# Machine Learning

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### 1 Regression

### 1.1 Linear regression

### 1.1.1 Squared error cost function

Measures how well line fits training data

$$J(w,b) = \frac{1}{2m} \sum_{i=1}^{m} (\hat{y}^{(i)} - y^{(i)})^2$$

m = num of training examples

 $y^{(i)} = \text{training example}$ 

 $\hat{y}^{(i)} = wx^{(i)} + b$ 

 $\frac{1}{m}$  finds average error for larger data sets,  $\frac{1}{2m}$  makes later calculations neater

### 1.1.2 Gradient descent

Find w, b for minimum of cost function J(w, b)

- 1. Start with some w, b (commonly 0, 0)
- 2. Look around starting point and find direction that will move the point furthest downwards for a small step size

 $\alpha = \text{learning rate}$ 

Must simultaneously update w and b

$$w_1 = w_0 - \alpha \frac{\partial}{\partial w} J(w_0, b_0)$$

$$b_1 = b_0 - \alpha \frac{\partial}{\partial b} J(w_0, b_0)$$

$$\frac{\partial}{\partial w} J(w, b) = \frac{1}{m} \sum_{i=1}^{m} (\hat{y}^{(i)} - y^{(i)}) x^{(i)}$$

$$\frac{\partial}{\partial b} J(w, b) = \frac{1}{m} \sum_{i=1}^{m} (\hat{y}^{(i)} - y^{(i)})$$

### 1.2 Multiple linear regression

 $n_f = \text{number of features}$ 

m = number of data points

 $\vec{w} = \text{vector of length } n_f$ 

X is a matrix of size  $m \times n_f$ 

Sum of predictions of all features is the prediction of multiple linear reg

$$f_{\vec{w},b}(\vec{x}) = \vec{w} \cdot \vec{x} + b$$

Gradient descent

$$\vec{w}_j = \vec{w}_j - \alpha \frac{\partial}{\partial \vec{w}_j} J(\vec{w}, b)$$
$$b = b - \alpha \frac{\partial}{\partial b} J(\vec{w}, b)$$

Cost function and its partial derivatives

$$J(\vec{w}, b) = \frac{1}{2m} \sum_{i=0}^{m-1} (f_{\vec{w}, b}(X^{(i)}) - y^{(i)})^2$$
$$\frac{\partial}{\partial \vec{w}_j} J(\vec{w}, b) = \frac{1}{m} \sum_{i=0}^{m-1} (f_{\vec{w}, b}(X^{(i)}) - y^{(i)}) x_j^{(i)}$$
$$\frac{\partial}{\partial b} J(\vec{w}, b) = \frac{1}{m} \sum_{i=0}^{m-1} (f_{\vec{w}, b}(X^{(i)}) - y^{(i)})$$

### 1.3 Logistic regression

Sigmoid function

$$g(z) = \frac{1}{1 + e^{-z}}$$
$$0 < g(z) < 1$$

From sigmoid function to logistic regression formula

$$z = \vec{w} \cdot \vec{x} + b$$
$$f_{\vec{w},b}(\vec{x}) = g(z)$$

The output of f can be interpreted as the "probability" that class is 1.

ex.  $f_{\vec{w},b}(\vec{x}) = 0.7$  means there is a 70% chance y is true

Logistic regression requires a new cost function because  $f_{\vec{w},b}(\vec{x})$  for logistic regression is non-convex, trapping gradient descend in local minima.

Cost function

$$J(\vec{w}, b) = \frac{1}{m} \sum_{i=1}^{m} L(f_{\vec{w}, b}(\vec{x}^{(i)}), y^{(i)})$$

$$L(f_{\vec{w}, b}(\vec{x}^{(i)}), y^{(i)}) = \begin{cases} -\log(f_{\vec{w}, b}(\vec{x}^{(i)}) & \text{if } y^{(i)} = 1\\ -\log(1 - f_{\vec{w}, b}(\vec{x}^{(i)})) & \text{if } y^{(i)} = 0 \end{cases}$$

Simplified form

$$L(f_{\vec{w},b}(\vec{x}^{(i)}), y^{(i)}) = -y^{(i)}\log(f_{\vec{w},b}(\vec{x}^{(i)})) - (1 - y^{(i)})\log(1 - f_{\vec{w},b}(\vec{x}^{(i)}))$$

The loss function will decrease as f approaches  $y^{(i)}$  on a graph of L vs f.  $\frac{\partial J(\vec{w},b)}{\partial w_j}$  and  $\frac{\partial J(\vec{w},b)}{\partial b}$  are the same as in linear regression, just the definition of f has changed.

### 1.4 Softmax regression

Generalization of logistic regression, y can have more than two possible values.

The most probable value of y is the value that when given to L yields the largest loss.

Calculate  $z_i$  with  $\vec{x}$  only consisting of data points that have label i?

 $n_f = \text{num features}$ 

 $n_y = \text{number of possible } y \text{ outputs}$ 

W is now a matrix of dimensions  $n \times n_f$ .

 $\vec{b}$  is now a vector of length  $n_y$ .

$$1 \le i \le n_y$$

$$z_i = \vec{W}_i \cdot \vec{x} + b_i$$

$$a_i = \frac{e^{z_i}}{\sum_{k=1}^{n_y} e^{z_k}}$$

$$L(\vec{a}, y) = \begin{cases} -\log a_1 & \text{if } y = 1\\ -\log a_2 & \text{if } y = 2\\ & \vdots\\ -\log a_n & \text{if } y = n \end{cases}$$
(1)

### 1.5 Feature scaling: z-score normalization

After z-score normalization, all features will have a mean of 0 and a standard deviation of 1

 $\mu_i = \text{mean of all values for feature } j$ 

 $\sigma_j = \text{standard deviation of feature } j$ 

$$x_j^{(i)} = \frac{x_j^{(i)} - \mu_j}{\sigma_j}$$

$$\mu_j = \frac{1}{m} \sum_{i=0}^{m-1} x_j^{(i)}$$

$$\sigma_j^2 = \frac{1}{m} \sum_{i=0}^{m-1} (x_j^{(i)} - \mu_j)^2$$

### Over / underfitting

Underfit / high bias: does not fit training set well  $(wx + b \text{ fit onto data points with } x + x^2 \text{ shape})$ 

Overfit / high variance: fits training set extremely well but does not generalize well  $(w_1x + w_2x^2 +$  $w_3x^3 + w_4x^4 + b$  fit onto training set of shape  $x + x^2$  can have zero cost but predicts values outside the training set inaccurately)

Addressing overfitting

- Collect more data
- Select features ("Feature selection")
- Reduce size of parameters ("Regularization")

#### 1.6.1Regularization

Small values of  $w_1, w_2, \dots, w_n, b$  for simpler model, less likely to overfit

Given n features, there is no way to tell which features are important and which features should be penalized, so all features are penalized.

$$J_r(\vec{w}, b) = J(\vec{w}, b) + \frac{\lambda}{2m} \sum_{j=1}^n w_j^2$$

Can include b by adding  $\frac{\lambda}{2m}b^2$  to  $J_r$  but typically doesn't make a large difference. The extra term in  $J_r$  is called the regularization term.

Effectively,  $\lambda \propto \frac{1}{w}$ . When trying to minimize cost, either the error term or the regularization term must decrease. The larger the lambda, the more the regularization term should decrease to minimize cost, decreasing w parameters.

### Regularized linear regression

$$J_r(\vec{w}, b) = \frac{1}{2m} \sum_{i=1}^m \left[ (f_{\vec{w}, b}(\vec{x}^{(i)}) - y^{(i)})^2 \right] + \frac{\lambda}{2m} \sum_{i=1}^n w_j^2$$

For gradient descent, only  $\frac{\partial J_r}{\partial w_i}$  changes (b is not regularized):

$$\frac{\partial J_r}{\partial w_j} = \frac{1}{m} \sum_{i=1}^{m} \left[ (f_{\vec{w},b}(\vec{x}^{(i)}) - y^{(i)}) x_j^{(i)} \right] + \frac{\lambda}{m} w_j$$

### Regularized logistic regression

$$J_r(\vec{w}, b) = \frac{1}{m} \sum_{i=1}^m L(f_{\vec{w}, b}(\vec{x}^{(i)}), y^{(i)}) + \frac{\lambda}{2m} \sum_{j=1}^n w_j^2$$

For gradient descent, only  $\frac{\partial J_r}{\partial w_i}$  changes (b is not regularized):

$$\frac{\partial J_r}{\partial w_j} = \frac{1}{m} \sum_{i=1}^{m} \left[ (f_{\vec{w},b}(\vec{x}^{(i)}) - y^{(i)}) x_j^{(i)} \right] + \frac{\lambda}{m} w_j$$

### 2 Neural networks

 $n_{\ell} = \text{num layers excluding input}$   $n_{n}^{[\ell]} = \text{n neurons in layer } \ell$   $n_{f} = \text{num features}$   $\vec{W}$  is a vector (length  $n_{\ell}$ ) of matrices of size  $n_{n}^{[\ell]} \times n_{f}$   $\vec{x}$  is a vector of outputs from each neuron in previous layer  $\vec{b}$  is a vector (length  $n_{\ell}$ ) of vectors (length  $n_{n}^{[\ell]}$ )  $\vec{z}$  and  $\vec{a}$ : same dimensions as  $\vec{b}$  g: activation function  $1 \leq i \leq n_{\ell}$ 

$$\begin{split} \vec{z}_i^{[\ell]} &= \vec{W}_i^{[\ell]} \vec{x} + \vec{b}_i^{[\ell]} \\ \vec{a}^{[\ell]} &= g(\vec{z}^{[\ell]}) \end{split}$$

a (activation) = scalar output of a single neuron

Superscript [i] is used to notate information relating to the ith layer in a neural network. Activation functions are functions a neuron uses to output a value, more in section 2.2. ReLU activation function:  $g(z) = \max(0, z)$ 

### 2.1 Choosing an activation function

sigmoid:  $a = \frac{1}{1+e^{-z}}$ tanh:  $a = \frac{e^z - e^{-z}}{e^z + e^{-z}}$ ReLU:  $a = \max(0, z)$ 

Leaky ReLU:  $a = \max(\epsilon z, z)$  where  $\epsilon$  is a small nonzero positive value < 1

### For output layer

Binary classification, y = 0 or 1: use sigmoid Regression,  $y \in \mathbb{R}$ : use linear activation function

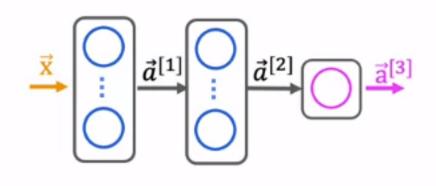
Regression,  $y \ge 0$ : use ReLU

### For hidden layer

ReLU is most common

### 2.2 Layer types

### Dense layer



Activation value of unit (neuron) j in layer  $\ell$ 

$$a_j^{[\ell]} = g(\vec{w}_j^{[\ell]} \cdot \vec{a}^{[\ell-1]} + b_j^{[\ell]})$$

Input layer is  $\ell = 0$ .

### Convolutional layer

Each neuron only looks at a part of the previous layer's output.

May have faster computation, and needs less training data (less prone to overfitting)