

Top Goal
X:ECU Y:NET [H|L]

```
graph TD; TG([Top Goal  
X:ECU Y:NET [H|L]]) --- SG1([Sub Goal 1  
X]); TG --- SG2([Sub Goal 2  
Y]); SG1 --- A1([Action1  
X]); SG1 --- A2([Action2  
Z]); SG2 --- A3([Action3  
[X .. A:AP]]); SG2 --- A4([Action 4]); SG2 --- A5([Action 5]); A3 -.-> SG2;
```

Sub
Goal 1
X

Sub
Goal 2
Y

Action1
X

Action2
Z

Action3
[X .. A:AP]

Action
4

Action
5