

Question 2a)

There are three different copies of x

| Parent | Child 1 | Child 2 | Code line number |
|---------|---------|---------|------------------|
| x = 100 | x = 100 | | Line 9 |
| | x = 90 | | Line 12 |
| | | x = 100 | Line 15 |
| x = 80 | | x = 80 | Line 16 |
| x = 70 | | | Line 18 |

So, the final answers are x = 70, x = 90 and x = 80.

```
1  #include <stdio.h>
2  #include <stdlib.h>
3  #include <sys/types.h>
4  #include <unistd.h>
5  #include <sys/wait.h>
6
7  int main(int argc, char** argv){
8      int child = fork();
9      int x = 100;
10
11     if(child == 0){//child
12         x-=10;
13     }
14     else{//parent
15         child = fork();
16         x-=20;
17         if(child){
18             x-=10;
19         }
20     }
21     return 0;
22 }
```

2b)

For this we would look at an example where we have two processes with several threads, in the case of user-level threads a thread would be picked and run until it is finished or becomes blocked, it then looks for another thread in the same process and continues. After the process is finished it moves onto the next process and repeats the process of running the threads as detailed before. The advantage of this is that this can be implemented in an operating system that does not support threads. User-level threading is done in Java.

Now in the case of kernel-level threads, the first thread is picked and run until it is blocked or complete. The kernel-level thread however has the option to either run a ready thread in the same process or if none are available it goes to the next process and runs a thread that is ready there. This repeats until both processes are finished. The advantage here is that if there is a page fault in a process the kernel can still move to another thread that is ready while the page is brought in from the disk. Windows implements kernel-level threading.

2c.

When a shared memory resource needs to be accessed, problems may arise where two processes are manipulating the same resource. To avoid complications, the Test and Set Lock Algorithm can be used, implementing the functions **enter_region** and **leave_region**.

enter_region:

```
TSL REG, FLAG
CMP REG, 0
JNE enter_region
return
```

First, the flag (lock) variable is copied to the shared memory register and set to 1. The flag is a shared variable. Secondly, a comparison is done to see if the register is locked (if set to 1). If it is locked, the program loops. Else, it returns to the caller.

leave_region

```
MOVE FLAG, 0
return
```

When the process wants to leave the critical region, it sets the flag value to zero.

2di)

The problem with Peterson's solution and the above TSL instruction is that they have an issue with requiring busy waiting. Essentially, for these solutions when a process waits to enter its critical region, it checks to see if the entry is allowed. If it is not, the process just sits in a tight loop waiting until it can enter the critical region, which can be costly to the CPU.