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Département Electronique



Predefined Primitive Channels (Mutexs, FIFOs, Signals)				
(Matoxo, File Co, Oighalo)				
Simulation Kernel	Threads & Methods	Channels & Interfaces	Data types Logic, Integers, Fixed point	
	Events, Sensitivity & Notification	Modules & Hierarchy		



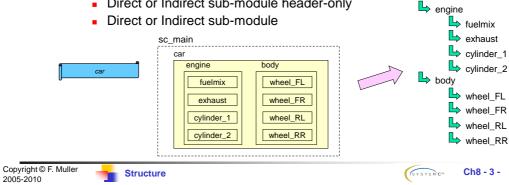
Module Hierarchy



sc_main

car

- Systems require partitioning and hierarchy
 - complexicity
 - better understanding
 - project management
- Implementations
 - Direct or Indirect top-level
 - Direct or Indirect sub-module header-only





Direct or Indirect top-level



Direct top module

```
int sc_main(int argc, char* argv[])
                                                             sub-design instances are instantiated
                                                             and initialized in one statement
     Wheel Wheel_FL("Wheel_FL"); Wheel Wheel_FR("Wheel_FR");
     sc start():
```

Indirect top module

```
int sc_main(int argc, char* argv[])
                                       pointer declaration
    Wheel *wheel_FL;
    Wheel *wheel_FR;
                                                           instance creation
    wheel_FL = new Wheel("Wheel_FL");
    wheel_FR = new Wheel("Wheel_FR");
    sc_start();
    delete wheel_FL;
    delete wheel_FR;
    return 0;
```

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Direct or Indirect sub-module header-only

Direct sub-module header-only Indirect sub-module header-only Body.h SC_MODULE(Body) SC_MODULE(Body) // Sub-module instances // Sub-module instances Wheel Wheel_FR; declaration pointer declaration Wheel *wheel_FR; Wheel Wheel_FL; Wheel *wheel_FL; Wheel *wheel_RR; Wheel Wheel_RR; Wheel Wheel_RL; Wheel *wheel_RL; // Constructor instance creation // Constructor SC_CTOR(Body) SC_CTOR(Body) initialization : Wheel_FL("Wheel_FL"), Wheel_FR("Wheel_FR"), wheel_FL = new Wheel("Wheel_FL"); Wheel_RL("Wheel_RL"), wheel_FR = new Wheel("Wheel_FR"); Wheel_RR("Wheel_RR") wheel_RL = new Wheel("Wheel_RL"); wheel_RR = new Wheel("Wheel_RR") }; // Destructor ~Body() delete wheel_FR; Copyright © F. Muller 2005-2010 (SYSTEM C™ Ch8 - 5 -Structure



Direct or Indirect sub-module With Separate Compilation

Wheel_RL("Wheel_RL"),

Wheel_RR("Wheel_RR")

sc_module(nm)



Body.h Body.h SC_MODULE(Body) SC_MODULE(Body) // Sub-module instances // Sub-module instances declaration only Wheel Wheel_FR; pointer declaration Wheel *wheel FR: Wheel Wheel_FL; Wheel *wheel_FL; Wheel Wheel RR: Wheel *wheel_RR; Wheel Wheel_RL; Wheel *wheel RL: // Constructor SC_HAS_PROCESS(Body); SC_HAS_PROCESS(Body); instance creation Body(sc_module_name nm); Body(sc_module_name nm); best approaches for IP! Body.cpp Body.cpp pre-compiled object files // Constructor // Constructor Body::Body(sc_module_name nm) Body::Body(sc_module_name nm) : sc_module(nm) : Wheel_FL("Wheel_FL"), Wheel_FR("Wheel_FR"),

Indirect sub-module

wheel_FL = new Wheel("Wheel_FL");

wheel_FR = new Wheel("Wheel_FR"); wheel_RL = new Wheel("Wheel_RL");

wheel_RR = new Wheel("Wheel_RR"); Copyright © F. Muller Structure (SYSTEM C™ Ch8 - 6 -





Level	Allocation	+	-
Main	Direct	Least code	Inconsistent with other levels
Main	Indirect	Dynamically configurable	Involves pointers
Module	Direct header-only	- All in one file - Easier to understand	Requires sub-module headers
Module	Indirect header-only	- All in one file - Dynamically configurable	Involves pointers
Module	Direct sub-module (separate compilation)	Hides implementation	Requires sub-module headers
Module	Indirect sub-module (separate compilation)	- Hides sub-module headers and implementation - Dynamically configurable	Involves pointers



