



UNIMORE

UNIVERSITÀ DEGLI STUDI DI
MODENA E REGGIO EMILIA

Basketball Intelligent System

Proof of Concept

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Project Goals

Introduction

Intelligent system capable of understanding the game of basketball and collect statistics through visual data

Test and analyze the pros and cons of different procedures to resolve the task of detection and identification of basketball players in videos

The Approaches

Classical Approach

Court Detection

Player Detection

Player Retrieval
Identification

Players Homography
to 2D

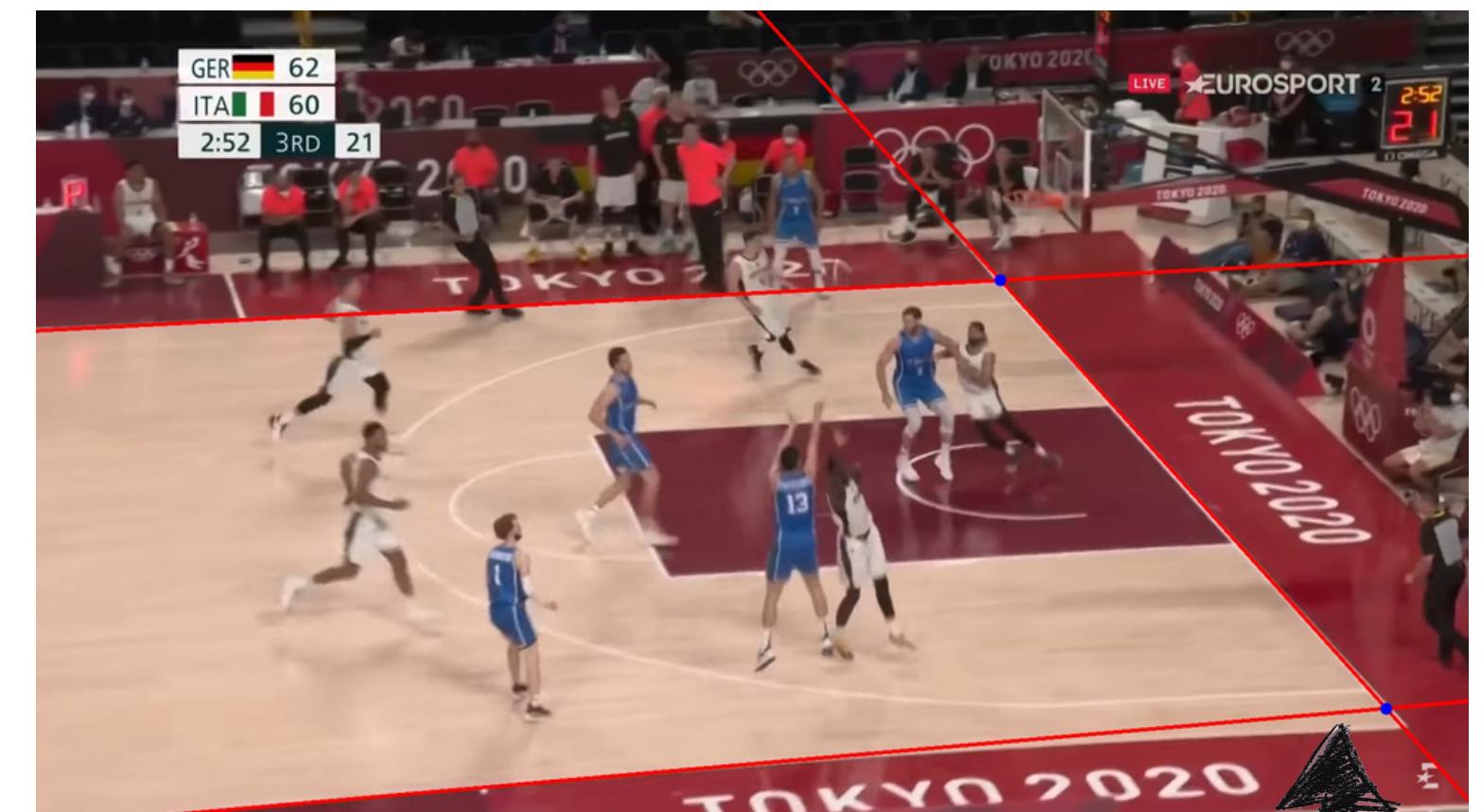
Deep Approach

YoloV5

01 Court Detection

Edge Based Hough lines

- To prevent errors due to noise some pre-processing steps were implemented including a gaussian blur
- Iterative approach changing the threshold of Canny and Hough in order to obtain only 3 lines



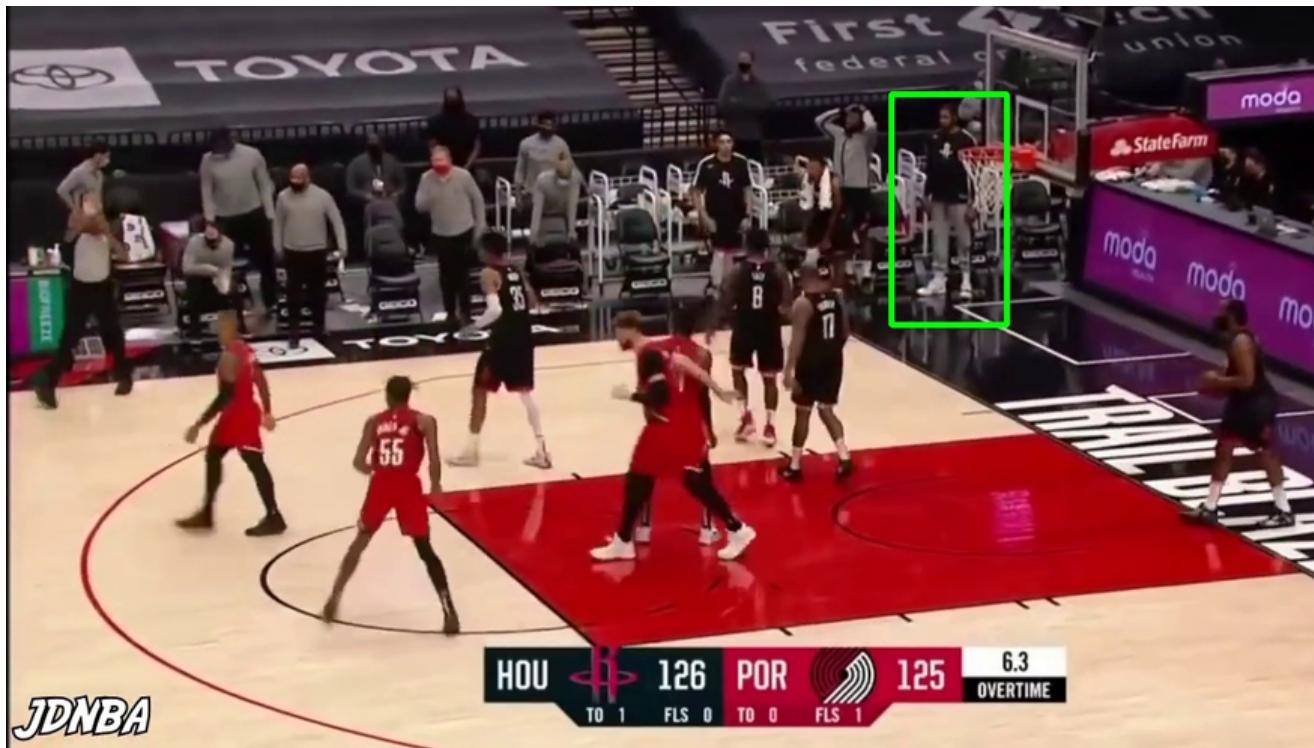
Lens distortion

02 Player Detection

HOG Detector combined with pre-trained SVM

Standard Parameters:

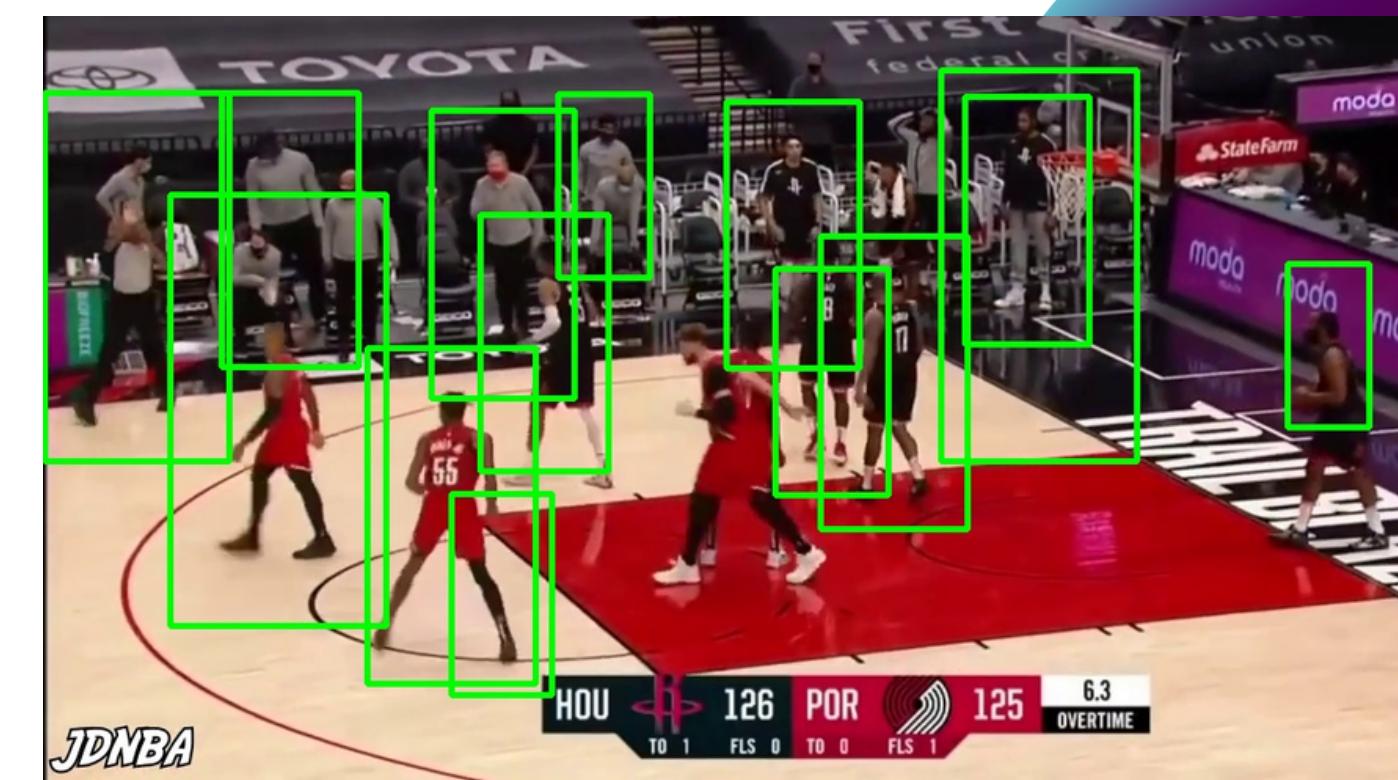
- `sliding_window: 8 * 8`
- `scales: 1.5`



HOG Detector combined with pre-trained SVM

Tuned Parameters

- `sliding_window: 4 * 4`
- `scales: 1.05`

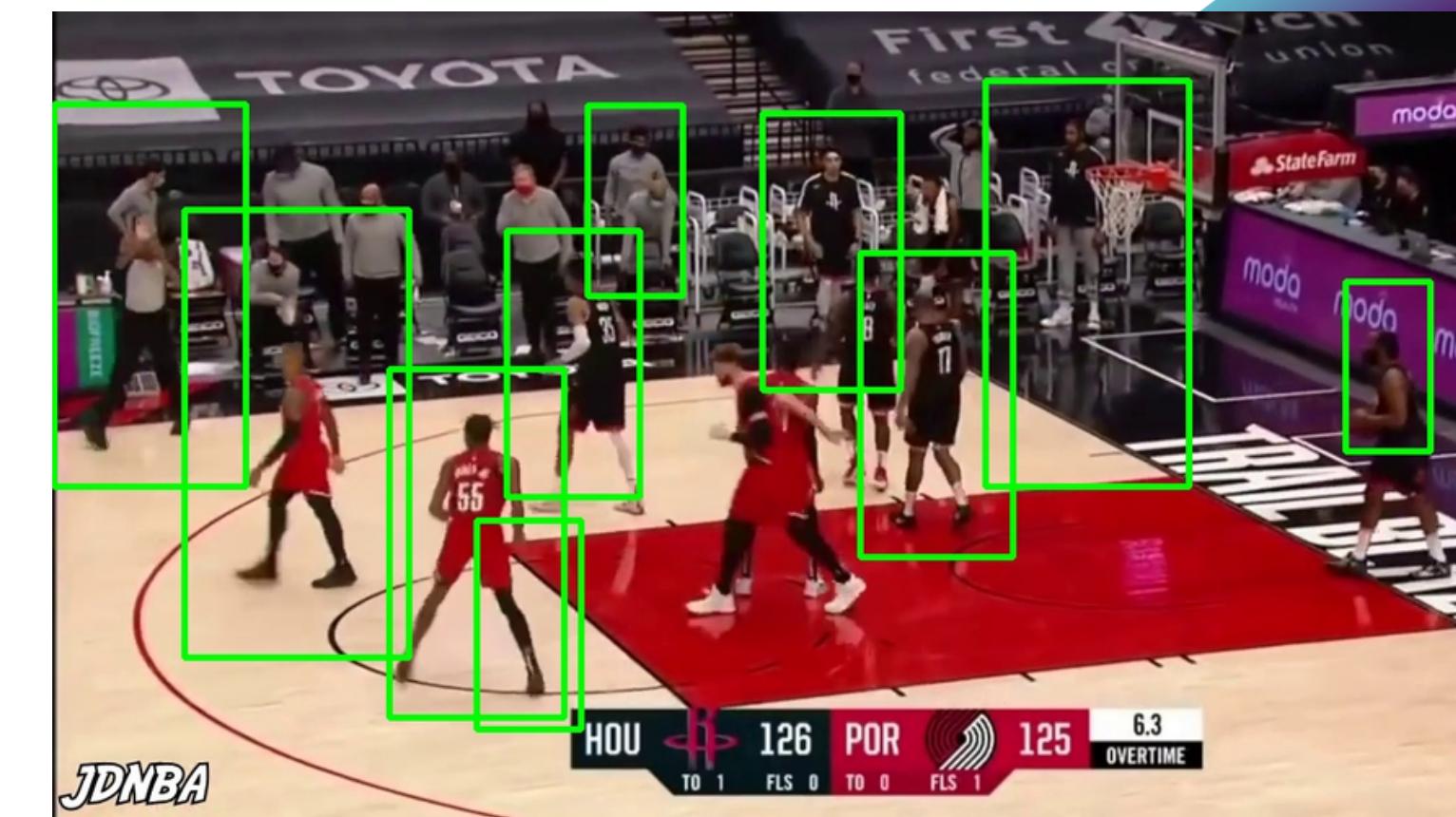


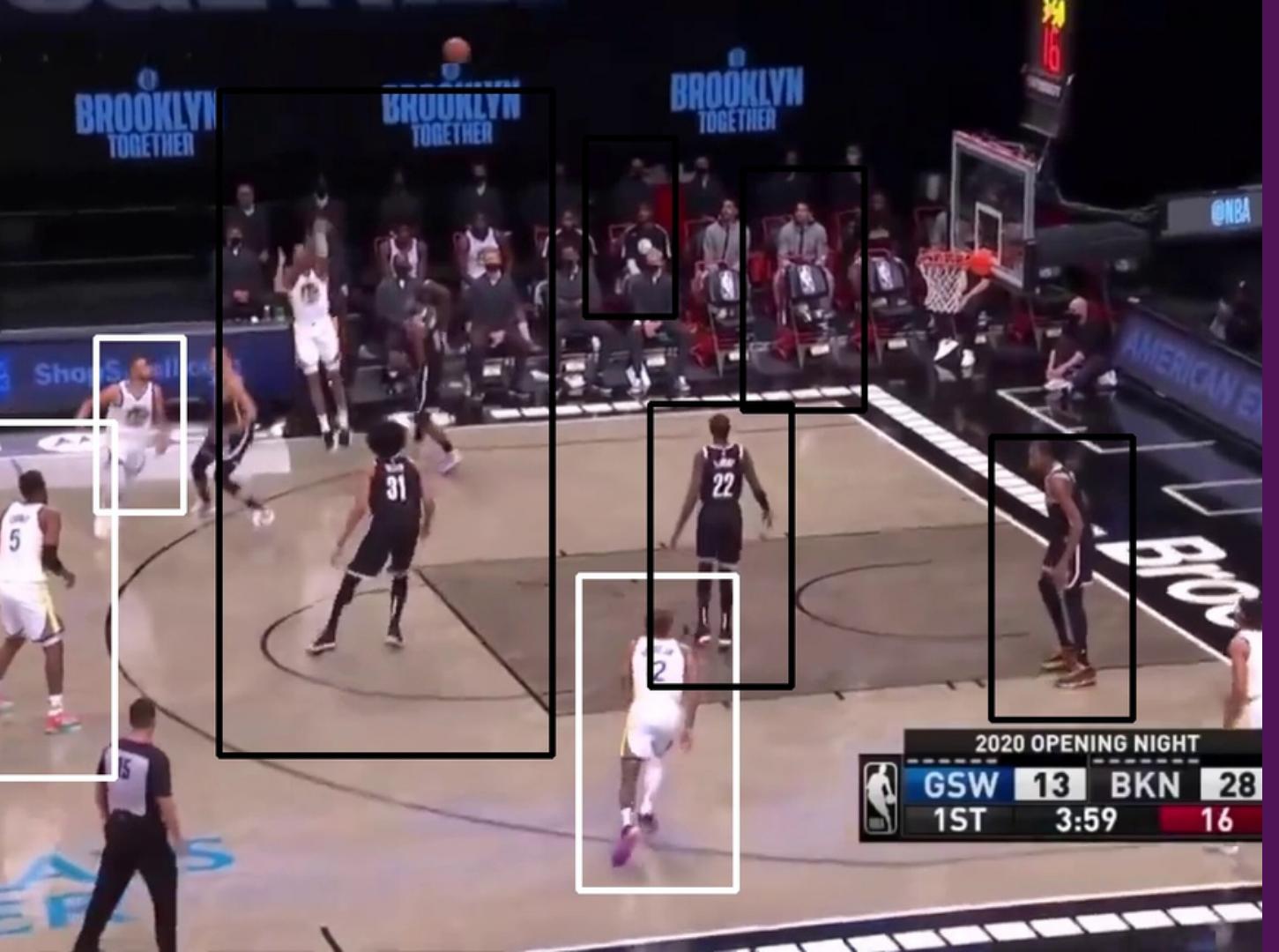
02 Player Detection

Non-Maximum
Suppression (NMS)

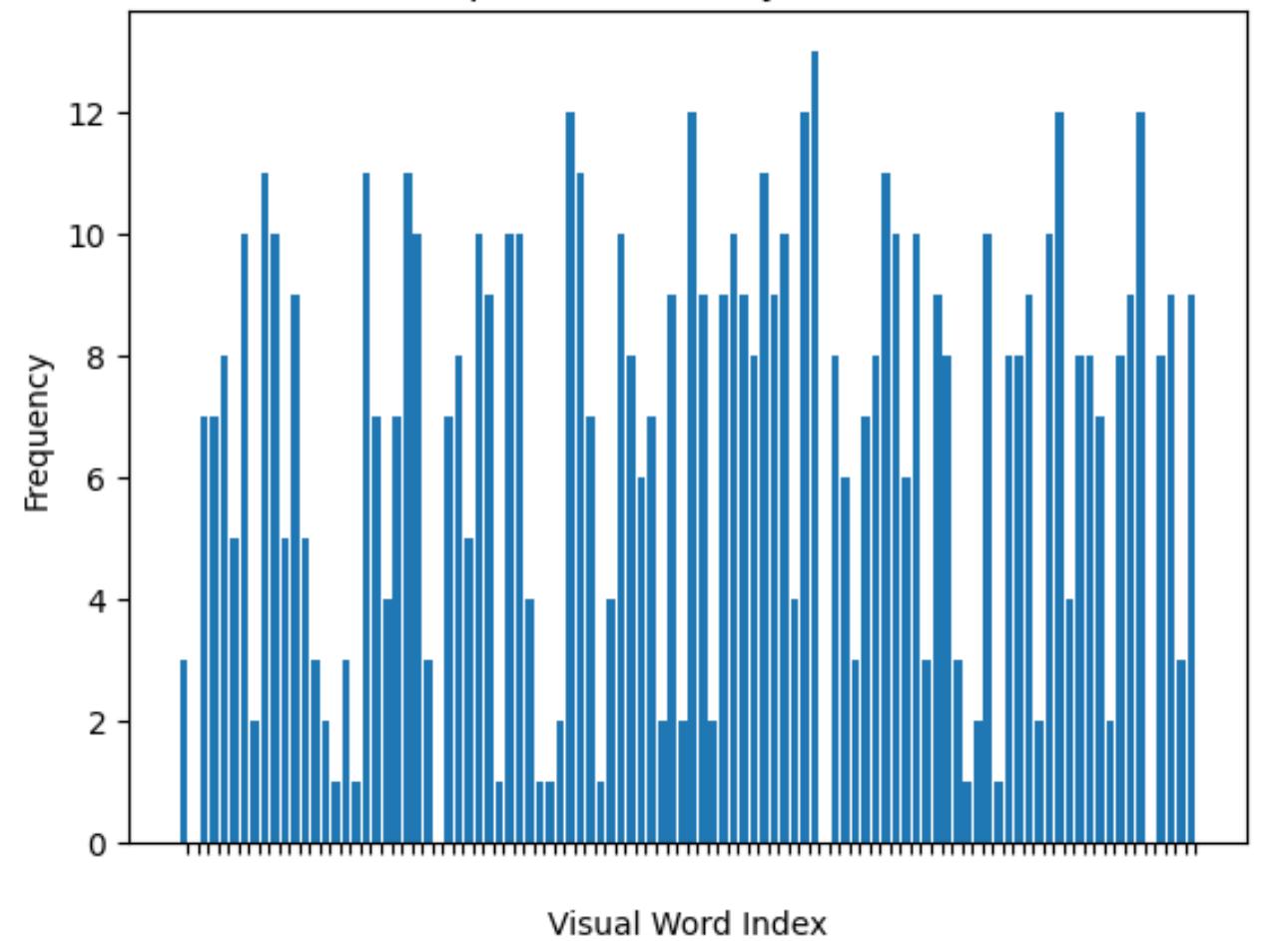


Final Results





Complete Vocabulary Generated



Query image



First retrieved image



Player Retrieval Identification

04

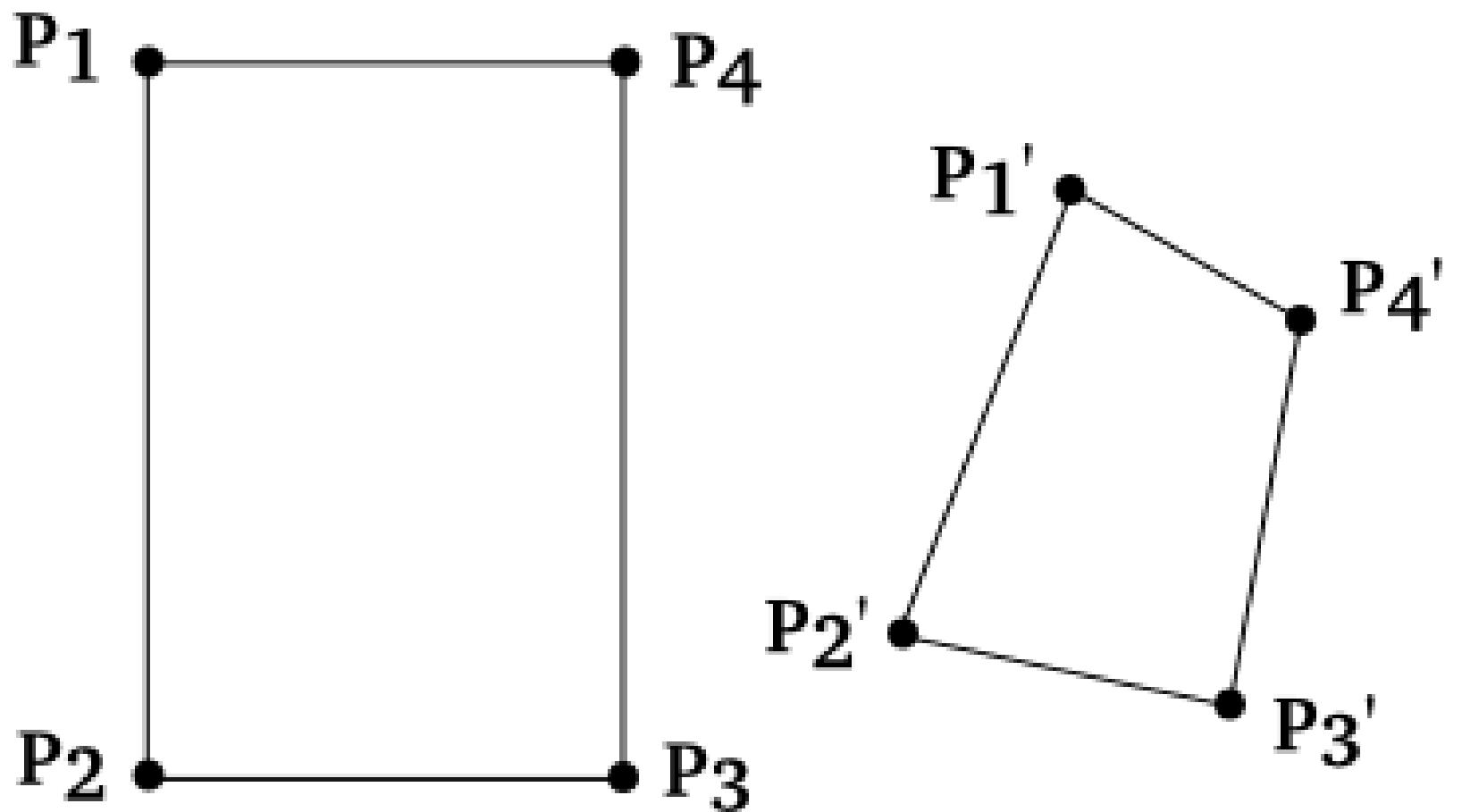
- A feature is created for every image using BoW with SIFT
- The histograms of visual words describing each image of the dataset are computed and stored
- Given a query image we calculate using our vocabulary its features descriptor
- Earth Mover's Distance is used to compare our image with the one of the dataset
- The algorithm return the closest image

05

Players

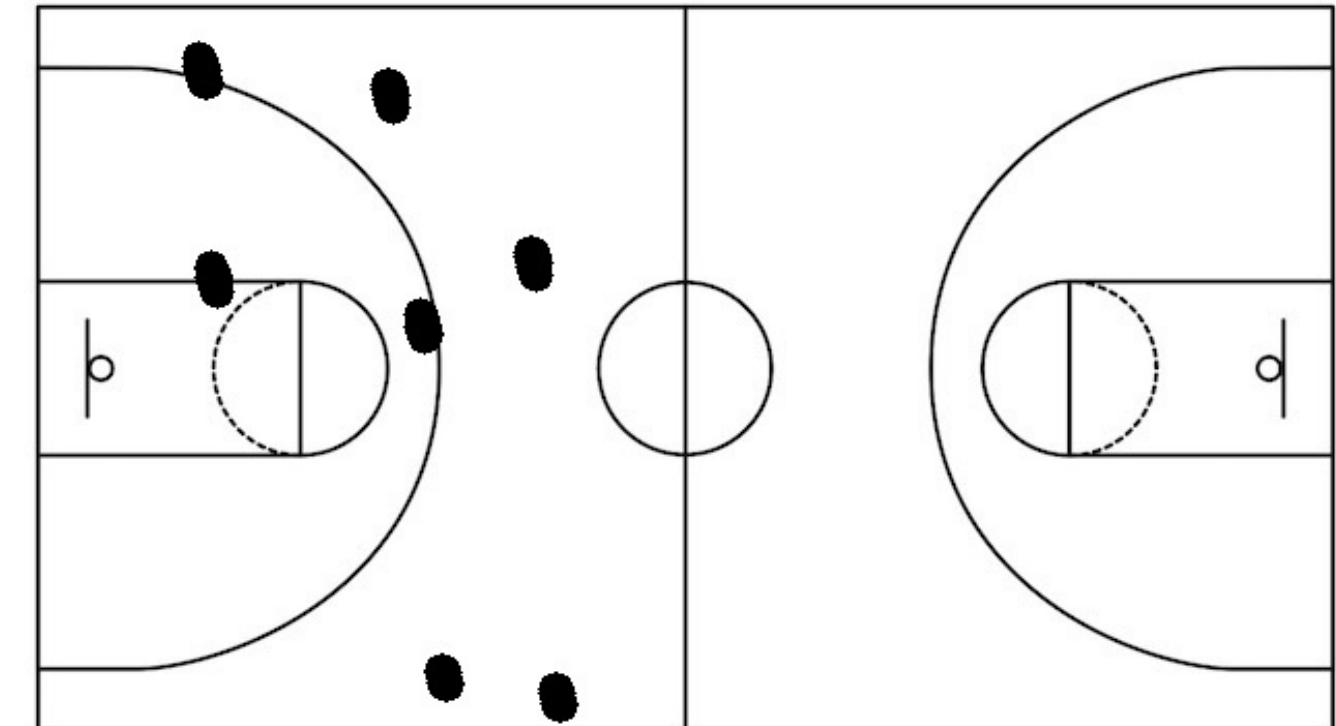
Homography

to 2D

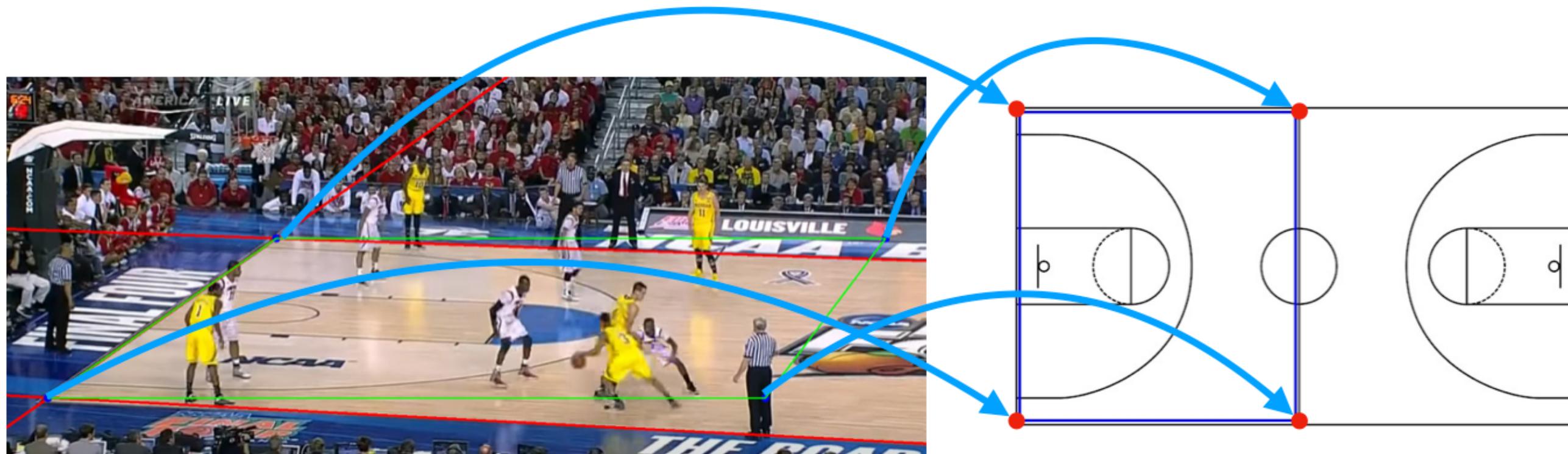


Goal

Find the bird view of the court in 3D, projecting the players coordinates in order to do tactic analysis



The Process 1/2



- ✓ `findHomography()`
- ✗ `getPerspectiveTransformation()`

The Process 2/2



- ✓ warpPerspective()
- ✗ warpAffine()

Future Improvements

Game Tactics Analysis

Through Homography Best Actions in a
2D court

Complete Pipeline

Direct link from video to analytics

The background features a dark purple gradient with three semi-transparent overlapping circles. One large circle is centered in the middle, another is in the top right corner, and a third is in the bottom left corner.

Deep Approach

Why YoloV5?

- All of the others object detection algorithms use regions to localize the object within the image and don't look the complete image
- YOLO v5 has a clear advantage in terms of run speed
- Easy to train and run inference on
- Small dataset and low power of our machine

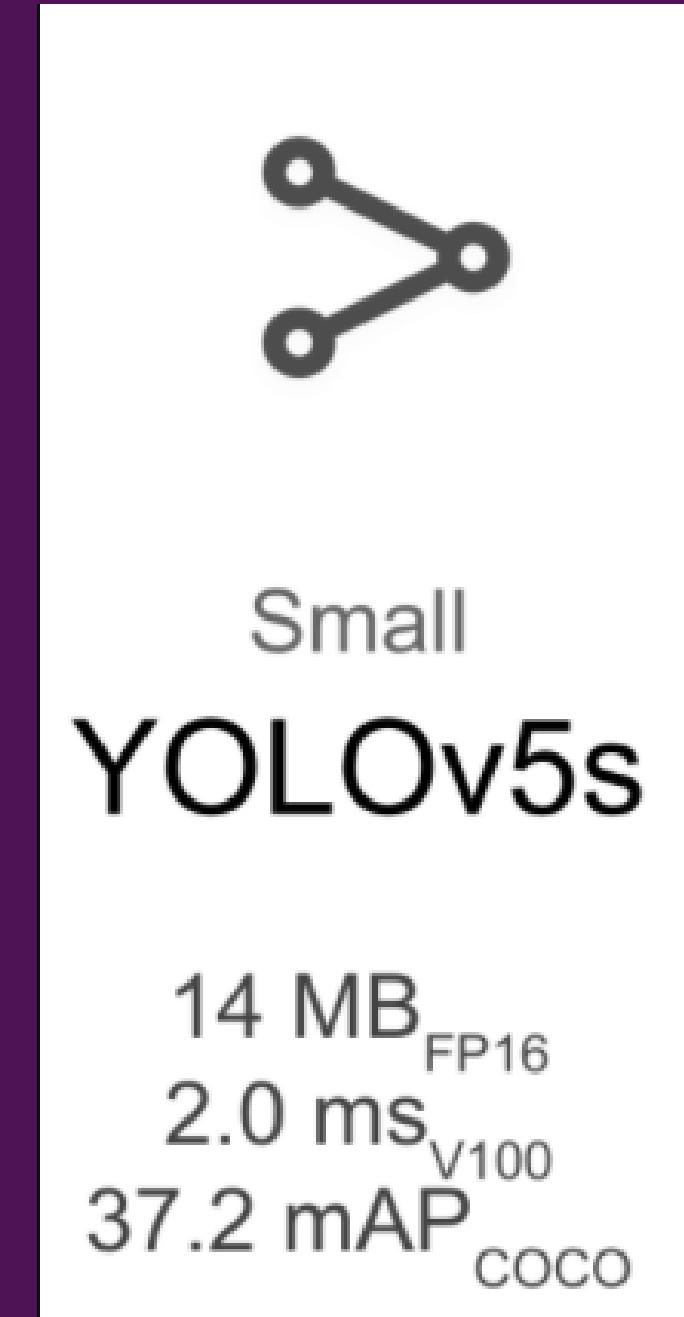
YoloV5 Training

Dataset closer to our needs, containing 500 images of basketball games, and label it by hand, using the LabelImg tool.

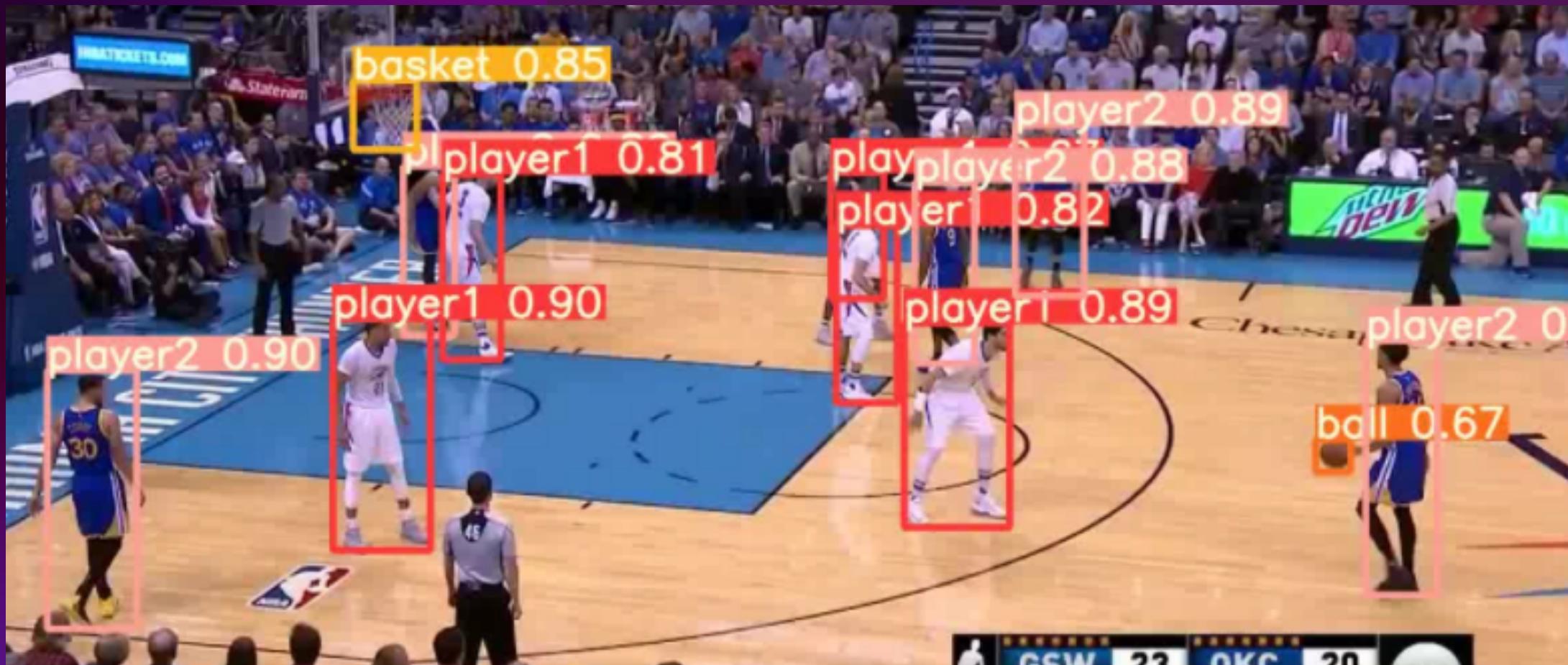
100 epochs

32 batch

640x640 images

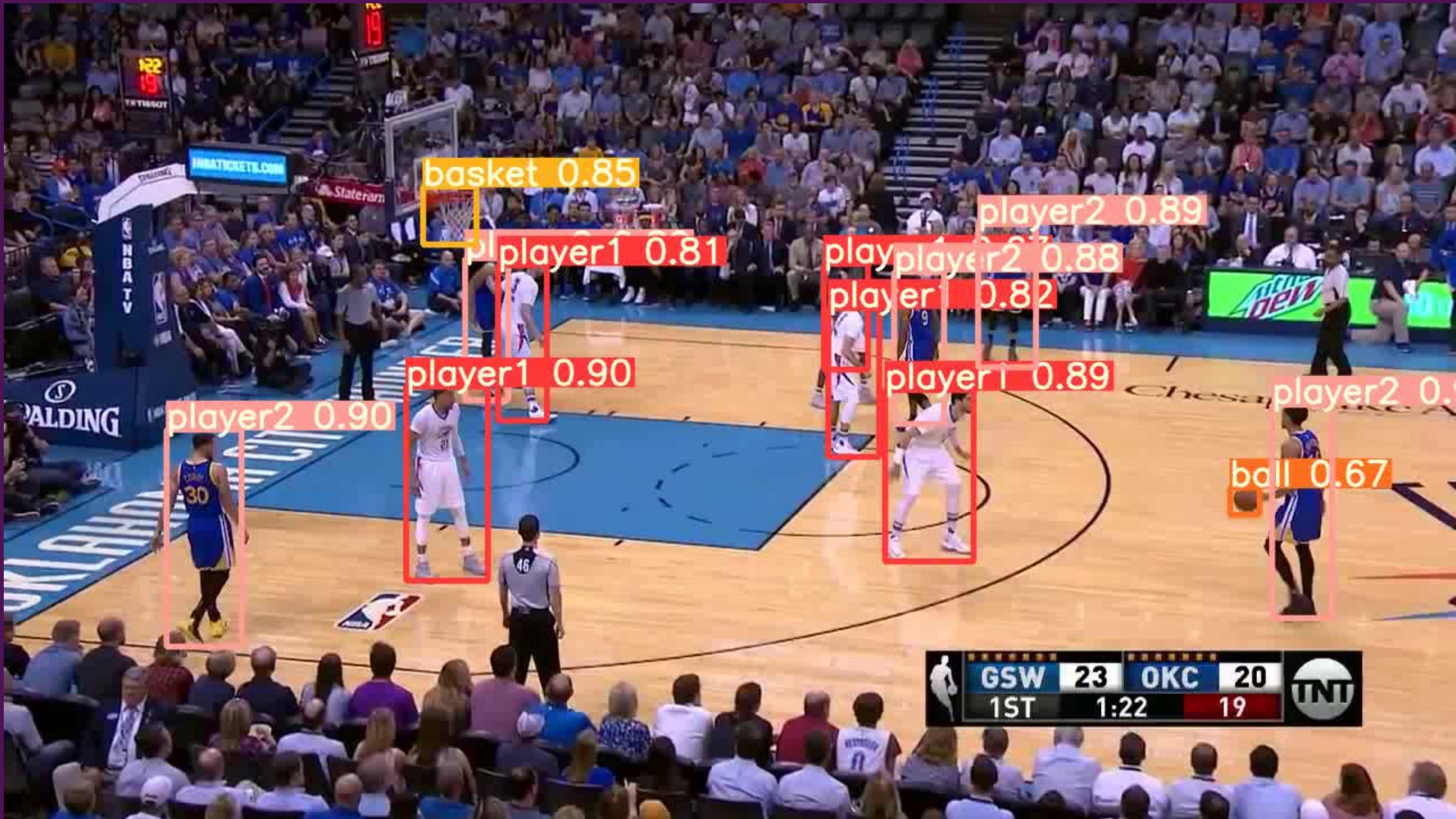


Player Detection & Team Identification

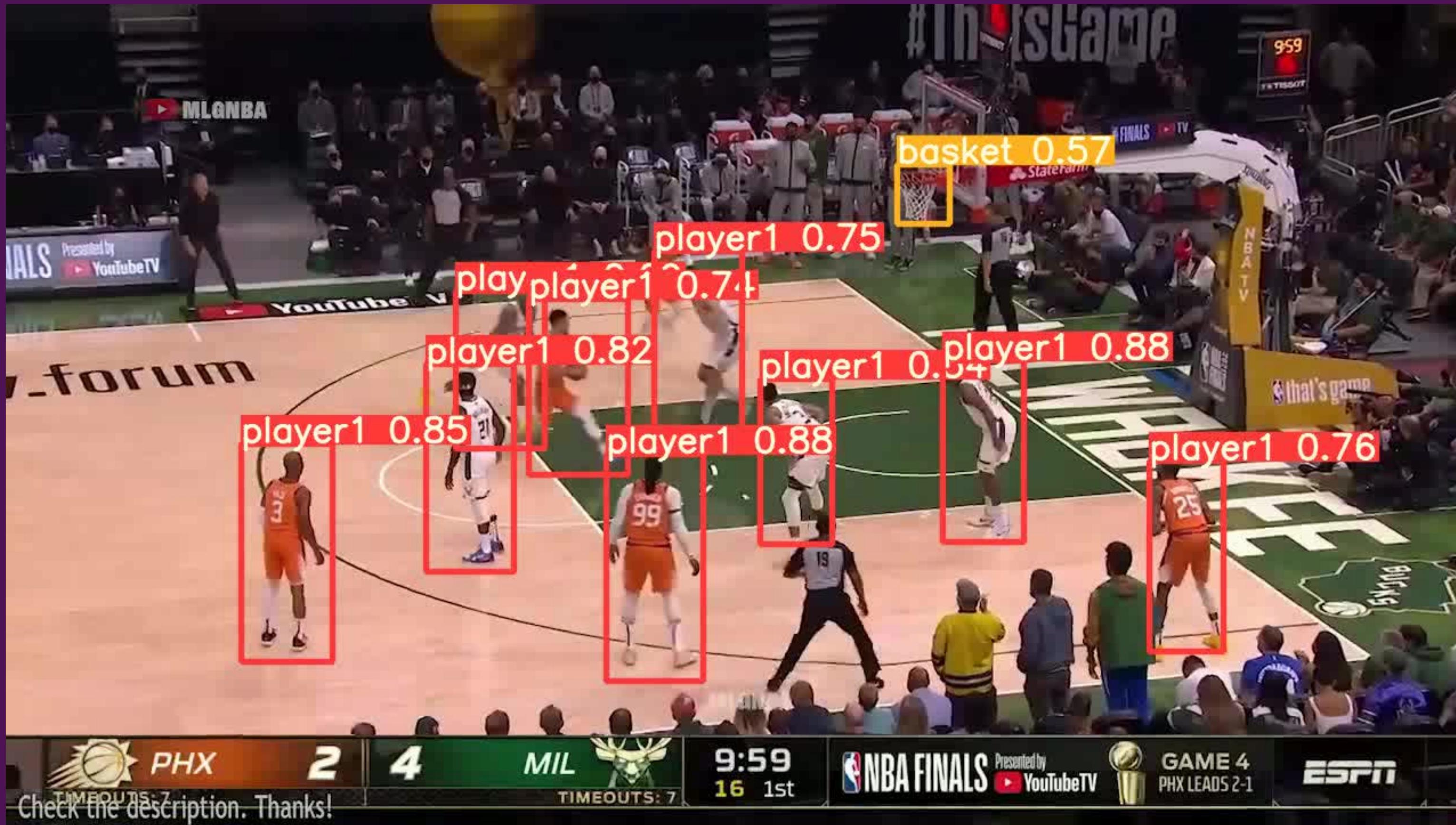


4 Labels:

- Player1
- Player2
- Ball
- Basket







Results

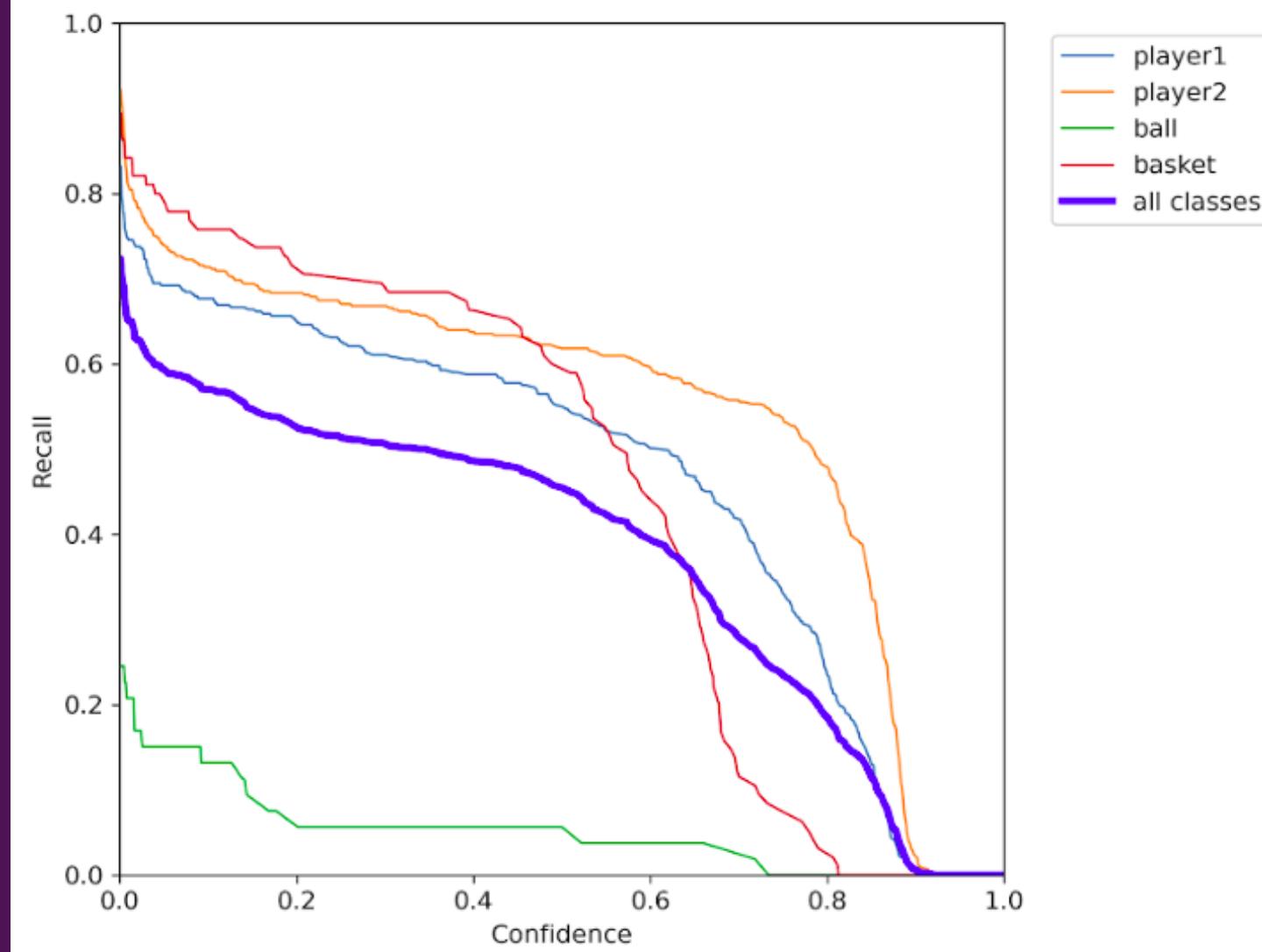
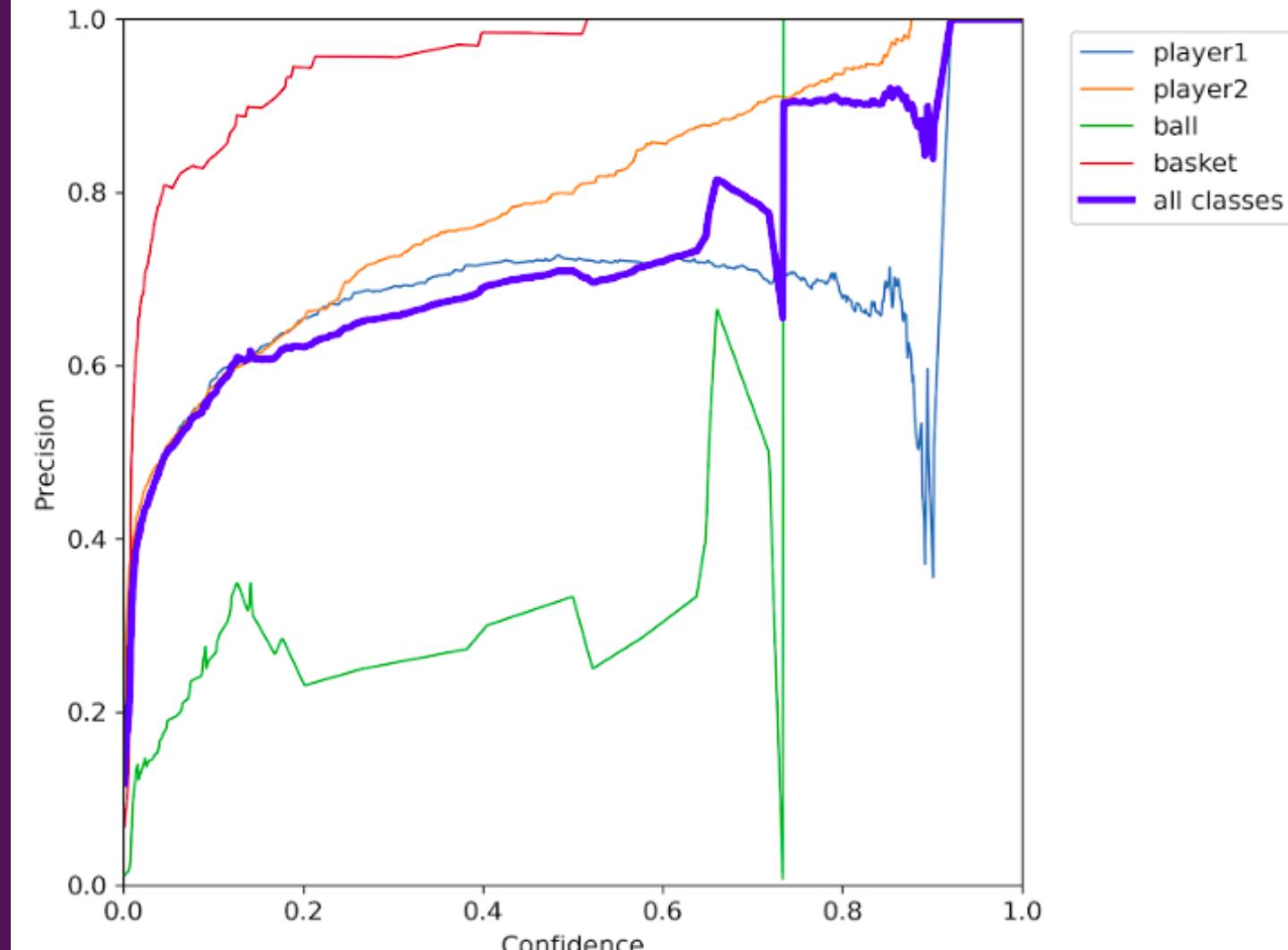
Test dataset of 100 images

Precision

• Overall	0.61
• Player1	0.6
• Player2	0.6
• Ball	0.35
• Basket	0.89

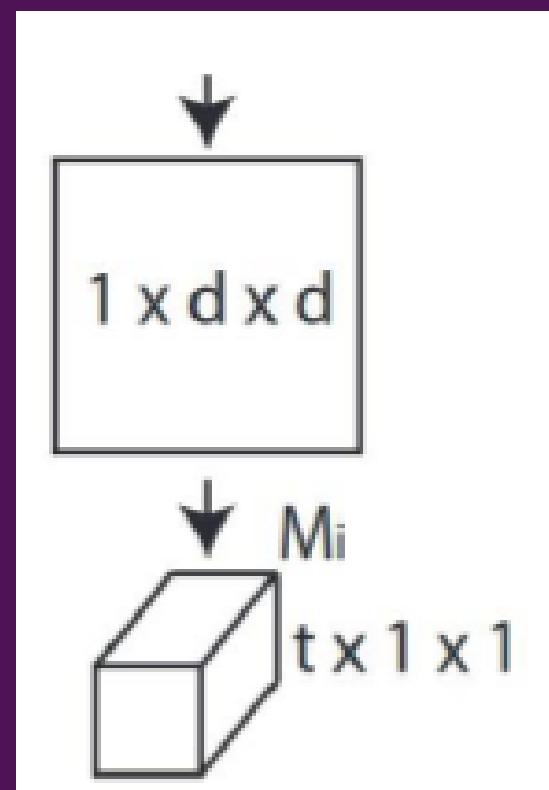
Recall

0.57
0.67
0.7
0.13
0.76

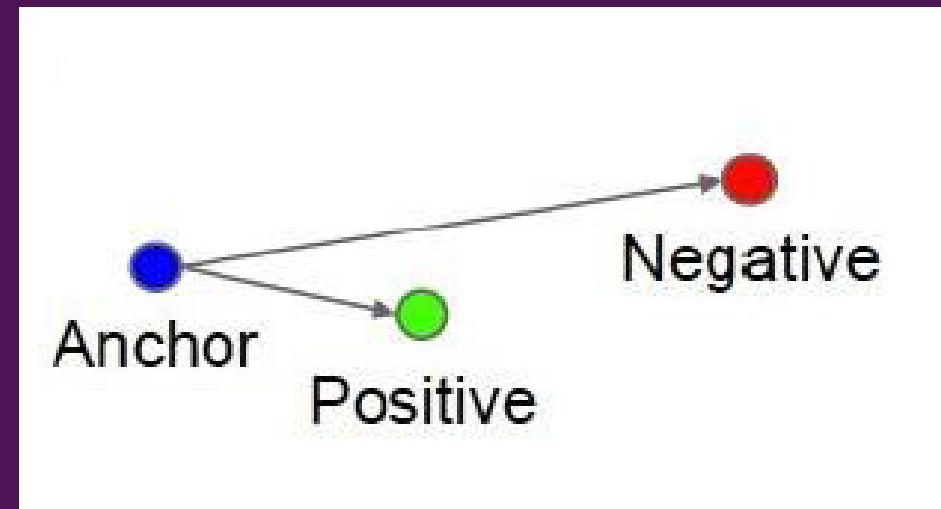


Future Improvements

Test a 2D + 1
neural network
for action
recognition



Deep network
with triplet loss
training
for player
identification



Improve dataset
quality and size



Conclusions

Classical Approach

- It was interesting to understand how to change the parameters to obtain the best possible results
- Some tasks are still difficult to solve
- Tuning of algorithms of this type is extremely complex in the face of a chaotic environment such as that of a basketball court.

Deep Approach

- We are able to observe the power of these networks despite the poor quantity and quality of data
- The computational power required for the training of these networks is to be taken into consideration (28 hours in our case).
- It became clear in us the capability of elegantly and compactly translating complex semantics such as sports.



Thank you!

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