
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$$\langle C, V^T V \rangle = 2.2827965824488148$$

Example with  $n = 4$  and  $k = 2$

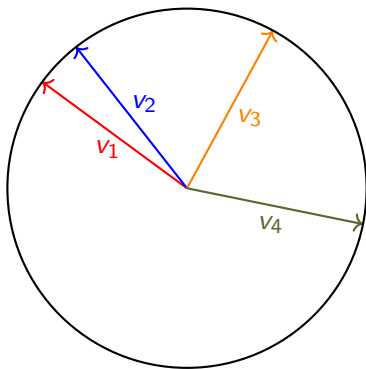
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$$\langle C, V^T V \rangle = 2.2828175664597827$$

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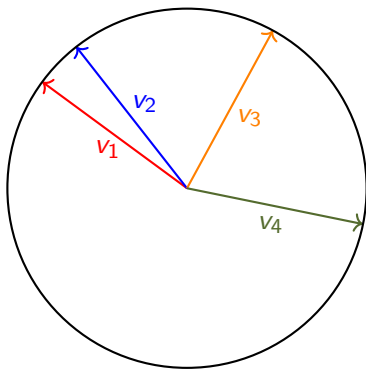
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$$\langle C, V^T V \rangle = 2.2828214514872149$$

Example with  $n = 4$  and  $k = 2$

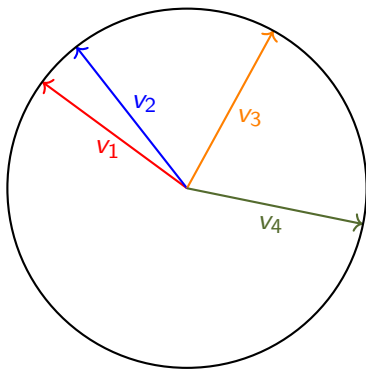
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$$\langle C, V^T V \rangle = 2.2828225671023645$$

Example with  $n = 4$  and  $k = 2$

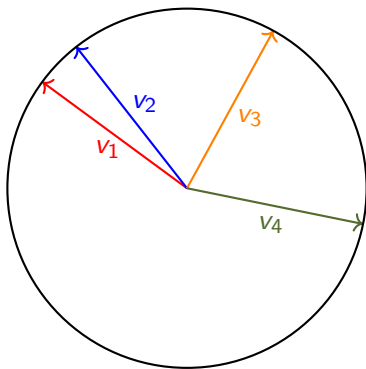
$$C = \frac{1}{4} \begin{pmatrix} 1 & 1 & 1 & -3 \\ 1 & -1 & 1 & -1 \\ 1 & 1 & -4 & 2 \\ -3 & -1 & 2 & 2 \end{pmatrix}$$



$$\langle C, V^T V \rangle = 2.2828245614424776$$

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$$\langle C, V^T V \rangle = 2.2828250454404815$$

# The Augmented Mixing Method

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## Algorithm 3 SDPLR

---

- ① Choose starting values  $V^0, y^0, \mu^0$ , and set  $p := 0$ .
  - ② While  $\|b - \mathcal{A}(V^p{}^\top V^p)\|$  too large:
    - ▶ Compute  $V^{p+1} := \arg \min_{V \in \mathbb{R}^{k \times n}} \mathcal{L}(V^p, y^p; \mu^p)$ .
    - ▶ If  $\|b - \mathcal{A}(V^{p+1}{}^\top V^{p+1})\|$  has sufficiently decreased:
      - ▶ Update  $y^{p+1} := y^p - \mu^p(\mathcal{A}(V^{p+1}{}^\top V^{p+1}) - b)$ .
      - ▶ Set  $\mu^{p+1} := \mu^p$ .
    - Otherwise:
      - ▶ Set  $y^{p+1} := y^p$ .
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    - end**
    - Set  $V^{p+1} := V^p$
    - ▶ If  $\|b - \mathcal{A}(V^{p+1}{}^\top V^{p+1})\|$  has sufficiently decreased:
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  - ▶ can easily be solved with **arbitrary precision**

# The Augmented Mixing Method

---

**Algorithm 3** Augmented Mixing Method

---

- ① Get  $V^0, y^0, \mu^0$  by warm-starting from SDPLR, and set  $p := 0$ .
- ② While  $\|b - \mathcal{A}(V^p{}^\top V^p)\|$  too large:
  - ▶ **For**  $i = 1, \dots, n$  **do**
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# Small subproblems

## Full augmented Lagrangian

$$\mathcal{L}(V, y; \mu) := \langle C, V^\top V \rangle + \frac{\mu}{2} \|b - \mathcal{A}(V^\top V)\|^2 + \langle y, b - \mathcal{A}(V^\top V) \rangle$$

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## Derivative w.r.t $v_i$

$$\frac{\partial}{\partial v_i} \mathcal{L}(V, y; \mu) = 2V \tilde{S}_{(i)}$$

where

$$\tilde{S} = C - \sum_{i=1}^m \tilde{y}_i A_i$$

$$\tilde{y} = y - \mu(\mathcal{A}(V^\top V) - b)$$

# Implementation

## Standard stopping criteria for SDPs

For  $X, Z \in \mathcal{S}_n^+$  and  $y \in \mathbb{R}^m$ :

$$\text{pinf} := \frac{\|\mathcal{A}(X) - b\|_2}{1 + \|b\|_2} < \text{tol}$$

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- ▶ SDPA-GMP needs roughly one minute for  $(n, m) = (20, 40)$

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**Thank you!**