Tunable Testbed for Detection and Attribution IDAG Workshop 2018

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Ordinary Least Squares (OLS)

Observed Quantities:

- y: The observed climate response of interest
- $m{X}^*$ The model-simulated forcing responses $m{X}^* = (m{x}_1^*, \dots, m{x}_m^*, \dots, m{x}_M^*)$

$$y = X^*\beta + u$$

Statistical Parameter of Interest:

- β Estimation provides detection, inference (CIs) gives us attribution Climate Variability:
 - ${m u}$ The error due to climate variability where ${m u}\sim \mathcal{N}(0,{m C})$
 - C Estimated through model control runs

Error-in-Variable (EIV)

Observed Quantities:

- y The climate response of interest
- \boldsymbol{X} The noisy responses to forcings $\boldsymbol{X} = (\boldsymbol{x}_1, \dots, \boldsymbol{x}_m, \dots, \boldsymbol{x}_M)$

$$y = X^*\beta + u_y$$
$$X = X^* + U$$

Latent Quantities:

- \mathbf{y}^* The 'true' climate response where $\mathbf{y}^* = \mathbf{X}^* \boldsymbol{\beta}$
- $m{\mathcal{X}}^*$ The 'true' responses to forcings $m{\mathcal{X}}^* = (m{x}_1^*, \dots, m{x}_M^*)$

Climate Variability:

- $\emph{\textbf{u}}_y$ As OLS formulation with $\emph{\textbf{u}}_y \sim \mathcal{N}(0, \textbf{C})$
- $oldsymbol{\textit{U}}$ The error on the forcing responses due to climate variability

$$\boldsymbol{U} = (\boldsymbol{u}_1, \dots, \boldsymbol{u}_M) \stackrel{\mathsf{iid}}{\sim} \mathcal{N}(0, \mathbf{C})$$

Error-in-Variable (EIV): Multimember Ensembles

For a given forcing m, we run ensemble of size L_m

$$\mathbf{x}_m = (\mathbf{x}_m^{(1)}, \dots \mathbf{x}_m^{(\ell)}, \dots, \mathbf{x}_m^{(L_m)}), \qquad \mathbf{x}_m^{(\ell)} \stackrel{\mathsf{iid}}{\sim} \mathcal{N}(\mathbf{x}_m^*, \mathsf{C})$$

The ensemble mean of the m^{th} forced response is

$$\overline{\mathbf{x}_m} = \frac{1}{L_m} \sum_{\ell=1}^{L_m} \mathbf{x}_m^{(\ell)}, \qquad \overline{\mathbf{x}_m} \sim \mathcal{N}\left(\mathbf{x}_m^*, L_m^{-1} \mathbf{C}\right)$$

Rewriting in the error-in-variable formulation

$$\overline{\mathbf{x}_m} = \mathbf{x}_m^* + L_m^{-1/2} \mathbf{u}_m$$

Or for all forcing responses with $\boldsymbol{L} = \text{diag}(L_1, \dots, L_M)$

$$\overline{X} = X^* + L^{-1/2}U$$

Error-in-Variable (EIV): Multimember Ensembles

$$\overline{X} = X^* + L^{-1/2}U$$

Plugging into our full error in variable formulation:

$$\mathbf{y} = \mathbf{X}^* \boldsymbol{\beta} + \mathbf{u}_y$$
 $\mathbf{u}_y \sim \mathcal{N}(0, \mathbf{C})$
 $\overline{\mathbf{X}} = \mathbf{X}^* + \mathbf{L}^{-1/2} \mathbf{U}$ $\mathbf{u}_m \stackrel{\text{iid}}{\sim} \mathcal{N}(0, \mathbf{C})$

$$\overline{m{X}}$$
 The ensemble means $\overline{m{X}}=(\overline{m{x}_1},\ldots,\overline{m{x}_M})$

L The ensemble sizes
$$\mathbf{L} = (L_1, \dots, L_M)$$

$$oldsymbol{U}$$
 The forcing variability matrix $oldsymbol{U}=(oldsymbol{u}_1,\ldots,oldsymbol{u}_M)$

Observed Response Variability

The incomplete expression for the climate response y is

$$\mathbf{y} = \mathbf{X}^* \boldsymbol{\beta} + \mathbf{u}_y \,, \qquad \mathbf{u}_y \sim \mathcal{N}(\mathbf{0}, \mathbf{C})$$

We propose three different \boldsymbol{y} states to fully incorporate all of the sources of variability.

$$m{y}^*$$
 The true climate response (latent) $m{y}^* = m{X}^*m{eta}$
 $m{y}_{rel}$ The realized climate response (latent) $m{y}_{rel} = m{y}^* + m{u}_Y$
 $m{y}_{obs}$ The observed climate response $m{y}_{obs} = m{y}_{rel} + m{\varepsilon}_Y$
 $m{v}_{obs} = m{y}_{rel} + m{\varepsilon}_Y$
 $m{v}_{obs} = m{v}_{rel} + m{\varepsilon}_Y$

with observational error $\varepsilon_Y \sim \mathcal{N}\left(0,\mathbf{W}\right)$

$$egin{aligned} oldsymbol{y}_{rel} &= oldsymbol{X}^*oldsymbol{eta} + oldsymbol{u}_y & oldsymbol{u}_y &\sim \mathcal{N}(0, oldsymbol{\mathsf{C}}) \ oldsymbol{y}_{obs} &= oldsymbol{y}_{rel} + oldsymbol{arepsilon}_y & arepsilon_y &\sim \mathcal{N}(0, oldsymbol{\mathsf{W}}) \end{aligned}$$

Observed Response Variability

$$egin{align} oldsymbol{y}_{rel} &= oldsymbol{X}^*oldsymbol{eta} + oldsymbol{u}_y & oldsymbol{u}_y \sim \mathcal{N}(0, oldsymbol{\mathsf{C}}) \ oldsymbol{y}_{obs} &= oldsymbol{y}_{rel} + oldsymbol{arepsilon}_y & oldsymbol{arepsilon}_y \sim \mathcal{N}(0, oldsymbol{\mathsf{W}}) \ \end{pmatrix}$$

Total Observation Variability: Since the observational and climate variability errors are independent, condense in terms of $\nu = u_y + \varepsilon_y$, the total climate variability

$$egin{aligned} oldsymbol{y}_{obs} &= oldsymbol{y}_{rel} + oldsymbol{arepsilon}_{y} \ &= oldsymbol{X}^{*}oldsymbol{eta} + oldsymbol{
u} \;, \qquad oldsymbol{
u} \sim \mathcal{N}(0, oldsymbol{\mathsf{C}} + oldsymbol{\mathsf{W}}) \end{aligned}$$

Note: Flexibility to add additional variability terms to u

- Linear approximation error (from statistical model)
- Climate model error

Observed Response Variability

$$egin{align} oldsymbol{y}_{rel} &= oldsymbol{X}^*oldsymbol{eta} + oldsymbol{u}_y & oldsymbol{u}_y \sim \mathcal{N}(0, oldsymbol{\mathsf{C}}) \ oldsymbol{y}_{obs} &= oldsymbol{y}_{rel} + oldsymbol{arepsilon}_y & oldsymbol{arepsilon}_y \sim \mathcal{N}(0, oldsymbol{\mathsf{W}}) \ \end{pmatrix}$$

Observational Ensembles: Following the notation of the multimember ensembles with L_y as the size of the observational ensemble

$$egin{aligned} oldsymbol{Y}_{obs} &= (oldsymbol{y}_{obs}^{(1)}, \cdots, oldsymbol{y}_{obs}^{(L_y)}) \ &= oldsymbol{Y}_{rel} + (oldsymbol{arepsilon}_y^{(1)}, \cdots, oldsymbol{arepsilon}_y^{(L_y)}) \,, \qquad oldsymbol{arepsilon}_y^{(\ell)} \stackrel{ ext{iid}}{\sim} \mathcal{N}(0, oldsymbol{\mathsf{W}}) \end{aligned}$$

Information on \mathbf{W} may be from gained from multiple observations, but information on \mathbf{C} does not increase!

Observed Response Variability

$$egin{align} oldsymbol{y}_{rel} &= oldsymbol{X}^*oldsymbol{eta} + oldsymbol{u}_y & oldsymbol{u}_y \sim \mathcal{N}(0, oldsymbol{\mathsf{C}}) \ oldsymbol{y}_{obs} &= oldsymbol{y}_{rel} + oldsymbol{arepsilon}_y & oldsymbol{arepsilon}_y \sim \mathcal{N}(0, oldsymbol{\mathsf{W}}) \ \end{pmatrix}$$

Observational Ensembles: Following the notation of the multimember ensembles with L_y as the size of the observational ensemble

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Bulleted List Subtitle

• Structure Color: text

Alert Color: TEXT

Bulleted List with Sub-bullets

- In general, falls somewhere in between the Hadley and Berkeley methods
- Main Point here
 - Sub-point here
- Has rudimentary uncertainty model that resembles Hadley

Numbered List

- Structure text: further stuff
- egular point

Blocks

Text outside of blocks

Block

Regular Block is Here

Example Block

Example is here

Alert Block

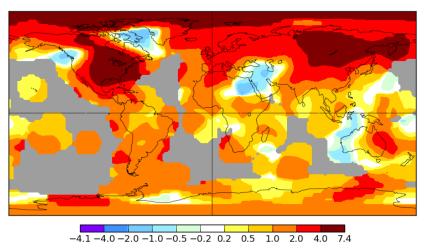
Alert block is here

Full Slide Figure

Subtitle Here

February 2017 Tsurf(°C) Anomaly vs 1951-1980

1.42



Source: Source Here

Two Column Slide (List and Figure)

- Point 1
- Point 2

