## **AE731**

## Theory of Elasticity

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### upcoming schedule

- Aug 28 Tensor Calculus
- Sep 2 Labor Day
- Sep 4 Displacement and Strain, Homework 1 Due
- Sep 9 Strain Transformation
- Sep 11 Exam 1 Review

# principal values

### principal values

- In the 2D coordinate transformation example, we were able to eliminate one value from a vector using coordinate transformation
- For second-order tensors, we desire to find the "principal values" where all non-diagonal terms are zero

#### principal directions

- The direction determined by the unit vector,  $n_j$ , is said to be the *principal direction* or *eigenvector* of the symmetric second-order tensor,  $a_{ij}$  if there exists a parameter,  $\lambda$ , such that  $a_{ij}n_j = \lambda n_i$
- Where  $\lambda$  is called the *principal value* or *eigenvalue* of the tensor

### principal values

- We can re-write the equation  $(a_{ij} \lambda \delta_{ij})n_j = 0$
- This system of equations has a non-trivial solution if and only if  $\det[a_{ij} \lambda \delta_{ij}] = 0$
- This equation is known as the characteristic equation, and we solve it to find the principal values of a tensor

### example

• Find the principal values of the tensor

$$A_{ij} = egin{bmatrix} 1 & 2 \ 2 & 4 \end{bmatrix}$$

• From the characteristic equation, we know that  $\det[A_{ij} - \lambda \delta_{ij}] = 0$ , or

$$\left|egin{array}{cc} 1-\lambda & 2 \ 2 & 4-\lambda \end{array}
ight|=0$$

### example

- Calculating the determinant gives  $(1 \lambda)(4 \lambda) 4 = 0$
- Multiplying out and simplifying, we find  $\lambda^2 5\lambda = \lambda(\lambda 5) = 0$
- This has the solution  $\lambda = 0, 5$

- Every tensor has some invariants which do not change with coordinate transformation
- These are known as *fundamental invariants*
- The characteristic equation for a tensor in 3D can be written in terms of the invariants  $\det[a_{ij} \lambda \delta_{ij}] = -\lambda^3 + I_{\alpha}\lambda^2 II_{\alpha}\lambda + III_{\alpha} = 0$

• The invariants can be found by the following equations

$$egin{aligned} I_lpha &= a_{ii} \ II_lpha &= rac{1}{2}(a_{ii}a_{jj} - a_{ij}a_{ij}) \ III_lpha &= \det[a_{ij}] \end{aligned}$$

• In the principal direction,  $a_{ij}$  will be

$$a_{ij}'=egin{bmatrix} \lambda_1 & 0 & 0 \ 0 & \lambda_2 & 0 \ 0 & 0 & \lambda_3 \end{bmatrix}$$

• Since invariants do not change with coordinate systems, we can also write the invariants as

$$egin{aligned} I_lpha &= \lambda_1 + \lambda_2 + \lambda_3 \ II_lpha &= \lambda_1 \lambda_2 + \lambda_2 \lambda_3 + \lambda_3 \lambda_1 \ III_lpha &= \lambda_1 \lambda_2 \lambda_3 \end{aligned}$$