Machine Learning (CSE 446): Pratical issues: optimization and learning

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Announcements

- Midterm summary:
 - stats: 71.5 std: 18
 - ► Office hours today: 1:15-2:30 (No office hours on Monday)
- ► Monday: John Thickstun guest lecture

 ► Grading: ~a ld scheme

 ► HW3 posted

 Since Hw

 Since
- - will be periodically updated for typos/clarifictions
 - extra credit posted soon
- ► Today:
 - Midterm review
 - GD/SGD: practical issues

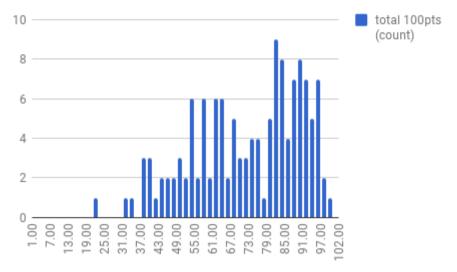


$$(X_1, X_2) \longrightarrow (X_1, X_2, X_1^2, X_2^2)$$

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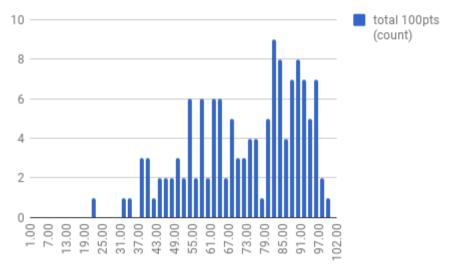
Midterm

Distribution of Midterm Scores



What is a good model of this distribution?

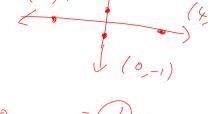
Distribution of Midterm Scores

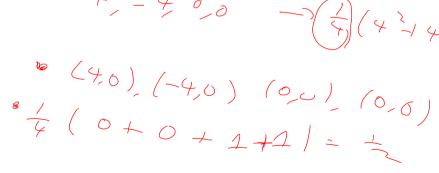


What is a good model of this distribution?

"A mixture of Gaussians"

Midterm Q4: scratch space when it has a solution (=) liner-ly solemble Midterm: scratch space





$$(4,0), (-4,0), (0,0), (0,0)$$



Midterm: scratch space

Today

The "general" Loss Minimization Problem

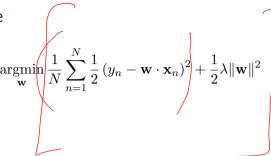
$$\mathbf{w}^* = \underset{\mathbf{w}}{\operatorname{argmin}} \frac{1}{N} \sum_{n=1}^{N} \underbrace{\ell(\mathbf{x}_n, y_n, \mathbf{w})}_{\ell_n(\mathbf{w})} + R(\mathbf{w})$$

How do we run GD? SGD? Which one to use?

How do run them?

Our running example

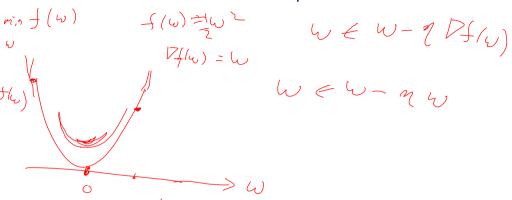
► GD? SGD?



▶ Note we are computing an average. What is a crude way to estimate an average?

Will it converge?

How does GD behave? A 1-dim example



GD: How do we set the step sizes?

- ► Theory:
 - square loss:
 - more generally:
- Practice:
 - square loss:
 - more generally:

try things out

to get it stable

► Do we decay the stepsize?

SGD for the square loss

```
 \begin{aligned} \mathbf{Data} &: \mathsf{step \ sizes} \ \langle \eta^{(1)}, \dots, \eta^{(K)} \rangle \\ \mathbf{Result} &: \mathsf{parameter \ w} \\ &\mathsf{initialize} \colon \mathbf{w}^{(0)} = \mathbf{0}; \\ \mathbf{for} \ k \in \{1, \dots, K\} \ \mathbf{do} \\ & \quad \mid \ n \sim \mathsf{Uniform}(\{1, \dots, N\}); \\ & \quad \mid \mathbf{w}^{(k)} = \mathbf{w}^{(k-1)} + \eta^{(k)} \left(y_n - \mathbf{w}^{(k-1)} \cdot \mathbf{x}_n\right) \mathbf{x}_n; \\ \mathbf{end} \\ &\mathsf{return \ w}^{(K)}; \end{aligned}
```

SGD for the square loss

```
 \begin{aligned} \mathbf{Data} &: \mathsf{step \ sizes} \ \langle \eta^{(1)}, \dots, \eta^{(K)} \rangle \\ \mathbf{Result} &: \mathsf{parameter \ w} \\ &\mathsf{initialize} \colon \mathbf{w}^{(0)} = \mathbf{0}; \\ \mathbf{for} \ k \in \{1, \dots, K\} \ \mathbf{do} \\ & \quad \mid \ n \sim \mathsf{Uniform}(\{1, \dots, N\}); \\ & \quad \mid \mathbf{w}^{(k)} = \mathbf{w}^{(k-1)} + \eta^{(k)} \left(y_n - \mathbf{w}^{(k-1)} \cdot \mathbf{x}_n\right) \mathbf{x}_n; \\ \mathbf{end} \\ &\mathsf{return \ w}^{(K)}; \end{aligned}
```

- ▶ where did the *N* go?
- ► regularization?
- minibatching?

SGD: How do we set the step sizes?

► Theory:

- ► Practice:
 - ► How do start it?
 - ▶ When do we decay it?

Stochastic Gradient Descent: Convergence

$$\mathbf{w}^* = \operatorname*{argmin}_{\mathbf{w}} \frac{1}{N} \sum_{n=1}^{N} \ell_n(\mathbf{w})$$

- $\mathbf{w}^{(k)}$: our parameter after k updates.
- ► Thm: Suppose $\ell(\cdot)$ is convex (and satisfies mild regularity conditions). There is decreasing sequence of step sizes $\eta^{(k)}$ so that our function value, $F(\mathbf{w}^{(k)})$, converges to the minimal function value, $F(\mathbf{w}^*)$.
- ► GD vs SGD: we need to turn down our step sizes over time!

Making features: scratch space