

Supervised Learning

Writeup for Assignment 01 - CS 6741

Magahet Mendiola

ABSTRACT

An analysis of two machine learning classification problems, including an evaluation of various learning algorithms performance and behavior on the datasets.

1. DATA

Two classification datasets have been chosen based on the following criteria: Each dataset includes a minimum of 3,000 instances to insure sufficient data to evaluate each learning algorithm. Test sets were created by taking a uniform random sample of 33% of the original instances without replacement. The remaining 66% were then used as a training superset. Smaller subsets were pulled from this partition as needed.

2. CLASSIFICATION - MUSHROOMS

The first dataset is titled, Mushroom [1] and was chosen from the UCI ML Repository. The classification task for this dataset is to determine whether a given mushroom is edible or poisonous based on the specimen's physical attributes. There are 22 recorded attributes which describe the physical appearance and olfactory perception of each sample. A full description of attributes can be found at <http://archive.ics.uci.edu/ml/datasets/Mushroom>.

This dataset allows for experimentation of various learning algorithms against attributes with only discrete values. The recorded attributes also require minimal domain knowledge to interpret, which reduces complexity in conceptualizing relationships and evaluating each learner's behavior.

2.1 Attribute characteristics

By examining the value distributions as seen in Figure 1, we first observe that the two classifications are fairly evenly distributed (48% edible, 52% poisonous). This allows for the evaluation of learning algorithm accuracy based on the percentage of classification mistakes made by the model on our test set. This metric will not be unduly weighted by a greater occurrence of one of the classes. It is worth considering the use case for such a classification task though. For example, if this model were to be used to decide whether to serve a given mushroom to a class full of students, we would prefer a hypothesis that favored misclassification of edible over that of poisonous. To be more precise, we would be most concerned with the recall of the poison class, to insure we identify a high percentage of those mushrooms that are in fact poisonous. For the purpose of this first classification task, we will focus on the simple metric of classification

error.

Each attribute includes a finite and limited set of values (min: 2, max:12). This indicates that information gain would provide a suitable metric for decision tree attribute selection, as the variance in value ranges is not significant and, similar to our reasoning for class distribution, we will not need to account for attributes with greater than average ranges of values.

With all the attributes taking discrete (nominal) values, learning algorithm options will be somewhat constrained. For example, neural network network input nodes will need to be setup for each attribute value pair; separating them into binary attributes for each value. The behavior of k-nn will also be constrained. Distance metrics for such attributes will either be simplistic (testing for exact matches) or less intuitive than measuring euclidean distance.

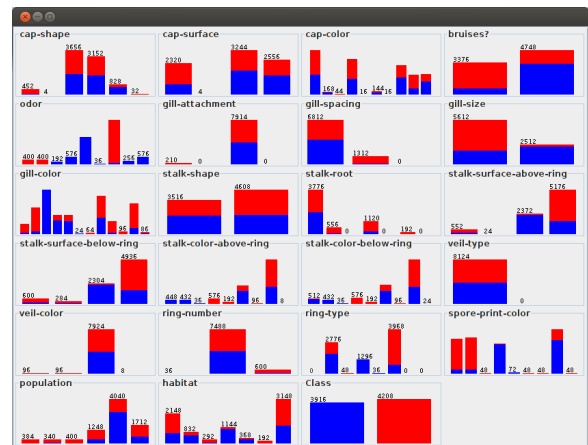


Figure 1: mushroom attribute distribution and classification

We can observe, visually, that a number of attributes provide clear separability between the target classes. This supports the intuition that our attributes do have some functional relationship to the classes. In fact, it appears from the figure that the attribute odor, by itself, could provide a fairly clear indicator of how a sample should be classified. Spore-print-color appears to provide decent class separation as well. We can predict that these attributes will be heavily weighted during the attribute selection or weighting process.

2.2 Algorithm Evaluations

Each learning algorithm has been applied to the training

data with the same procedure. As described earlier, a subset of data was partitioned and preserved as a training set. The remain instances were then sample from to create smaller training sets for use in evaluating each learning algorithms' performance and behavior.

2.2.1 Learning Curves

Evaluation began by choosing conservative starting values for each learners' parameters. Then each learner was trained against a range of training set sizes between 10 and 2000 instances (increments of 10). After each training phase, the original test data (1/3 of the original dataset) was used to evaluate the learner's performance. In this case classification error was used as the performance metric. The plot in Figure 2 shows each learning algorithm's results.

A number of assumptions are made for this initial evaluation. The goal of the exercise being to obtain a general intuition regarding each algorithms' performance, and not to present ideal conditions. Further parameter changes are discussed in subsequent sections of this analysis. The following describes the initial conditions for each learning algorithm.

Decision Tree Weka's open source version of the C4.5 algorithm (J48) was chosen, which uses normalized information gain ratio to select attributes. Post-pruning was done with a minimum leaf size of 2 instances a confidence factor of 0.25.

Boosting Although it would be beneficial to compare our single iteration C4.5 to the same learner with boosting enable, unfortunately that was not possible with this dataset. As can be observed in the learning curve plots below, the training error for J48 was negligible. This caused the AdaBoost algorithm to compute a zero classification error tree in most cases. This resulted in the boosting process returning after a single decision tree is built. This result persisted even with more aggressive post-pruning parameters. In order to evaluate boosting, a weaker learner was chosen in place of C4.5. Boosting was performed on a decision stump learner, which is a simplistic decision tree algorithm that creates a single node/attribute tree.

Neural Network A multilayer perceptron network was used with one hidden layer using a sigmoid activation function. Input nodes were created for each attribute/value pair, and 63 hidden nodes were used, which is the number of input nodes plus the number of output nodes divided by two. The algorithm performs gradient decent to adjust weights, and includes both a learning rate and a momentum factor to slow down and smooth weight changes. For this test, both terms are held static (learning rate = 0.3, momentum = 0.2).

k-NN For the initial tests, the nearest neighbor algorithm was set to $k = 1$. This matches the single closest instance from the training set to determine a classification. The distance metric used is euclidean distance. The plot titles for k-NN are IBk, which is the Weka implementation of k-NN.

SVM SVM was run initially with a linear kernel. Both polynomial and radial basis function kernels are evaluated later. The plot title for SVM is SMO, which is Weka's implementation of SVM.

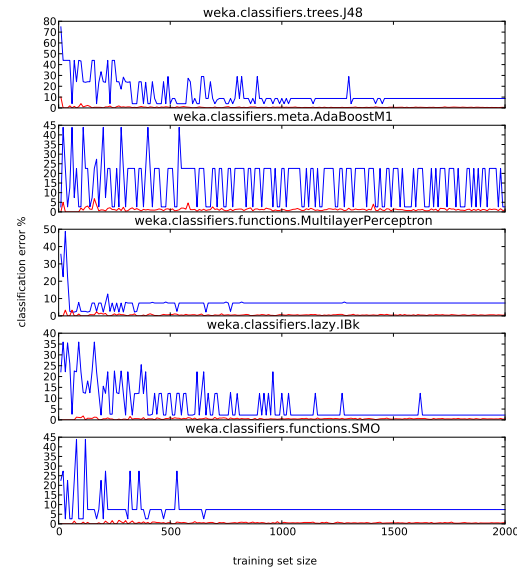


Figure 2: Mushroom - Classification Error by Training Size

The results show training error (red lines) for every learner remain below 10%. In all cases, except decision trees, this error was never higher than 5% even with only 10 samples to train from. This indicates that our learners were able to converge to a hypothesis that fit the training data very well for even small sample sizes. The overall dataset seems to have a little variance and each learner is able to closely model the training data.

The test error plots also exhibit low error for most learners, with the exception of boosting. As expected, smaller training sample sizes show higher misclassification rates. The error rates quickly drop to below 10% for training sets around 1,000 samples. Comparing each learner, we see that our perceptron network was able to reach this low level of classification error with the smallest number of training examples (100). However, the runtime plot in Figure 3 shows that this learner was the slowest to train by an order of magnitude. Depending on the use case, a trade-off can be made for which learner to implement.

Another interesting result is from our boosting algorithm, which struggled to reach the same level of classification error as the others. The intuition for this is that as there are certain attributes with much greater performance metric results which unduly influenced the ability of the weak learner to find suitable attributes other than those with the most influence on the classification.

2.2.2 Training Times

The elapsed time required for each learner to consume the training set has been plotting in Figure 3. Results from this data indicate that C4.5 performed well empirically. Training time for decision trees appeared to run two orders of magnitude faster than our neural network, and one order greater than SVM. The perceptron network seemed to grow linearly and remained far above any other learner. The one surprise in the results was k-NN, which seemed to take

longer to train than decision trees. This may be due to the preprocessing of samples to prepare them for distance measurements, such as pre-sorting.

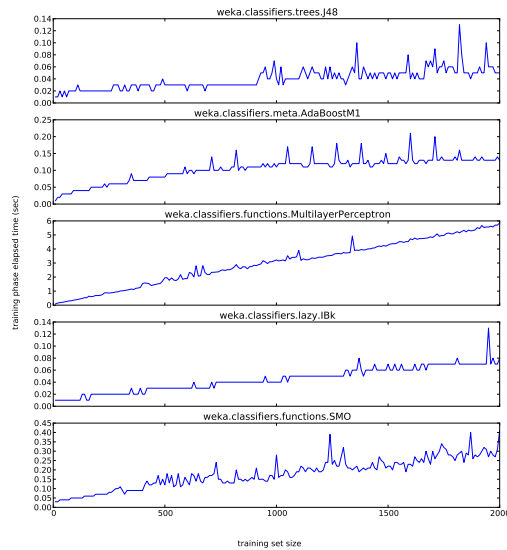


Figure 3: Mushroom - Training Time by Training Size

2.3 Decision Trees

Further experimentation into the decision tree learner was performed on subsets of the original data. As before, 1/3 of the data was partitioned for testing. The training set was then taken as 1,000 instances from the remaining set.

As a baseline, the learner was run with initial settings, which included post-pruning with a 0.25 confidence factor and a minimum leaf size of 2 instances. These settings produced the tree in Figure 4. This tree produced no training classification error and 12% error on the test set. The majority of training instances were classified based on two attributes, odor and stalk-shape.

The discrepancy in training and testing error indicates that the learner may be overfitting the training data. This is further supported by the small number of instances categorized by deeper leaves. To try to archive better generalize, the same process was repeated with more aggressive post-pruning parameters. The results of setting the confidence factor to 0.01 is shown in Figure 5.

Although a negligible number of instances were miscategorized from the training set, the classification error on the test set dropped to 4%. The resulting tree is made up of a single attribute node with nine leaves. This confirms the initial hypothesis that overfitting was occurring with the initial parameters. We can also see that, as expected, the odor attribute does in fact exert a great deal of influence on correct classification. To validate this further, Weka's attribute evaluator tool was used to calculate the information gain for this attribute, which came out at 0.83. This confirms further the strength of this attribute in classification.

We should note that Adjusting the post-pruning parameters further would have no effect on the tree, as there is only

```
odor = a: e (69.0)
odor = l: e (77.0)
odor = c: p (37.0)
odor = y: p (6.0)
odor = f: p (234.0)
odor = m: e (0.0)
odor = n
|   stalk-shape = e
|   |   habitat = g: p (3.0)
|   |   habitat = l
|   |   |   bruises? = t: p (3.0)
|   |   |   bruises? = f: e (4.0)
|   |   habitat = m: p (4.0)
|   |   habitat = p: e (0.0)
|   |   habitat = u: e (16.0)
|   |   habitat = w: e (18.0)
|   |   habitat = d
|   |   |   stalk-surface-above-ring = f: p (0.0)
|   |   |   stalk-surface-above-ring = y: p (0.0)
|   |   |   stalk-surface-above-ring = k: p (4.0)
|   |   |   stalk-surface-above-ring = s: e (4.0)
|   stalk-shape = t: e (468.0)
odor = p: p (51.0)
odor = s: p (2.0)
```

Number of Leaves : 20

Size of the tree : 25

Figure 4: c4.5 decision tree with 0.25 confidence interval

```
odor = a: e (69.0)
odor = l: e (77.0)
odor = c: p (37.0)
odor = y: p (6.0)
odor = f: p (234.0)
odor = m: e (0.0)
odor = n: e (524.0/14.0)
odor = p: p (51.0)
odor = s: p (2.0)
```

Number of Leaves : 9

Size of the tree : 10

Figure 5: c4.5 decision tree with 0.01 confidence interval

a single node left and cannot be pruned further. When run with no post-pruning performed, the same tree is produced as with the initial settings.

2.4 Neural networks

The neural network learner was able to reach a low classification error with a very small training set (around 100 instances). To evaluate this learner in greater detail, the experiment was repeated with the following conditions:

- training set size was held at 1,000 instances
- learning rate (how much weights are changed each iteration), were varied from 0.1 to 3.0
- training iterations are varied between 10 and 1,000 (by 10s)
- number of hidden nodes are varied manually

The results from varying the learning rate and training iterations is displayed in Figures 21 and 22. These plots show variance in the classification error for training iterations and learning rate. However, there is no discernible trend that would indicate better performance of the learner with a specific parameter value.

From examination of the attribute value distribution, and interpreting the results from the decision tree algorithm, it can be hypothesized that very few attributes have an influence on classification. Furthermore, there seems to be a direct relationship between those attributes and the class. This leads to the intuition that hidden layers in our neural network may be superfluous. It turns out, through repeating the experiment with decreasing numbers of hidden nodes, that classification error does not increase considerably. When a network with no hidden layer is trained, the error actually dropped from 7.7% to 7.6%. The significant advantage to this simplified network is the training time difference. The new network, with 63 fewer nodes, was able to train on the dataset in 1% of the original time.

It is also interesting to note that the attributes identified by the decision tree algorithm as being the most relevant show the highest weights on the output nodes. This can be seen in the subset of weight outputs in Figure 23.

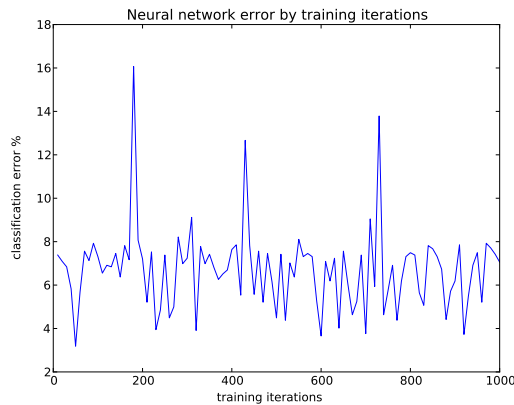


Figure 6: mushroom - neural network error by training iterations

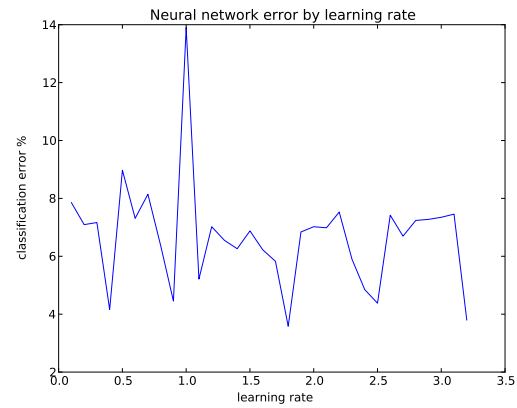


Figure 7: mushroom - neural network error by learning rate

Attrib cap-color=u	0.32909165328321105
Attrib cap-color=e	0.27084200618784854
Attrib cap-color=w	-0.6781600170313064
Attrib cap-color=y	-0.0944215007903694
Attrib bruises?	-0.20164966240021834
Attrib odor=a	1.9591467769018915
Attrib odor=l	2.163249089101404
Attrib odor=c	-1.938000290279853
Attrib odor=y	-0.7210176961657636
Attrib odor=f	-1.4655475615783258
Attrib odor=m	-0.0022502391144373773
Attrib odor=n	2.249162579023187
Attrib odor=p	-2.08204828811813
Attrib odor=s	-0.2329200532370795
Attrib gill-attachment=a	-0.016241324327899875
Attrib gill-attachment=d	0.0167616393841718
Attrib gill-attachment=f	0.04167201385764717
Attrib gill-attachment=n	-0.023866806192559844
Attrib gill-spacing=c	-0.8456690489234284
Attrib gill-spacing=w	0.8125552864255976

Figure 8: neural network sample output node weights

2.5 Boosting

As noted earlier, the boosting algorithm continued to oscillate between high and low classification errors as the training set size increased. A follow up test was performed to see if differing boosting iterations would have an effect on the overall error. The results are shown in Figure 24. This plot shows that after around 50 training iterations, boosting began producing models with higher classification error on the test set. This indicates that overfitting begins to occur and the model is no longer able to generalize well.

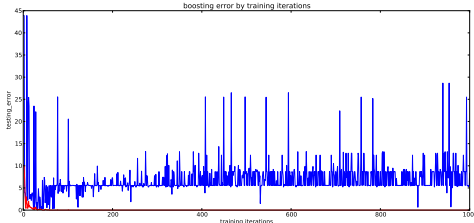


Figure 9: Mushroom - error by boosting iterations

An examination of the boosting behavior shows that, as expected, the odor attribute was chosen by the weak learner (decision stump), for many of the boosting iterations. Each time the instance weight distribution caused the learner to select a different attribute, the next iteration odor was again the attribute chosen.

2.6 Support Vector Machines

The SVM performance in the initial experiment performed well in regards to quickly converging to low classification error with just over 500 samples. This learner also performed quite consistently at the low test error rate as more training data was added. The SVM training times were the second highest, being consistently double to triple that of the other eager learners. It was still significantly faster than the neural network. Even after dropping the 63 nodes in the hidden layer, the neural network was still significantly slower than SVM at the same training set size.

Follow up experiments were performed to see how changes to the SVM kernel would affect its performance. It can be seen from Figure 25 that using a polynomial kernel function with degree 6 produced the smallest classification error (2%), which is significantly lower than that achieved by the linear kernel (7%).

The SVM kernel was then changed to a radial basis kernel to evaluate its behavior. Figure 26 shows that the smallest classification error (2%) was reached with a gamma of 0.225. This is the same error as that found using the degree 6 polynomial kernel. However, the RBF kernel took twice as long to train (0.8 sec vs. 0.4).

2.7 k-nearest neighbor

Initial performance results, with a single nearest neighbor, show a classification error of 3%. Figure 27 shows the results of experimenting with various values for k. The plot indicates that k=3 lowered the error on a 1,000 instance training set to 2.5%.

3. CLASSIFICATION - INCOME

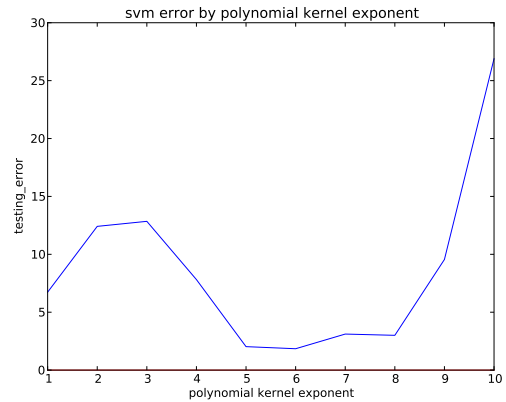


Figure 10: Mushroom - error by svm polynomial kernel exponent

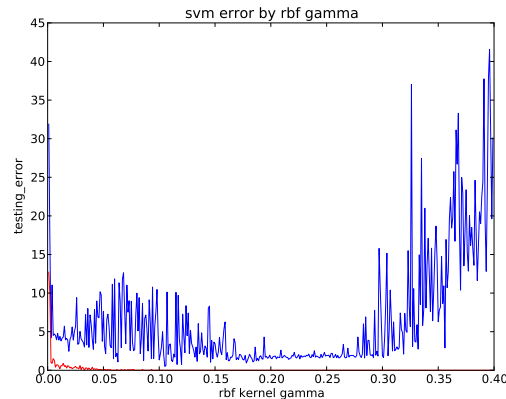


Figure 11: Mushroom - error by svm rbf gamma

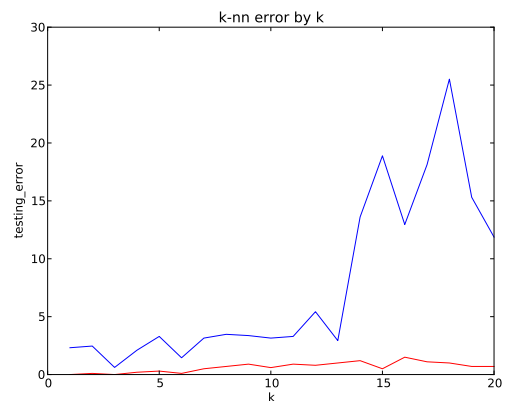


Figure 12: Mushroom - error by number of k-nn neighbors

Our second dataset was also chosen from the UCI ML Repository and is titled, Adult [1]. The classification task in this case is to determine if one's household income exceeds \$50,000/yr based on 14 biographical attributes. The data was collected from a census database from 1994. Attributes include the subject's age, level of education, marital-status, occupation, race, sex, etc. The full description of attributes can be found at <http://archive.ics.uci.edu/ml/datasets/Adult>.

Unlike the first classification task, this dataset is made up of both nominal and numerical attributes. This will encourage comparisons between each learner's behavior with the differing profile of attribute types.

3.1 Attribute characteristics

Value distributions for the income dataset are shown in Figure 13. In this classification task, it is not as clear as before what attributes will contribute to correct classifications. Classes are fairly evenly distributed amongst the various attribute values. Some domain knowledge could help to make intuitive judgments. For example, individuals with high capital gains or losses would suppose greater net worth and likely greater income. Income could also correlate to one's occupation or education level.

Another difference with this dataset is that the two classifications are not as evenly distributed (76% under 50k, 24% over 50k). This will have implications when analyzing the performance of the various learners. The chosen metric will need to conform to the use cases for the resulting model. For example, if the end user is most interested in correctly identifying all individuals with incomes greater than 50k, the performance metric should be the recall for that class. As can be seen in the example accuracy results from Figure 14, the classifier did well at positively identifying people making under 50k (0.95 true positive rate). However, it was only able to correctly identify 55% of those making over 50k.

For the purposes of evaluating the current set of learners, the weighted average f-score (f-measure in Weka) was used. This provides a measure of both precision and recall metrics across both classifications. Thus testing each learner's ability to achieve a balanced confusion matrix.

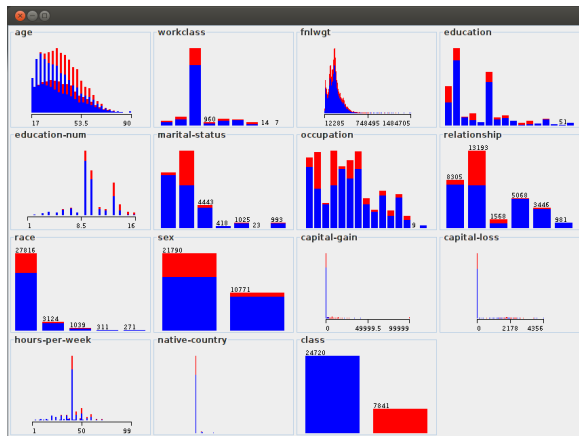


Figure 13: income attribute distribution and classification

3.2 Algorithm Evaluations

```

=== Detailed Accuracy By Class ===

```

	TP Rate	FP Rate	Precision	Recall	F-Measure	ROC Area	Class
	0.952	0.449	0.873	0.952	0.911	0.865	<=50K
	0.551	0.048	0.779	0.551	0.645	0.865	>50K
Weighted Avg.	0.858	0.355	0.851	0.858	0.849	0.865	

```

=== Confusion Matrix ===

```

a	b	-- classified as
8064	406	a = <=50K
1168	1433	b = >50K

Figure 14: example accuracy metrics for income

3.2.1 Learning Curves

As before, the same starting parameters were chosen for each learner. Then training was performed against a range of training set sizes (10 to 2,000 by 10). The difference in this task is that instead of using classification error as our performance metric, we will be using the weighted f-score. Figure 15 shows the results of this initial experiment (blue=testing set, red=training set).

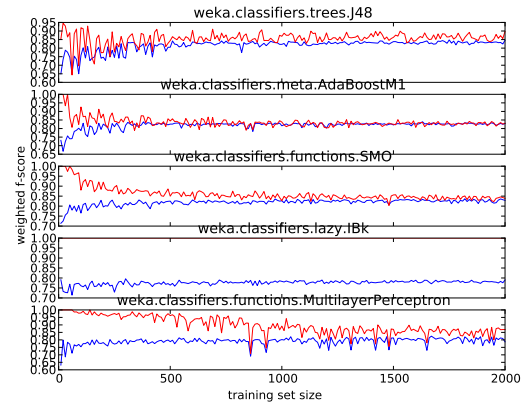


Figure 15: Income - F-Score by Training Size

It is interesting to observe how the f-score on the testing set begins low and raises as training instances are added, while the opposite behavior occurs with the training set f-score. This is expected behavior, as it is easier to find a hypothesis that fits a small set of training data, but does not generalize well to the test set. Conversely, it becomes more difficult to fit a larger training set and the learner is forced to find a hypothesis that generalizes better. The learner could overfit the data, in which case the training error would remain low and the testing error would eventually begin raising again. This behavior was not exhibited in the initial experiment.

3.2.2 Training Times

Each learner, with naive parameters, seems to perform similarly across the training set sizes, with k-NN achieving slightly lower f-scores. However, there is a significant difference in the training times as seen in Figure 16. As seen in the previous classification experiment, the neural network took significantly longer to train for each training set size. In this case the difference was nearly three orders of magnitude greater than the other eager learners.

Again, k-NN did take some time to process the training set, which is believed to be attributed to sorting the in-

stances for faster distance calculations.

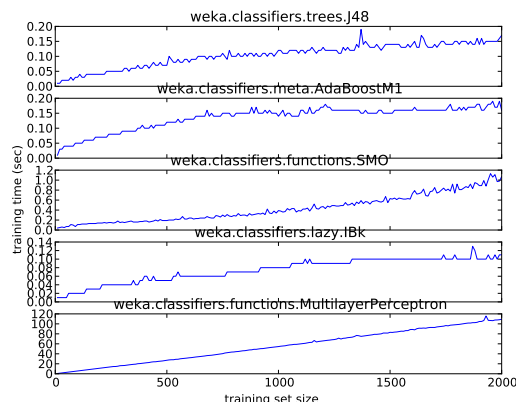


Figure 16: Income - Training Time by Training Size

3.3 Decision Trees

The fact that this dataset is made up of both continuous and discrete attributes means that we must address the issue of how to split numerical attributes at decision nodes. The C4.5 algorithm, which is used in this case, is natively able to handle continuous attributes by finding a value threshold that maximizes the information gain ratio on the resulting two sets of instances.

The results of running the C4.5 decision tree algorithm on a 1,000 instance training set and a 0.25 confidence factor for post-pruning resulted in the tree shown in Figure 17. We can observe a few interesting results from this tree. First, the capital-gain attribute was chosen as the first node despite the fact that its information gain at the first node is quite small compared to other attributes (0.08978 vs. 0.18 for relationship). This discrepancy is accounted for by examining the instances directly. We see that capital-gain has a value of 0 for most of the instances. In contrast, other attributes take on a wide range of values and thus have an unfair advantage in the information gain calculation. To compensate for this, C4.5 uses the normalized information gain ratio, which is specifically designed to account for these cases of imbalanced value distribution. Using this metric, we see that capital-gain does rank highest among the attributes (0.3 vs. 0.085 for relationship).

In order to determine if the resulting tree is overfitting the data, experiments were run with varying degrees of post-pruning, including disabling pruning altogether. The results in Figure 18 show us that our weighted f-score does not vary significantly with larger or smaller trees. We do see from Figures 19 and 20 that recall for the greater than 50k class is better with the larger tree (0.623 vs. 0.545). It turns out that most of the under 50k classified instances are identified near the top of the tree. Adding additional nodes helps to identify more over 50k instances, but does not impact the tree's ability to classify the under 50k class.

3.4 Neural networks

The neural network learner was again evaluated with a number of varying parameters. Our network in this case was smaller with the initial settings due to the

J48 pruned tree

```
capital-gain <= 5013
|   education-num <= 11
|   |   age <= 28: <=50K (221.0/1.0)
|   |   age > 28
|   |   |   capital-loss <= 625: <=50K (442.0/70.0)
|   |   |   capital-loss > 625
|   |   |   |   capital-loss <= 1651: <=50K (7.0/1.0)
|   |   |   |   capital-loss > 1651: >50K (12.0/3.0)
|   |   education-num > 11
|   |   |   marital-status = Never-married: <=50K (76.0/9.0)
|   |   |   marital-status = Married-civ-spouse: >50K (147.0/41.0)
|   |   |   marital-status = Divorced
|   |   |   |   hours-per-week <= 44: <=50K (22.0)
|   |   |   |   hours-per-week > 44
|   |   |   |   |   fnlwgt <= 112497: >50K (4.0)
|   |   |   |   |   fnlwgt > 112497: <=50K (8.0/1.0)
|   |   |   marital-status = Married-spouse-absent: <=50K (7.0/1.0)
|   |   |   marital-status = Separated: <=50K (2.0/1.0)
|   |   |   marital-status = Married-AF-spouse: <=50K (0.0)
|   |   |   marital-status = Widowed: <=50K (2.0)
capital-gain > 5013: >50K (50.0/2.0)
```

Number of Leaves : 14

Size of the tree : 22

Figure 17: c4.5 decision tree with 0.25 confidence interval

Pruned	Confidence Factor	Weighted F-Score	Tree Size
no	n/a	0.837	136
yes	0.25	0.836	22
yes	0.1	0.833	16
yes	0.01	0.834	12

Figure 18: decision tree results with various levels of pruning

```
=== Detailed Accuracy By Class ===
              TP Rate  FP Rate  Precision  Recall  F-Measure  ROC Area  Class
              0.939    0.455    0.864    0.939    0.9        0.758    <=50K
              0.545    0.061    0.742    0.545    0.629    0.758    >50K
Weighted Avg.   0.842    0.359    0.835    0.842    0.834    0.758

=== Confusion Matrix ===
      a    b  <-- classified as
 7851  513 |  a = <=50K
1231 1476 |  b = >50K
```

Figure 19: performance metrics - C4.5 - 12 node tree

```
=== Detailed Accuracy By Class ===
              TP Rate  FP Rate  Precision  Recall  F-Measure  ROC Area  Class
              0.91     0.377    0.882    0.91     0.896    0.857    <=50K
              0.623    0.09     0.693    0.623    0.656    0.857    >50K
Weighted Avg.   0.84     0.307    0.836    0.84     0.837    0.857

=== Confusion Matrix ===
      a    b  <-- classified as
 7615  749 |  a = <=50K
1020 1687 |  b = >50K
```

Figure 20: performance metrics - C4.5 - 136 node tree

- training set size was held at 1,000 instances
- learning rate (how much weights are changed each iteration), were varied from 0.1 to 3.0
- training iterations are varied between 10 and 1,000 (by 10s)
- number of hidden nodes are varied manually

The results from varying the learning rate and training iterations is displayed in Figures 21 and 22. These plots show variance in the classification error for training iterations and learning rate. However, there is no discernible trend that would indicate better performance of the learner with a specific parameter value.

From examination of the attribute value distribution, and interpreting the results from the decision tree algorithm, it can be hypothesized that very few attributes have an influence on classification. Furthermore, there seems to be a direct relationship between those attributes and the class. This leads to the intuition that hidden layers in our neural network may be superfluous. It turns out, through repeating the experiment with decreasing numbers of hidden nodes, that classification error does not increase considerably. When a network with no hidden layer is trained, the error actually dropped from 7.7% to 7.6%. The significant advantage to this simplified network is the training time difference. The new network, with 63 fewer nodes, was able to train on the dataset in 1% of the original time.

It is also interesting to note that the attributes identified by the decision tree algorithm as being the most relevant show the highest weights on the output nodes. This can be seen in the subset of weight outputs in Figure 23.

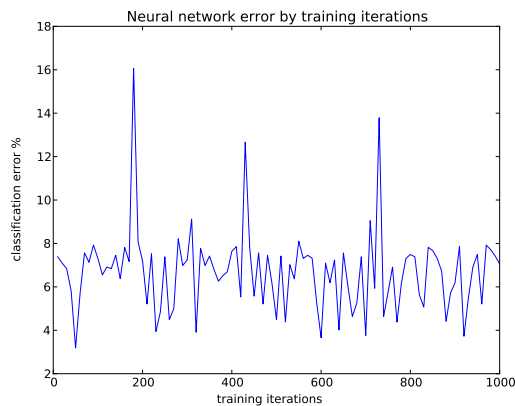


Figure 21: mushroom - neural network error by training iterations

3.5 Boosting

As noted earlier, the boosting algorithm continued to oscillate between high and low classification errors as the training set size increased. A follow up test was performed to see if differing boosting iterations would have an effect on the overall error. The results are shown in Figure 24. This plot shows that after around 50 training iterations, boosting began producing models with higher classification error on the

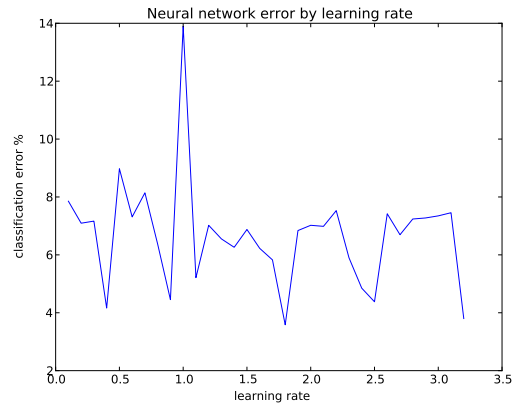


Figure 22: mushroom - neural network error by learning rate

```
Attrib cap-color=u    0.32909165328321105
Attrib cap-color=e    0.27084200618784854
Attrib cap-color=w   -0.6781600170313064
Attrib cap-color=y   -0.0944215007903694
Attrib bruises?     -0.20164966240021834
Attrib odor=a       1.9591467769018915
Attrib odor=l       2.163249089101404
Attrib odor=c      -1.938000290279853
Attrib odor=y      -0.7210176961657636
Attrib odor=f      -1.4655475615783258
Attrib odor=m      -0.0022502391144373773
Attrib odor=n       2.249162579023187
Attrib odor=p      -2.08204828811813
Attrib odor=s      -0.2329200532370795
Attrib gill-attachment=a -0.016241324327899875
Attrib gill-attachment=d  0.0167616393841718
Attrib gill-attachment=f  0.04167201385764717
Attrib gill-attachment=n -0.023866806192559844
Attrib gill-spacing=c  -0.8456690489234284
Attrib gill-spacing=w   0.8125552864255976
```

Figure 23: neural network sample output node weights

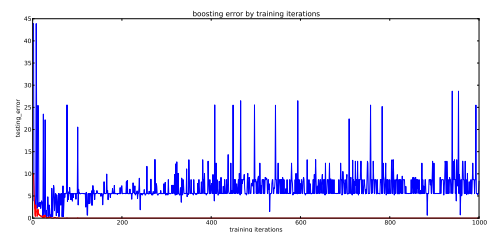


Figure 24: Mushroom - error by boosting iterations

test set. This indicates that overfitting begins to occur and the model is no longer able to generalize well.

An examination of the boosting behavior shows that, as expected, the odor attribute was chosen by the weak learner (decision stump), for many of the boosting iterations. Each time the instance weight distribution caused the learner to select a different attribute, the next iteration odor was again the attribute chosen.

3.6 Support Vector Machines

The SVM performance in the initial experiment performed well in regards to quickly converging to low classification error with just over 500 samples. This learner also performed quite consistently at the low test error rate as more training data was added. The SVM training times were the second highest, being consistently double to triple that of the other eager learners. It was still significantly faster than the neural network. Even after dropping the 63 nodes in the hidden layer, the neural network was still significantly slower than SVM at the same training set size.

Follow up experiments were performed to see how changes to the SVM kernel would affect it's performance. It can be seen from Figure 25 that using a polynomial kernel function with degree 6 produced the smallest classification error (2%), which is significantly lower than that achieved by the linear kernel (7%).

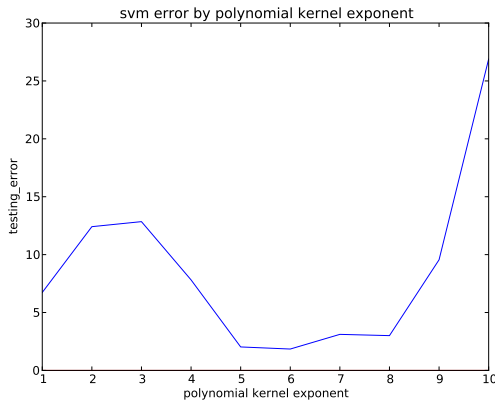


Figure 25: Mushroom - error by svm polynomial kernel exponent

The SVM kernel was then changed to a radial basis kernel to evaluate it's behavior. Figure 26 shows that the smallest classification error (2%) was reached with a gamma of 0.225. This is the same error as that found using the degree 6 polynomial kernel. However, the RBF kernel took twice as long to train (0.8 sec vs. 0.4).

3.7 k-nearest neighbor

Initial performance results, with a single nearest neighbor, show a classification error of 3%. Figure 27 shows the results of experimenting with various values for k. The plot indicates that k=3 lowered the error on a 1,000 instance training set to 2.5%.

4. ANALYSIS

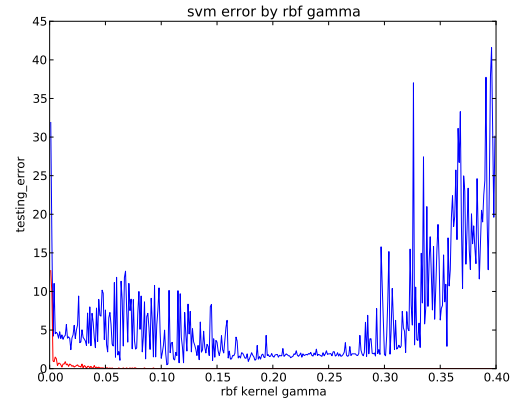


Figure 26: Mushroom - error by svm rbf gamma

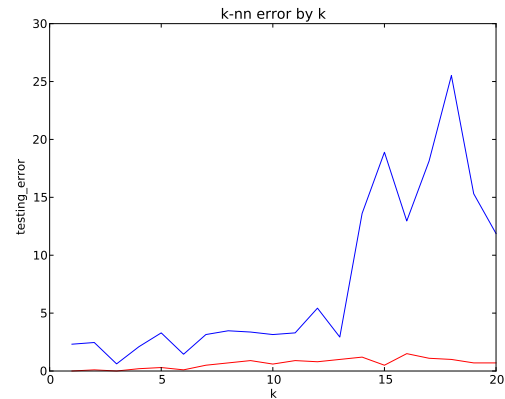


Figure 27: Mushroom - error by number of k-nn neighbors

4.1 Overview of Results

4.2 Algorithm Comparison

5. REFERENCES

- [1] K. Bache and M. Lichman UCI Machine Learning Repository 2013 <http://archive.ics.uci.edu/ml>
University of California, Irvine, School of Information and Computer Sciences