

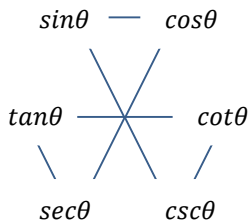
Derivatives (도함수)

$$\frac{df(x)}{dx} = \lim_{h \rightarrow 0} \frac{f(x+h) - f(x)}{h} = f'(x)$$

Natural logarithm (자연 로그)

$$e^x = \lim_{n \rightarrow \infty} \left(1 + \frac{x}{n}\right)^n$$

Trigonometric Function (삼각 함수)



$$\sin^2 \theta + \cos^2 \theta = 1$$

$$\tan^2 \theta + 1 = \sec^2 \theta$$

$$1 + \cot^2 \theta = \csc^2 \theta$$

$$\sin(A \pm B) = \sin A \cos B \pm \cos A \sin B$$

$$\cos(A \pm B) = \cos A \cos B \mp \sin A \sin B$$

$$\tan(A \pm B) = \frac{\tan A \pm \tan B}{1 \mp \tan A \tan B}$$

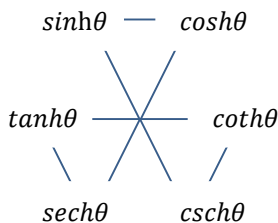
$$\sin(A+B) + \sin(A-B) = 2 \sin A \cos B$$

$$\sin(A+B) - \sin(A-B) = 2 \cos A \sin B$$

$$\cos(A+B) + \cos(A-B) = 2 \cos A \cos B$$

$$\cos(A+B) - \cos(A-B) = -2 \sin A \sin B$$

Hyperbolic Function (쌍곡선 함수)



$$\sinh \theta = \frac{e^\theta - e^{-\theta}}{2}$$

$$\cosh \theta = \frac{e^\theta + e^{-\theta}}{2}$$

$$\tanh \theta = \frac{\sinh \theta}{\cosh \theta}$$

$$-\sinh^2 \theta + \cosh^2 \theta = 1$$

$$-\tanh^2 \theta + 1 = \operatorname{sech}^2 \theta$$

$$-1 + \coth^2 \theta = \operatorname{csch}^2 \theta$$

$$\sinh(A \pm B) = \sinh A \cosh B \pm \cosh A \sinh B$$

$$\cosh(A \pm B) = \cosh A \cosh B \pm \sinh A \sinh B$$

$$\tanh(A \pm B) = \frac{\tanh A \pm \tanh B}{1 \pm \tanh A \tanh B}$$

$$\sinh(A+B) + \sinh(A-B) = 2 \sinh A \cosh B$$

$$\sinh(A+B) - \sinh(A-B) = 2 \cosh A \sinh B$$

$$\cosh(A+B) + \cosh(A-B) = 2 \cosh A \cosh B$$

$$\cosh(A+B) - \cosh(A-B) = 2 \sinh A \sinh B$$

$$\sinh' x = \cosh x$$

$$\cosh' x = \sinh x$$

$$\tanh' x = \operatorname{sech}^2 x$$

Gamma Function

$$\Gamma(n) = \int_0^\infty e^{-x} x^{n-1} dx \quad (n > 0)$$

$$\Gamma(n+1) = n\Gamma(n)$$

$$\Gamma(n) = (n-1)!$$

$$\Gamma\left(\frac{1}{2}\right) = \sqrt{\pi}$$

$$\int_0^\infty e^{-\alpha x} x^n dx = \frac{\Gamma(n+1)}{\alpha^{n+1}}$$

$$\int_0^\infty e^{-\alpha x^2} x^n dx = \frac{1}{2} \frac{\Gamma\left(\frac{n+1}{2}\right)}{\alpha^{\frac{n+1}{2}}}$$

Complex Number

$$e^{iy} = \cos y + i \sin y$$

$$\sin z = \frac{e^{iz} - e^{-iz}}{2i}$$

$$\cos z = \frac{e^{iz} + e^{-iz}}{2}$$

$$\sinh z = \frac{e^z - e^{-z}}{2}$$

$$\cosh z = \frac{e^z + e^{-z}}{2}$$

1계 상미분방정식

변수 분리법

$$g(y)y' = f(x) \rightarrow g(y)dy = f(x)dx$$

$$\rightarrow \int g(y)dy = \int f(x)dx + c$$

확장방법

$$u = \frac{y}{x} \rightarrow y = ux \rightarrow y' = u'x + u$$

$$y' = f\left(\frac{y}{x}\right) \rightarrow u'x + u = f(u) \rightarrow u'x = f(u) - u$$

$$\rightarrow \frac{du}{f(u) - u} = \frac{dx}{x} \rightarrow \int \frac{1}{f(u) - u} du = \int \frac{1}{x} dx + c$$

전미분, 완전미분방정식

$$du = f_x(x, y)dx + f_y(x, y)dy = \frac{\partial u}{\partial x}dx + \frac{\partial u}{\partial y}dy$$

완전미분방정식의 필요충분조건

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

적분인자

$$Pdx + Qdy = 0$$

$$F(x) = \exp\left(\int \frac{1}{Q}\left(\frac{\partial P}{\partial y} - \frac{\partial Q}{\partial x}\right)dx\right)$$

완전미분방정식의 해법

$du = M(x, y)dx + N(x, y)dy = 0$ 에서 필요충분조건 검사
완전미분방정식이 아닐 때, 적분인자를 곱함.

$$\frac{\partial u}{\partial x} = M(x, y) \xrightarrow{x\text{에 대하여 적분}} u(x, y) = \int M(x, y)dx + k(y)$$

$$\frac{\partial u}{\partial y} = N(x, y) \rightarrow \frac{dk}{dy} \rightarrow k(y)$$

$$\therefore u(x, y) = \int M(x, y)dx + k(y)$$

$$\xrightarrow{\text{검증}} du = \frac{\partial u(x, y)}{\partial x} dx + \frac{\partial u(x, y)}{\partial y} dy = 0$$

$$\rightarrow du = M(x, y)dx + N(x, y)dy = 0$$

제차 미분방정식의 해법(변수 분리법)

$$y' + p(x)y = 0 \rightarrow \frac{dy}{dx} - p(x)y \rightarrow \frac{dy}{y} - p(x)dx$$

$$\rightarrow \ln|y| = -\int p(x)dx + c_0 \rightarrow y = c_1 e^{-\int p(x)dx}$$

비제차 미분방정식의 해법(완전미분방정식의 해법 응용)

$$y' + p(x)y = r(x) \rightarrow \frac{dy}{dx} + p(x)y - r(x) = 0$$

$$\rightarrow dy + (py - r)dx = 0 \rightarrow Q = 1, P = py - r$$

$$\rightarrow \frac{\partial P}{\partial y} = p \neq 0 = \frac{\partial Q}{\partial x} (\because \text{완전미분형이 아님})$$

-적분인자 구하기

$$R = \frac{1}{Q} \left(\frac{\partial P}{\partial y} - \frac{\partial Q}{\partial x} \right) = p (\because Q = 1) \rightarrow F = e^{\int p dx}$$

-적분인자 곱하여 해 구하기

$$(py - r)dx + dy = 0$$

$$\xrightarrow{\text{적분인자 곱하기}} e^{\int p dx} (py - r)dx + e^{\int p dx} dy = 0 = du$$

$$\frac{\partial u}{\partial y} = e^{\int p dx} \xrightarrow{y\text{에 대하여 적분}} u(x, y) = ye^{\int p dx} + l(x)$$

$$\frac{\partial u}{\partial x} = pye^{\int p dx} + l'(x) = e^{\int p dx} (py - r)$$

$$\rightarrow l'(x) = -re^{\int p dx} \rightarrow l(x) = -\int re^{\int p dx} dx + c$$

$$\therefore u = ye^{\int p dx} - \int re^{\int p dx} dx = c$$

$$\rightarrow ye^{\int p dx} = \int re^{\int p dx} dx + c$$

$$\therefore y = e^{-\int p dx} (\int re^{\int p dx} dx + c)$$

2계 선형상미분방정식

차수 축소법

$$y'' + p(x)y' + q(x)y = 0 \xrightarrow{\text{when know } y_1} y = y_2 = uy_1$$

$$\rightarrow y' = y_2' = y_1' u + uy_1'$$

$$\rightarrow y'' = y_2'' = u''y_1 + 2u'y_1' + uy_1''$$

$$\xrightarrow{\text{대입}} (u''y_1 + 2u'y_1' + uy_1'') + p(u'y_1 + uy_1') + quy_1 = 0$$

$$\xrightarrow{\text{divide } y_1} u'' + \left(2\frac{y_1'}{y_1} + p \right) u' = 0$$

$$\xrightarrow{u=u', u'=u''} U' + \left(2\frac{y_1'}{y_1} + p \right) U = 0$$

$$\rightarrow \frac{dU}{U} = -\left(2\frac{y_1'}{y_1} + p \right) dx \rightarrow \ln|U| = -2\ln|y_1| - \int p dx$$

$$\therefore U = \frac{1}{y_1^2} e^{-\int p dx}, \quad y_2 = uy_1 = y_1 \int U dx$$

상수계수를 갖는 2계 제차 선형상미분방정식

$$y'' + ay' + by = 0 \xrightarrow{\text{특성방정식}} \lambda^2 + a\lambda + b = 0$$

$$\lambda = \frac{-a \pm \sqrt{a^2 - 4b}}{2}$$

case I) if $a^2 - 4b > 0 \rightarrow$ two real roots

case II) if $a^2 - 4b = 0 \rightarrow$ a real double root

case III) if $a^2 - 4b < 0 \rightarrow$ complex conjugate roots

Summary of Cases I-III

Case	Basis of	General Solution of
I	$e^{\lambda_1 x}, e^{\lambda_2 x}$	$y = c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x}$
II	$e^{-\lambda}, x e^{-\lambda}$	$y = (c_1 + c_2 x) e^{\lambda x}$
III	$e^{-\frac{a}{2}x} \cos \omega x$ $e^{-\frac{a}{2}x} \sin \omega x$	$y = e^{-\frac{a}{2}x} (A \cos \omega x + B \sin \omega x)$

$$\omega = \frac{i}{2} \sqrt{a^2 - 4b}$$

비감쇠 시스템

$$my'' + ky = 0 \rightarrow y(t) = A \cos \omega_0 t + B \sin \omega_0 t$$

$$= C \cos(\omega_0 t - \delta), \quad \omega_0^2 = \frac{k}{m}$$

감쇠 시스템

$$my'' + cy' + ky = 0$$

case I) if $c^2 - 4mk > 0 \rightarrow$ 과감쇠

case II) if $c^2 - 4mk = 0 \rightarrow$ 임계감쇠

case III) if $c^2 - 4mk < 0 \rightarrow$ 저감쇠

비제차방정식과 일반해

$$y'' + p(x)y' + q(x)y = r(x)$$

$$y(x) = y_h(x) + y_p(x)$$

미정계수법

$r(x)$ 의 항	y_p 에 대한 선택
ke^{rx}	Ce^{rx}
$kx^n (n = 0, 1, \dots)$	$K_n x^n + K_{n-1} x^{n-1} + \dots + K_0$
$k \cos \omega x, k \sin \omega x$	$K \cos \omega x + M \sin \omega x$
$ke^{ax} \cos \omega x, ke^{ax} \sin \omega x$	$e^{ax} (K \cos \omega x + M \sin \omega x)$

미정계수법을 위한 법칙

기본법칙 - 비제차방정식에서 $r(x)$ 가 미정계수법의 열에 있는 함수 중의 하나라면, 대응하는 함수 y_p 를 선택하고, y_p 와 그 도함수를 비제차방정식에 대입하여 미정계수를 결정.

변형법칙 - y_p 로 선택된 항이 비제차 방정식에 대응하는 제차방정식의 해가 된다면, x 또는 x^2 을 곱한다.

합법칙 - $r(x)$ 가 첫번째 열에 있는 함수의 합일 경우, 두 번째 열의 대응하는 줄에 있는 함수들의 합으로 ky_p 를 선택한다.

비감쇠강제진동

주기적인 외력

$$my'' + ky = F_0 \cos \omega t$$

$$\rightarrow y = C \cos(\omega_0 t - \delta) + \frac{F_0}{m(\omega_0^2 - \omega^2)} \cos \omega t, \omega_0^2 = \frac{k}{m}$$

맥놀이 현상

$$my'' + ky = F_0 \cos \omega t$$

$$\rightarrow y = C \cos(\omega_0 t - \delta) + \frac{F_0}{m(\omega_0^2 - \omega^2)} \cos \omega t$$

$$\rightarrow y = \frac{F_0}{m(\omega_0^2 - \omega^2)} (\cos \omega t - \cos \omega_0 t)$$

공진

$$my'' + ky = F_0 \cos \omega_0 t$$

$$\rightarrow y = C \cos(\omega_0 t - \delta) + \frac{F_0}{2m\omega_0} t \sin \omega t$$

오일러-코시 방정식

$$x^2 y'' + ax y' + by = 0$$

$$y = x^m, y' = mx^{m-1}, y'' = m(m-1)x^{m-2}$$

$$x^2 y'' + ax y' + by = m(m-1)x^m + amx^m + bx^m = 0$$

$$\xrightarrow{\text{divide } x^m} m(m-1) + am + b = m^2 + (a-1)m + b = 0$$

case I) if two real roots

$$y = c_1 x^{m_1} + c_2 x^{m_2}$$

case II) if a real double root

$$y = (c_1 + c_2 \ln x) x^m$$

case III) if complex conjugate roots

$$y = x^\mu [A \cos(v \ln x) + B \sin(v \ln x)], m = \mu \pm iv$$

전기회로

$$E_R = Ri, \quad E_L = L \frac{di}{dt}, \quad E_C = \frac{1}{C} \int i dt$$

$$E_R + E_L + E_C = E(t)$$

$$\rightarrow L \frac{dl}{dt} + RI \frac{1}{C} \int I dt = E(t)$$

$$\rightarrow L \frac{d^2 l}{dt^2} + R \frac{dl}{dt} + \frac{1}{C} I = E'(t)$$

매개변수 변환법

$$y'' + p(x)y' + q(x)y = r(x)$$

$$\rightarrow y_h = c_1 y_1 + c_2 y_2, \quad y_p = u(x)y_1 + v(x)y_2$$

$$\xrightarrow{u'y_1 + v'y_2 = 0} u'y_1' + v'y_2' = r(x)$$

$$\xrightarrow{W=y_1 y_2' - y_2 y_1'} u' = -\frac{y_2 r}{W}, \quad v' = \frac{y_1 r}{W}$$

$$u = -\int \frac{y_2 r}{W} dx, \quad v = \int \frac{y_1 r}{W} dx$$

$$\therefore y_p(x) = -y_1 \int \frac{y_2 r}{W} dx + y_2 \int \frac{y_1 r}{W} dx$$

고계 선형상미분방정식