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6.036 pre1 4.

1. Neural Networks.

$$[x_1, x_2] = [3, 14]$$

$$z_1 = 3 + 0 - 1 = 2 ; f(z_1) = 2.$$

$$z_2 = 14 - 1 = 13 ; f(z_2) = 13.$$

$$z_3 = -3 - 1 = -4 ; f(z_3) = 0$$

$$z_4 = -14 - 1 = -15 ; f(z_4) = 0$$

$$u_1 = 2 + 13 = 15 ; f(u_1) = 15$$

$$u_2 = -2 - 13 - 2 = -17 ; f(u_2) = 0$$

$$O_1 = \frac{e^{15}}{e^{15} + 1} ; O_2 = \frac{1}{e^{15} + 1}$$

b. Draw decision boundaries.

$$z_1 = 0$$

$$\Rightarrow x_1 - 1 = 0$$

$$z_2 = 0$$

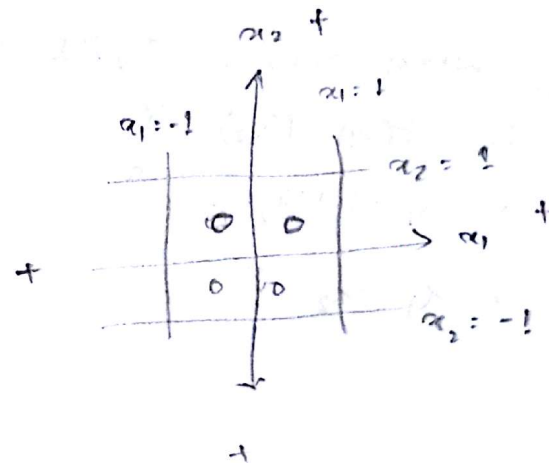
$$x_2 - 1 = 0$$

$$z_3 = 0$$

$$-x_1 - 1 = 0$$

$$z_4 = 0$$

$$-x_2 - 1 = 0$$



c.

$$f(z_1) + f(z_2) + f(z_3) + f(z_4) = 0$$

Since, $f(x)$ is all positive, the above expression becomes zero when all of them are zero.

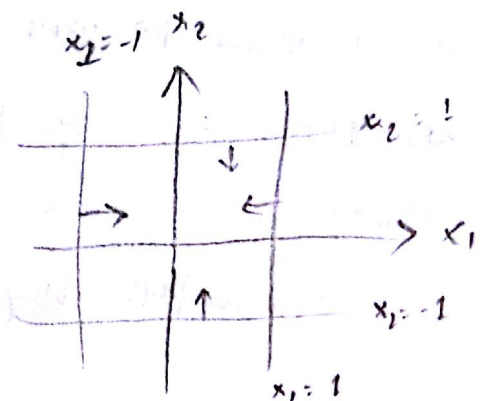
$$f(z_1) = 0 \quad \forall \quad x_1 - 1 \leq 0 \Rightarrow x_1 \leq 1$$

$$f(z_2) = 0 \quad \forall \quad x_2 - 1 \leq 0 \Rightarrow x_2 \leq 1$$

$$f(z_3) = 0 \quad \forall \quad -x_1 - 1 \leq 0 \Rightarrow x_1 \geq -1$$

$$f(z_4) = 0 \quad \forall \quad -x_2 - 1 \leq 0 \Rightarrow x_2 \geq -1$$

So, the region bounded is



$$f(z_1) + f(z_2) + f(z_3) + f(z_4) = 1$$

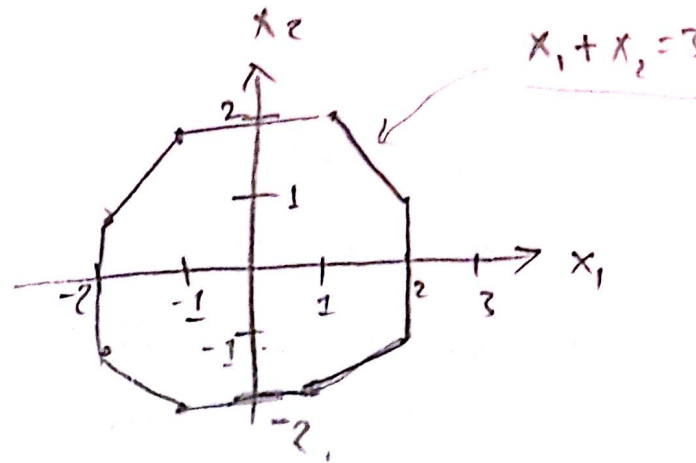
$$\text{for } z_1 > 1, z_2 > 1; \quad f(z_3) = 0 \quad f(z_4) = 0$$

$$f(z_1) + f(z_2) = 1$$

$$\Rightarrow x_1 - 1 + x_2 - 1 = 1$$

$$\Rightarrow x_1 + x_2 = 3.$$

Similarly, we can obtain eqn for different segments.



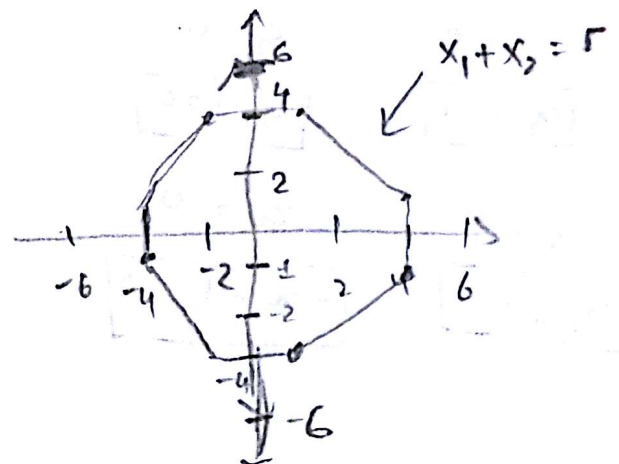
$$f(z_1) + f(z_2) + f(z_3) + f(z_4) = 3$$

$$\text{Similarly, when } z_1 > 1, z_2 > 1 \Rightarrow f(z_3) = 0, f(z_4) = 0$$

$$\text{i.e. } f(z_1) + f(z_2) = 3$$

$$\Rightarrow x_1 - 1 + x_2 - 1 = 3$$

$$\Rightarrow x_1 + x_2 = 5$$



d. Modified softmax: with β .

This increases the probability range for the ^{higher} values outputted. i.e. if $\beta = 2$, the exponential normalization of output covers higher range than $\beta = 1$.

It concentrates higher prob to higher activation.

$$\delta_j^L = \frac{\partial C}{\partial z_j^L} = \sum_{i=1}^K \frac{\partial C}{\partial z_i^{L+1}} \cdot \frac{\partial z_i^{L+1}}{\partial z_j^L}$$

$$= \sum_K \delta_K^{L+1} \frac{\partial}{\partial z_j^L} (a_K^L \cdot w_{Kj}^{L+1} + b_j^{L+1})$$

$$= \sum_K \delta_K^{L+1} \cdot w_{Kj}^{L+1} \cdot \frac{\partial}{\partial z_j^L} f(z_j^L)$$

$$= \sum_K \delta_K^{L+1} \cdot w_{Kj}^{L+1} \cdot f'(z_j^L)$$

$$(ii) \quad \frac{\partial C}{\partial w_{jk}^L} = \frac{\partial C}{\partial z_j^L} \cdot \frac{\partial z_j^L}{\partial w_{jk}^L} = \delta_j^L \cdot \frac{\partial (w_{jk}^L a_k^{L-1} + b_j^L)}{\partial w_{jk}^L}$$

$$= \delta_j^L \cdot a_k^{L-1}$$

$$\frac{\partial C}{\partial b_j^L} = \frac{\partial C}{\partial z_j^L} \cdot \frac{\partial z_j^L}{\partial b_j^L} = \delta_j^L \cdot 1 = \delta_j^L$$

(iii) Calculate feed forward signals.

Calculate output Error & cost function 'C'.

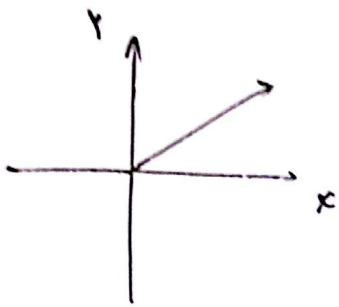
Backpropagate the error by weights in previous layer and gradients of associated activation function.

Calculating the gradients $\frac{\partial C}{\partial w}$ or backpropagated signals.

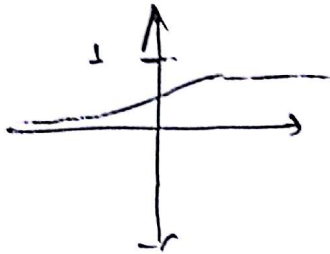
$$w = 0 \cdot w - \eta \frac{\partial C}{\partial w}$$

for every weight matrix.

⑥.



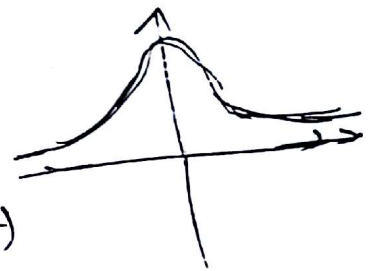
Relu function.



Sigmoid function.

$$\frac{\partial}{\partial x} \frac{1}{(e^x + 1)} = \frac{e^{-x}}{(1 + e^{-x})^2} = \frac{1 + e^{-x}}{(1 + e^{-x})^2} - \frac{1}{(1 + e^{-x})^2}$$

$$= \frac{1}{1 + e^{-x}} - \frac{1}{(1 + e^{-x})^2} = \sigma - \sigma^2 = \sigma(1 - \sigma)$$



⑦

It is a smooth function almost linear at its mean.
It's nonlinearity and have finite limits.

⑧

$$\frac{\partial C}{\partial w_1} = \frac{\partial}{\partial w_1} \frac{1}{2}(y - t)^2 = (y - t) \cdot \frac{\partial y}{\partial z_2} \cdot \frac{\partial z_2}{\partial w_1} \cdot \frac{\partial a_1}{\partial z_1} \cdot \frac{\partial z_1}{\partial w_1}$$

$$= (y - t) \cdot \sigma(z_2)(1 - \sigma(z_2)) \cdot w_2 \cdot w_1$$

$$\frac{\partial C}{\partial w_2} = \frac{\partial}{\partial w_2} \frac{1}{2}(y - t)^2 = (y - t) \cdot \frac{\partial y}{\partial z_2} \cdot \frac{\partial z_2}{\partial w_2} = (y - t) \cdot \sigma(z_2)(1 - \sigma(z_2)) \cdot w_1$$

Part. 2

Input.	x_0	x_1	x_2	x_3	x_4	x_5
1.	0	0	0.76	-0.76	0.76	-0.381
2.	0.76	-0.76	0.381	0.76	-0.76	X

⑥ The visible state carries information about the previous states we during the training since we have auto recurrent loop.

⑦. $W_{xx} = -50$

d. $t = 1$
 $\alpha = 3$
 $\omega_1 = 0.01$
 $\omega_2 = -5$
 $b = -1.$

$y =$

$$\frac{\partial C}{\partial \omega_1} = (y - t) \sigma(z_1) (1 - \sigma(z_1)) \cdot \omega_1$$

$$= \cancel{+0.6588} \cdot 0.6588$$

$$\omega_1 \leftarrow \omega_1 - 0.6588 \eta$$

$$\omega_1 \leftarrow \omega_1 - 0.6588 \eta$$

Similarly,

$$\omega_2 \leftarrow \omega_2 + 0.0013 \eta$$