

Texture

Where are we?

- 3D scene
 - Object
 - Shape
 - Material
 - Scattering
 - **Texture**
 - Camera
 - Light
 - Rendering
 - Image
-
- ```
graph LR; A[3D scene] --> B[Texture]; B --> C[Texture]; C --> D[Texture]
```

# Introduction

# Texture

- Term **texture** is used differently in various disciplines and everyday life: texture of fabric, texture of food, texture in music, texture in image processing, texture in...
- Texture doesn't have well established definition. It spans over multiple scales and over space.
- Texture is something we perceive based on geometrical, physical and chemical properties of objects



# Texture

- For vision, surface texture is its look and feel
  - Bark of a tree, surface of stones, oil painting, etc.
- <IMAGE>

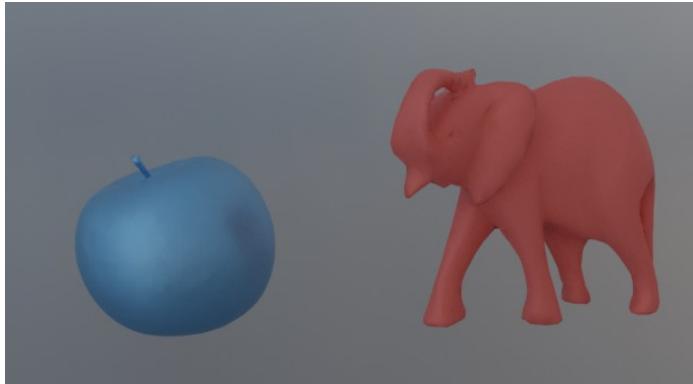
# Big picture



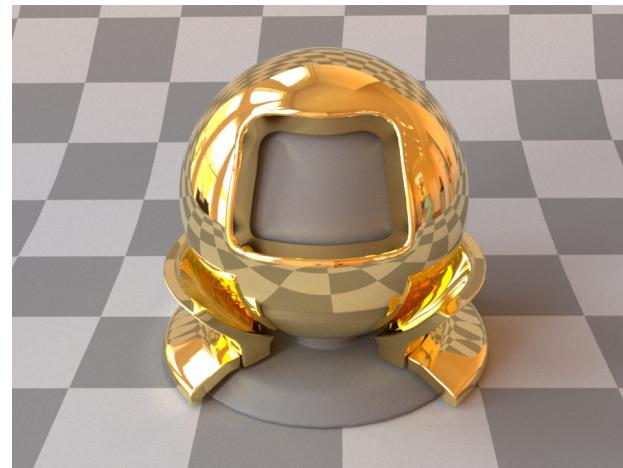
# Material characteristics

- Characteristics that needed to be modeled in order to obtain required appearance. We can classify any material by following variations:

Spectral: color



Directional



Spatial



# Texture in computer graphics

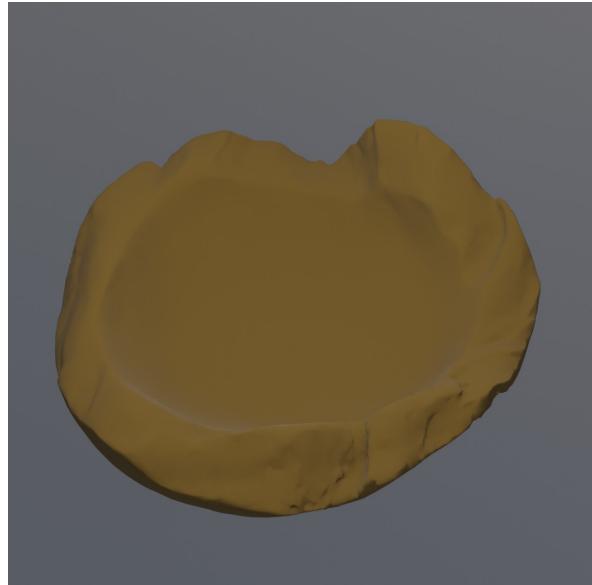
- For 3D modeling, we can try to define texture as function which **varies material properties over surface**.



# Variation of material over surface

- Real objects rarely have only one material or same material properties over the surface → **homogeneous material**
  - Example: wood has structural texture (e.g., grain) at a scale of about 1mm. Also it has cellular texture at lower scale. The material of wood fiber is different. Therefore, the rich appearance of wood comes from material variation of fibers. This richness is called **texture**.

Homogeneous materials look too smooth and perfect.  
Missing details, variations and imperfections.



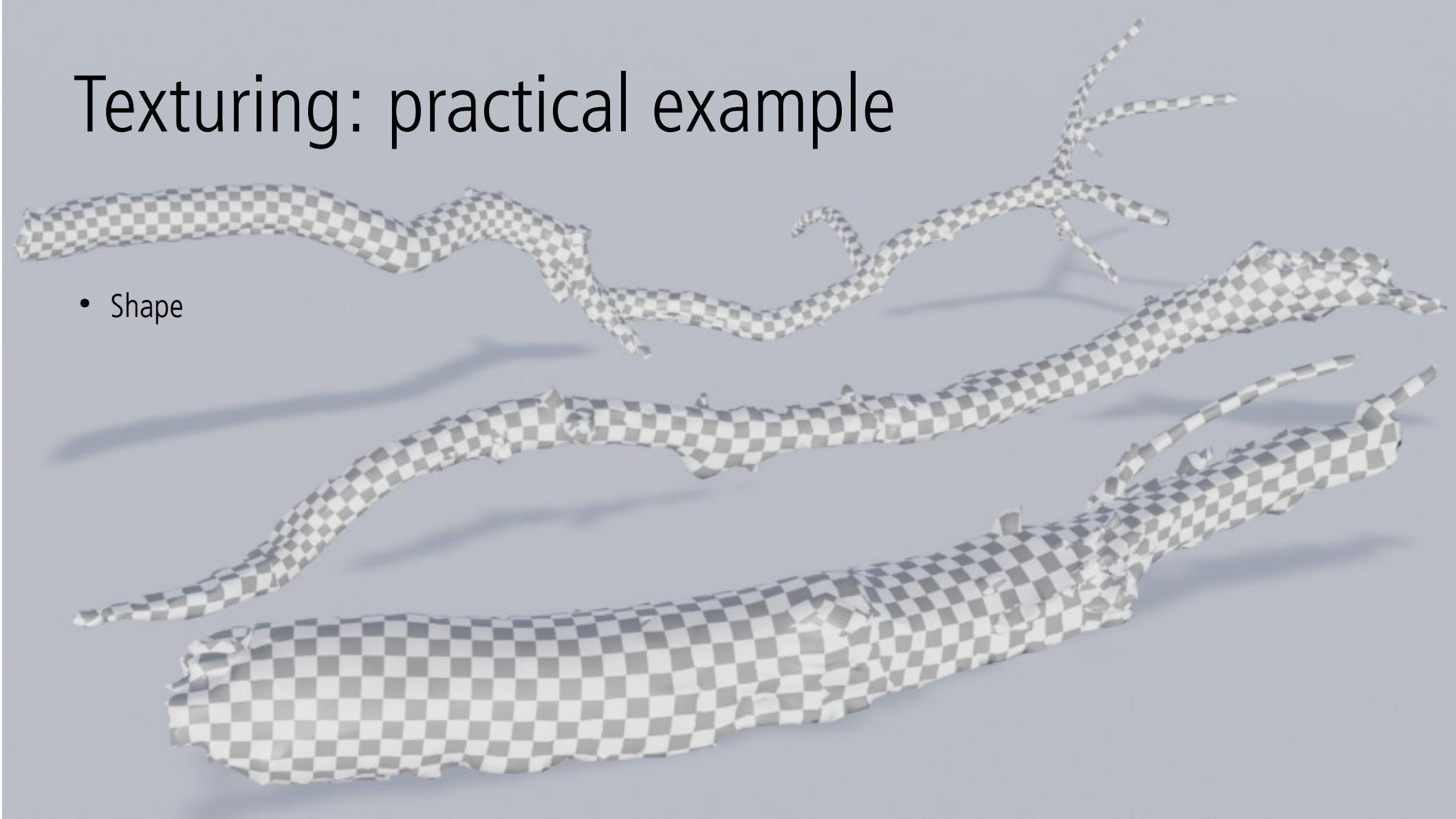
# Texture

- Visual variation on the object surface – **spatial variation**:
  - Directional or color characteristics → **scattering function parameters**
  - Small-scale geometrical characteristics: bumps, pores, imperfections, etc. → **surface normals**
- In computer graphics, **texturing** is process that takes surface and modifies its appearance at each location using image, function or other data source.
  - Used to add details\* and richness to surfaces

\* Remember that computer graphics is all about simulation and approximation in order to achieve required appearance. It is a trade-off between quality and speed. Depending on viewing distance and size of objects in 3D scene, some details can be represented with lower quality. For example, modeling all details on geometrical (shape) level can be very expensive. Thus, texturing come in which represent cheaper way to model details.

# Texturing: practical example

- Shape



- 
- Shape
  - Scattering function (diffuse)
    - Albedo parameter (color) → texture variation



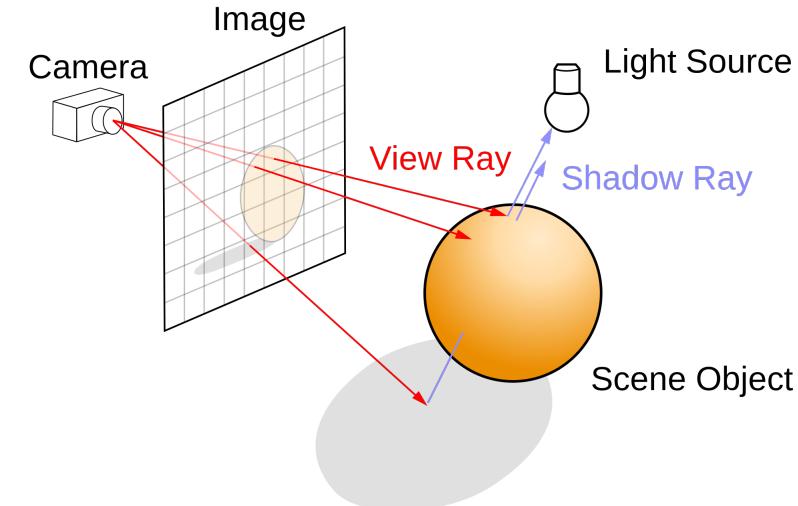
- Shape
- Scattering function (diffuse)
  - Albedo parameter (color) → texture variation
- Small-scale geometry (surface normals) → texture variation

# Texturing: variation

- Textures introduce
  - Scattering function parameters and color variation
  - Small-scale geometry variation → Shading normal variation
- Texturing scale
  - Variation on **microscale** → scattering function and color
  - Variation **mesoscale** → shading normal
  - **Macroscale** is given by the object shape.
- Different texturing algorithms with varying complexity and thus quality exists.

# Texture and rendering

- Rendering: computing color of pixels in an image
- Color of pixels → color of objects visible from camera
  - For each pixel, viewing ray is generated, traced into scene for closest intersection.
  - Color calculated at intersection → pixel color.
- **Shading:** calculating color at viewing ray intersection with object → **shading point**.



# Texture and shading

- Shading uses material, shape, viewing and light to calculate the color in shading point
- Material describes interaction of light with surface:
  - Scattering model
  - Texture model
- For each shading point, scattering model is evaluated using texture information at that point
- Final rendered image, due to variation of colors and intensities over object, the surface will contain pattern
  - Surface with pattern is called textured surface

# Note on “texture”

- Texture in material modeling context carries information needed for shading
  - For example, color of texture is not one on one in the rendered image – it is used to calculate that color.
- Texture function vs texture
  - Texture function defines shading parameters over object surface → something that we model
  - Texture is what we see as rendering result on a surface – a pattern
- Texture is generally overloaded term and it is furthermore overloaded in computer graphics and depends on context:
  - Texture can be used for modeling object appearance (material)
  - On GPU, texture, besides material modeling, can be used to store arbitrary data (e.g., geometry)

# Texturing pipeline

# Texturing pipeline: example



TODO

- Wooden floor
  - During rendering, **object position** (x,y,z) on wooden floor is found
  - **Projector function** finds mapping from (x,y,z) to (u,v). In this case simple projection can be used:  $u \sim = x$ ,  $v \sim = y$  so that u,v are in [0,1] – texture coordinates
  - **Corresponder function** uses texture coordinates for finding corresponding pixel in the image of wooden floor. If image has resolution 1024x1024 then pixel positions are integer of  $1024 \cdot u$ ,  $1024 \cdot v$
  - **Texture reading** is performed using texture space locations
  - Finally, color encoded in texture can not be directly used for rendering, **transformation on values** is done (e.g., sRGB → linear). Resulting values are used.
  - <ILLUSTRATE>

# Texturing pipeline

- Texturing: variation of shading parameters over surface – **position dependency**
- **Location in space of object**
  - Shading point → object-space coordinates
- **Projection function.**
  - Mapping process: object space coordinates → texture space coordinates
- **Corresponder function**
  - Transform texture coordinates in **texture space locations**
- **Obtaining texture values (sampling)**
  - Texture space location is used for obtaining texture value
- **Value transform**
  - Optional additional transformations are done on texture value
- **Usage**
  - Final value is used to modify property of surface at that point: scattering function parameter or normal.

Object space location

Projector function

Texture coordinate

Corresponder function

Texture space location

Texture obtain

Texture value

Value transform

Transformed value

Texturing pipeline.  
Some steps may be omitted  
depending on object types.

# Object space location

- Object surface location → intersection (shading) point
- World space object location can also be used
  - In this case, as object moves, the coordinates change!

Object space location

Projector function

Texture coordinate

Corresponder function

Texture space location

Texture obtain

Texture value

Value transform

Transformed value

# Projector function

- First step in texturing process:
  - Maps surface (**object**) location into **texture coordinate space**
  - Example: 3D object point to 2D space (s,t)
- Texture coordinates can be calculated:
  - On the fly during rendering
  - During object modeling and stored per-vertex – Modeling packages allow artists to edit (u,v) coordinates.
- Many possible ways of obtaining texture coordinates exists:
  - **Mesh unwrapping**
  - **Texture projections**

Object space location

Projector function

Texture coordinate

Corresponder function

Texture space location

Texture obtain

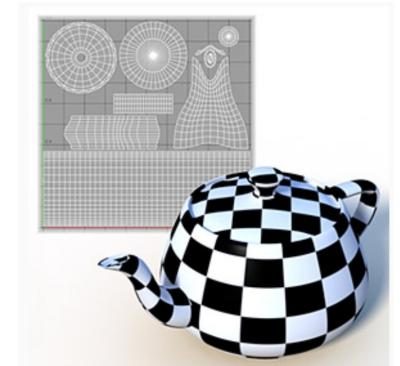
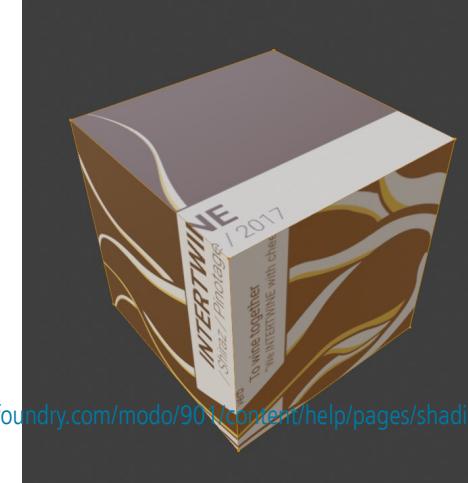
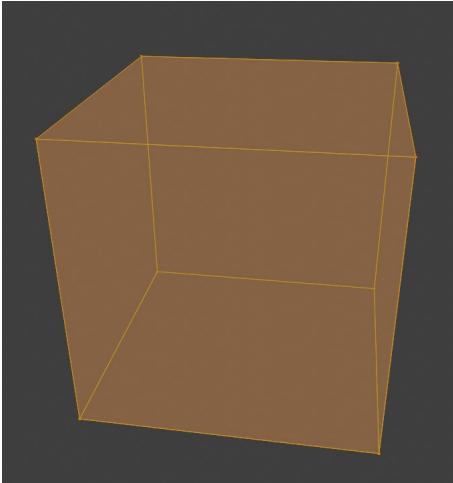
Texture value

Value transform

Transformed value

# Projector function: mesh unwrapping

- Mesh unwrapping tries to “unwrap” 3D surface onto 2D space so that each vertex is assigned with 2D texture coordinate (u,v)
- Unwrapping methods belongs to larger field called **mesh parametrization**
- Modeling packages offer different methods for unwrapping and a way to manually enhance the results
  - Goal is that each polygon gets fair share of texture area (e.g., evade stretching) but maintaining connectivity – which determines where separate parts of texture meet and visible seams.



# Projector function: texture projection

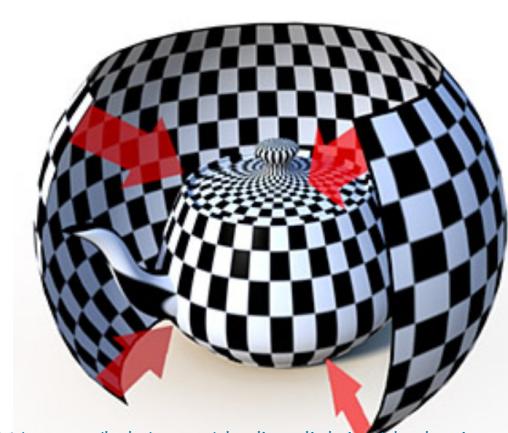
- The goal is to transform 3D point in space into texture coordinate\* using projections:
  - Spherical
  - Cylindrical
  - Planar
  - Cubic
  - Box
  - Front

[https://learn.foundry.com/modo/901/content/help/pages/shading\\_lighting/shader\\_items/projection\\_type\\_samples.html](https://learn.foundry.com/modo/901/content/help/pages/shading_lighting/shader_items/projection_type_samples.html)

\* Note that the goal is really to find texture coordinates and not to find a way of pasting a 2D image on 3D object. This is more general. Once texture coordinates are found, different types of textures can be used: image or procedural, etc.

# Projector function: spherical texture projection

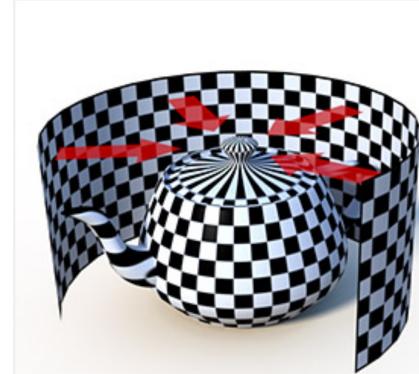
- Spherical: texture is wrapped into a spherical shape and projected onto a shape. Good for texturing round objects. Surfaces perpendicular to projection cause stretching



[https://learn.foundry.com/modo/901/content/help/pages/shading\\_lighting/shader\\_items/projection\\_type\\_samples.html](https://learn.foundry.com/modo/901/content/help/pages/shading_lighting/shader_items/projection_type_samples.html)

# Projector function: cylindrical texture projection

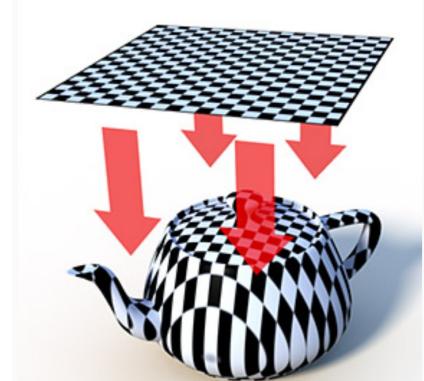
- Cylindrical: texture is wrapped in cylindrical shape and projected onto surface. Good for cylindrical surfaces (cans, bottles). Surfaces perpendicular to projection might cause stretching.



[https://learn.foundry.com/modo/901/content/help/pages/shading\\_lighting/shader\\_items/projection\\_type\\_samples.html](https://learn.foundry.com/modo/901/content/help/pages/shading_lighting/shader_items/projection_type_samples.html)

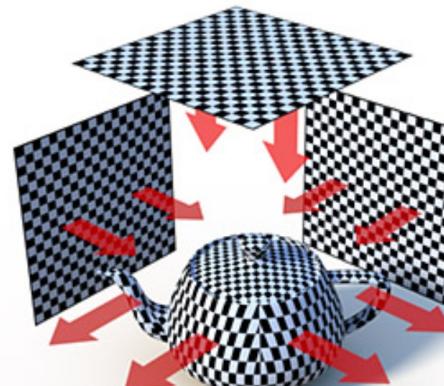
# Projector function: planar texture projection

- Planar: similar to concept of movie projector but image is projected orthographically. Great for flat or nearly flat surfaces. Other surfaces might cause stretching of texture. Any vector defining projection plane can be used. Useful for decals.



# Projector function: cubic texture projection

- Cubic: texture is planar-projected on a surface from all three axis directions, X, Y, and Z
- Polygon receives a certain projection, based on its normal direction.
- Best for cube-shaped objects, and occasionally on detailed surfaces where texture seams are not of great concern



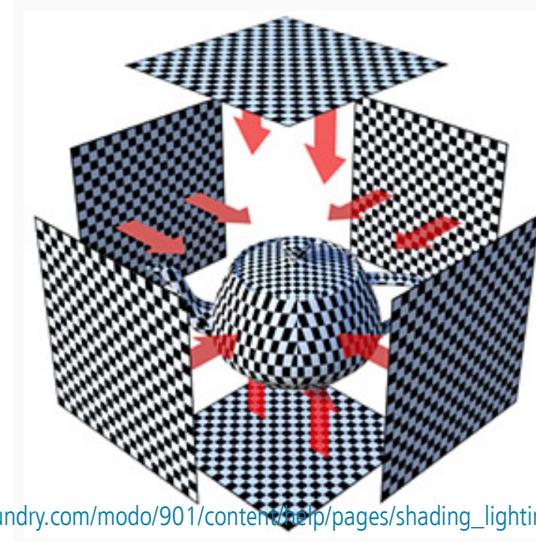
[https://learn.foundry.com/modo/901/content/help/pages/shading\\_lighting/shader\\_items/projection\\_type\\_samples.html](https://learn.foundry.com/modo/901/content/help/pages/shading_lighting/shader_items/projection_type_samples.html)

# Projector function: box texture projection

- Projects a texture in a planar fashion from all six directions, eliminating reverse projections on rear facing polygons inherent to the Cubic method (aka **triplanar mapping**)
- Best on cube-shaped objects, and occasionally on detailed surfaces where texture seams are not of great concern
  - For curved and tilted surfaces efficient **blending** of multiple projection planes must be used.



<https://ryandowlingsoka.com/unreal/triplanar-dither-biplanar/>



[https://learn.foundry.com/modo/901/content/help/pages/shading\\_lighting/shader\\_items/projection\\_type\\_samples.html](https://learn.foundry.com/modo/901/content/help/pages/shading_lighting/shader_items/projection_type_samples.html)

# Projector function: front texture projection

- Texture is projected out from a camera or light's position



[https://learn.foundry.com/modo/901/content/help/pages/shading\\_lighting/shader\\_items/projection\\_type\\_samples.html](https://learn.foundry.com/modo/901/content/help/pages/shading_lighting/shader_items/projection_type_samples.html)

# Projector function: complex shapes

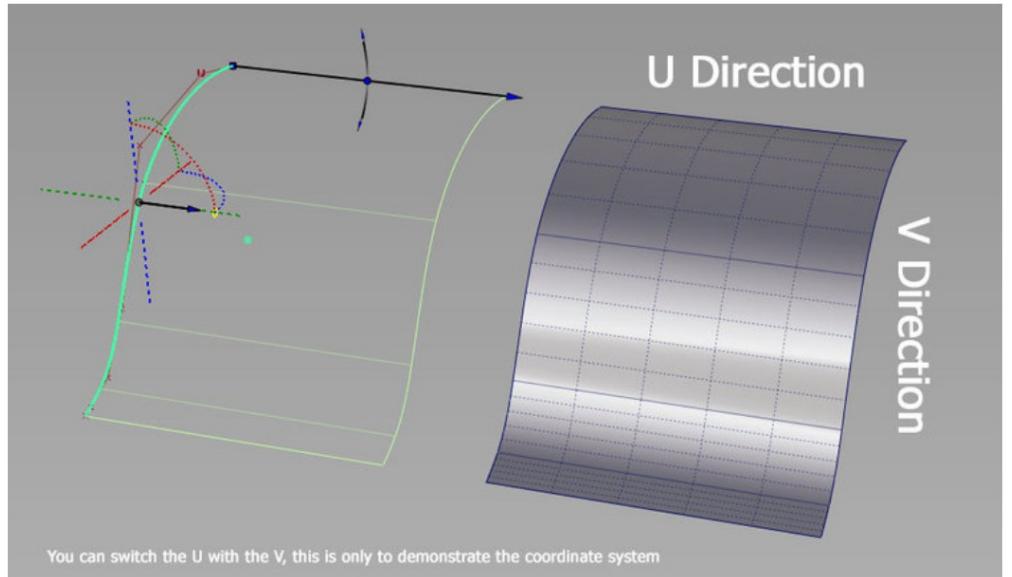
- For highly complex shapes, separating into simpler shapes can be done and then texture projection can be done separately.
- [983] Pagán, Tito, "Efficient UV Mapping of Complex Models," *Game Developer*, vol. 8, no. 8, pp. 28-34, August 2001

# Projector function: different approaches

- If object is supplied with any kind of additional information (e.g., curvature or temperature) this can be used for texture coordinate generation
  - Main point is that texture coordinates must be generated in this step. Using position and normal for deriving those is only one way of doing it.

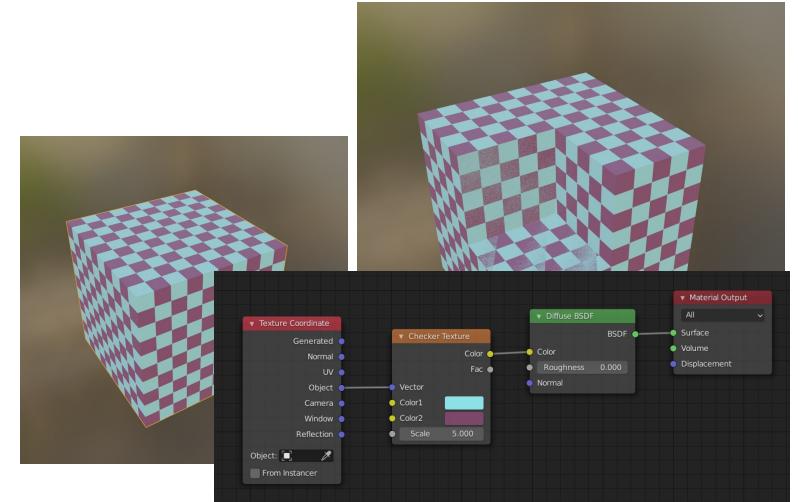
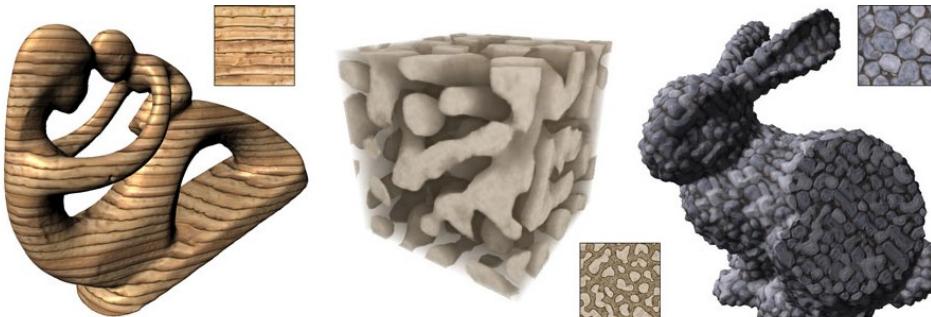
# Projector function: inherent texture coordinates

- Parametric surfaces (e.g., NURBS) have natural set of (u,v) which defines any (x,y,z) point on surface
- In this case, we can say that surface representation already has inherent texture coordinates and projector function is not needed.



# Projector function: different texture coordinates

- Texture coordinate space doesn't have to be always 2D
- If texture is used for volumetric objects, then texture coordinates are (u,v,w)
  - procedural texturing can directly rely on object locations (x,y,z) – solid texturing.
- For animation, texture coordinates can be (u,v,w,t) where t is time and determines change in texture



# Projector function: multiple texture coordinates

- Multiple textures can be applied on objects and thus multiple sets of texture coordinates can be applied
- Idea is the same: those texture coordinates are interpolated across surface and used for obtaining texture value
- <example of multiple textures>

# Corresponder function

- Transform texture coordinates in **texture space locations**
  - For image texture, this might be indices to retrieve pixel values
  - For procedural texture, this might be domain of procedural function
- Task: convert texture coordinates to texture space locations
  - e.g.,  $(u,v)$  coordinate to pixel index in image

Object space location

Projector function

Texture coordinate

Corresponder function

Texture space location

Texture obtain

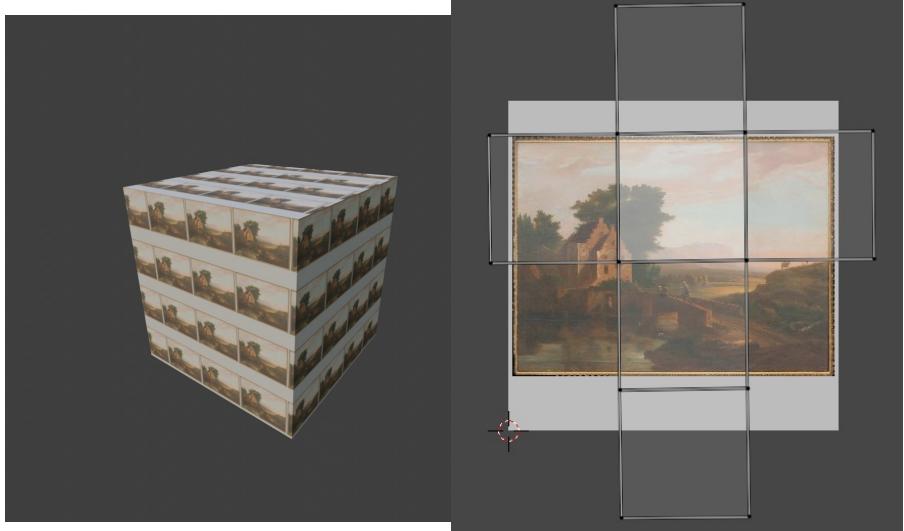
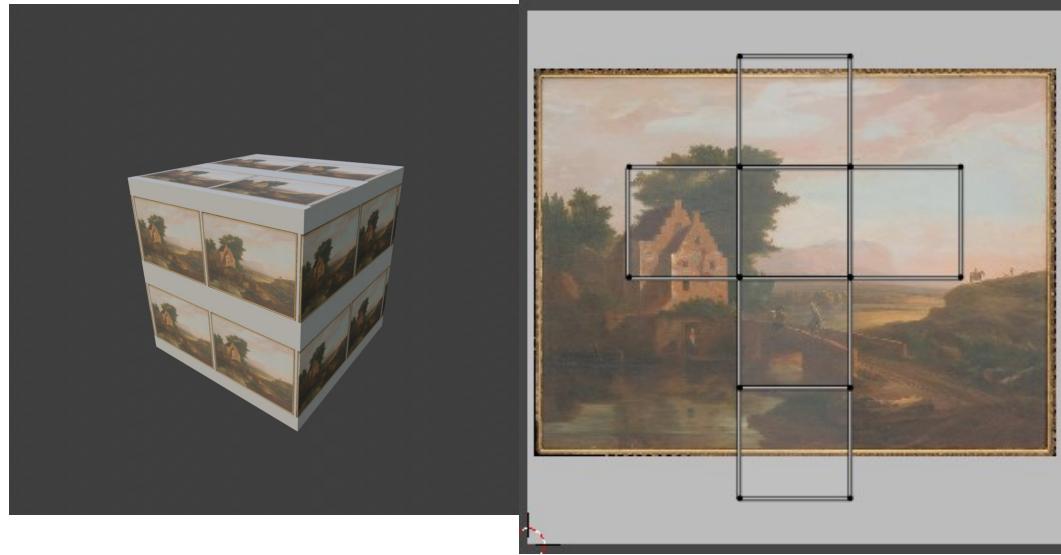
Texture value

Value transform

Transformed value

# Corresponder function

- Corresponder function:
  - Determine part of texture will be used
  - Transformations: rotate, scale, translate, shear or project
  - How image is applied if  $(u,v)$  is larger than 1 or smaller than 0: repeat (other: wrap, mirror, clamp, border, wang tiles, etc.)



Demo:

# Obtaining texture values

- Texture space location is used for obtaining texture value reading image texture or evaluating procedural texture

Object space location

Projector function

Texture coordinate

Corresponder function

Texture space location

Texture obtain

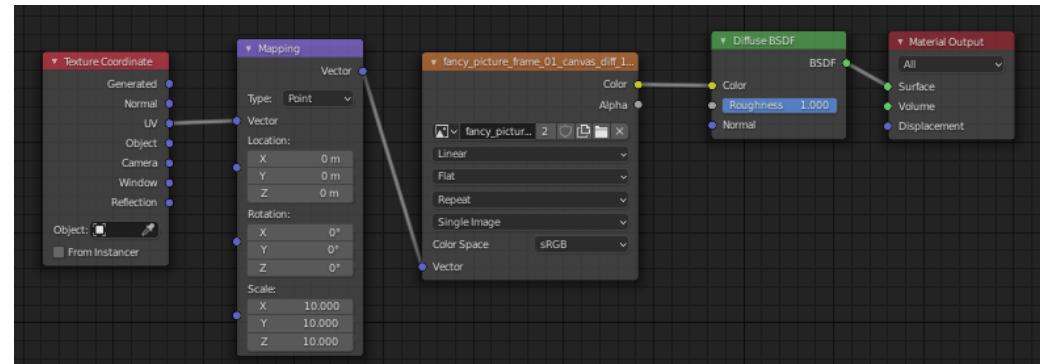
Texture value

Value transform

Transformed value

# Obtaining texture values

- Correspondence function gave texture space coordinates
- Those coordinates are used for:
  - Obtaining image texture values
  - Evaluating procedural textures values



# Transforming texture values

- Optional additional transformations are done on texture value

Object space location

Projector function

Texture coordinate

Corresponder function

Texture space location

Texture obtain

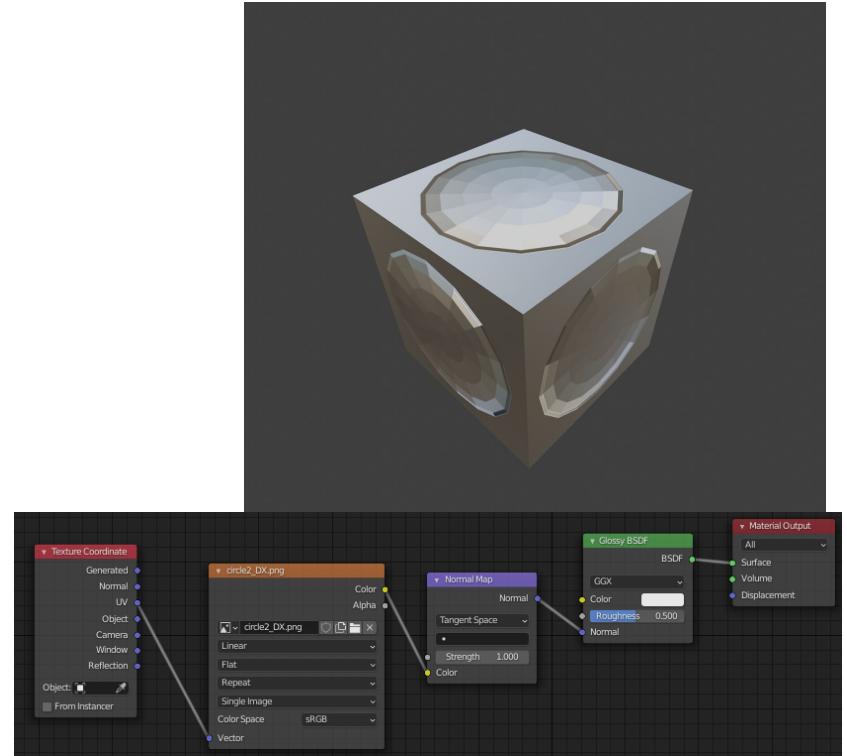
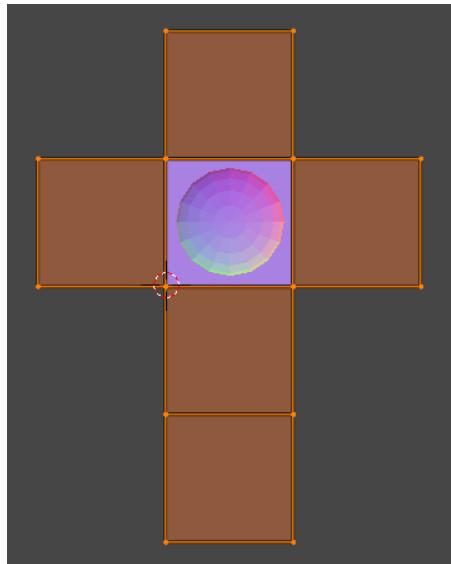
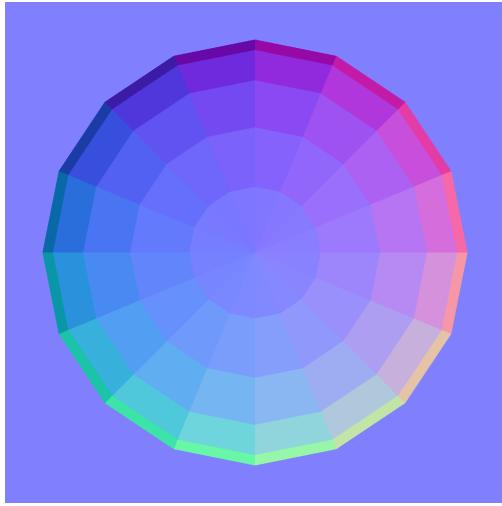
Texture value

Value transform

Transformed value

# Transforming texture values

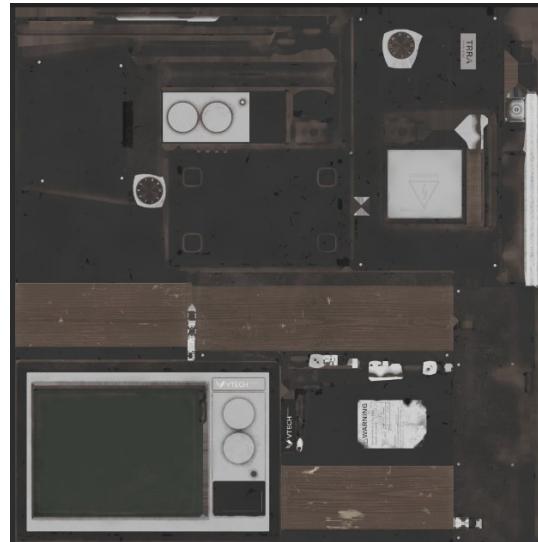
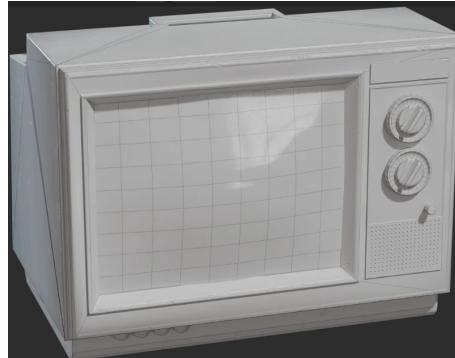
- Image textures contain RGB(A) values.
- Many data types can be stored/encoded using those values. Thus, although image textures always contain color values, those values can be interpreted differently than color.
- Therefore, values obtained from texture are optionally transformed to required datatype.
- Example: encoding normal vectors into image: normal maps



# Image textures

# Image textures

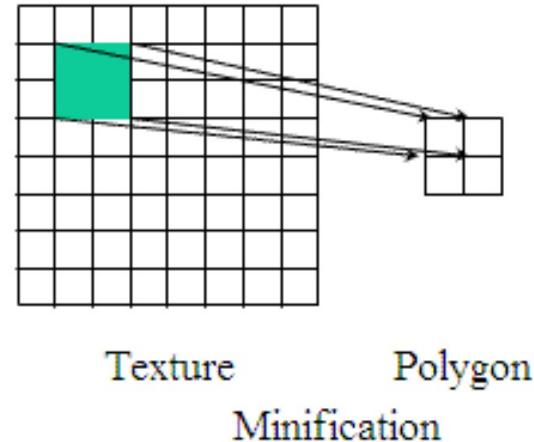
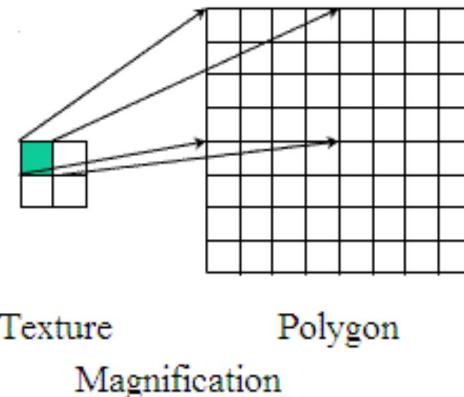
- Image texturing process can be seen as “gluing” image on 3D surface
- For particular position on surface we explained how to obtain texture coordinates. These coordinates are (u,v)
- Image textures are usually  $2^m \times 2^n$  texels. Thus called power-of-two textures (POT)\*
- Texture image can be created:
  - By drawing
  - Taking photographs
  - Measurements
  - Baking



\* Older GPUs couldn't support mipmapping for non-POT textures. Modern GPUs handle all textures correctly.

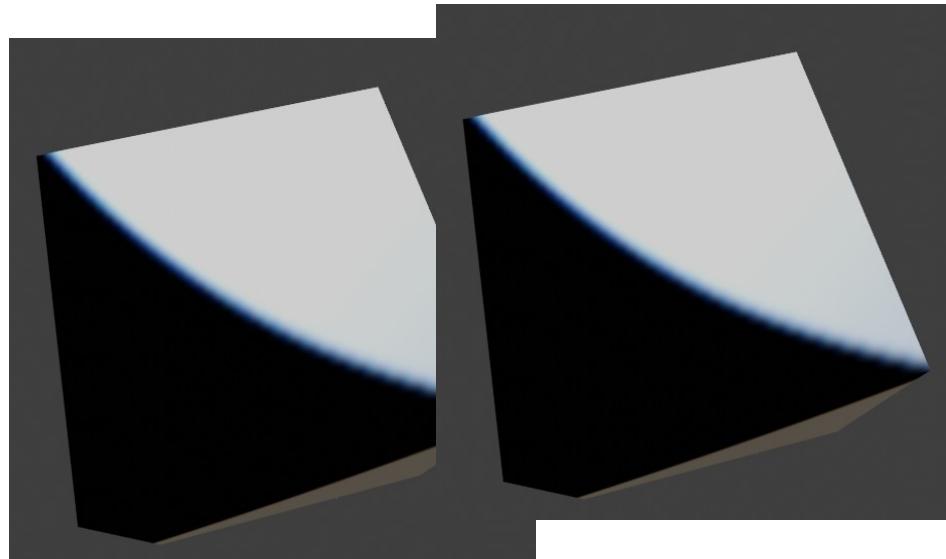
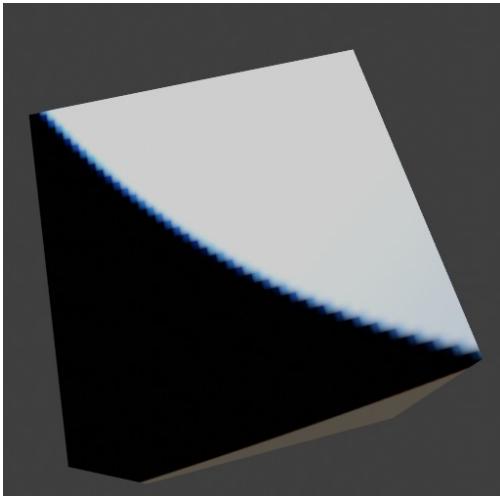
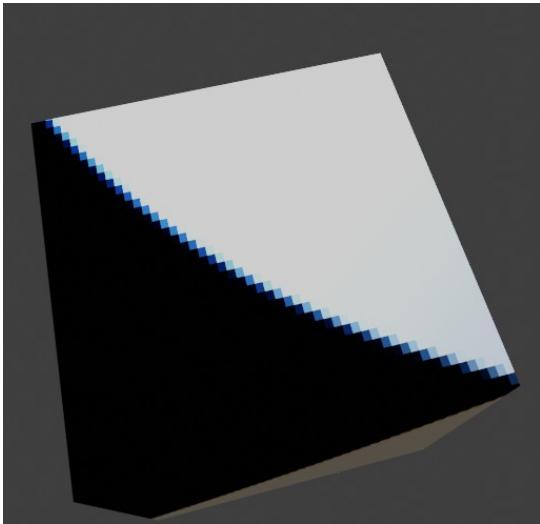
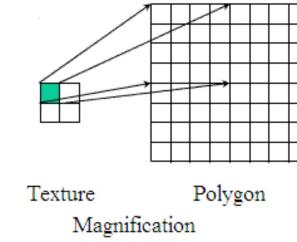
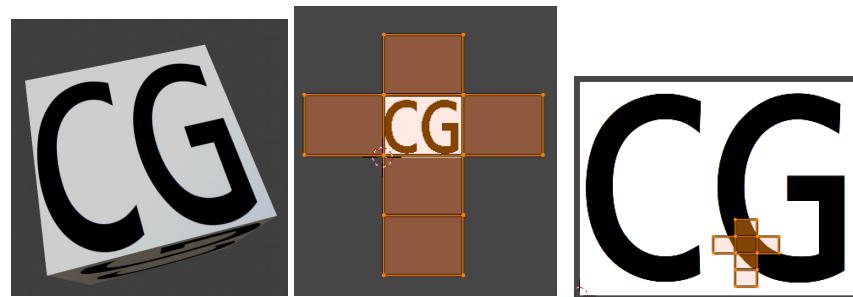
# Magnification and minification

- If more than one pixel cover a texel: **magnification**.
- If more than one texels cover pixel: **minification**



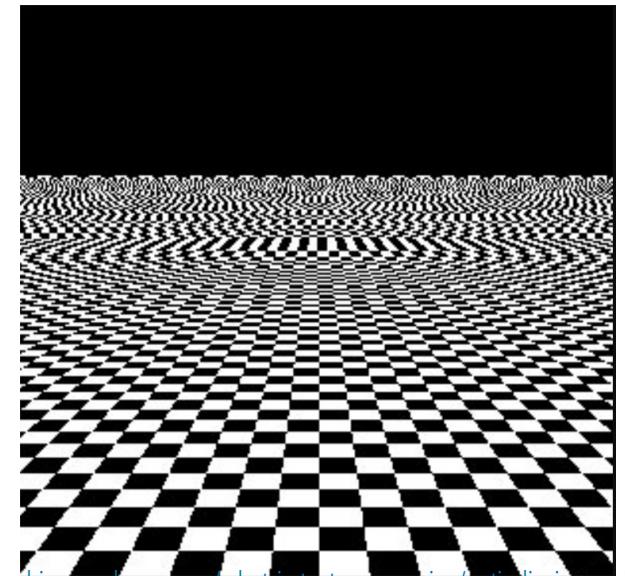
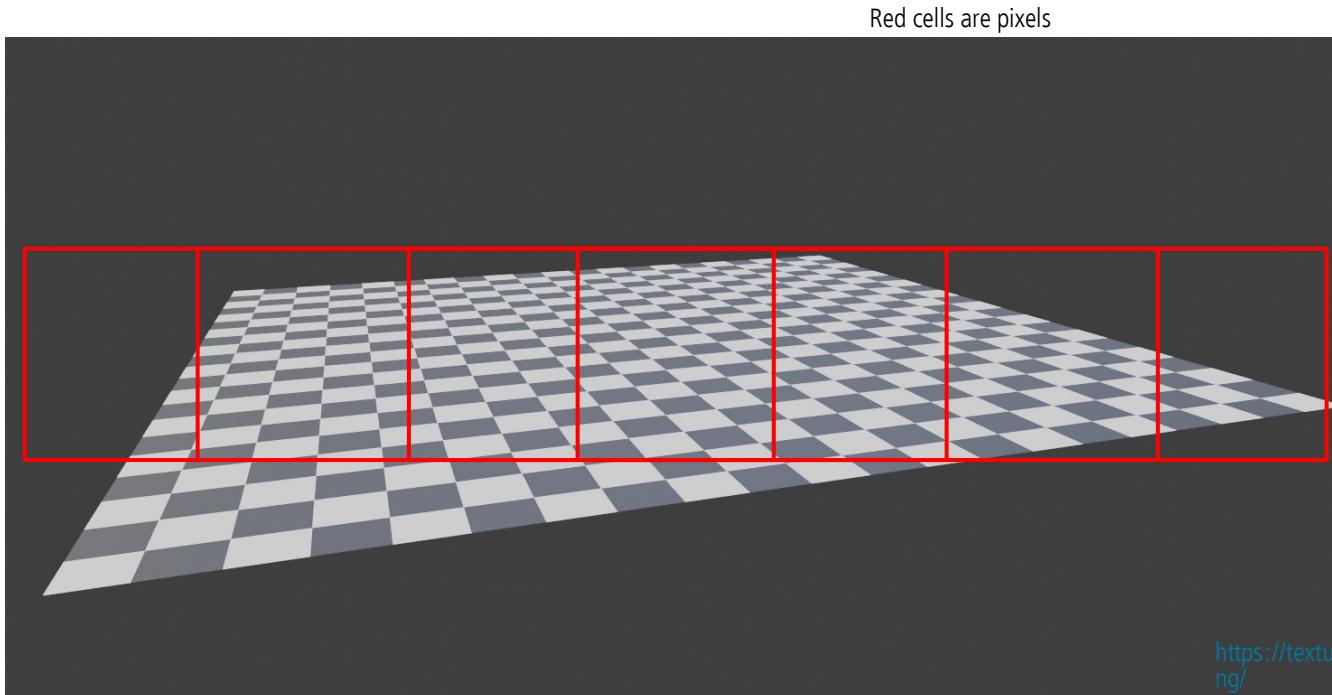
# Texture magnification

- Texture system must magnify the texture. Magnification types:
  - Nearest neighbor (closest): pixelization
  - Linear
  - Cubic filtering
  - Bilinear interpolation: blur



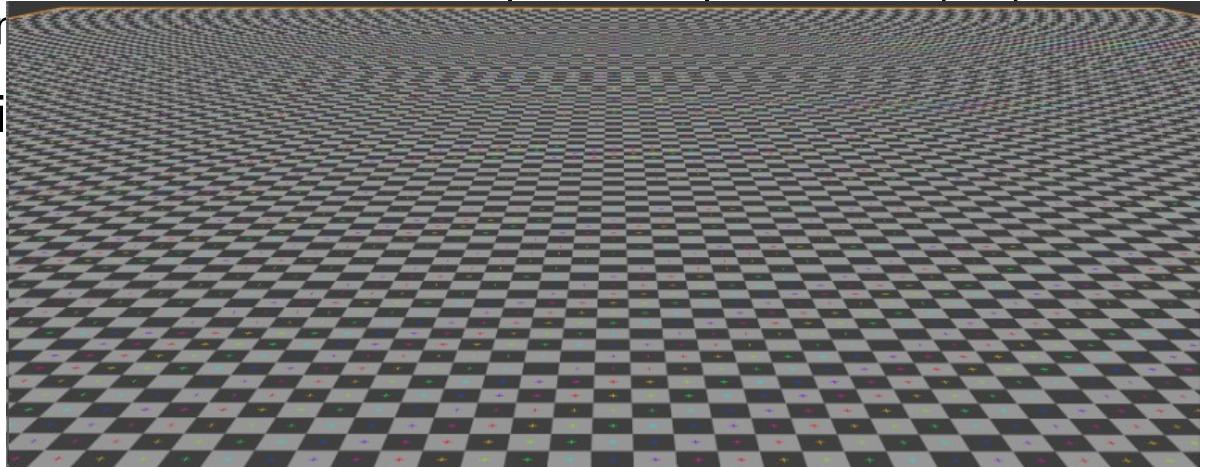
# Texture minification

- If several texels cover pixel cell, **minification** takes place, then cumulative effect of texels influencing the pixel must be taken in account.
  - Nearest neighbour: heavy **aliasing** and temporal aliasing (when camera is moving)
  - Bilinear interpolation: if pixel is covered by more than four texels then **aliasing** again becomes the problem



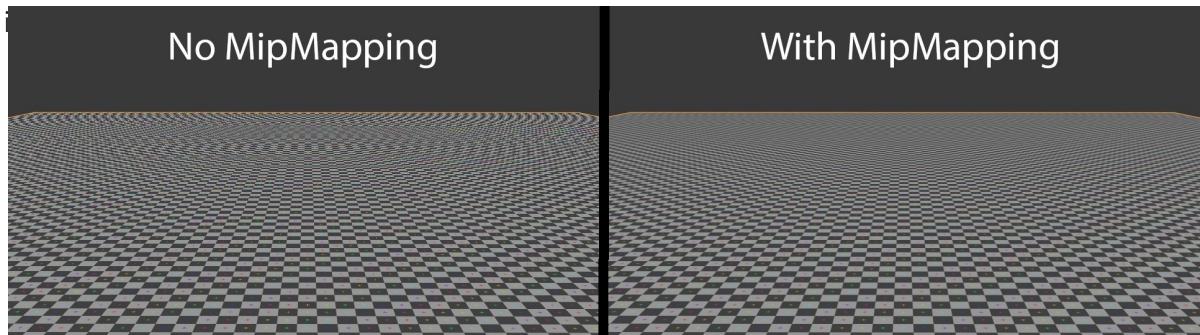
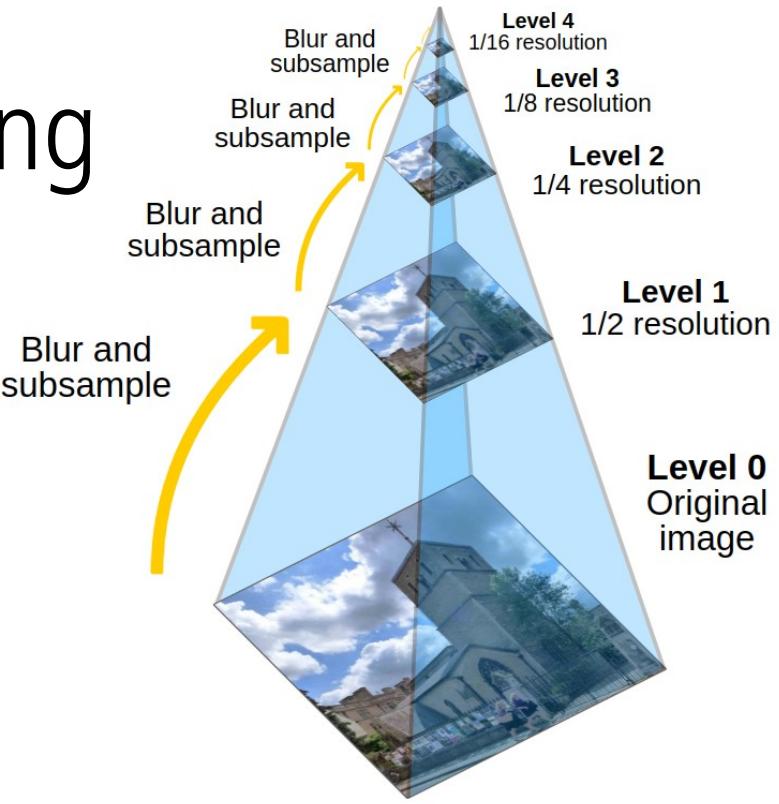
# Aliasing

- Frequency of a texture depends how closely are spaced texels on the screen.
- Nyquist limit – texture frequency must be not larger than half the sample frequency.  
To properly display a texture on a screen, we need at least one texel per pixel
- Anti-aliasing techniques:
- Texture frequency must decrease:
  - Pixel sampling frequency must i



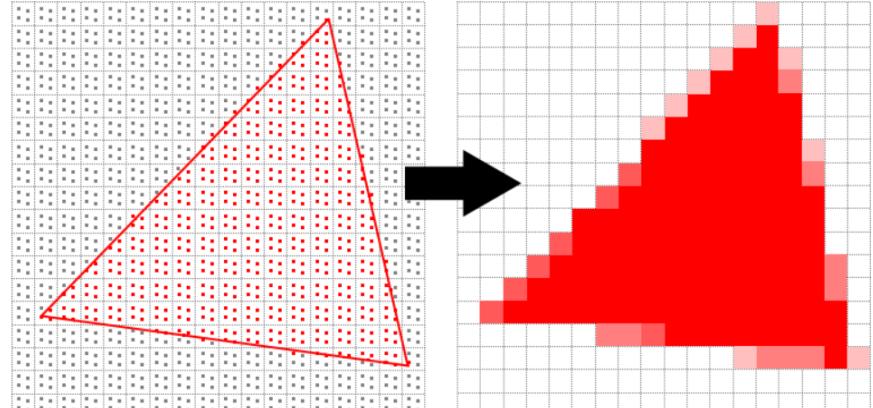
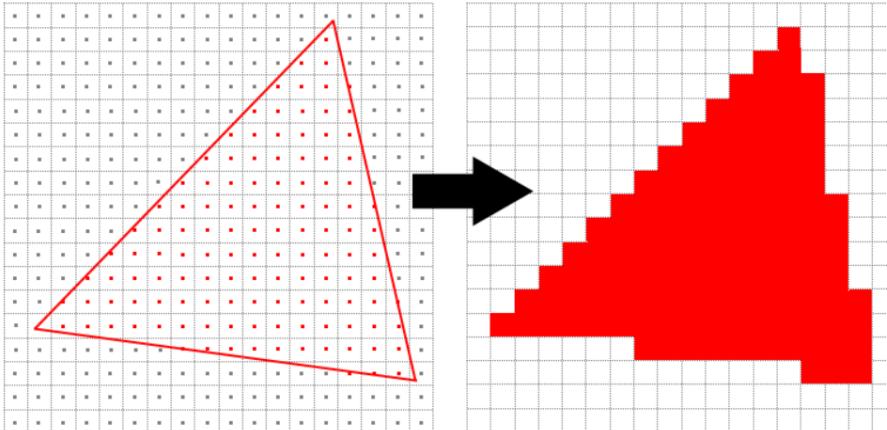
# Anti-aliasing: mipmapping

- MIP – multum in parvo (latin) – many things in small place – minimization filter
  - Original image is filtered down repeatedly into smaller images.
  - Before rendering, original image is augmented with sets of smaller versions of this image
  - Using mipmaps to achieve 1:1 pixel to texel ratio to achieve Nyquist rate.
- Image pyramid, Mipmap chain:
  - Original texture is downsampled by quarter of original area. New texel is calculated as average of four neighbor texels in original image. Newly create texture is called sub-texture
  - This process is repeated until one or both of image texture dimensions equal to one.
- High quality mip mapping requires:
  - Good filtering: averaging new texel value from 2x2 of texels it Gaussian, Lanczos or Kaiser filter
  - Images must be in linear colorspace



# Antialiasing: sampling

- With image minification we introduced the problem of aliasing
- Aliasing appears always when there are a lot of details under a pixel footprint in the scene
- To solve this, multiple sample per pixels can be used to “catch” high frequency details.
  - This method is called Multisample anti-aliasing (MSAA)



MSAAx4

# Alpha texture values

- Image textures have (R,G,B) and alpha channels.
- Alpha values are used for blending or alpha testing for transparency. This enables:
  - **Decals/cutouts**: rendering only parts of the image on object surface.
  - **Billboarding** method is used for standalone flat polygons with image texture, always facing the camera.
  - Alpha value is very much used when adding VFX to rendered or real images - **compositing**.



<https://www.soundstripe.com/blogs/the-best-techniques-tools-for-compositing>



Cut-out texture: only part of image is rendered

<https://xoio-air.de/2017/10-free-cutout-trees-from-tony-textures/>



<https://80.lv/articles/how-to-fake-a-large-scale-forest-in-blender/>

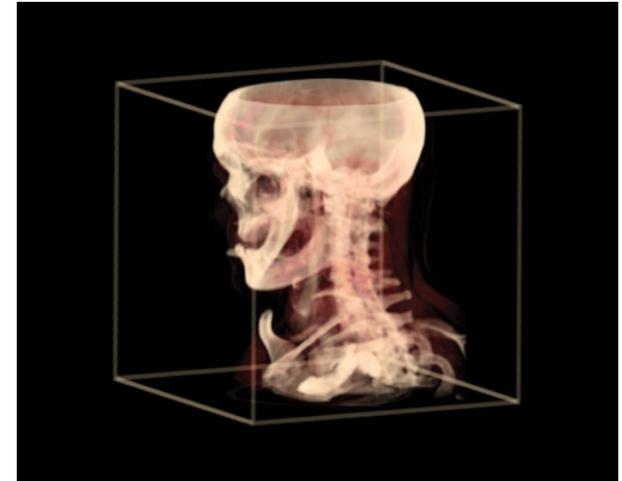
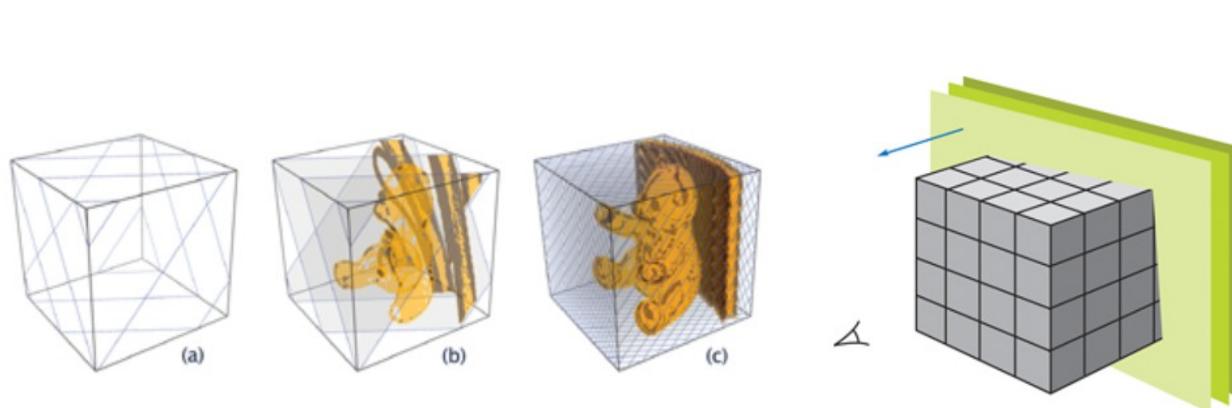


# Sources of image textures

- Substance library: <https://substance3d.adobe.com/assets/allassets?assetType=substanceMaterial&assetType=substanceAtlas&assetType=substanceDecal>
- PolyHaven: <https://polyhaven.com/textures>

# Volume textures

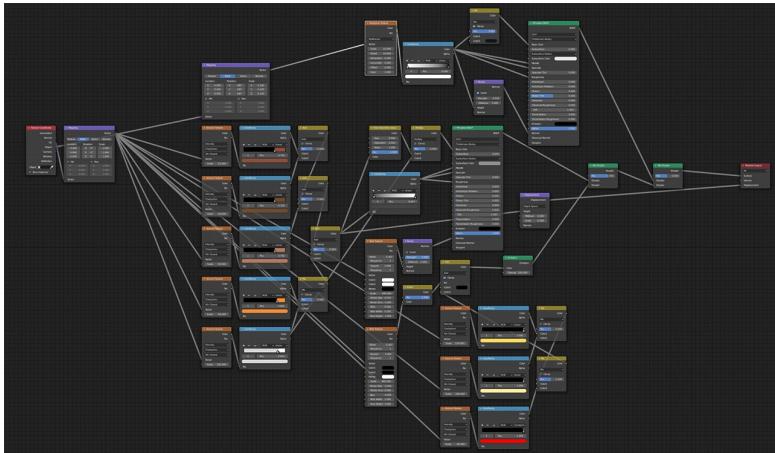
- Extension of 2D image is 3D image accessed with (u,v,w) coordinates
- Complex problem of finding good 2D parameterize for 3D mesh is not needed since object locations can be used as texture coordinates.
- Volume texture can represent volumetric structure of material such as wood or marble.
- Example: medical imaging data
  - Three dimensional grid is visualized as slices by moving polygon through it or using ray-casting.
- Problem: volumetric image textures are very space demanding



# Procedural textures

# Procedural textures

Umbrella term for a number of techniques in computer graphics to create 3D models and textures from sets of rules - code segments or algorithms that specify some characteristic of a computer-generated model or effect<sup>1</sup>

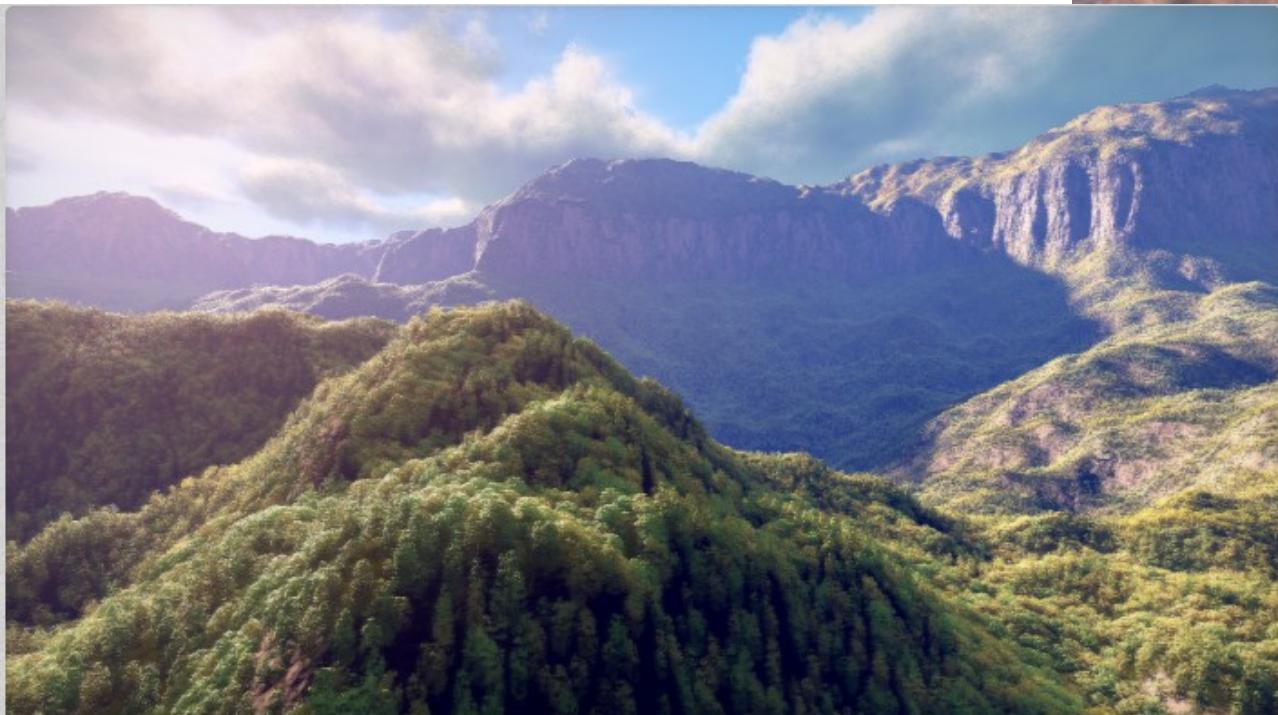


1. Musgrave, F. K., Peachey, D., Perlin, K., & Worley, S. (1994). Texturing and modeling: a procedural approach. Academic Press Professional, Inc.

[https://www.reddit.com/r/blender/comments/khkz98/finished\\_my\\_first\\_nodevember\\_li/](https://www.reddit.com/r/blender/comments/khkz98/finished_my_first_nodevember_li/)

# Procedural textures

- Texture values, instead of image lookup, are **evaluated from a function**
- Procedural texture defines values for every point in 3D space or 3D surface point.
  - Parametrization of surface is therefore not needed
  - This way natural phenomena such as seas, clouds and mountains can be created.
- They are often based on **noise function**.

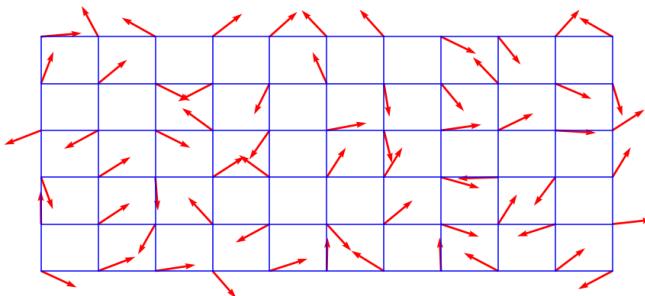


<https://www.rebelway.net/clouds-houdini-tutorial/>

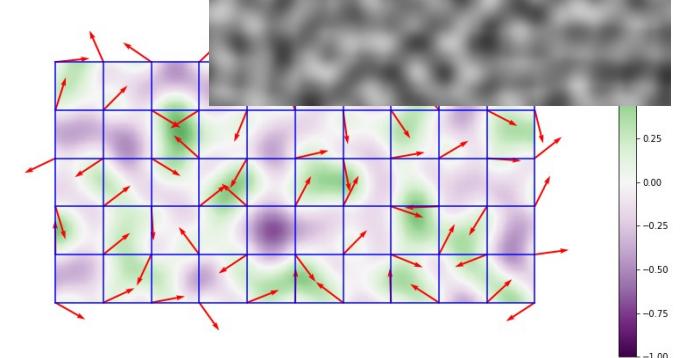
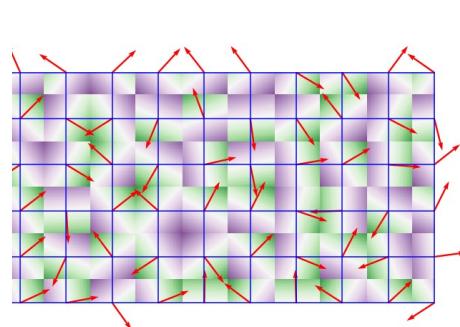
<https://www.shadertoy.com/view/4ttSWf>

# Procedural textures: Perlin noise

- Property: local changes are gradual, while global changes can be large
- Most popular noise function upon which wide range of methods is built
- Type of gradient noise.
  - N dimensional grid where each grid intersection has associated n dimensional unit length gradient vector
  - To calculate point inside grid: (1) find cell inside which point lies, (2) calculate dot product of vector from this point to cell corner and gradient vector, (3) interpolate dot products

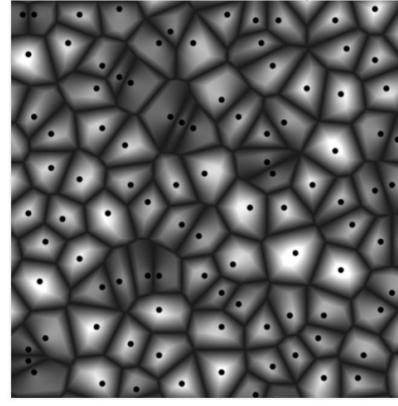
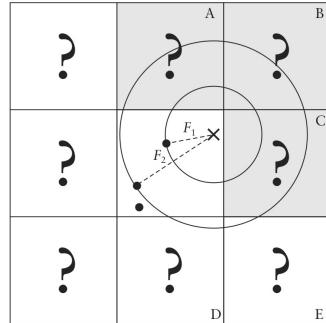
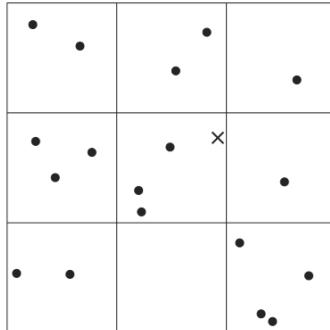


[https://en.wikipedia.org/wiki/Perlin\\_noise](https://en.wikipedia.org/wiki/Perlin_noise)



# Procedural textures: Cellular texture

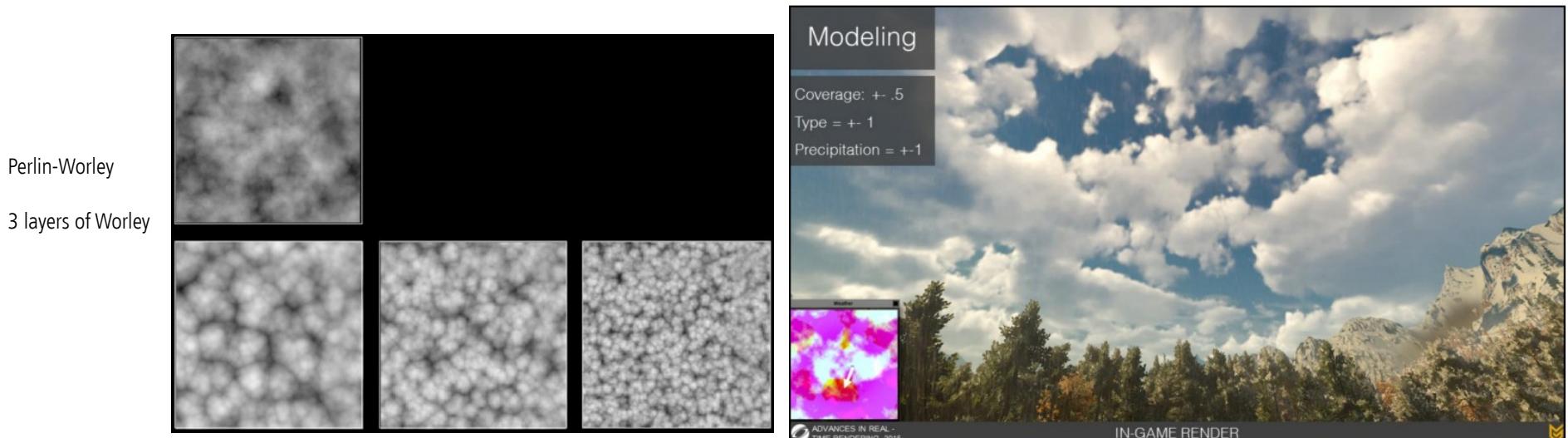
- Steven Worley introduced Voroni-like textures that can be used for many natural textures: cells, flagstones, lizard skin
  - Another fundamental procedural texture upon which more complex procedural textures are built
- This method is based on measuring distance from feature points
  - Space is diced into cubes. Each cube contain random feature points.
  - For current point, find cube inside which lies and check distance to feature points in this and neighboring cubes.
  - First distance is used as value. More combinations with distances are possible.



<https://thebookofshaders.com/12/>

# Noise in production

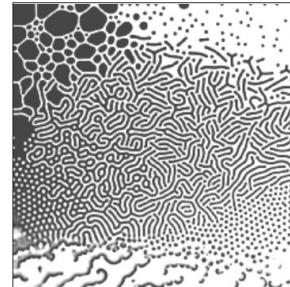
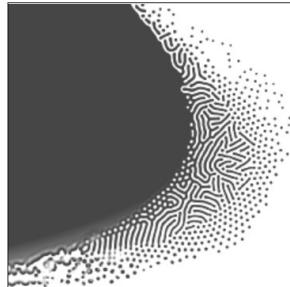
- More complex types of noise are built using Perlin and Worley noise:
  - Fractal noise
  - Simplex noise
- Combining Perlin and Worley noise is often used for more richer details.
- Volume textures are attractive application for procedural texturing since they can be synthesized on the fly



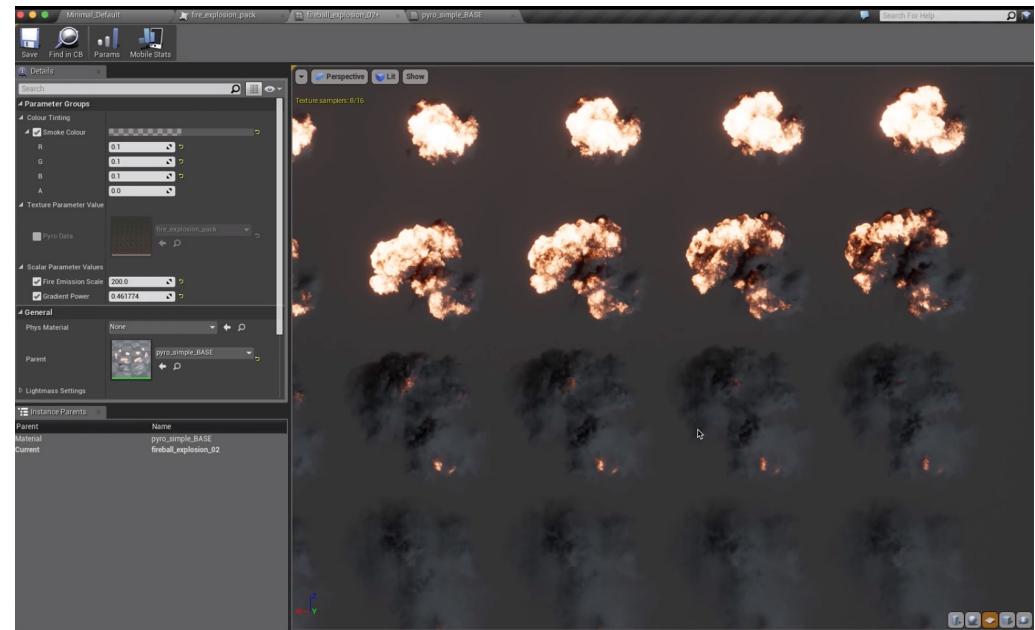
<https://www.guerrilla-games.com/read/the-real-time-volumetric-cloudscapes-of-horizon-zero-dawn>

# Procedural texture: physical simulation

- Perlin and Cellular textures are mathematical models and phenomenological models for representing natural phenomena
- Physically based simulation can also be used to create textures
  - Reaction-diffusion model
  - Fluid simulation to texture



<https://www.karlsims.com/rd.html>



# Procedural textures: Antialiasing

- Procedural texturing is much more popular in offline applications while in real-time rendering image textures are far more common
  - GPUs are extremely efficient with image textures and antialiasing is easier.
- Procedural textures can be hard to antialias
- Helping factor is that “inside information” about the texture is available:
  - For example, if procedural texture is built on summing noise functions, then frequencies which would cause aliasing can be omitted

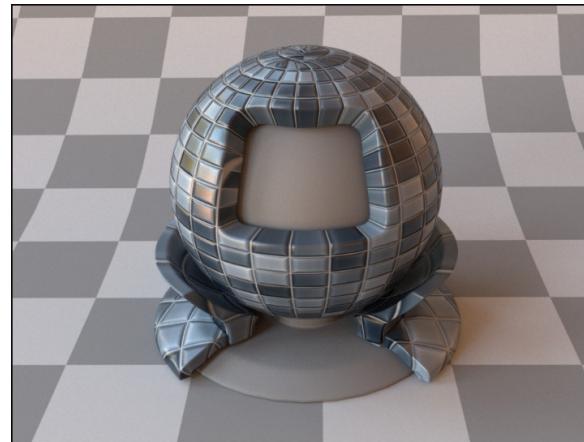
# Material variation

# Material mapping: variation of parameters

- We discussed how to relate image or procedural texture to object surface
  - To obtain texture value given location on object surface.
- Now, we will discuss how texture values are used to modify material across object, that is scattering function and shading parameters over surface
  - Example: 3D scene → rendering → shading: shading reads texture information and uses it for calculating surface color

# Usage of texture values

- Texture is used for **varying material parameters** over surface:
  - Scattering function parameters: color, reflectance, roughness, etc.
  - Small scale surface geometry: bumps, irregularities, etc.



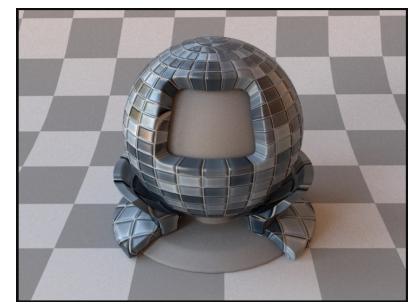
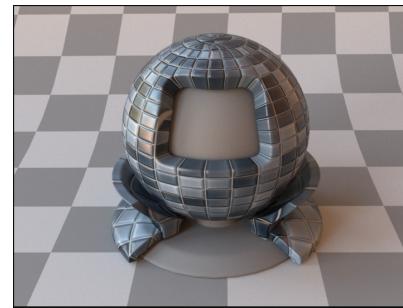
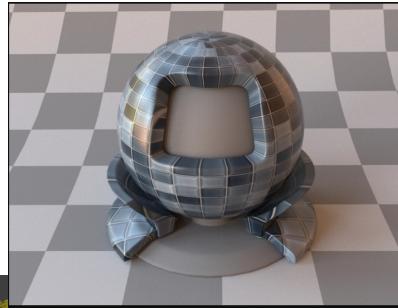
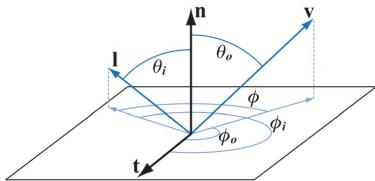
# Scattering function parameters

- Color, reflectance, roughness, etc.

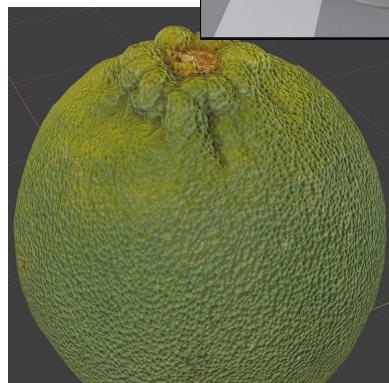


# Small scale surface geometry

- Small scale surface geometry is represented using texture which values are used for perturbing surface or surface normal
  - Perturbing surface or surface normal causes perturbing of BSDF basis and variation in light reflection



<https://mitsuba2.readthedocs.io/en/latest/generated/plugins.html#textures>



<https://learnopengl.com/Advanced-Lighting/Normal-Mapping>

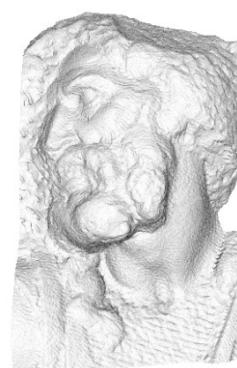
# Small-scale geometry: scale of modeling

- Details on object can be classified:
  - **Macro-features:** cover many pixels. Represented by **model shape** (e.g., polygonal mesh). For character modeling, limbs are modeled at macroscale
  - **Meso-features:** cover few pixels across. Everything between two scales. It represents detail that is too complex to render using shape representation (e.g., polygonal mesh) but large enough to be observable. For character modeling: skin or cloth wrinkles are modeled on mesoscale. For this scale family of **bump mapping methods** is used.
  - **Micro-features.** Described with **scattering function** in shading step. It uses texture values for computing the color. It simulates the microscopic response of surface geometry and substance. Shiny and diffuse objects are modeled on micro-scale

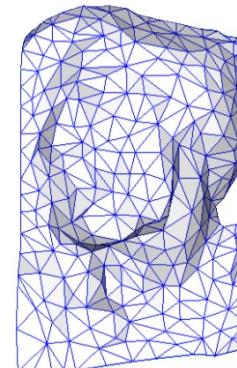


# Small-scale geometry: models

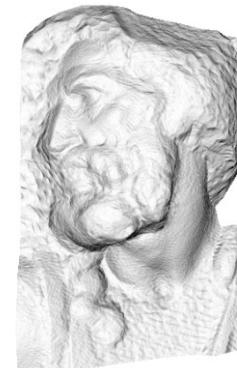
- Texture is employed in shading step during rendering to give more richer 3D appearance than just color
- Methods which do not introduce additional geometrical information. Only approximation to achieve desired surface details:
  - **Bump, normal mapping**
    - Large family of small-scale detail representations
  - **Parallax mapping**
- Methods which require additional geometrical information. Give more realistic surface appearance but are computationally expensive:
  - **Displacement mapping**



original mesh  
4M triangles



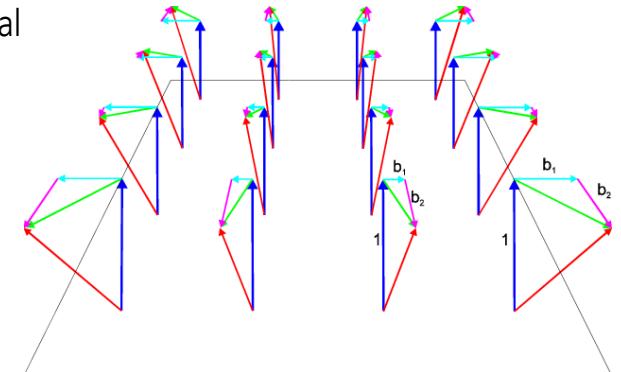
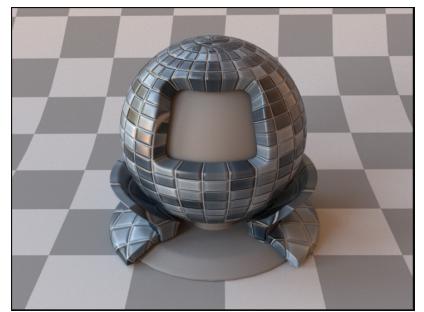
simplified mesh  
500 triangles



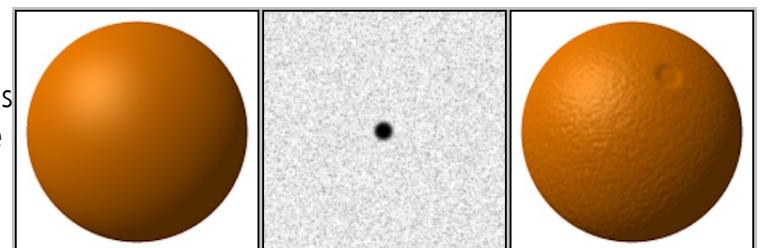
simplified mesh  
and normal mapping  
500 triangles

# Bump mapping

- Main idea (**Blinn method**):
  - Surface will appear to have small scale details during shading process, if surface normal is slightly perturbed.
- Information for perturbing surface normal can be encoded in image texture as color or procedural texture.
- Original bump mapping – **offset vector bump map** - method required two signed values to be stored per texel in texture
  - Those correspond to amount of normal to be varied in u and v image axis – which way surface faces at the point.
  - Those values are used to scale vectors perpendicular to normal (tangent and bitangent)
  - Resulting vectors are added to normal to change direction
- Another approach is to use **heightfield** to modify surface normal direction
  - Image texture contains one floating point number per texel representing height
  - Those values are used to derive u and v signed values similar to those in original method – this taking differences between neighboring columns are rows to obtain u and v (Sobel filter can be

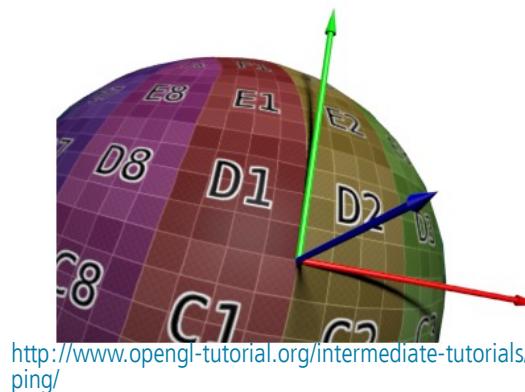
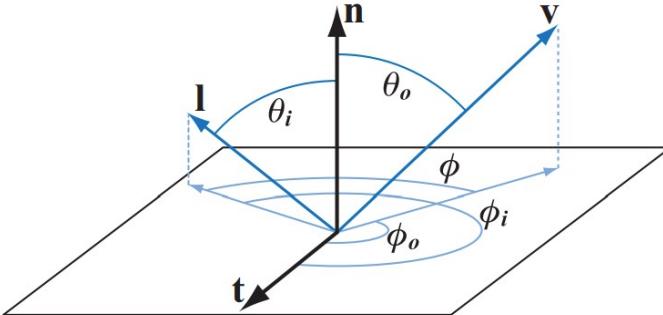


[https://www.researchgate.net/publication/228890410\\_Antialiasing\\_of\\_Bump\\_Maps](https://www.researchgate.net/publication/228890410_Antialiasing_of_Bump_Maps)



# Bump mapping: frame of reference

- Perturbing surface normal must be done with respect to some frame of reference: **tangent frame basis**
- On this basis, scattering model is evaluated
  - Perturbing the basis by perturbing the normal we achieve different incoming light and viewing directions – just like the surface contain small bumps and dents.
  - Also, directions of light and viewing are often transformed in this space – so they are in the same space as surface normal which is needed for correct evaluation.
  - Tangent frame is used to determine orientation of material on the surface which is important for **anisotropic** surfaces



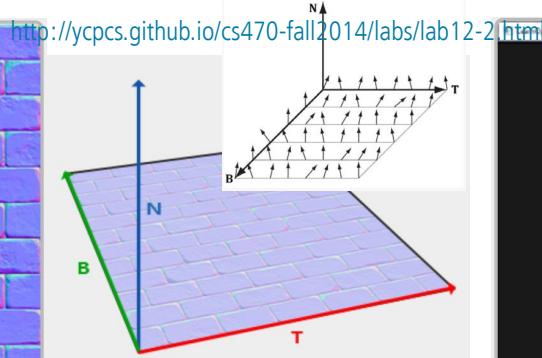
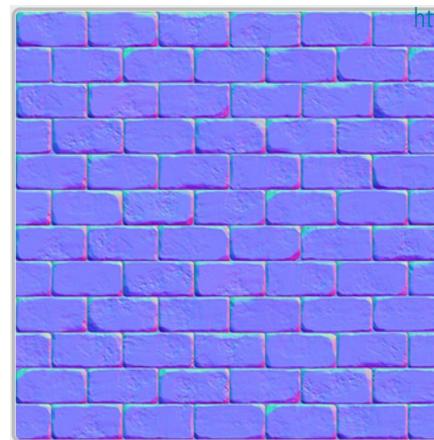
<http://www.opengl-tutorial.org/intermediate-tutorials/tutorial-13-normal-mapping/>



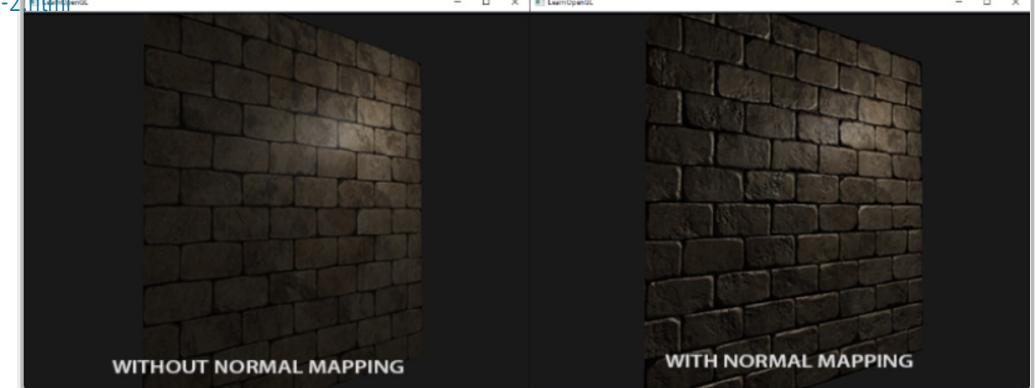
<https://learnopengl.com/Advanced-Lighting/Normal-Mapping>

# Normal mapping

- Normal vectors can be directly stored into image texture or evaluated from procedure
- Normal map image texture encodes (x,y,z) vector with values in [-1,1] to (R,G,B) image
  - For PNG images, 8bit unsigned int is used. Therefore,  $[-1,1] \rightarrow [0,255]$
- Normal map are often defined in **tangent space**\*
  - Color of normal map is determined with x,y and z directions of encoded vectors

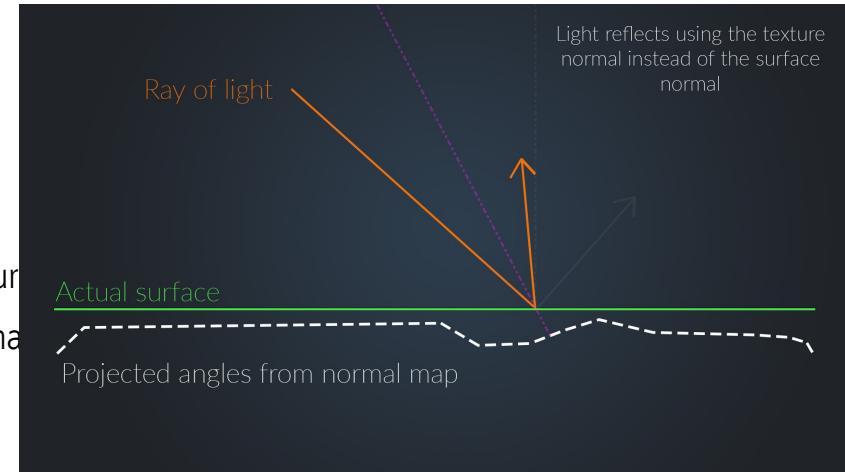


<https://cgcookie.com/posts/normal-vs-displacement-mapping-why-games-use-normals>



<https://learnopengl.com/Advanced-Lighting/Normal-Mapping>

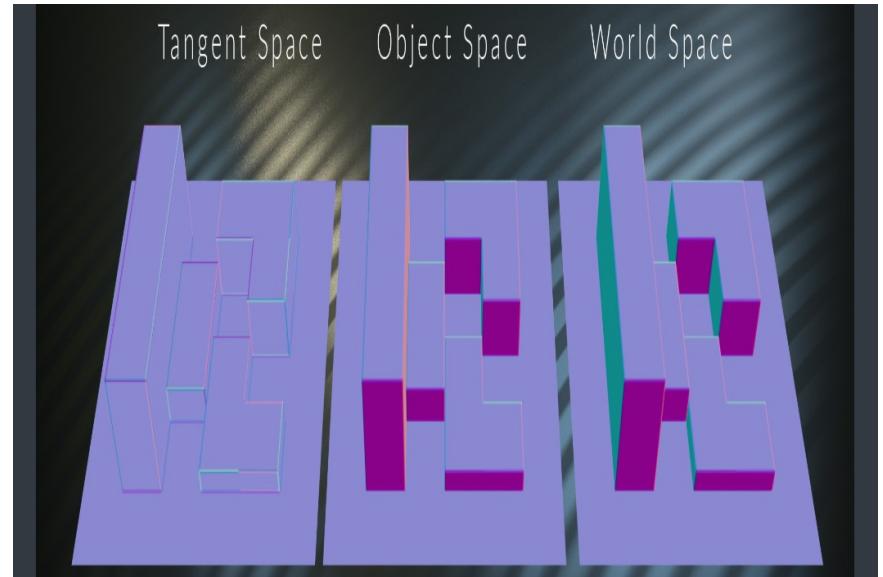
\* Originally, they were defined in world or object space but this was limited to specific geometry for particular orientation.



Light reflects using the texture  
normal instead of the surface  
normal

# Normal map types

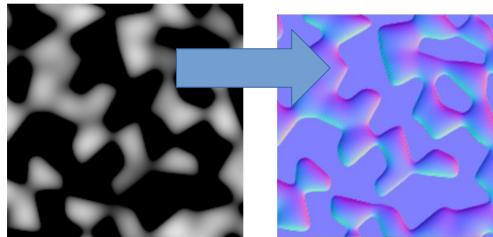
- **Tangent space:** based on tangent direction of face.  
Normal map can be then maximally reused for different objects, transformations and deformations.
  - Blue: normal direction
  - Red: left/right tangent direction
  - Green: up/down tangent direction
- **Object space:** based on entire object rather than each face individually
  - Faster to compute, tied to particular model which can not be deformed
- **World space:** based on global coordinates
  - Object must not be rotated
  - Useful for large, static environment objects



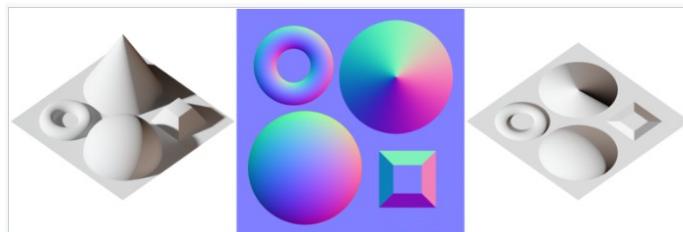
<https://cgcookie.com/posts/normal-vs-displacement-mapping-why-games-use-normals>

# Creating bump/normal maps

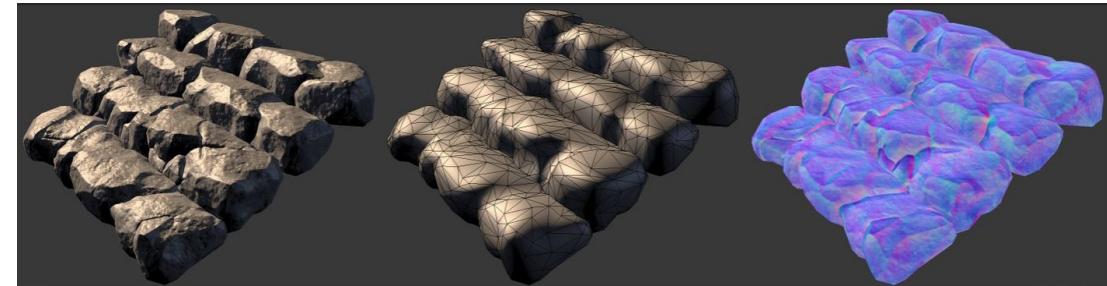
- Baking normal maps from high quality 3D models (often done for real-time graphics applications)
- **Image editing/painting software:** converting photo textures into normal maps, procedural normal map images, hand-painting normal maps
- Scanning heights from real world and converting them to normal map.
- Normal map can be derived from height map.



<https://docs.gimp.org/2.10/en/gimp-filter-normal-map.html>



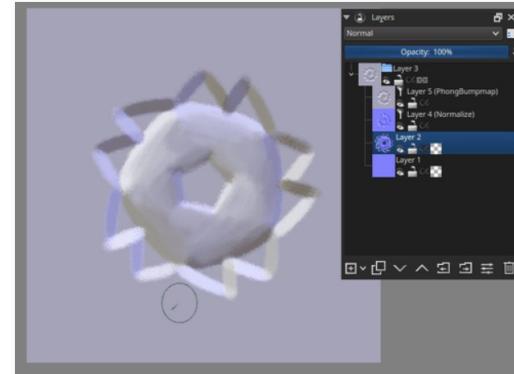
Normal map baked from geometry  
[https://en.wikipedia.org/wiki/Normal\\_mapping](https://en.wikipedia.org/wiki/Normal_mapping)



High quality geometry from which normal map is baked and applied on low quality geometry to achieve computationally cheap high quality appearance.

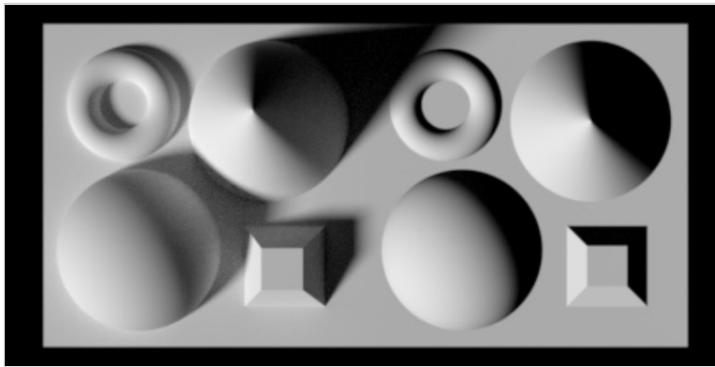
[http://wiki.polycount.com/wiki/Normal\\_map](http://wiki.polycount.com/wiki/Normal_map)

Hand-painting normal maps.  
[https://docs.krita.org/en/reference\\_manual/brushes/brush\\_engines/tangen\\_normal\\_brush\\_engine.html](https://docs.krita.org/en/reference_manual/brushes/brush_engines/tangen_normal_brush_engine.html)

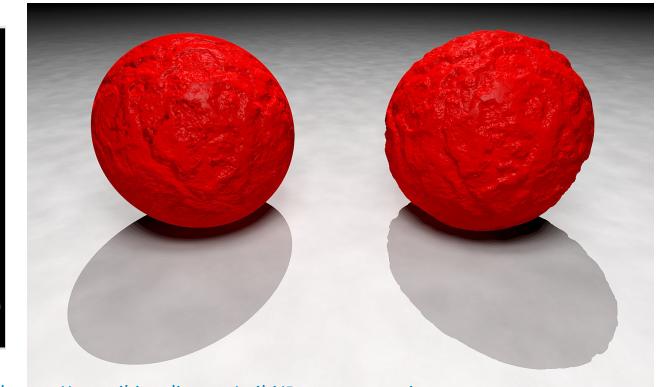
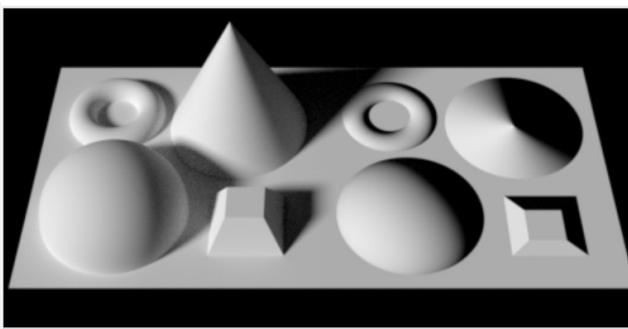


# Bump and Normal mapping: practical notes

- Relationship between normal and shaded color is not linear\*. Therefore, filtering of normal maps for **anti-aliasing** requires additional work.
- Problem with normal mapping, as with bump mapping, is that additional geometry is not created. Thus effects of light being shadowed\*\* by geometry and casting shadow on its own surface is not possible.
  - Solution is **horizon mapping** method which enables normals having bumps which cast shadow on their surfaces.



[https://en.wikipedia.org/wiki/Normal\\_mapping](https://en.wikipedia.org/wiki/Normal_mapping)



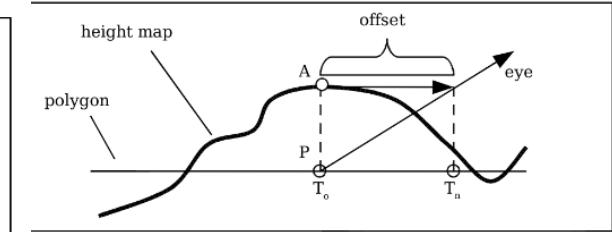
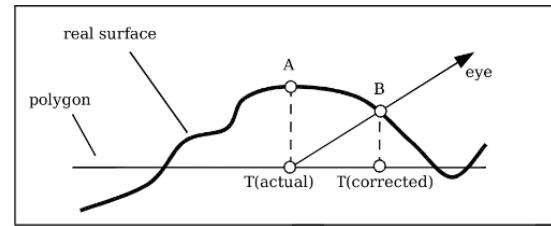
[https://en.wikipedia.org/wiki/Bump\\_mapping](https://en.wikipedia.org/wiki/Bump_mapping)

\* Normal map applied to specular surface results in non-linear relationship between shaded color and normal map. Lambertian (diffuse) surface has almost linear relationship between shaded color and normal map since base of lambertian shading is based on dot product with normal which is linear operation.

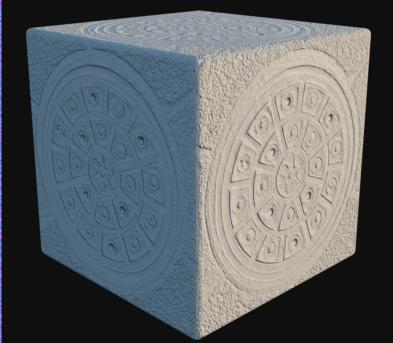
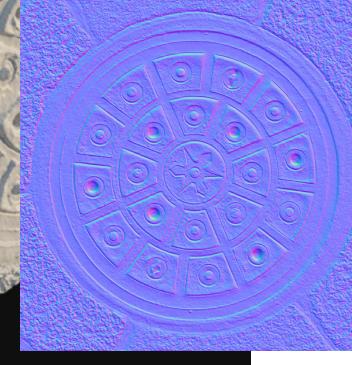
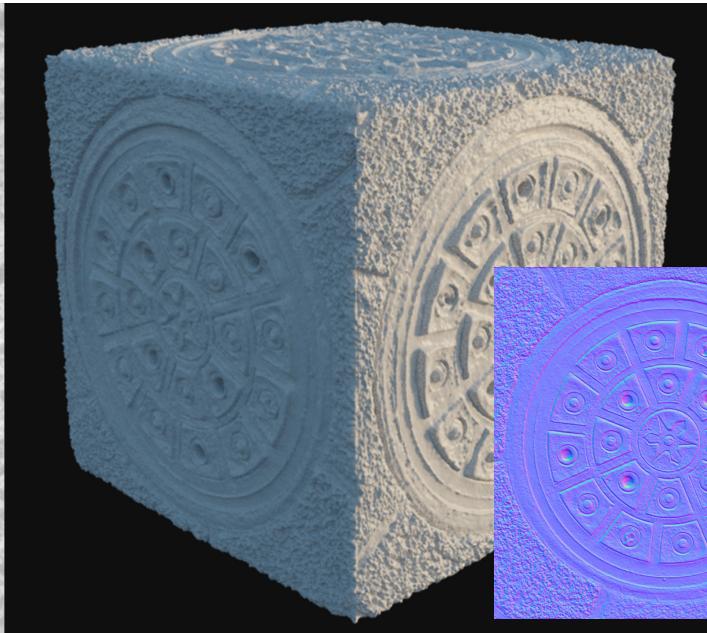
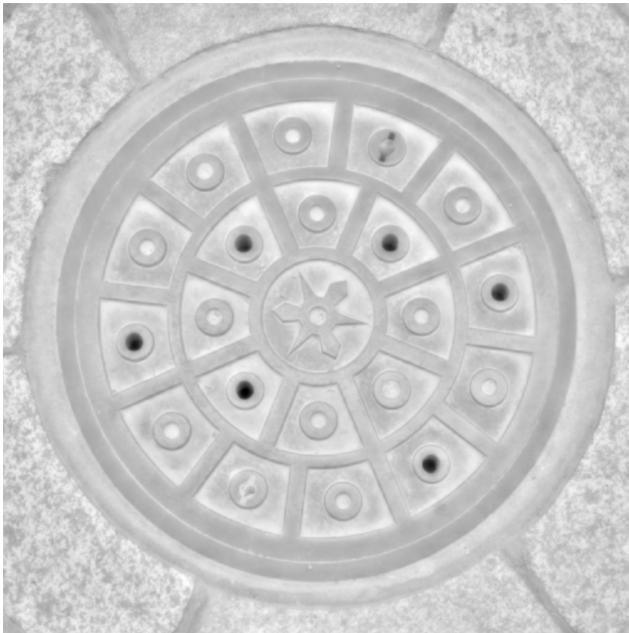
\*\* Generally, when light falls on surface with bumps, multiple scattering, masking and shadowing effects happen which are not possible with normal mapping.

# Parallax mapping

- Bump and normal mapping never shift location with the view angle, nor block each other
- Parallax: positions of objects move relative to one another as the observer moves
- Parallax mapping: approximation technique which is offsetting texture coordinates based on height: what should have been seen in pixel by examining the height of what was found to be visible.
  - Also known as virtual displacement mapping
- When viewing surface at a given pixel, height value is retrieved at that location and used to shift the texture coordinate to retrieve a different part of the surface. Amount of shift is based on retrieved height and angle of the eye to the surface
- Enhancement: **parallax occlusion mapping or relief mapping**: ray-marching is used along view vector until approximate intersection point on height-field texture

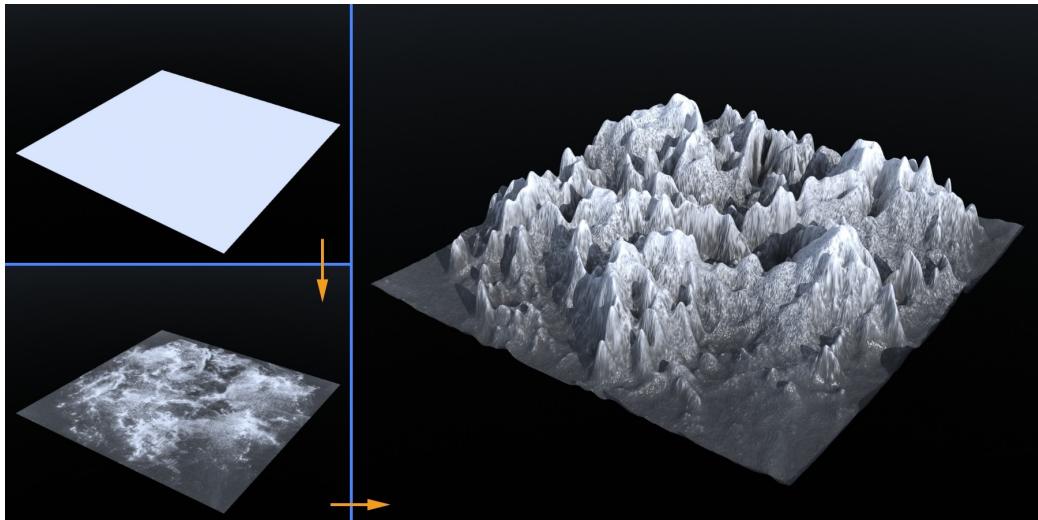


<https://github.com/marcusstenbeck/tncg14-parallax-mapping/tree/master/documents>

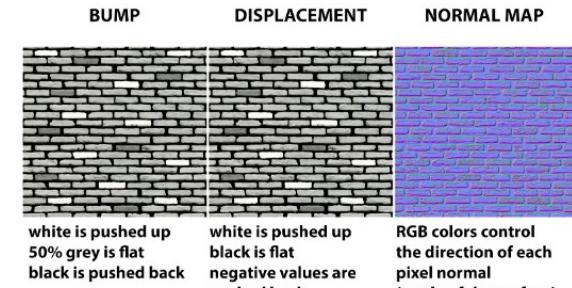
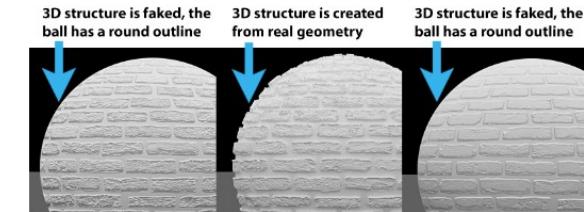
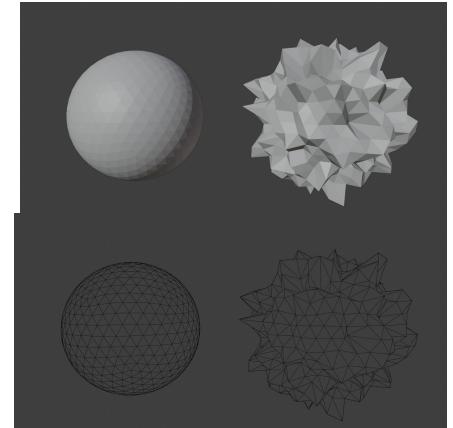


# Displacement mapping

- This method changes the locations of actual geometry vertices in a mesh using height texture information.
  - Height map for displacement mapping can have negative values
- Most computationally expensive technique which requires fine geometry (a lot of vertices which can be displaced).
- Good for modeling larger geometry features such as terrains.



[https://ca.wikipedia.org/wiki/Displacement\\_mapping](https://ca.wikipedia.org/wiki/Displacement_mapping)



<https://garagefarm.net/blog/how-displacement-maps-work-and-how-to-optimize-them-in-v-ray-part-1>

# Note on small scale geometry

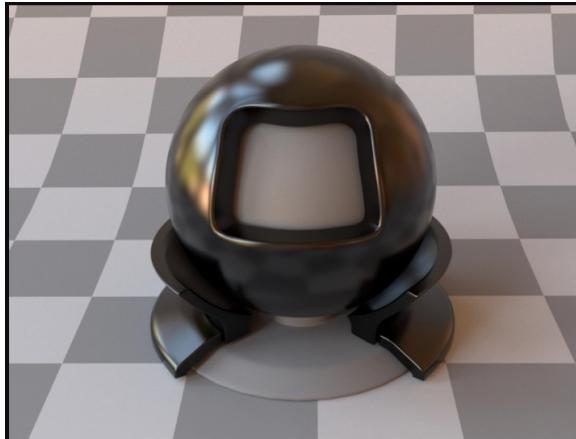
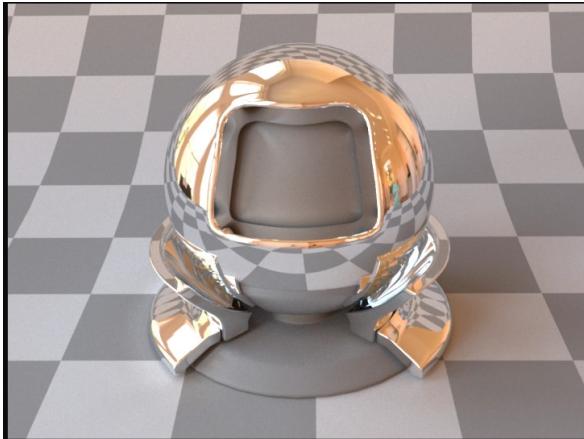
- Note that texture is often used to represent small scale geometry which is expensive to represent and render directly.
- However, there are rendering/representation techniques which enable modeling and rendering of high quality geometry without need for normal, bump, parallax or displacement mapping.



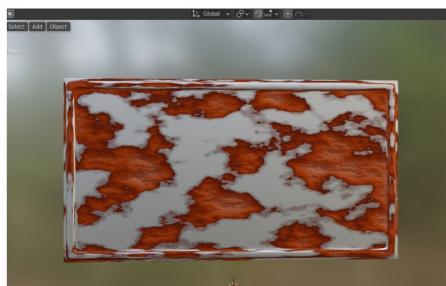
<https://docs.unrealengine.com/5.0/en-US/nanite-virtualized-geometry-in-unreal-engine/>

# Merging materials

- Texture is also used to **distribute different materials** over surface
  - Texture can be used as a “mask” which determines which scattering function and shading calculations will be performed where



<https://mitsuba2.readthedocs.io/en/latest/generated/plugins.html#textures>



<https://blender.stackexchange.com/questions/231205/how-do-i-combine-these-two-textures>

# Texture modeling and texture application

- When we talk about textures in computer graphics, we can separate the work in creating/modeling a texture and applying it. Often, line between these two is blurred.
- Reminder: we said that material modeling (which includes texture) can be performed separately of modeling 3D shape.
  - Creation of texture is often separated of modeling 3D shape and it is done in so called “texture space”.
  - Texture application is process where we “apply” texture on a 3D shape. That is, map it from texture to object space.
- Texture modeling can be described as process of developing a function which maps some property to each point of the surface. Texture modeling can be separated into:
  - Creating image textures
  - Creating procedural textures
- Texture application can be described as a process of adding actual texture on the object.
  - Often, term texture mapping is used. This term is due to historical reasons where details were painted on 3D model and those details were stored in array of images called textures. The process of corresponding each vertex of model to a location in image was called mapping.
  - Main task in texture application is to find mapping between texture and object space.
- Texture, simply speaking, contains information about surface details. It can be color (albedo), normals, roughness, etc.

# Storing and transferring materials

- Similarly to mesh information, standards for material storage and transfer are defined
- Material standards:
  - MaterialX
- Certain formats that we mentioned for mesh storage are used for storing the whole scene including the material:
  - GLTF, USD

# Practical note: textures

- Generally, outside of computer graphics field, term texture is overloaded
- In computer graphics this term is also overloaded
- On modeling level of abstraction, texture is a way to modify scattering function/shading parameters over surface.
- On development level of abstraction, especially while programming in graphics API, texture is nothing more than a memory buffer that is sent from CPU to GPU.
  - RGBA channels can encode any information. Examples: octree, mesh, etc.

# Exploring textures

- Industry standard texturing tool:  
<https://www.adobe.com/products/substance3d-painter.html>
- Textures are often used for layering materials (RTR 9.12)

# More into topic

- Procedural texturing
- Texture mapping
- <https://www.realtimerendering.com/#texture>

Practical insights

- Show how material is generated in practice using different scattering functions and textures

# To remember

- Texture is used to vary material properties over surface
- Texturing pipeline
  - Projection, corresponding, value obtain and transform
- Image textures
  - Aliasing and mip mapping
- Procedural textures
  - Noise functions
- Material variation
  - Scattering function parameters variation
  - Small scale geometry: bump, normal, parallax and displacement mapping

# Literature

- <https://github.com/lorentzo/IntroductionToComputerGraphics/wiki/Foundations-of-3D-scene-modeling>