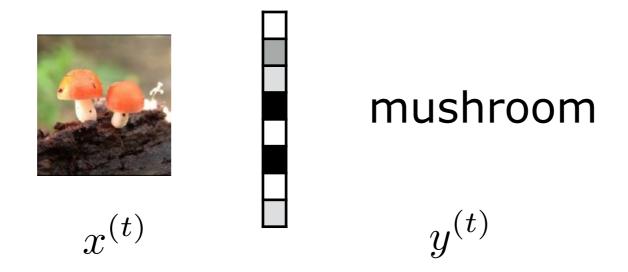
# 6.036 Introduction to Machine Learning

Recurrent Neural Networks

### recap (what you should know)

- Feed-forward (layered) neural networks
  - units, weights, activation functions
  - layer-wise forward propagation
  - back-propagation of error
  - stochastic gradient descent
- Convolutional neural networks (CNNs)
  - filters, feature maps, pooling

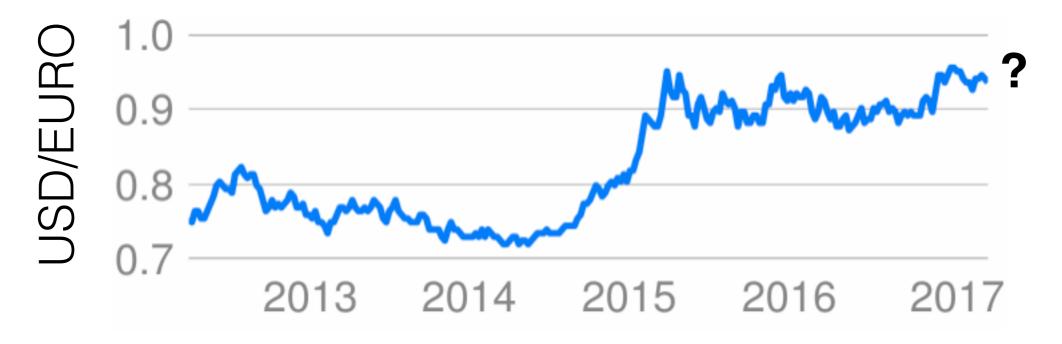




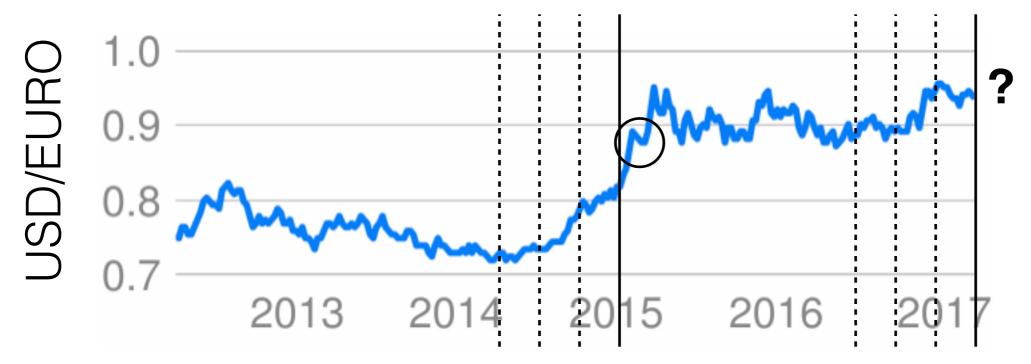
#### **Multi-way classification**

(explained on the board; see notes)

How to cast as a supervised learning problem?



How to cast as a supervised learning problem?



 Historical data can be broken down into feature vectors and target values (sliding window)

$$\begin{bmatrix} 0.82 \\ 0.80 \\ 0.73 \\ 0.72 \end{bmatrix} \qquad 0.89$$
$$x^{(t)} \qquad y^{(t)}$$

Language modeling: what comes next?

This course has been a tremendous ...

Language modeling: what comes next?

This course has been a tremendous ...

tremendous :

?

8

$$x^{(t)}$$
  $y^{(t)}$ 

Language modeling: what comes next?

This course has been a tremendous ...

1

 $\begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$ 

tremendous

been

$$x^{(t)}$$

$$y^{(t)}$$



#### What are we missing?

- Sequence prediction problems can be recast in a form amenable to feed-forward neural networks
- But we have to engineer how "history" is mapped to a vector (representation). This vector is then fed into, e.g., a neural network
  - how many steps back should we look at?
  - how to retain important items mentioned far back?
- Instead, we would like to learn how to encode the "history" into a vector



#### Learning to encode/decode

Language modelingThis course has been a

success (?)

Sentiment classification
 I have seen better lectures

-1

Machine translationI have seen better lectures

Olen nähnyt parempia luentoja

encoding

decoding



### Key concepts

- Encoding
  - e.g., mapping a sequence to a vector
- Decoding
  - e.g., mapping a vector to, e.g., a sequence



#### Encoding everything

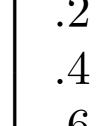
words 
$$\begin{bmatrix} .1 \\ .3 \\ .4 \end{bmatrix} \begin{bmatrix} .7 \\ .1 \\ .0 \end{bmatrix} \begin{bmatrix} .2 \\ .8 \\ .3 \end{bmatrix}$$

"Efforts and courage are not enough without purpose and direction" — JFK

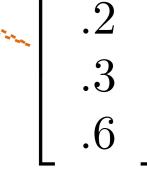
sentences

images



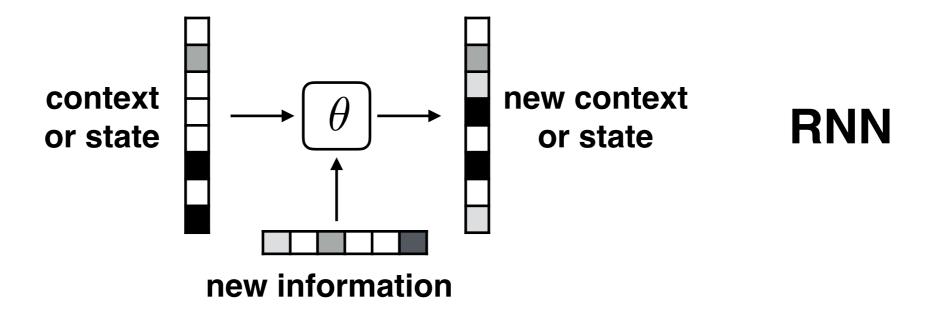


events





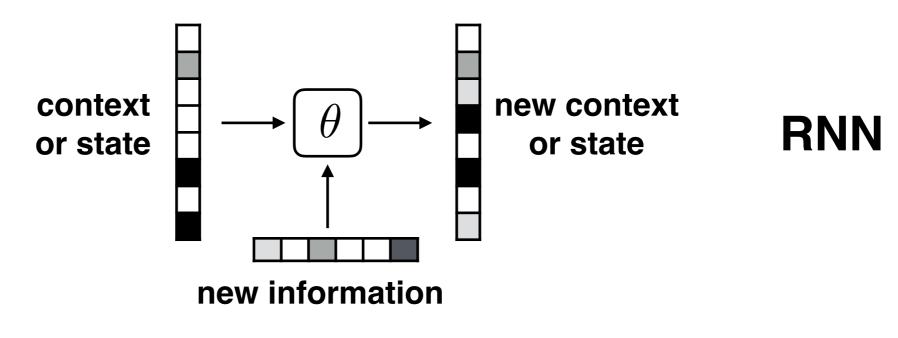
 Easy to introduce adjustable "lego pieces" and optimize them for end-to-end performance



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Efforts and courage are not ...

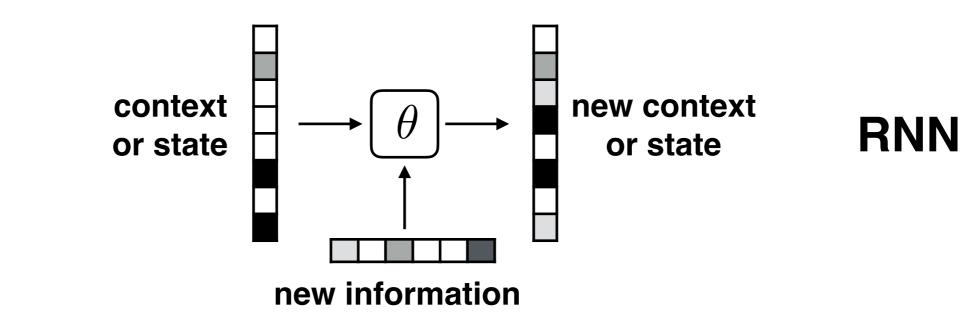
 Easy to introduce adjustable "lego pieces" and optimize them for end-to-end performance



$$s_t = \tanh(W^{s,s} s_{t-1} + W^{s,x} x_t)$$

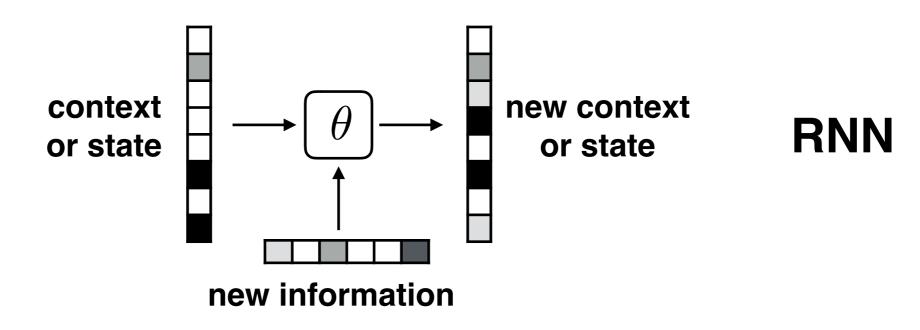
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Efforts and courage are not ...

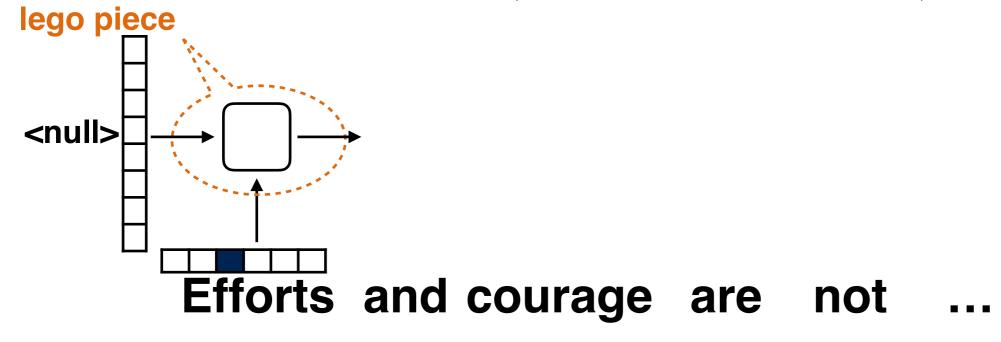


$$s_t = \tanh(W^{s,s} s_{t-1} + W^{s,x} x_t)$$

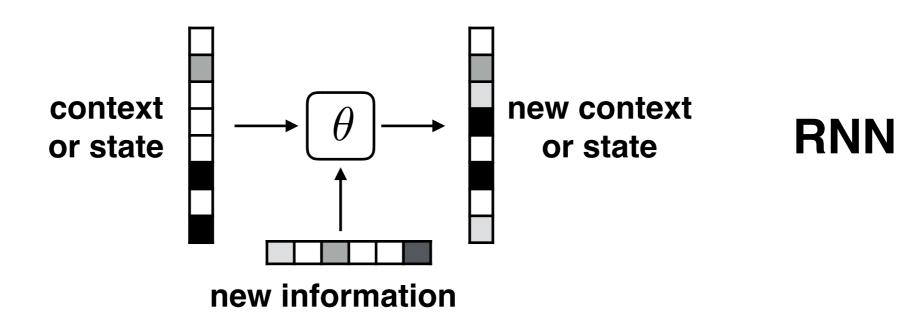




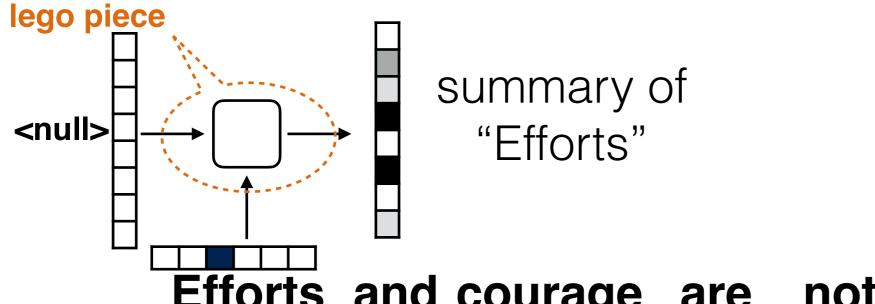
$$s_t = \tanh(W^{s,s} s_{t-1} + W^{s,x} x_t)$$



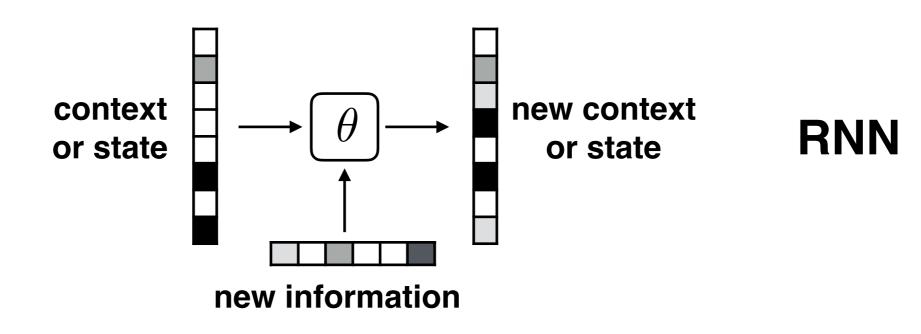
 Easy to introduce adjustable "lego pieces" and optimize them for end-to-end performance



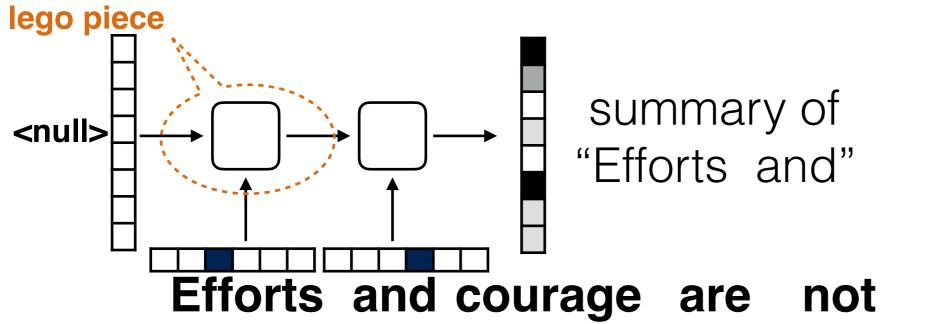
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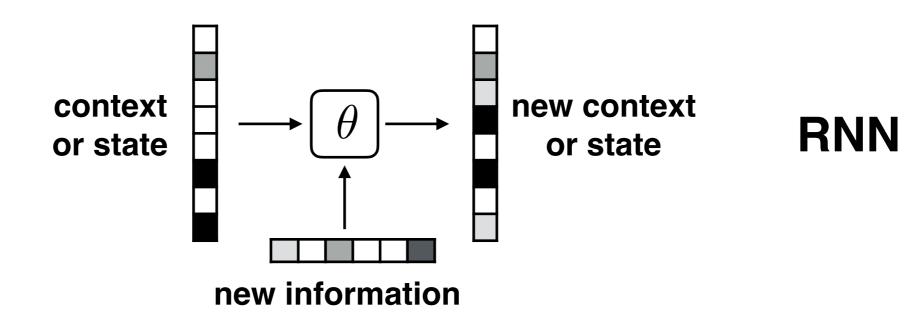


Efforts and courage are not

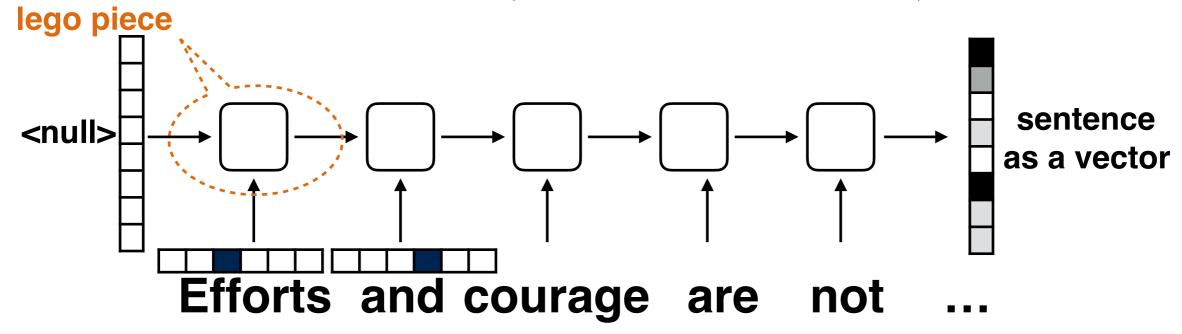


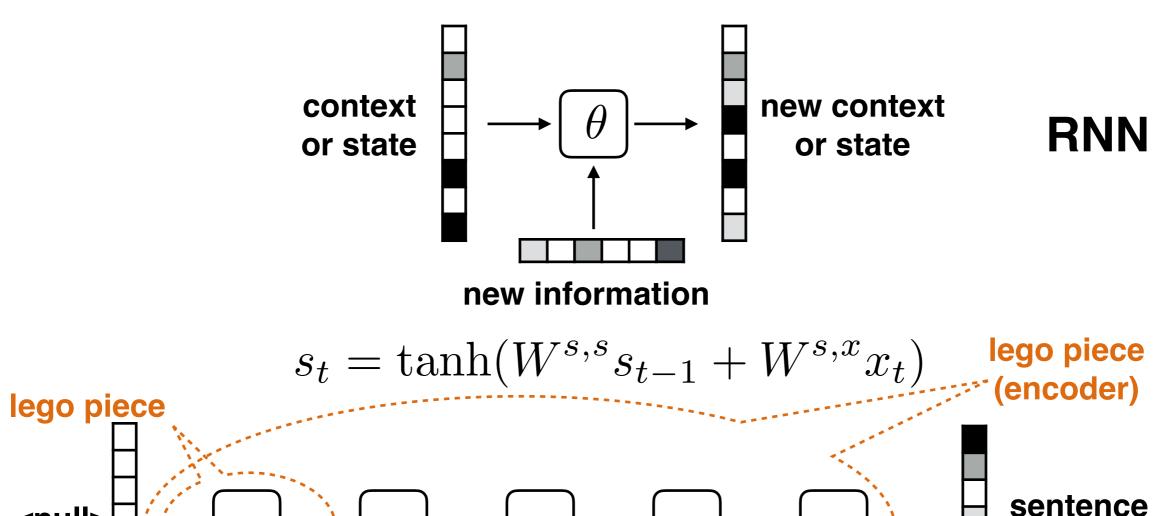
$$s_t = \tanh(W^{s,s} s_{t-1} + W^{s,x} x_t)$$

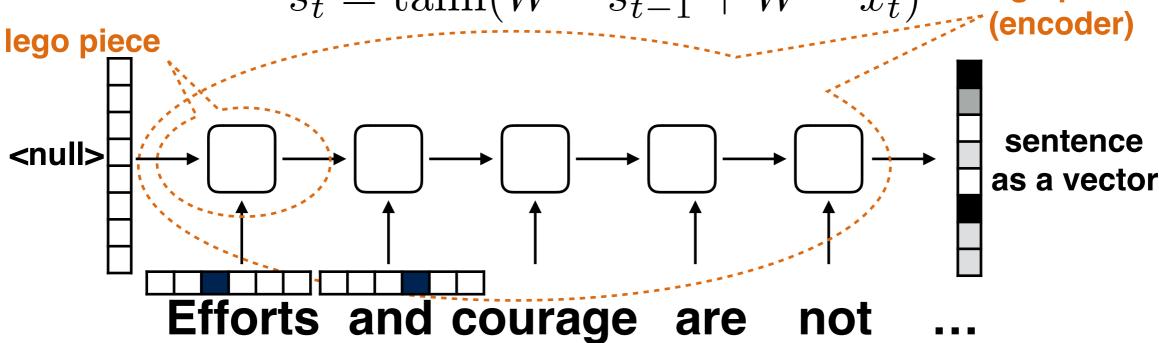




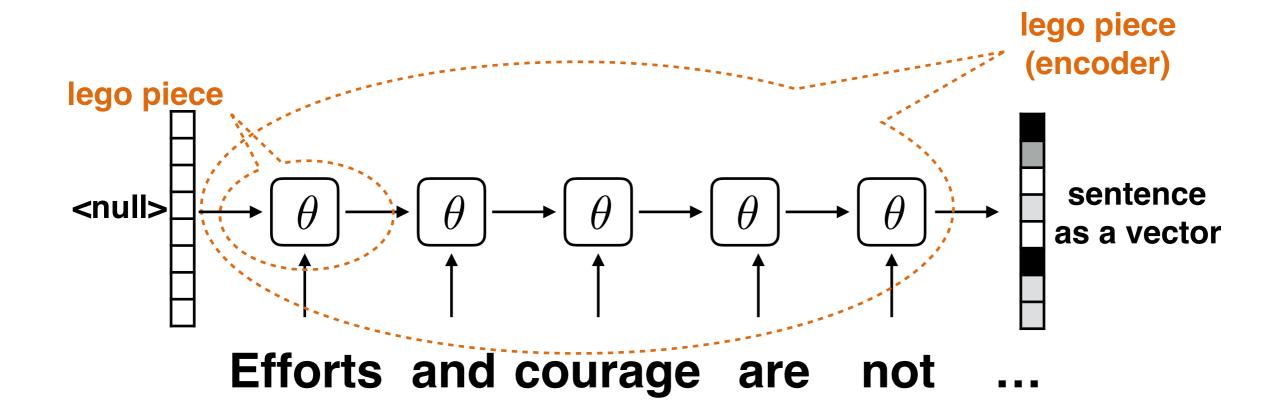
$$s_t = \tanh(W^{s,s} s_{t-1} + W^{s,x} x_t)$$







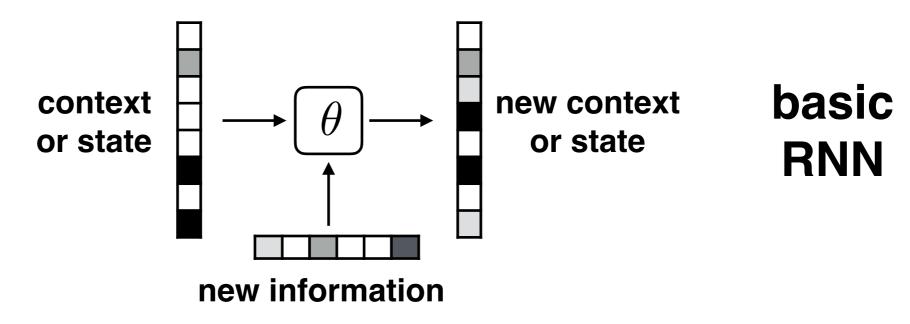
- There are three differences between the encoder (unfolded RNN) and a standard feed-forward architecture
  - input is received at each layer (per word), not just at the beginning as in a typical feed-forward network
  - the number of layers varies, and depends on the length of the sentence
  - parameters of each layer (representing an application of an RNN) are shared (same RNN at each step)





#### What's in the box?

We can make the RNN more sophisticated...

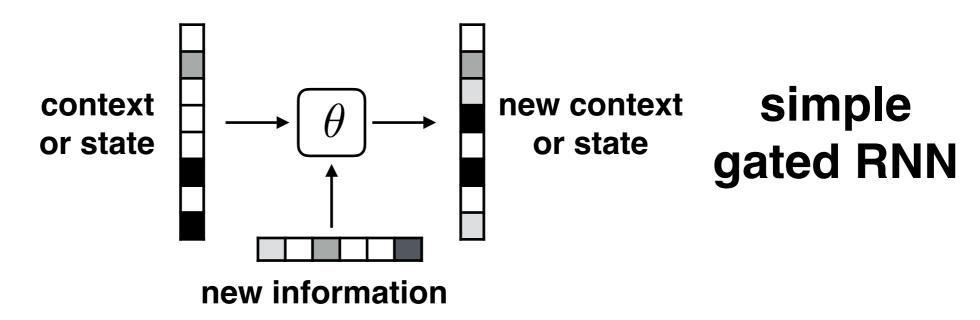


$$s_t = \tanh(W^{s,s} s_{t-1} + W^{s,x} x_t)$$



#### What's in the box?

We can make the RNN more sophisticated...



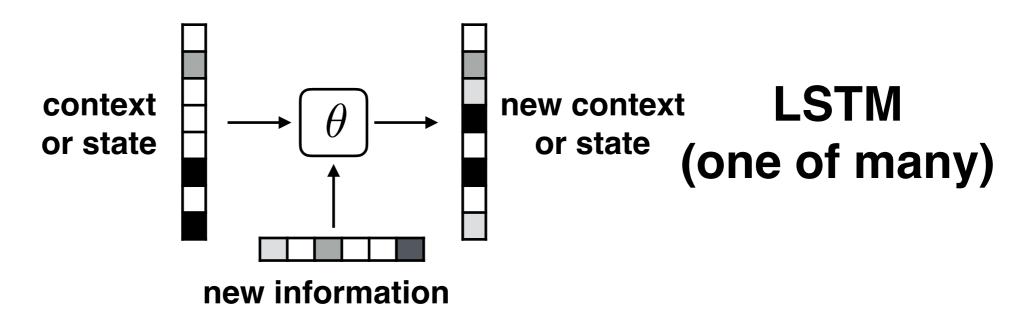
$$g_t = \text{sigmoid}(W^{g,s} s_{t-1} + W^{g,x} x_t)$$

$$s_t = (1 - g_t) \odot s_{t-1} + g_t \odot \tanh(W^{s,s} s_{t-1} + W^{s,x} x_t)$$



#### What's in the box?

We can make the RNN more sophisticated...



$$f_t = \operatorname{sigmoid}(W^{f,h}h_{t-1} + W^{f,x}x_t)$$
 forget gate  $i_t = \operatorname{sigmoid}(W^{i,h}h_{t-1} + W^{i,x}x_t)$  input gate  $o_t = \operatorname{sigmoid}(W^{o,h}h_{t-1} + W^{o,x}x_t)$  output gate  $c_t = f_t \odot c_{t-1} + i_t \odot \tanh(W^{c,h}h_{t-1} + W^{c,x}x_t)$  memory  $c_t = o_t \odot \tanh(c_t)$  visible state



 Our RNN now needs to also produce an output (e.g., a word) as well as update its state

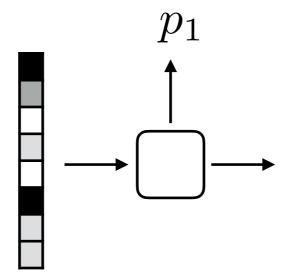
vector encoding
of a sentence
"I have seen better
lectures"



 Our RNN now needs to also produce an output (e.g., a word) as well as update its state

#### distribution over the possible words

vector encoding
of a sentence
"I have seen better
lectures"

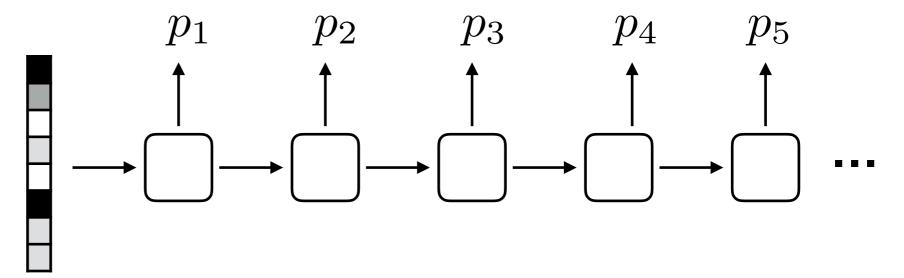




 Our RNN now needs to also produce an output (e.g., a word) as well as update its state

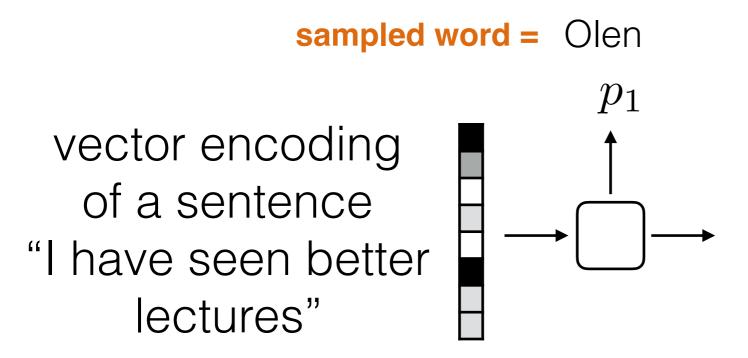
### distribution over the possible words

vector encoding
of a sentence
"I have seen better
lectures"



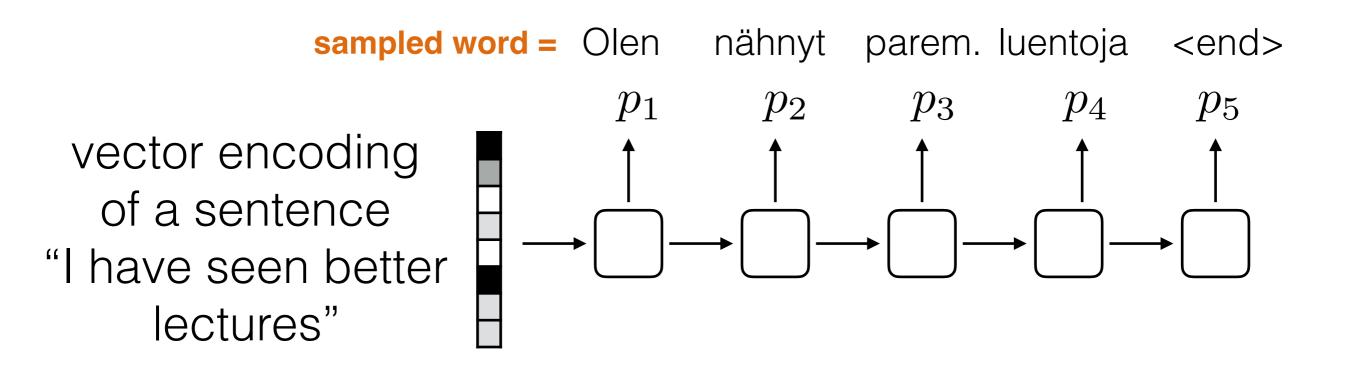


 Our RNN now needs to also produce an output (e.g., a word) as well as update its state



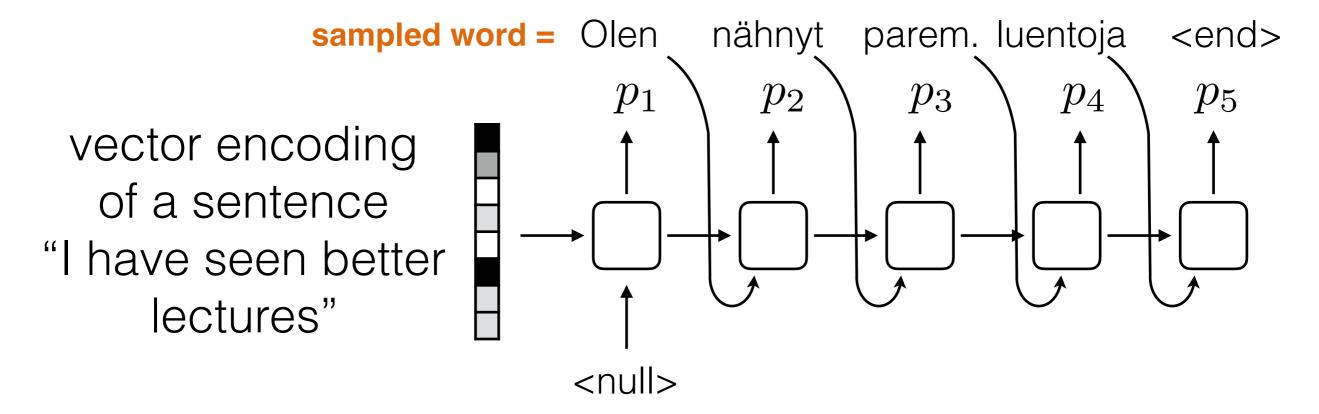


 Our RNN now needs to also produce an output (e.g., a word) as well as update its state





- Our RNN now needs to also produce an output (e.g., a word) as well as update its state
- The output is fed in as an input (to gauge what's left)

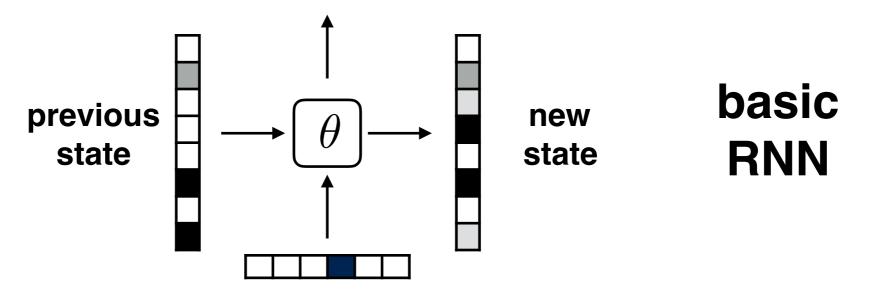




#### Decoding: what's in the box

 Our RNN now needs to also produce an output (e.g., a word) as well as update its state





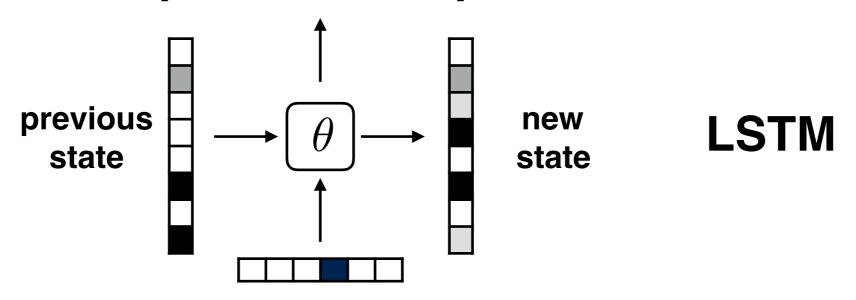
previous output as an input x

$$s_t = \tanh(W^{s,s} s_{t-1} + W^{s,x} x_t)$$
 state  $p_t = \operatorname{softmax}(W^o s_t)$  output distribution



#### Decoding: what's in the box

 $[0.1, 0.3, \ldots, 0.2]$  output distribution



previous output as an input x

$$f_t = \operatorname{sigmoid}(W^{f,h}h_{t-1} + W^{f,x}x_t)$$
 forget gate

$$i_t = \operatorname{sigmoid}(W^{i,h}h_{t-1} + W^{i,x}x_t)$$
 input gate

$$o_t = \operatorname{sigmoid}(W^{o,h}h_{t-1} + W^{o,x}x_t)$$
 output gate

$$c_t = f_t \odot c_{t-1} + i_t \odot \tanh(W^{c,h} h_{t-1} + W^{c,x} x_t) \xrightarrow{\text{memory}}$$

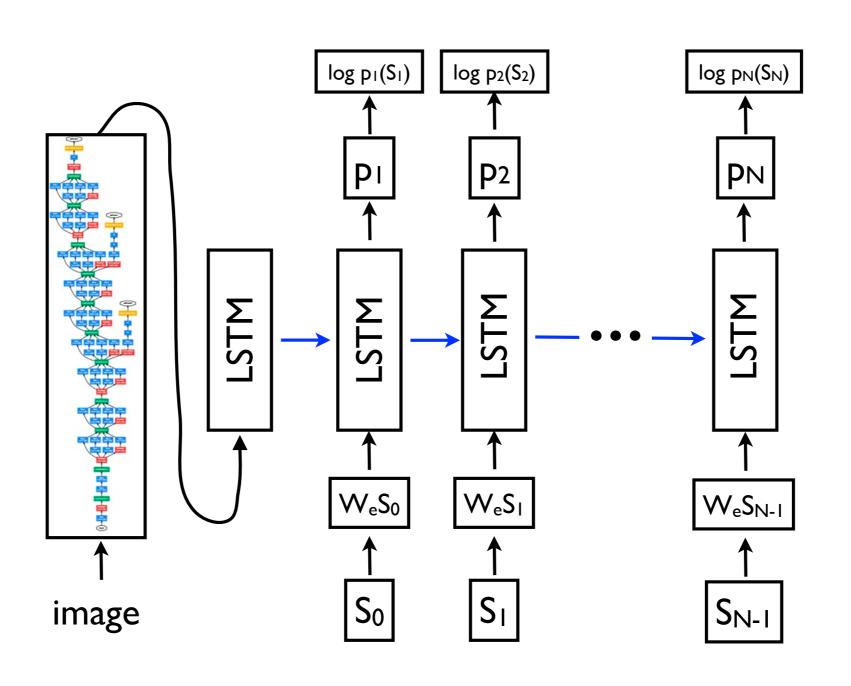
 $h_t = o_t \odot \tanh(c_t)$  visible state

$$p_t = \operatorname{softmax}(W^o h_t)$$
 output distribution





### Mapping images to text





### Examples

A person riding a motorcycle on a dirt road.



A group of young people



A herd of elephants walking across a dry grass field.



Two dogs play in the grass.



Two hockey players are fighting over the puck.



A close up of a cat laying on a couch.



A skateboarder does a trick



A little girl in a pink hat is



A red motorcycle parked on the



A dog is jumping to catch a



A refrigerator filled with lots of food and drinks.



A yellow school bus parked



#### **Key things**

- Multi-way classification (explained on the board)
  - softmax, loss
- Neural networks for sequences
  - encoding/decoding
- RNNs, unfolded
  - state evolution, gates
  - relation to feed-forward neural networks
  - back-propagation (conceptually)
- Issues: vanishing/exploding gradient
- LSTM (operationally)