



North South University

DEPARTMENT OF ELECTRICAL AND COMPUTER ENGINEERING

PROJECT PROPOSAL

Smart Blind Stick Using Ultrasonic Sensor and Arduino Uno

Course Information

Operating Systems Design
CSE323 (Section 5)
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Submitted by

Student Name	Student ID
Saif Mohammed	2121913042
Humayra Rahman Nipa	2121128042

Submitted to

Dr. Mosabber Uddin Ahmed [MUA3]
Adjunt Professor
Department of Electrical and Computer Engineering
North South University

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1. Objectives

- Create a portable smart stick to assist visually impaired individuals.
- Detect obstacles using an ultrasonic sensor.
- Provide audio and visual alerts based on obstacle proximity.
- Use an Arduino Uno R3 for efficient system control.
- Improve user safety and independent mobility.

2. Required Components

Serial No.	Component Name	Cost (BDT)
1	Arduino Uno R3	790
2	HC-SR04 Ultrasonic Sensor	100
3	Piezo Buzzer	20
4	LED	5
5	9V Battery	75
6	LM7805 Voltage Regulator	15
7	Jumper Wires	65
8	Breadboard	100
Total		1170

3. Software and Hardware Details

3.1. Software Details

- Arduino IDE for coding, compiling, and uploading.
- Programming in C/C++ to manage sensor input and output responses.
- A lightweight control loop mimicking basic OS task management.

3.2. Hardware Details

- **Arduino Uno R3:** Main controller processing input from sensors and sending output signals.
- **HC-SR04 Ultrasonic Sensor:** Detects obstacles and sends distance measurements.
- **Piezo Buzzer:** Emits sound alerts to warn the user.
- **LED:** Provides visual indications when obstacles are detected.
- **Battery:** 9V portable power source for the entire system.
- **Voltage Regulator (LM7805):** Maintains stable 5V output for safe component operation.
- **Jumper Wires:** Enable circuit connectivity.
- **Breadboard:** Used for assembling and testing the prototype.

The system is mounted on a walking stick with the ultrasonic sensor placed at the front to detect oncoming obstacles. When an object is detected within a certain range, the microcontroller activates the buzzer and LED to alert the user. The compact design and low power consumption allow for prolonged usage.