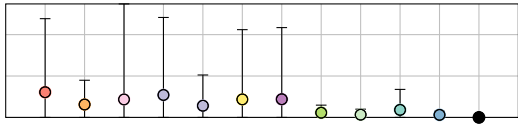


Energy

Over Optimal (%)

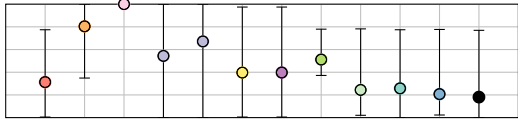
(lower is better)

200
100
0

Deadline

Misses (%)

(lower is better)

100
80
60
40
20
0

Race-to-idle

PID-Control

Online

Offline

Netflix

HBM

Adaptive-Control

CALOREE-NoPole

CALOREE-Online

CALOREE-Netflix

CALOREE-HBM

Optimal