

# Thevenin's Equivalent of Photovoltaic Source Models for MPPT and Power Grid Studies

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**Abstract**—The model of a photovoltaic (PV) source is needed for Maximum Power Point Tracking (MPPT) and power grid studies. The single diode model can fairly emulate PV's characteristic. The only nonlinear element in this model is the single diode. This paper proposes Thevenin's equivalent model for a PV source by piecewise linearization of the diode characteristic. The variation of the parameters with the change in temperature and irradiance is also studied. It is shown that Thevenin's equivalent model of PV produces a voltage-current characteristic which represents the PV source operation fairly well.

**Index Terms:** Modeling, photovoltaics (PVs), power grid.

## I. INTRODUCTION

WITH the supply of fossil fuel dwindling and the threat of global warming looming large, alternative sources of energy have to be put into wider use. The European Union has set an objective of reaching a penetration of renewable energy of 12% [1]. Solar energy is a renewable source of energy which is available in abundance and can be converted into electrical energy directly by photovoltaic (PV) sources. The European Union is campaigning for one million PV systems with a total capacity of 1 GW (peak) by 2010 [1]. The increased penetration of the PV system necessitates a mathematical model, which can be used for the study of power grids [2].

A PV source has a non-linear voltage-current (V-I) characteristic, which can be modeled using current sources, diode(s), and resistors. Single-diode and double-diode models are widely used to simulate PV characteristics. The single-diode model emulates the PV characteristics fairly accurately. The manufacturer provides information about the electrical characteristics of PV by specifying certain points in its V-I characteristics, which are called remarkable points [3].

This paper uses the single-diode model to develop a Thevenin's equivalent model of PV. It first discusses the parameter estimation of a single-diode model for a given temperature and irradiance and then it discusses develop-

ing Thevenin's equivalent model by using those parameters.

As shown in Figure 1, the single diode model for PV consists of a current source representing the photo-generated current, a diode, and two resistances (series and parallel). From Kirchhoff's current law, the output current can be written as in (1) [4-6].

$$I = I_{ph} - I_0 \left\{ \exp \left( \frac{V + IR_s}{n_s V_t} \right) - 1 \right\} - \frac{V + IR_s}{R_{sh}} \quad (1)$$

where  $V$  and  $I$  are the module output voltage and current, respectively;  $I_{ph}$  and  $I_0$  are the photo-generated current and the dark saturation current, respectively;  $V_t$  is the junction thermal voltage,  $R_s$  and  $R_{sh}$  are the series and parallel resistances, respectively;  $n_s$  is the number of cells in the module connected in series.

The thermal voltage of the diode is related to the junction temperature as given by (2),

$$V_t = \frac{kTA}{q} \quad (2)$$

where  $k$  is the Boltzmann's constant,  $T$  is the junction temperature,  $A$  is the diode quality factor, and  $q$  is the electronic charge.

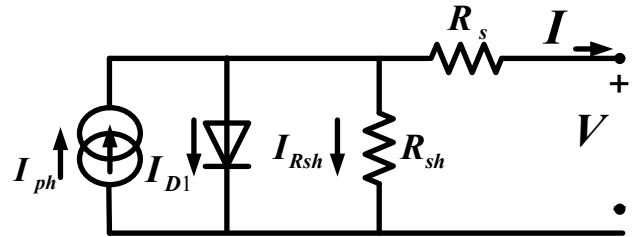


Fig. 1. The single-diode model of a PV source.

There are five unknown parameters in the single-diode model which need to be estimated before developing Thevenin's equivalent of the model. These unknown parameters are  $I_{ph}$ ,  $I_0$ ,  $V_t$ ,  $R_s$ , and  $R_{sh}$ . The estimation of

these parameters is performed from the information provided by the manufacturers' datasheet. Once the parameters are known, they are adjusted for the changing environmental conditions. With the parameters known, the model is linearized to obtain Thevenin's equivalent model of PV as seen back into PV from its output terminals. Other related papers are given in [7-11].

## II. PARAMETER ESTIMATION

The manufacturers' datasheet provides the remarkable points and the temperature coefficients of the voltage,  $k_v$ , and current,  $k_i$ . The remarkable points are points of interest on the V-I curve of PV at standard test condition (STC) which is usually a junction temperature of 25° C and an irradiance of 1000 Wm<sup>-2</sup> [12]. The open-circuit voltage,  $V_{oc}$ , the short-circuit current,  $I_{sc}$  and the voltage,  $V_{mpp}$ , and current,  $I_{mpp}$ , at maximum power point (MPP) are provided from the datasheet. Using the above information, the five unknown parameters are estimated [3].

The estimation process is simplified by neglecting the '-1' in (1), since the exponential term is large compared to 1. Three equations, (3) through (5), are obtained from the V-I characteristic by substituting the remarkable points into (1). Since there are five unknown parameters, two more equations are needed.

$$I_{sc} = I_{ph} - I_o \cdot \exp\left\{\frac{I_{sc} \cdot R_s}{n_s \cdot V_t}\right\} - \frac{I_{sc} \cdot R_s}{R_{sh}} \quad (3)$$

$$I_{mpp} = I_{ph} - I_o \cdot \exp\left\{\frac{V_{mpp} + I_{mpp} \cdot R_s}{n_s \cdot V_t}\right\} - \frac{V_{mpp} + I_{mpp} \cdot R_s}{R_{sh}} \quad (4)$$

$$I_{oc} = 0 = I_{ph} - I_o \cdot \exp\left\{\frac{V_{oc}}{n_s \cdot V_t}\right\} - \frac{V_{oc}}{R_{sh}} \quad (5)$$

The next equation is derived from the power at the maximum power point, and therefore, the derivative of power with respect to voltage at that point is zero:

$$\left.\frac{dP}{dV}\right|_{V=V_{mpp}, I=I_{mpp}} = 0 \quad (6)$$

With four of the five equations formed, the fifth equation is formed from the slope of the V-I curve at short circuit point as shown in (7).

$$\left.\frac{dI}{dV}\right|_{V=0, I=I_{sc}} = -\frac{1}{R_{sho}} \quad (7)$$

It is observed that the value of  $R_{sho}$  is approximately equal to the parallel resistance,  $R_{sh}$  and the equation (7) is now written as in (8). Utilizing this fact, all of the five parameters can now be estimated from the information provided by the datasheet only.

$$\left.\frac{dI}{dV}\right|_{V=0, I=I_{sc}} \approx -\frac{1}{R_{sh}} \quad (8)$$

The variables above are now changed for systematic mathematical representation as listed in Table I.

TABLE I  
LIST OF VARIABLE TRANSFORMATIONS

Datasheet values		
$I_{sc}$	$a_1$	Short-circuit current
$V_{oc}$	$a_2$	Open circuit voltage
$V_{mpp}$	$a_8$	Voltage at MPP
$I_{mpp}$	$a_4$	Current at MPP
$n_s$	$a_5$	Number of cells in series in a module
Unknown parameters		
$I_{ph}$	$x_1$	Photo-generated current
$I_o$	$x_2$	Dark saturation current
$V_t$	$x_3$	Junction voltage
$R_s$	$x_4$	Series resistance
$R_{sh}$	$x_5$	Parallel resistance
$R_{sho}$	$x_6$	Effective resistance at short circuit
Output quantities of the PV source		
$I$	$y_1$	Output current
$V$	$y_2$	Output voltage
$P$	$y_3$	Output power

Simplifying the five equations, (3) through (6), and (8), in a method shown in [13], we arrive at five equations, (9) through (13), which are solved to obtain the parameters:

$$x_1 = x_2 \exp\left\{\frac{a_2}{a_5 \cdot x_3}\right\} + \frac{a_2}{x_5} \quad (9)$$

$$x_2 = \left(a_1 - \frac{a_2 - a_1 x_4}{x_5}\right) \exp\left\{-\frac{a_2}{a_5 \cdot x_3}\right\} \quad (10)$$

$$x_3 = \frac{a_4 \cdot x_4 + a_3 - a_2}{J} \quad (11)$$

where  $J = a_5 \cdot \log \left( \frac{a_1 x_4 + a_1 x_5 - a_4 x_4 - a_4 x_5 - a_3}{a_1 x_4 + a_1 x_5 - a_2} \right)$

$$x_4 = \frac{a_2 - a_3 + a_5 x_3 \cdot \ln(M)}{a_4} \quad (12)$$

where

$$M = \frac{a_5 x_3 (a_4 x_4 + a_4 x_5 - a_3)}{a_1 x_4 a_3 + a_1 x_5 a_3 + a_4 a_2 x_4 - a_4 a_1 x_4^2 - a_4 a_1 x_5 x_4 - a_3 a_2}$$

$$x_5 = \frac{a_5 x_3 x_4 + a_5 x_3 x_5 + N}{a_5 x_3 + N} \quad (13)$$

where  $N = x_4 \cdot \exp \left\{ \frac{a_1 x_4 - a_2}{a_5 x_3} \right\} \cdot (a_1 x_4 + a_1 x_5 - a_2)$ .

It is seen that equations (11) through (13) are transcendental equations, whereas (9) and (10) are not. Therefore, the solution of the above equations reduces down to a numerical solution of three equations and then we use the parameters found to obtain the values of the remaining two parameters of (10) and (9), respectively.

### III. CASE STUDY

A case study to find the parameters of the PV module produced by Mitsubishi Electric, PV-MF165EB3, was conducted at STC and at varying environmental conditions. Table II lists the values provided on the datasheet, followed by the values of the estimated unknown parameters.

TABLE II  
DATASHEET VALUES AND ESTIMATED PARAMETERS OF A MODULE

Datasheet Values		Estimated Parameters	
$I_{sc}$	7.36 A	$I_{ph}$	7.36 A
$V_{oc}$	30.4 V	$I_o$	0.104 $\mu$ A
$V_{mpp}$	24.2 V	$A$	1.310
$I_{mpp}$	6.83 A	$R_s$	0.251 ohm
$n_s$	50	$R_{sh}$	1168 ohm
Temperature coefficients			
$K_i$	0.057%	$K_v$	-0.346%

### IV. TEMPERATURE AND IRRADIANCE DEPENDENCE

The V-I characteristics of PV change with the change in the irradiance and the junction temperature. The de-

velopment of power in PV, as a result of irradiance on it, is modeled in the single diode model as the current source represented by the photo-generated current. As a result, the photo-generated current is directly proportional to the irradiance as given in (14). And since the short circuit current is directly proportional to the photo-generated current, equation (15) follows:

$$x_1(G) = x_1(G_{stc}) \cdot \frac{G}{G_{stc}} \quad (14)$$

$$a_1(G) = a_1(G_{stc}) \cdot \frac{G}{G_{stc}} \quad (15)$$

where  $G$  is the irradiance on the module and  $G_{stc}$  is the irradiance on the module at STC.

The open-circuit voltage, however, is not directly proportional to the irradiance: rearranging (9), the open-circuit voltage, as a function of irradiance is given by (16).

$$a_2(G) = a_5 \cdot x_3 \ln \left( \frac{x_1(G) \cdot x_5 - a_2(G)}{x_2 \cdot x_5} \right) \quad (16)$$

The manufacturer's datasheet provides the temperature coefficients of both short-circuit current and open-circuit voltage as in (17) and (18), respectively [13].

$$x_1(T) = x_1(T_{stc}) + K_i (T_{stc} - T) \quad (17)$$

$$x_2(T) = x_2(T_{stc}) + K_v (T_{stc} - T) \quad (18)$$

The dark saturation current of the diode is a function of temperature only. Its value at a given temperature is derived by expressing the terms in (10) as a function of temperature, as given in (19).

$$x_2(T) = \left( a_1(T) - \frac{a_2(T) - a_1(T)x_4}{x_5} \right) \exp \left\{ -\frac{a_2(T)}{a_5 \cdot x_3} \right\} \quad (19)$$

The photo-generated current is also a function of temperature, and its value at a given temperature is found by writing the terms in (9) as functions of temperature as given in (20).

$$x_1(T) = x_2(T) \exp \left\{ \frac{a_2(T)}{a_5 \cdot x_3} \right\} + \frac{a_2(T)}{x_5} \quad (20)$$

Following (14) through (20), the parameters of the PV which change with temperature and irradiance are adjusted. It should be noted that the photo-generated current and the dark saturation current are the only two parameters which change with temperature and irradiance. The other parameters remain unaffected.

## V. LINEARIZATION OF DIODE

The only non-linear element in the model shown in Figure 1 is the diode. The voltage and current (V-I) in a diode are related by an exponential relationship as given by Shockley and is given in (21) [14]:

$$I_D = I_o \left\{ \exp \left( \frac{V_D}{n_s V_t} \right) - 1 \right\} \quad (21)$$

where  $V_D$  and  $I_D$  are the diode voltage and current, respectively.

The piecewise linearization is used to linearize the diode as shown in Figure 2. In this technique, the function is divided into a number of small regions. In each region, a straight line is used to closely approximate the actual nonlinear function, as shown in Figure 2. It is assumed that the non-linear function can be approximated by the straight line in that region.

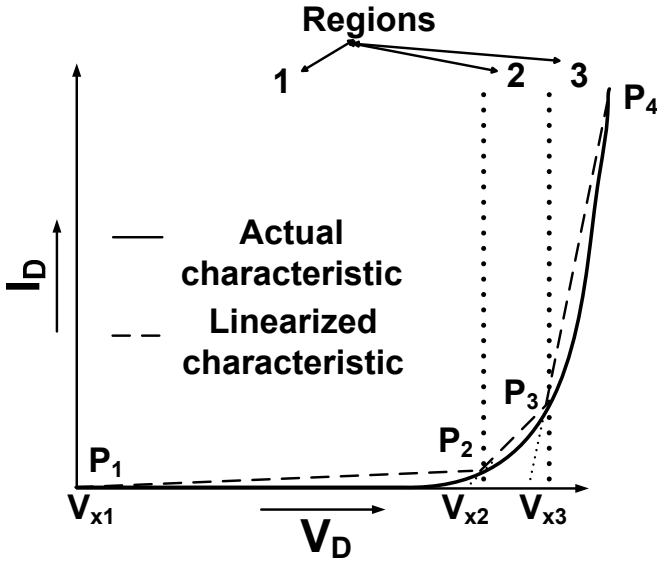


Fig. 2. Voltage current characteristic of diode showing actual characteristic and the linear approximation [14].

In Figure 2, the diode characteristic has been approximated by dividing its characteristic into three regions, in each of which a diode is represented by a straight line. In terms of circuit, each of these lines can be approximated by a voltage source  $V_x$  and a resistance  $R_D$ . The voltage

source  $V_x$  is actually the voltage axis intercept of the straight lines represented by  $V_{x1}$ ,  $V_{x2}$ , and  $V_{x3}$  in Figure 2 for regions 1, 2, and 3 respectively. The resistance  $R_{D1}$ ,  $R_{D2}$ , and  $R_{D3}$  are the inverse of the slope of the lines in each region. It goes without saying that as the number of regions is increased, the piecewise linearization approximates the actual diode characteristic more closely, decreasing the error caused by the approximation.

The PV model, where the diode is linearized, is shown in Figure 3. The value of  $R_D$  and  $V_x$  will depend on the region of operation.

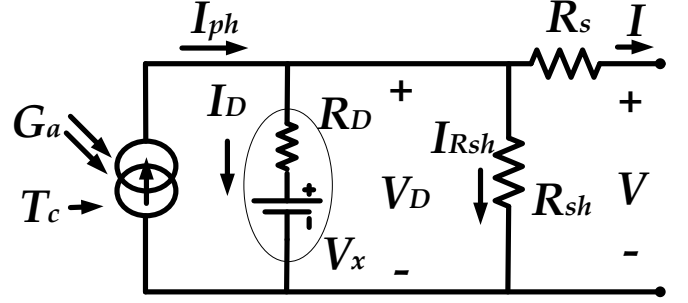


Fig. 3. PV model with diode linearized

The linearized model of Figure 3 can now be represented by Thevenin's equivalent voltage and resistance given by (22) and (23):

$$V_{Th,i} = V_{x,i} + R_{D,i} \cdot \frac{I_{ph} \cdot R_{sh} - V_{x,i}}{R_{sh} + R_{D,i}} \quad (22)$$

$$R_{Th,i} = R_s + \frac{R_{sh} \cdot R_{D,i}}{R_{sh} + R_{D,i}} \quad (23)$$

where,  $V_{Th,i}$  and  $R_{Th,i}$  are Thevenin's equivalent voltage and resistance of the model of Figure 3 at region  $i$  ( $i = 1, 2, \dots, \text{number of regions}$ ). Thevenin's equivalent circuit of the PV looking back from its output terminals is shown in Figure 4.

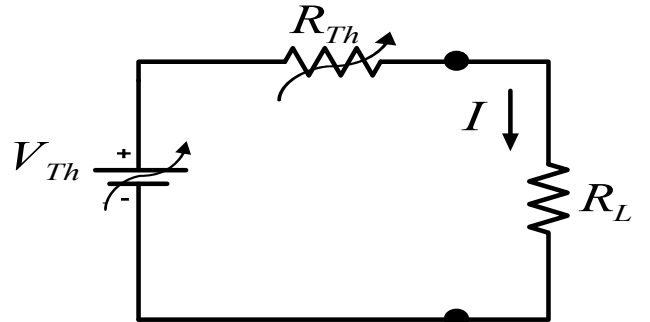


Fig. 4. Thevenin's equivalent circuit of PV

The piecewise linearization is an approximation technique, which has inherent error at points which do not coincide with the actual function. It is only those points given by the boundaries of the regions where the approximation exactly matches with the original function. Hence, at the boundaries of the regions, the error is zero.

The PV source is controlled to operate at maximum power point. Hence, it is desired that the approximation is error free at the point of operation. Therefore, one of the boundaries is chosen at MPP. Other boundaries can be either distributed evenly over the voltage range of operation or chosen, such that the error is minimal.

## VI. VOLTAGE-CURRENT CHARACTERISTIC OF PV

Once the five parameters of the PV are determined, the diode characteristic defined by  $A$  and  $I_o$  is also known. From the maximum power point of PV, the corresponding point on the diode voltage-current characteristic is also determined. One of the points for linearization is chosen at this point on the diode characteristic, so that when maximum power point tracking (MPPT) is applied, PV operates on the exact MPP instead of the approximated point. The other points are chosen on either side of the PV characteristics. More points are chosen on the right side of the PV characteristics as it is more curved and lesser on the left, as the characteristic is almost linear.

Since the relationship between the output voltage and current of PV is implicit, a numerical solution is needed to obtain the value of current at a given voltage. Several computational and simulation methods of voltage current characteristics are found in the literature [15-18]. But with the linearization of the diode characteristic and obtaining Thevenin's equivalent circuit of PV, the numerical solution is avoided.

## VII. SIMULATION RESULTS

Thevenin's equivalent model of PV is simulated at various temperatures and irradiances to see the effect of linearizing the diode characteristic of PV. The error in the approximation is plotted to show its accuracy. Here, the linearization has been done with ten points of linearization between zero and open circuit voltage. This means that there are nine regions with different Thevenin's voltages and resistances.

Figure 5 shows the voltage-current and voltage-power characteristic of PV for both the actual case and Thevenin's equivalent at STC along with the percent error in the plot for Thevenin's equivalent model. Table III lists the Thevenin's equivalent voltage and resistance at STC and for different values of currents.

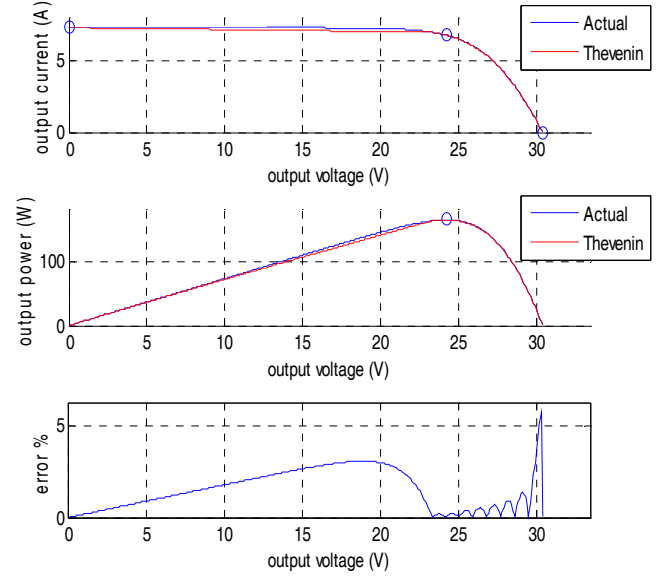


Fig. 5. Plot of Thevenin's equivalent circuit in comparison with the actual response at STC (25° C and 1000  $Wm^{-2}$ )

TABLE III

THEVENIN'S VOLTAGE AND RESISTANCE FOR 25° C AND 1000  $Wm^{-2}$

$T = 25^{\circ} C, G = 1000 Wm^{-2}$		
Output current, A	Thevenin's voltage, V	Thevenin's resistance, $\Omega$
0 to 0.9624	42.1000	1.2469
0.9624 to 1.7514	42.3638	1.5210
1.7514 to 2.3709	43.0926	1.9371
2.3709 to 2.8361	44.6160	2.5797
2.8361 to 3.1709	47.4633	3.5836
3.1709 to 3.4033	52.4730	5.1635
3.4033 to 3.5600	60.9636	7.6583
3.5600 to 3.6634	74.9968	11.6002
3.6634 to 3.8700	608.9235	157.3446

Figure 6 shows the voltage-current and voltage-power characteristic of PV for both the actual case and Thevenin's equivalent at 25° C and 200  $Wm^{-2}$  along with the percent error in the plot for Thevenin's equivalent model. Table IV lists the Thevenin's equivalent voltage and resistance at the above conditions and for different values of currents.

Figure 7 shows the voltage-current and voltage-power characteristic of PV for both the actual case and Thevenin's equivalent at 100° C and 1000  $Wm^{-2}$ , along with the percent error in the plot for Thevenin's equivalent model. Table V lists the Thevenin's equivalent voltage and resistance at the mentioned conditions and for different values of currents.

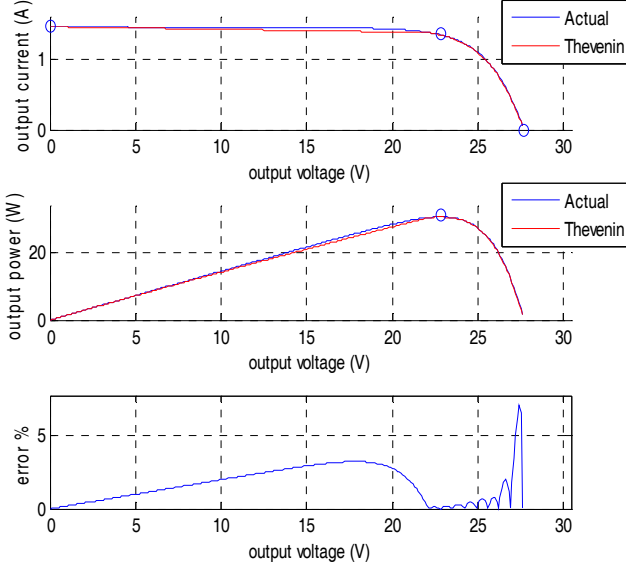


Fig. 6. Plot of Thevenin's equivalent circuit in comparison with the actual response at 25° C and 200  $Wm^{-2}$

TABLE IV

THEVENIN'S VOLTAGE AND RESISTANCE FOR 25° C AND 200  $Wm^{-2}$

$T = 25^{\circ}C, G = 200 Wm^{-2}$		
Output current, A	Thevenin's voltage, V	Thevenin's resistance, $\Omega$
0 to 0.2320	37.8812	4.6605
0.2320 to 0.3879	38.2880	6.4143
0.3879 to 0.4896	39.2314	8.8464
0.4896 to 0.5708	40.9328	12.3213
0.5708 to 0.6275	43.9640	17.6319
0.6275 to 0.6669	48.8218	25.3733
0.6669 to 0.6942	56.3153	36.6094
0.6942 to 0.7132	67.5644	52.8133
0.7132 to 0.7740	380.3989	491.4715

It is seen from the plots shown in Figures 5 through 7 that Thevenin's equivalent model closely approximates the response of the single-diode model. The error is zero at the points of linearization. Since MPP is one of the points of linearization, the error is also zero at that point. PV is controlled to operate at MPP; therefore, Thevenin's model leads to an operation at the exact MPP. The error between two points of linearization increases and reaches a maximum of 7% for 25° C and 200  $Wm^{-2}$  at a point close to open circuit. This is a point where PV will seldom operate. The error near the MPP where PV is most likely to operate with MPP is negligible. Tables III through V tabulate Thevenin's equivalent voltage and impedance for different environmental conditions and as a function of output current.

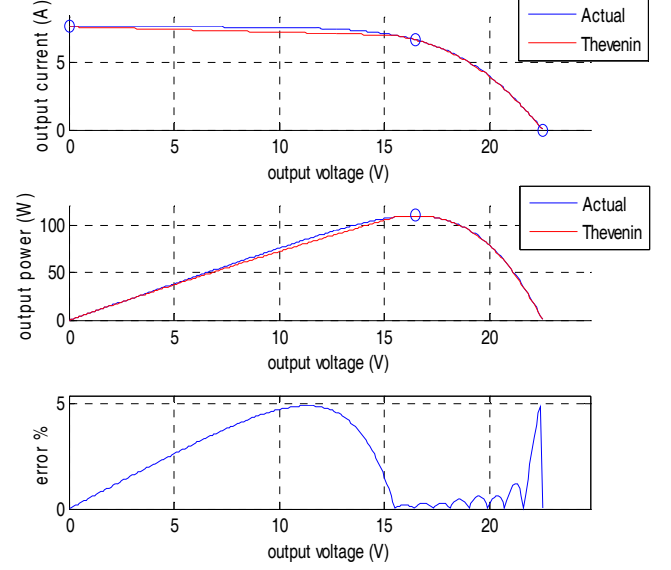


Fig. 7. Plot of Thevenin's equivalent circuit in comparison with the actual response at 100° C and 1000  $Wm^{-2}$

TABLE V

THEVENIN'S VOLTAGE AND RESISTANCE FOR 100° C AND 1000  $Wm^{-2}$

$T = 100^{\circ}C, G = 1000 Wm^{-2}$		
Output current, A	Thevenin's voltage, V	Thevenin's resistance, $\Omega$
0 to 0.9388	36.1001	1.3849
0.9388 to 0.7151	36.3720	1.6745
0.7151 to 2.2936	37.0576	2.0743
2.2936 to 2.7843	38.3764	2.6493
2.7843 to 3.1286	40.7044	3.4854
3.1286 to 3.4051	44.5086	4.7013
3.4051 to 3.5902	50.5825	6.4851
3.5902 to 3.7332	59.9197	9.0851
3.7332 to 4.0587	324.3096	79.9064

The accuracy of the Thevenin's equivalent model depends on the number of points chosen for linearization. The error in the Thevenin's equivalent model will decrease with an increase in the number points. There are several algorithms which can be employed to determine where exactly the points should be located. One of them locates the points based on the equal area of error. This means that the area under the error curve for all the regions should be the same. This ensures a good accuracy throughout the curve. However, this algorithm comes with higher degree of complication and requires iterative method of solving for the area of the error. Moreover, if this method is employed, the MPP may not be one of the points of linearization where the error is zero. Since the PV source is mostly operated at MPP, the error at that

point is desired to be zero. In the simulation shown here, the points are uniformly distributed on the voltage axis, between the MPP and the open circuit voltage. Most points are selected on the right side of the MPP because the curve is more nonlinear in this region. Only one point is selected between MPP and zero voltage. From Fig. 5 to 7, it is seen that the error is mostly small on the left hand side even when there is only one point to the left of the MPP. Whereas, the error is relatively high for the regions to the right of MPP. If the PV is not made to operate at the MPP, it is desired that it operates at a point to the right of it so that the voltage regulation of the PV is good. Therefore, more points for linearization should be placed on the right side to reduce the error in linearization.

### VIII. CONCLUSION

Thevenin's equivalent model derived from the single-diode model closely approximates PV characteristics as seen from the simulation results. This paper proposes to piecewise linearize the diode characteristic to develop Thevenin's equivalent circuit of a PV source. The simulation results show that the error in Thevenin's equivalent model is negligible at the maximum power point, a point where PV is controlled to operate at a given irradiance and temperature. From the simulation, it is concluded that the developed Thevenin's equivalent model can be used for simulation to study the behavior of PV. The advantage of using this model is that it avoids a numeric solution of the V-I characteristics of PV.

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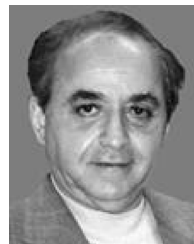
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