

Bounding the error in approximations

Let $f: \mathbb{R}^n \rightarrow \mathbb{R}$ be a strictly convex function and assume that we can bound its Hessian H from below as

$$H \succeq H_0 \succ 0$$

(where $H \succeq H_0$ means that $H - H_0$ is positive semidefinite).

Now let \vec{x}^* denote the minimizer of the function f and \vec{x}^0 an approximation and write $\vec{y} = \vec{x}^0 - \vec{x}^*$. Using Taylor's theorem in the Lagrange form, we find

$$f(\underbrace{\vec{x}^* + \vec{y}}_{\vec{x}^0}) = f(\vec{x}^*) + \frac{1}{2} \vec{y}^T H(\vec{s}^*) \vec{y}$$

where \vec{s}^* is a vector somewhere between \vec{x}^* and \vec{x}^0 . Note that the linear order vanishes because \vec{x}^* is a minimizer.

Similar we can do a Taylor expansion around \vec{x}^0 and find

$$f(\underbrace{\vec{x}^0 - \vec{y}}_{\vec{x}^*}) = f(\vec{x}^0) - \vec{g}(\vec{x}^0)^T \vec{y} + \frac{1}{2} \vec{y}^T H(\vec{s}^0) \vec{y}$$

\uparrow
gradient

Substituting the first equation into the second one yields

$$\begin{aligned} f(\vec{x}^*) &= f(\vec{x}^*) + \frac{1}{2} \vec{y}^T H(\vec{s}^*) \vec{y} - \vec{g}(\vec{x}^0)^T \vec{y} \\ &\quad + \frac{1}{2} \vec{y}^T H(\vec{s}^0) \vec{y} \end{aligned}$$

$$\Rightarrow 0 = -\vec{g}^T(\vec{x}^0)^T \vec{\gamma} + \frac{1}{2} \vec{\gamma}^T \underbrace{\left(H(\vec{x}^0) + H(\vec{x}^0) \right)}_{\vec{\gamma}^T H_0} \vec{\gamma}$$

$$\Rightarrow 0 \geq -\vec{g}(\vec{x}^0)^T \vec{\gamma} + \vec{\gamma}^T H_0 \vec{\gamma}$$

$$\Leftrightarrow \vec{\gamma}^T H_0 \vec{\gamma} \leq \vec{g}(\vec{x}^0)^T \vec{\gamma}$$

Now we can use the Cauchy-Schwarz inequality to get

$$|\vec{g}^T \vec{\gamma}| = (\vec{H}_0^{-1/2} \vec{g})^T (\vec{H}_0^{1/2} \vec{\gamma}) \leq \|\vec{H}_0^{-1/2} \vec{g}\| \cdot \sqrt{\vec{\gamma}^T \vec{H}_0 \vec{\gamma}}$$

Then we obtain a bound for the deviation in the form

$$\Rightarrow |\vec{\gamma}^T H_0 \vec{\gamma}| \leq \vec{g}(\vec{x}^0)^T \vec{H}_0^{-1/2} \vec{g}(\vec{x}^0)$$

Three remarks:

→ The bound does not depend on \vec{x}^k , we just need the gradient \vec{g} at \vec{x}^0 and a lower bound for the Hessian.

→ The success of this method crucially depends on whether we find a good bound to ...

→ If we include constraints, we typically have to work with the Lagrangian instead of the objective function itself.