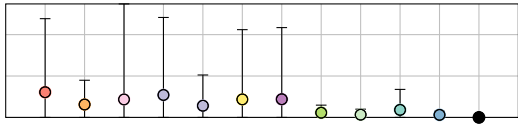


Energy

Over Optimal (%)

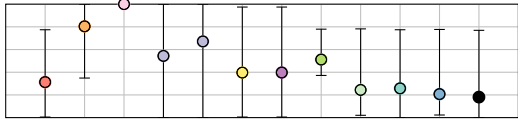
(lower is better)

200  
100  
0

Deadline

Misses (%)

(lower is better)

100  
80  
60  
40  
20  
0

Race-to-idle  
PID-Control  
Online  
Offline  
Netflix  
HBM  
Adaptive-Control  
CALOREE-NoPole  
CALOREE-Online  
CALOREE-Netflix  
CALOREE-HBM  
Optimal