

#### strace

- strace is a user mode utility that monitors the interaction of user processes with the kernel (i.e. system calls).
- strace may attach and detach an executing process, or start a process.
- Tracing may be inherited via fork's of traced processes when they spawn child processes.
- strace reports parameters passed and values returned by system calls.



#### strace Example

```
# strace 1s
open(".", O RDONLY|O NONBLOCK|O LARGEFILE|O DIRECTORY) = 3
fstat64(3, {st mode=S IFDIR|0755, st size=4096, ...}) = 0
fcntl64(3, F SETFD, FD CLOEXEC)
getdents64(3, /* 21 entries */, 4096) = 664
getdents64(3, /* 0 entries */, 4096) = 0
close(3)
                                    = 3
open("/proc/meminfo", O RDONLY)
fstat64(3, {st mode=S IFREG|0444, st size=0, ...}) = 0
mmap2 (NULL, 4096, PROT READ | PROT WRITE,
MAP PRIVATE | MAP ANONYMOUS, -1, 0) = 0 \times 4023d000
read(3, "MemTotal: 6235008 kB\nMemFre"..., 4096) = 771
close(3)
munmap (0x4023d000, 4096)
fstat64(1, {st mode=S IFCHR|0620, st rdev=makedev(136, 1),
\dots\}) = 0
mmap2 (NULL, 4096, PROT READ | PROT WRITE,
MAP PRIVATE | MAP ANONYMOUS, -1, 0) = 0 \times 4023d000
write(1, "bitops.c copy page.S csum-"..., 87) = 87
```



#### **More Features of strace**

- The output may be captured to a file (-o file).
- Generate "time-stamped" output (-r).
- Show the time spent in each system call (-T).
- Follow fork's (-f).
- Limit tracing to a group of system calls (e.g. -e
   trace=file trace only file system related system calls).



#### **Printk**

- printk is the simplest debug technique.
- It allows reporting information from any place in the code.
- Yet, it has some downsides:
  - Too many messages, make it hard to identify situations for which you are actually debugging.
  - Messages that were printed during a system panic, are likely to be lost. They won't appear in /var/log/messages following the reboot.
  - Hard to debug hang conditions.
  - Require a "post debug" cleanup.



# /proc

- Many module activities, have a foot print in /proc:
  - Device numbers allocation / registration /proc/devices
  - Interrupt handler registration /proc/interrupts
  - Receipt of interrupts /proc/interrupts
  - Registration of I/O ports /proc/ioports
  - Registration of I/O memory /proc/iomem
  - Slab caches /proc/slabinfo



# /sys

- Kernel modules have a foot print in /sys
  - Module parameters, and their current values -/sys/module/<name>/parameters
  - What modules are referencing a module -/sys/module/<name>/holders
  - Device classes that are currently defined /sys/class
  - Device that are associated with a class -/sys/class/<class-name>
  - More...



# The /proc File System

- /proc is a collection of kernel functions that are logically laid out in a structure of a file system.
- Each /proc entry corresponds to kernel function(s), each responsible for implementing a file system operation (read, write, etc.).
- The functions are called when a /proc entry is accessed with a corresponding system call.
- The /proc file system does not consume any storage.



# The /proc File System - Continued

- The /proc file system is a linked list of structures that contain "file" names, access permissions, and pointers to functions.
- A read function that is associated with a /proc entry creates a byte stream that is returned, when the /proc entry is read from.
- A write function interprets and handles data that is written to a /proc entry.
- It is not mandatory to implement both read and write.



# **Using The /proc Filesystem**

- /proc provides a wealth of information, in addition to the per-process directories that have already been discussed:
  - Each entry in /proc/sys corresponds to a kernel tunable parameter. Writing to entries under /proc/sys alters the values of kernel parameters, and the system's behavior accordingly.
  - Module information.
  - File Systems information.
  - Device drivers information.
  - More..



# /proc API Change

- The old API for creating, and managing entries in /proc was retired in release 3.10 after 14+ years of faithful service (since release 2.2.26).
- The new API announces the full integration of the proc pseudo file system with the standard Linux file system API.
- The new API associates a file\_operations structure with each proc file system entry.
- The file\_operations structure grants the flexibility to expand the limited repertoire that was provided by the old API (only read and write).



## **Creating a Proc Entry**

- proc\_create\_data, creates a pseudo file in /proc that may be used for retrieving module information, and setting of module data.
- path is the path of the new proc entry that will be created.
  It may contain \'/es.
- mode is the creation mode of the proc entry. Symbolic constants for mode are defined in linux/stat.h>.



# **Creating a Proc Entry - Continued**

- parent is the proc\_dir\_entry of the directory to which path is relative. path will be created relative to /proc when parent is null.
- proc\_fops is the set of file operations that are applicable to the proc entry.
- data is a block of data that will be assigned as this entries private data.

data is very useful when a set of proc file operations is to be used with multiple proc entries (e.g. in per process directories).



## **Removing a Proc Entry**

```
#include <linux/proc_fs.h>
void proc_remove (struct proc_dir_entry *pentry);
```

- proc\_remove, removes a proc entry that was previously created.
- pentry is the proc\_dir\_entry to remove.



## **A Mystery Solved**

- The old /proc API passed proc\_dir\_entry->data as an argument to the reader, and writer functions.
- The new file operations based API lacks this argument. How can proc\_dir\_entry->data be accessed and made use of?
- The long answer:
  - The proc\_inode structure embeds VFS's inode structure, and a pointer to the proc dir entry.
  - Use container\_of to acquire a pointer to the proc\_inode, during open.



## **A Mystery Solved - Continued**

The short answer:

Call PDE, from your open file operation, and set
 filp->private\_data to the returned pointer.

```
#include <linux/proc_fs.h>
static struct proc_dir_entry *PDE(const struct inode *inode)
```



## **Extending The Proc API**

- The proc API supports has several additional operations:
  - proc\_symlink Create a symbolic link under /proc.
  - proc mkdir Create a directory under /proc.
  - proc\_set\_user Set the user and grop of a proc entry.
  - remove\_proc\_subtree Remove an entire subtree under /proc.
  - more ...



#### **Exercise**

- Extend the net filter that you implemented in the previous chapter to cache the source of the last 50 arp replies.
- As a part of your net filter module, implement a /proc file that will list the MAC addresses of remote hosts, that are currently cached by it.



# debugfs

- debugfs is a RAM based file system intended for debugging purposes -
  - The use of /proc should be limited to process information and management.
  - An implementer of an entry in /sys is required to adhere to a policy of "single value per file".

None of the constraints listed above is imposed on debugfs.



# debugfs

- debugfs first appeared in Linux 2.6.10.
- debugfs support is enabled at
   Kernel hacking->Debug Filesystem
- Use the following command to mount debugfs:

```
mount -t debugfs nodev /sys/kernel/debug
```

- Various kernel modules have built in debugfs entries.
- Linux provides a simple API for adding debugfs entries.



#### a Scenario For Using debugfs

The author of a kernel module may maintain a buffer, in which module events may be recorded:

- Time stamp
- PID
- Module function name
- Event type (e.g. function called, function returned, etc.)
- Event data (e.g. function arguments, return value, etc.)

 A debugfs entry may be used to represent the data in the buffer in a human readable form.



## **Creating debugfs Entries**

```
#include <linux/debugfs.h>
struct dentry
*debugfs_create_dir(const char *name, struct dentry *parent);
```

 A directory called name will be created within the directory described by parent.

 The directory will be created under debugfs' root when parent is NULL.

ERR\_PTR (-ENODEV) is returned to indicate that debugfs is not configured.



## **Creating debugfs Entries**

- A regular file called name will be created under parent.
- The files access permissions will be per mode.
- The operations possible will be defined by fops. A minimum of read, and / or write is required.
- data will be assigned to the i\_private field of the inode, thus making it available to the file operations.

#### **Removing debugfs Entries**

```
#include <linux/debugfs.h>
void debugfs_remove(struct dentry *dentry);
void debugfs_remove_recursive(struct dentry *dentry);
```

 debugfs\_remove, removes the entry described by dentry.

 debugfs\_remove\_recursive, removes all the file system sub-structure rooted at dentry.



# **eBPF - The Extended Berkeley Packet Filter**

The Berkeley packet filter (AKA BPF) originated in 1992 with the purpose of avoiding the flow on un-needed network packets from the kernel to user space.

BPF implements a virtual machine that executes byte code.

 The byte code gets injected from user space, and implements that rules by which packets get filtered.



# **eBPF - The Extended Berkeley Packet Filter**

- The ability to filter packets as early as possible, is extremely useful for network traffic monitoring software, such as tepdump that heavily relies on it.
- tcpdump is an application that represents a model in which there are far more packets that are of no interest than packets that require processing.
- In such a model, the ability to discard unneeded packets as early as possible saves both CPU and memory resources.



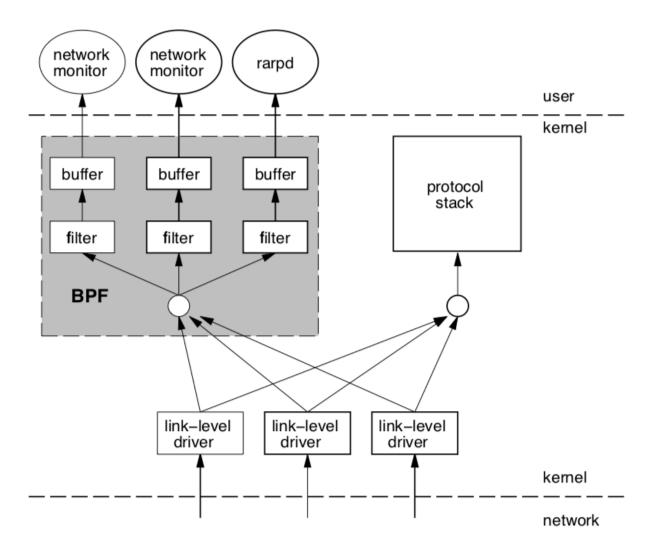
## **eBPF - The Extended Berkeley Packet Filter**

BPF was completely reshaped on 2013 by Alexei
 Starovoitov, to acquire its contemporary sense as an extended BPF.

 The original implementation of BPF is nowadays known as cBPF – classic Berkeley Packet Filter.







Michele Di Stephano – Berkeley Packet Filter: Theory, Practice & Perspectves



#### **cBPF Byte Code Example**

 Assuming that a packet is an ethernet packet, keep it only if it is an IPv4 packet:

The pseudo Assembly instructions above end up as the following byte code:

```
{ 0x28, 0, 0, 0x0000000c },
{ 0x15, 0, 1, 0x00000800 },
{ 0x6, 0, 0, 0x00040000 },
( 0x6, 0, 0, 0x00000000 }
```

```
This code may be generated by macro expansion:

BPF STMT (BPF LD+BPF H+BPF ABS, 12)
```



#### **cBPF Concerns**

- Injection of user space code into the kernel rises some concerns such as:
  - The code might read, or write kernel memory beyond the scope of the sk\_buff that it is supposed to handle.
  - The code might cause a kernel hang, or a kernel crash.
- These concerns are handled by a verifier that examines the filter code to assure that all instructions are valid, there are no backward jumps, and no jumps or memory references that are out of scope.



#### **eBPF**

- eBPF made its debut in kernel 3.15.
- It extends the functionality of the cBPF virtual machine to the extent of making it possible to write kernel code beyond packet / system call filtering, while preserving kernel / user space boundaries.
- It allows kernel / user space communication via data structures known as maps.



#### **eBPF Architecture**

- The number of general purpose registers has been increased to 11 32/64 bit registers.
- The instruction set has been extended to include some real CPU instructions (mostly derived from x86\_64).
- eBPF supports multiple program types:
  - BPF\_PROG\_TYPE\_SOCKET\_FILTER Retains the cBPF functionality.
     It attaches to a socket, and is applied to every sk\_buff that is associated with that socket.



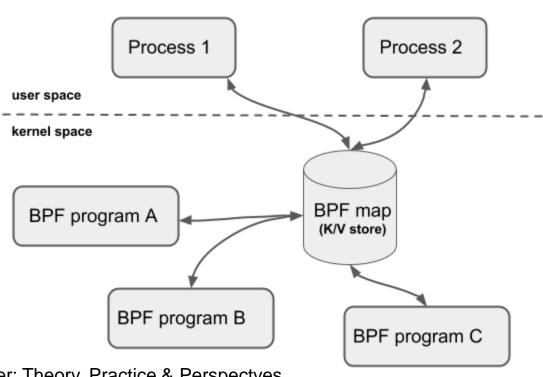
#### **eBPF Architecture**

- BPF\_PROG\_TYPE\_XDP eXpress Data Path. This type of program execute as close as possible to the hardware. It has 3 possible modes of operation:
  - driver Code is executed by the driver. The driver must have XDP support.
  - generic Code is executed at a higher level in the stack.
  - hardware offload Code is executed directly on the NIC
- BPF\_PROG\_TYPE\_TRACEPOINT Used for kernel instrumentation.
- Helper functions A subset of the kernel functions that eBPF code may call. The callable functions vary, depending on the program type.



#### **eBPF Architecture**

- BPF Maps Data structures that allow communication between user space programs and eBPF programs.
- BPF maps may be use to maintain states.
- Maps are key, value pairs, that have an arbitrary user defined structure.



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# **Running eBPF Code**

- eBPF has concerns, similar to these of cBPF. Hence, eBPF code is verified when it is loaded into the kernel. eBPF has implemented its own verifier that is far more complex than the verifier that was available with cBPF.
- All the operation that relate to eBPF are done with the system call bpf.
- eBPF programs are written in restricted C (a subset of C), and compiled by //vm/clang that generates the byte code.



# **Running eBPF Code**

- The user-space code loads the eBPF program into the kernel specifying the program type, which determines accessible kernel's functions.
- The kernel checks if the program is safe through the verifier.
- The kernel, if possible and if it is desirable, JIT-compiles the eBPF bytecode to native machine code, otherwise the program is interpreted.



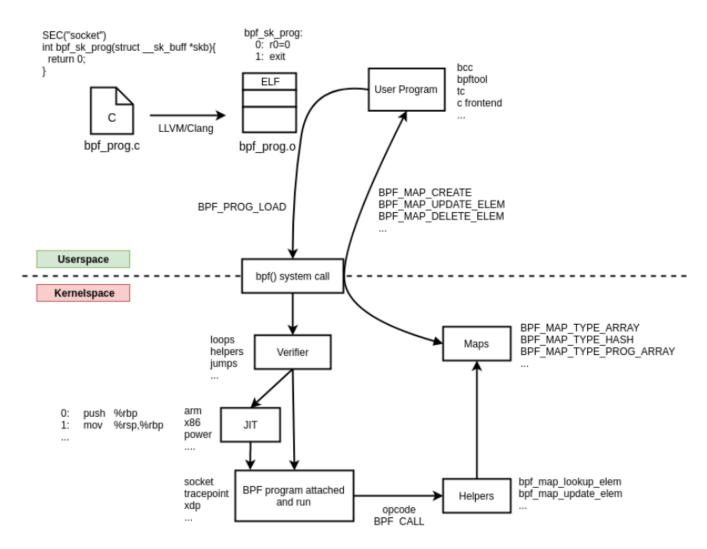
# **Running eBPF Code**

 The injected code is attached to an event and is executed every time that event occurs.

 The loaded code through the helpers can write data to maps and ring-buffers and the user-space code can read/write from them.



#### **eBPF Usage Overview**



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## **eBPF** pre-requisites

- The kernel should be build with the following features enabled:
  - General setup->Enable bpf() system call
  - Mernel hacking->
     Compile-time checks and compiler options->
     Compile the kernel with debug info->
     Generate BTF typeinfo
- Failing to set the later will trigger unexpected program crashes



# **Available eBPF Program collections**

- The Linux kernel source provides a collection of eBPF programs that were written in restricted C.
  - Compile with make M=samples/bpf/ (assuming that your in the build directory.
- The bcc collection provide a python module that provides the "glue" between python and eBPF's C based API, along more that 200 eBPF based tools.



## **kprobes**

- Kernel probes are a method for collecting debugging and performance information at (almost) any arbitrary point in the kernel.
- Kernel probes are dynamically inserted and removed, without touching the code being probed.
- Probe types:
  - kprobe May monitor any kernel instruction.
  - jprobe Monitor entry to kernel functions.
  - kretprobe Monitor return of kernel functions.



#### **Implementing Kernel Probes**

- Kernel probes are implemented as kernel modules.
- A kernel probe module:
  - Implements functions that report values of variables, and / or registers (e.g. printk, dedicated debugfs entries, etc.).
  - Registers the functions to be triggered when a specific code address is reached (module's init function).
  - Un-registers the functions (module's exit function).
- Each probe type has a type specific API, defined in linux/kprobes.h>



## **kprobes - Probing Functions**

- The struct kprobe argument<sup>†</sup>, is the structure that was used to register this kprobe. It may be embedded into a structure, accessible via container\_of, that may provide additional data to the probe.
- The struct pt\_regs argument, stores the saved values of the CPU registers that were saved, when the probed address was hit.



# **kprobes - Probing Functions**

 The pre\_handler function is executed before the probed instruction is executed.

- The return value of the pre\_handler indicates whether:
  - pt\_regs were altered return 1.
  - Otherwise, return 0.



# **kprobes - Probing Functions**

- The post\_handler function is executed after the probed instruction has completed.
- The flags argument should indicate the probe's status flags. Yet, it seems that it is not used and o is always passed here.

 See <u>Documentation/kprobe.txt</u> for additional probing functions.



# **kprobes - Registration**

Preparing the kprobe structure:

```
static struct kprobe kp = {
   .addr = <instruction-address>,
   .pre_handler = my_pre_hdlr,
   .post_handler = my_post_hdlr,
};
```

Registration:

```
ret = register_kprobe (&kp);
```

- Returns 0 on success, otherwise a negated error code.
- Un-Registration:

```
unregister_kprobe (&kp);
```



## **jprobes Entry Function**

```
// Function to probe (defined elsewhere):
int probed_func (int i, char c) {
    . . . .
}
// The jprobe entry function:
static int jprobed_func (int i, char c) {
    . . . .
    jprobe_return ();
    return 0;
}
```

- The arguments of a jprobe entry function, have to be identical to these of the probed function.
- The function should always call jprobe\_return(), to transfer control back to the kernel probes subsystem.



# jprobes - Registration

Preparing a jprobe structure:

```
static struct jprobe jp = {
    .entry = jprobed_func,
    .kp = {
        .symbol_name = "probed_func",
     },
};
```

Registration:

```
ret = register_jprobe (&jp);
```

Un-Registration:

```
unregister_jprobe (&jp);
```



## **kretprobe - Entry & Return Functions**

- The kretprobe entry function is called when the probed function is entered.
- The kretprobe return function is called when the probed function returns.
- The struct kretprobe\_instance communicates data between the entry and return functions.
- The struct pt regs is the set of saved CPU registers.



#### kretprobe - kretprobe\_instance

```
struct kretprobe_instance {
   struct hlist_node hlist;
   struct kretprobe *rp;
   kprobe_opcode_t *ret_addr;
   struct task_struct *task;
   char data[0];
};
```

- The fields that are relevant to the entry and return functions are:
  - rp The struct kretprobe† with which this kretprobe was registered.
  - task The task\_struct associated with this instance.
  - data Arbitrary data for communication between entry and return functions.



#### **kretprobe - Accessing Instance Data**

```
/* per-instance private data */
struct my data {
        ktime t entry stamp;
};
/* Here we use the entry handder to timestamp function entry */
static int entry handler(struct kretprobe instance *ri,
                                                struct pt regs *regs)
        struct my data *data;
        if (!current->mm)
                return 1;
                                /* Skip kernel threads */
        data = (struct my data *)ri->data;
        data->entry stamp = ktime get();
        return 0;
```



# **kretprobes - Registration**

Preparing a kretprobe structure:

Registration:

```
ret = register_kretprobe (&krp);
```

• Un-Registration:

```
unregister_kretprobe (&krp);
```



## **Kernel Probes - Tips**

- When the probed address is not in the beginning if a function:
  - Compile the kernel with "CONFIG DEBUG INFO = y".
  - Use 'objdump -d -l vmlinux' to obtain source to object mapping.
- When probes are applied to functions symbol\_name may be used to specify the probed function. This requires "CONFIG\_KALLSYMS\_ALL" to be set to "y".



#### Magic sysrq

- Magic SysRq This is a "magical" key to which the kernel will respond regardless what it is doing.
- Configuring the Magic SysRq:
  - Kernel hacking->Magic SysRq Key sets CONFIG\_MAGIC\_SYSRQ to Y.
- Enabling the Magic SysRq:

```
# echo 1 > /proc/sys/kernel/sysrq
```

 Magic SysRq command may be entered writing to /proc/sysrqtrigger.



#### **Magic SysRq - Commands**

- b Request an immediate reboot without unmounting or synching disks.
- h Display a help message, that describes all the Magic SysRq commands.
- 1 Request a back trace of all the active CPU's.
- s Request an emergency sync of all mounted file systems.
- g Enter the kernel debugger.



# Kgdb

- Kgdb Is implemented by a stub that behaves like gdbserver
- Kgdb requires a debug host with the following elements:
  - A copy of the kernel image running on the target host.
  - The source tree that was used to build the kernel of the target host.
  - gdb , or a cross debugger (when the target system is an embedded system).
- Kgdb is a source level symbolic debugger.



#### Kdb

 kdb implements a shell on the system that is being debugged.

 kdb is accessible via the system's console, and may be redirected to any of the system' serial ports

kdb's shell implements a rich set of commands.

kdb is an assembly level debugger.



#### Kdb

 kdb is designed to be extensible by developers of modules to suit their module's requirements.

Details and an example how to add commands to kdb can be found in: <kernel-root>/samples/kdb/kdb\_hello.c

• kdb was contributed to Linux, as a patch, by Sgi on 2002. Yet, it was integrated into the main line Linux kernel in version 2.6.35.



# A Sample kdb Session (RPI 2b)+

Enable the Magic SysRq:

```
# echo 1 > /proc/sys/kernel/sysrq
```

Set the serial port that the debugger will interact with:

```
# echo "ttyAMA0,115200" >/sys/module/kgdboc/parameters/kgdboc
```

Use the Magic SysRq to escape into the debugger:

```
# echo g > /proc/sysrq-trigger
[ 7623.603732] SysRq : DEBUG

Entering kdb (current=0xb922bf40, pid 3088) on processor 0 due to Keyboard Entry
[0]kdb>
```



#### A Sample kdb Session (RPI 2b)+

Display kdb's help:

```
[0]kdb> help
                 [<vaddr>]
                                      Set/Display breakpoints
bp
bl
                 [<vaddr>]
                                      Display breakpoints
bc
                 <bpnum>
                                      Clear Breakpoint
                                      Enable Breakpoint
                 <bpnum>
be
bd
                 <bpnum>
                                      Disable Breakpoint
                                      Single Step
SS
```

Display the stack trace:

# A Sample kdb Session (RPI 2b)†

Leave kdb and resume kernel execution:

```
[0]kdb> go
#
```



#### **Panic**

 The term panic applies to a condition when the kernel cannot continue execution, due to a severe internal inconsistency.

 If kernel dumps are enabled, the crash dump of the kernel may be used after reboot, to analyze the cause for the panic.



#### **Oops**

- An oops may be looked upon as a "civilized panic".
- An oops will occur when a severe condition, that would have otherwise caused a panic, can be associated with a specific process.
- When an oops occurs, the offending process is killed.
- The kernel logs a call trace when an oops occurs. The call trace may be used to debug the cause for the oops.



# **Handling a Grave Condition**

- A grave condition in the context of the kernel, is a condition at which something bad that has no possible recovery, has been detected (e.g. a device driver has failed to initialize it's file\_operations structure).
- The macro <u>Bug\_on</u> will assert a condition to check if a grave condition has incurred.
- If the assertion is true, it is assumed that a grave condition has incurred, BUG ON will panic the system.
- Example panic the system if a pointer is null:
  - BUG ON (ptr == 0);



## WARN\_ON

 The macro warn\_on can be viewed upon as a civilized version of BUG\_ON. It will issue a warning when the assertion succeeds, but will not panic the system.

- Example issue a warning if no data is available:
  - WARN\_ON (data\_avail == 0);

