

## Econometrics 1, Class Week 2

Back-up Video: Class week 2 video ([click here](#))

### Learning Outcomes

- (a) Gauss Markov Theorem: Proof.
- (b) Orthogonal projectors.
- (c) Unbiasedness of the Ordinary Least Squares (OLS) estimator for the variance parameter  $\sigma_0^2$ .
- (d) Generalized Least Squares (GLS) estimator of  $\beta_0$ .

## Prerequisites

### 1. Concepts in Linear Algebra:

- rank of a matrix (p.37 of Auxiliary Math Notes [AMN]);
- bilinearity of variance-covariance matrices (AMN p.105);
- positive semi-definiteness of square matrices (AMN p.45);
- trace of a square matrix (AMN p.43).

### 2. Concepts in Mathematical Statistics:

- mean vector, variance-covariance matrix of vector-valued random variables (AMN p.105).

(a) Setting of Gauss Markov Theorem:

$T$  observation collected in outcomes vector  $\mathbf{y}$  and matrix of  $k$  regressors  $\mathbf{X}$ ,  $T > k$ , related by *linear* model

$$\underset{T \times 1}{\mathbf{y}} = \underset{T \times k}{\mathbf{X}} \underset{k \times 1}{\beta_0} + \underset{T \times 1}{\mathbf{u}} \quad (1)$$

where  $\mathbf{u}$  is a vector of regression errors.

Interpretation: Want to explain the variation in  $\mathbf{y}$  through (its co-)variation with the columns of  $\mathbf{X}$ , assumed to be non-stochastic and exogenous.

This covariation is determined by the true, but unknown population parameter  $\beta_0$  (a  $k$ -vector of population constants) which we seek to estimate.

This parameter enters the relationship (1) linearly.

## Gauss - Markov Assumptions

Assumptions about population errors  $\mathbf{u}$ :

A1 mean zero errors:  $\mathbb{E}[\mathbf{u}] = \mathbf{0}_{T \times 1}$ .

A2 homoskedastic errors:  $\mathbb{E}[\mathbf{u}\mathbf{u}'] = \sigma_0^2 \mathbf{I}_T$ , where  $\mathbf{I}_T$  is the identity matrix of dimension  $T \times T$  and  $\sigma_0^2 > 0$  is the true, but unknown scalar variance parameter in the population.

I.e. each element  $u_t$  of the vector  $\mathbf{u}$  has variance  $\mathbb{E}[u_t^2] = \sigma_0^2$ , and there are no covariances,  $\mathbb{E}[u_t u_s] = 0$  whenever  $t \neq s$ .

A3 Linearity of (1) in  $\beta_0$ .

OLS estimator of  $\beta_0$

$$\hat{\beta} = (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{y}, \text{ linear in } \mathbf{y} \text{ which is premultiplied by } k \times T \text{ matrix } \underset{k \times T}{\mathbf{X}'} \underset{T \times k}{\mathbf{X}}^{-1} \underset{k \times T}{\mathbf{X}'}$$

Note: Need additional assumption that

A4 rank of  $\mathbf{X}$  is  $\text{rk}(\mathbf{X}) = k$ ; otherwise, inverse does not exist.

Gauss-Markov Theorem: Under the assumptions A1 - A4 about the population,  $\hat{\beta}$  is the best linear and unbiased estimator (BLUE) of  $\beta_0$ .

Proof of Linearity: immediate, because  $\hat{\beta}$  is linear in  $\mathbf{y}$ .

Proof of Unbiasedness:

Unbiasedness means:  $\mathbb{E}[\hat{\beta}] = \beta_0$ .

To verify,

$$\begin{aligned}\mathbb{E}[\hat{\beta}] &= \mathbb{E}[(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{y}] \\ &= (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbb{E}[\mathbf{y}] \text{ because } \mathbf{X} \text{ is non-stochastic} \\ &= (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbb{E}[\mathbf{X}\beta_0 + \mathbf{u}] \text{ by (1)} \\ &= \beta_0 + (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbb{E}[\mathbf{u}] \\ &= \beta_0 \text{ by A1.}\end{aligned}$$

## Proof of Best (within Class of Linear Unbiased Estimators):

Suppose there exists another linear, unbiased estimator  $\tilde{\beta}$  of  $\beta_0$ .

Strategy: Will show its variance-covariance matrix is larger (in a positive semi-definite sense) than that of  $\hat{\beta}$ .

Linearity of  $\tilde{\beta}$ :  $\tilde{\beta}_{k \times 1} = \mathbf{A}_{k \times T} \mathbf{y}_{T \times 1}$ , for some  $k \times T$  matrix  $\mathbf{A}$ .

Unbiasedness of  $\tilde{\beta}$ :  $\mathbb{E}[\tilde{\beta}] = \beta_0$ , i.e.

$$\begin{aligned}\beta_0 &= \mathbb{E}[\tilde{\beta}] \\ &= \mathbb{E}[\mathbf{A}\mathbf{y}] \\ &= \mathbb{E}[\mathbf{A}(\mathbf{X}\beta_0 + \mathbf{u})] \\ &= \mathbf{A}\mathbf{X}\beta_0 \text{ by A1,}\end{aligned}$$

for *any* conceivable  $\beta_0$ . Hence,

$$\mathbf{A}\mathbf{X} = \mathbf{I}_k. \quad (2)$$

So linearity and unbiasedness place this restriction on  $\mathbf{A}$  in definition of  $\tilde{\beta}$ .

## Proof of Best (continued)

$$\begin{aligned}
 \text{var}(\tilde{\beta})_{k \times k} &= \mathbb{E}[(\tilde{\beta} - \beta_0)_{k \times 1}(\tilde{\beta} - \beta_0)_{1 \times k}'] \\
 &= \text{var}((\tilde{\beta} - \hat{\beta}) + \hat{\beta}) \\
 &= \text{var}(\hat{\beta}) + \text{var}(\tilde{\beta} - \hat{\beta}) + \dots \\
 &\quad \dots \text{cov}(\hat{\beta}, \tilde{\beta} - \hat{\beta}) + \text{cov}(\tilde{\beta} - \hat{\beta}, \hat{\beta}) \\
 \text{cov}(\tilde{\beta} - \hat{\beta}, \hat{\beta}) &= \text{cov}(\mathbf{A}\mathbf{y} - (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{y}, (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{y}) \\
 &= (\mathbf{A} - (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}')\text{cov}(\mathbf{y}, \mathbf{y})\mathbf{X}(\mathbf{X}'\mathbf{X})^{-1} \\
 &\quad (\text{see p. 105 of auxiliary math notes}) \\
 &= (\mathbf{A} - (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}')\sigma_0^2\mathbf{I}_T\mathbf{X}(\mathbf{X}'\mathbf{X})^{-1} \text{ by A2} \\
 &= \sigma_0^2(\mathbf{A} - (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}')\mathbf{X}(\mathbf{X}'\mathbf{X})^{-1} \\
 &= \sigma_0^2(\mathbf{A}\mathbf{X} - \mathbf{I}_k)(\mathbf{X}'\mathbf{X})^{-1} \\
 &= \mathbf{0}.
 \end{aligned}$$

where the last equality follows from (2).

Therefore,

$$\begin{aligned}
 \text{var}(\tilde{\beta}) &= \text{var}(\hat{\beta}) + \text{var}(\tilde{\beta} - \hat{\beta}) \\
 \text{var}(\tilde{\beta}) &\geq \text{var}(\hat{\beta}),
 \end{aligned}$$

because variance-covariance matrices are positive semi-definite.

This completes the proof of the Gauss-Markov Theorem.

If  $\mathbf{X}$  were stochastic, all conclusions hold *conditional on*  $\mathbf{X}$ . Also, need additional assumption:

A5:  $\mathbb{E}[\mathbf{X}'\mathbf{u}] = \mathbf{0}$ . (regressors and errors uncorr.)

This is the typical setting in econometrics.



(b) Orthogonal Projectors  $P_X = \mathbf{X}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'$  and  $M = \mathbf{I}_T - P_X$ .

(i) Idempotency of  $M$ :

$$\begin{aligned} MM &= (\mathbf{I}_T - P_X)(\mathbf{I}_T - P_X) \\ &= \mathbf{I}_T + P_X - 2P_X \text{ by idempotency of } P_X \\ &= \mathbf{I}_T - P_X = M. \end{aligned}$$

(ii) Orthogonality of  $M$  and  $P_X$ :

$$\begin{aligned} MP_X &= (\mathbf{I}_T - P_X)P_X \\ &= P_X - P_X P_X \\ &= P_X - P_X \text{ by idempotency of } P_X \\ &= \mathbf{0}. \end{aligned}$$

(iii) Regression residuals  $\hat{\mathbf{u}}$ :

$$\begin{aligned} \hat{\mathbf{u}} &= \mathbf{y} - \mathbf{X}\hat{\boldsymbol{\beta}} \\ &= (\mathbf{I}_T - \mathbf{X}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}')\mathbf{y} \\ &= M(\mathbf{X}\boldsymbol{\beta}_0 + \mathbf{u}) \\ &= M\mathbf{u} \text{ because } M\mathbf{X} = \mathbf{X} - \mathbf{X} = \mathbf{0}. \end{aligned}$$

(c) Unbiasedness of OLS estimator  $s^2 = \frac{1}{T-k} \hat{\mathbf{u}}' \hat{\mathbf{u}}$  of  $\sigma_0^2$

$$\begin{aligned}
\mathbb{E}[s^2] &= \frac{1}{T-k} \mathbb{E}[\hat{\mathbf{u}}' \hat{\mathbf{u}}] \\
&= \frac{1}{T-k} \mathbb{E}[\mathbf{u}' M \mathbf{u}] \text{ by (i) and (iii)} \\
&= \frac{1}{T-k} \text{tr}[\mathbb{E}[\mathbf{u}' M \mathbf{u}]] \text{ b/c trace of scalar is scalar} \\
&= \frac{1}{T-k} \mathbb{E}[\text{tr}[\mathbf{u}' M \mathbf{u}]] \text{ b/c lin. operators commute} \\
&= \frac{1}{T-k} \mathbb{E}[\text{tr}[\mathbf{u} \mathbf{u}' M]] \text{ by properties of trace} \\
&= \frac{1}{T-k} \text{tr}[\mathbb{E}[\mathbf{u} \mathbf{u}'] M] \text{ b/c lin. operators commute} \\
&\quad \text{and } M = \mathbf{I}_T - P_X \text{ is non-stochastic} \\
&= \frac{1}{T-k} \text{tr}[\sigma_0^2 M] \text{ by A2} \\
&= \frac{\sigma_0^2}{T-k} (\text{tr}[\mathbf{I}_T] - \text{tr}[P_X]) \\
&= \frac{\sigma_0^2}{T-k} (\text{tr}[\mathbf{I}_T] - \text{tr}[(\mathbf{X}' \mathbf{X})^{-1} \mathbf{X}' \mathbf{X}]) \\
&= \frac{\sigma_0^2}{T-k} (\text{tr}[\mathbf{I}_T] - \text{tr}[\mathbf{I}_k]) \\
&= \sigma_0^2.
\end{aligned}$$

### (d) Generalized Least Squares (GLS)

Change A2 to  $\mathbb{E}[\mathbf{u}\mathbf{u}'] = \sigma_0^2\Omega$  (i.e. errors are no longer homoskedastic).

What is variance of OLS estimator?

$$\begin{aligned}\text{var}(\hat{\beta}) &= \text{var}(\beta_0 + (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{u}) \\ &= (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\text{var}(\mathbf{u})\mathbf{X}(\mathbf{X}'\mathbf{X})^{-1} \\ &= \sigma_0^2(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\Omega\mathbf{X}(\mathbf{X}'\mathbf{X})^{-1}.\end{aligned}$$

GLS estimator  $\tilde{\beta}$  solves

$$\mathbf{0} = \mathbf{X}'\Omega^{-1}(\mathbf{y} - \mathbf{X}\tilde{\beta}), \quad (3)$$

so

$$\tilde{\beta} = (\mathbf{X}'\Omega^{-1}\mathbf{X})^{-1}\mathbf{X}'\Omega^{-1}\mathbf{y}. \quad (4)$$