

## Bounding the error in approximations

Let  $f: \mathbb{R}^n \rightarrow \mathbb{R}$  be a strictly convex function and assume that we can bound its Hessian  $H$  from below as

$$H \succeq H_0 \succeq 0$$

(where  $H \succeq H_0$  means that  $H - H_0$  is positive semidefinite).

Now let  $\vec{x}^*$  denote the minimizer of the function  $f$  and  $\vec{x}^0$  an approximation and write  $\vec{y} = \vec{x}^0 - \vec{x}^*$ . Using Taylor's theorem in the Lagrange form, we find

$$f(\underbrace{\vec{x}^* + \vec{y}}_{\vec{x}^0}) = f(\vec{x}^*) + \frac{1}{2} \vec{y}^T H(\vec{\xi}^*) \vec{y}$$

where  $\vec{\xi}^*$  is a vector somewhere between  $\vec{x}^*$  and  $\vec{x}^0$ . Note that the linear order vanishes because  $\vec{x}^*$  is a minimizer.

Similar we can do a Taylor expansion around  $\vec{x}^0$  and find

$$f(\underbrace{\vec{x}^0 - \vec{y}}_{\vec{x}^*}) = f(\vec{x}^0) - \underbrace{\vec{g}(\vec{x}^0)^T}_{\substack{\uparrow \\ \text{gradient}}} \vec{y} + \frac{1}{2} \vec{y}^T H(\vec{\xi}^0) \vec{y}$$

Substituting the first equation into the second one yields

$$f(\vec{x}^*) = f(\vec{x}^*) + \frac{1}{2} \vec{y}^T H(\vec{\xi}^*) \vec{y} - \vec{g}(\vec{x}^0)^T \vec{y} + \frac{1}{2} \vec{y}^T H(\vec{\xi}^0) \vec{y}$$



$$\Rightarrow 0 = -g^T(\bar{x}_0) \bar{y} + \frac{1}{2} \bar{y}^T \underbrace{(H(\bar{y}) + H(\bar{y}^0))}_{\approx H_0} \bar{y}$$

$$\Rightarrow 0 \geq -g(\bar{x}_0)^T \bar{y} + \bar{y}^T H_0 \bar{y}$$

$$\Leftrightarrow \bar{y}^T H_0 \bar{y} \leq g(\bar{x}_0)^T \bar{y}$$

Now we can use the Cauchy-Schwarz inequality to get

$$|g^T \bar{y}| = (H_0^{-1/2} g)^T (H_0^{1/2} \bar{y}) \leq \|H_0^{-1/2} g\| \cdot \sqrt{\bar{y}^T H_0 \bar{y}}$$

Then we obtain a bound for the deviation in the form

$$\Rightarrow \bar{y}^T H_0 \bar{y} \leq \bar{g}(\bar{x}_0)^T H_0^{-1/2} \bar{g}(\bar{x}_0)$$

~~Three~~ remarks:

- The bound does not depend on  $\bar{x}^*$ , we just need the gradient  $\bar{g}$  at  $\bar{x}_0$  and a lower bound for the Hessian.
- The success of this method crucially depends on whether we find a good bound  $H_0$ ...
- If we include constraints, we typically have to work with the Lagrangian instead of the objective function itself.