DAT280 – Lab A: "Parallel Programming in Haskell"

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Setup

The benchmarks have been performed on the following machine:



macOS Sierra

Version 10.12.4

MacBook Pro (Retina, 13-inch, Late 2013)
Processor 2,4 GHz Intel Core i5
Memory 8 GB 1600 MHz DDR3
Startup Disk Macintosh HD
Graphics Intel Iris 1536 MB
Serial Number C02M26YNFH00

System Report...

Software Update...

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The complete model name for the processor is Intel(R) Core(TM) i5-4258U CPU @ 2.40GHz. This processor has two physical and four logical cores.

The executable has been run with the following additional flags to increase performance and reduce time spent garbage collecting: -N4 - A100M -H2G.

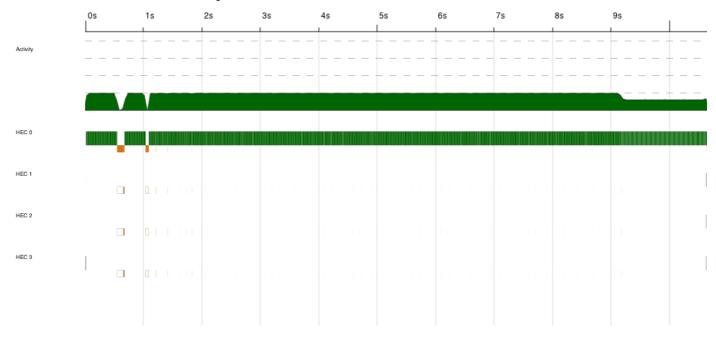
The executable was also compiled with the **-O2** flag to allow the GHC compiler to perform as many optimisations as possible.

All implementations with manual granularity have been run with a depth of 2 since this gave the best result.

Assignment 1

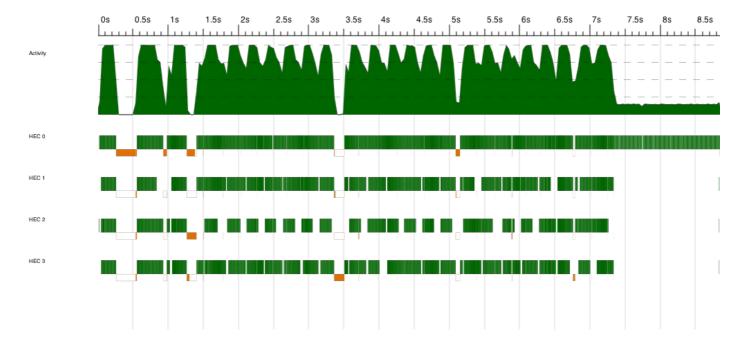
We start by running a benchmark on the standard map function as a starting point for our comparisons.

Benchmark 1.1 - map



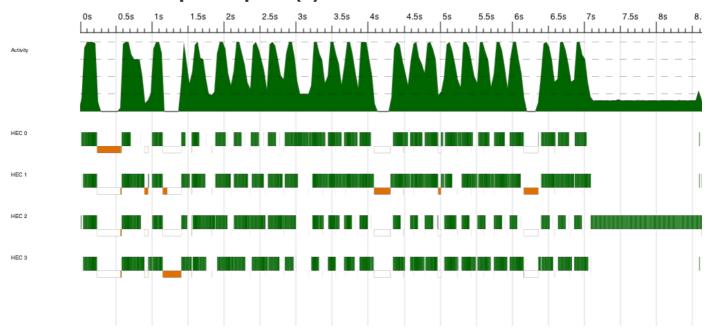
The second benchmark is done on Main.parMap which uses par and depth. It does not use pseq to wait for sub results since we found that the runtime were faster without. This leads to a slight increase in performance from a runtime of approximately 11 seconds in benchmark 1.1 to 9 seconds in 1.2.

Benchmark 1.2 - Main.parMap (a)



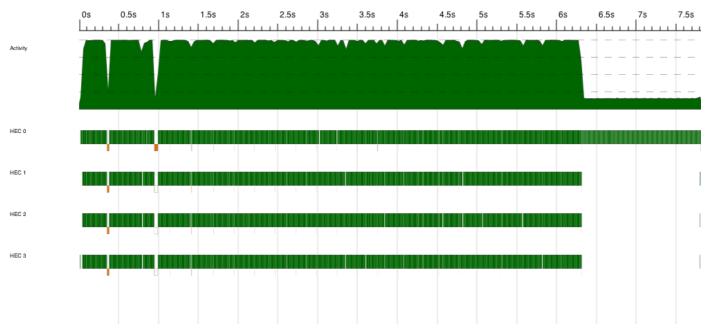
The third benchmark is done on parMapRD which is implemented in a similar way as Main.parMap but uses the Eval-monad instead. The runtime is around 9 seconds here as well as in 1.2, which is expected since it is basically the same function but wrapped in a monad instead.

Benchmark 1.3 - parMapRD (b)

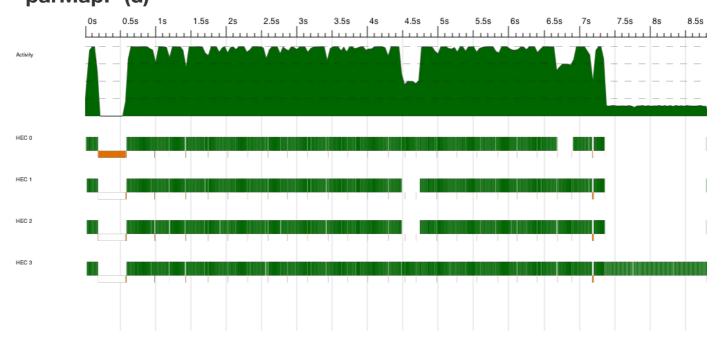


Benchmark 1.4 is done on parMapS which uses the Strategies library. Different from 1.2 and 1.3 is that it does not use depth but creates a spark for each element in the list that could theoretically be run in parallel. This yields a further increase in performance to a runtime of around 8 seconds.

Benchmark 1.4 – parMapS (c)



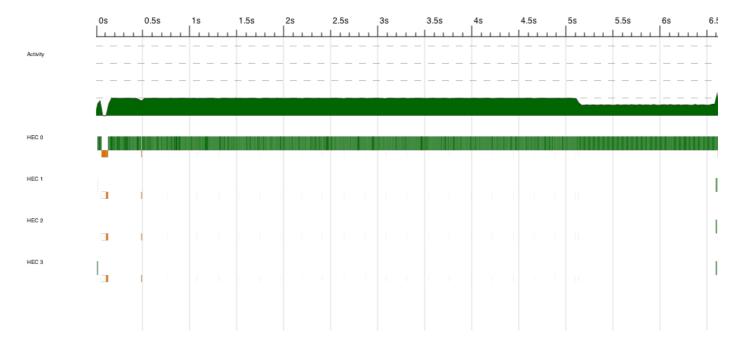
Finally, the fifth benchmark is done on parMapP which uses the Parmonad without depth. The runtime is around 9 seconds. **Benchmark 1.5** – parMapP (d)



Assignment 2

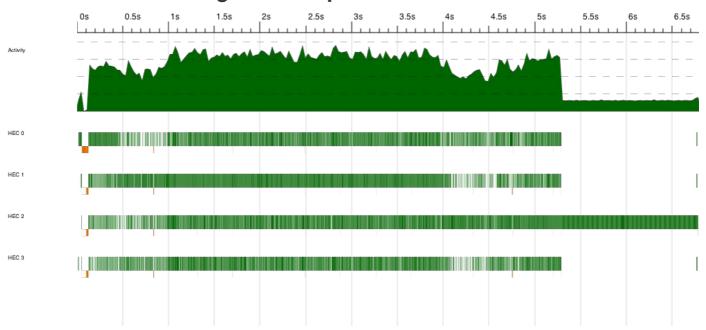
As in the previous case we start with a benchmark of a standard implementation of merge sort. The runtime is around 6.5 seconds.

Benchmark 2.1 - mergesort



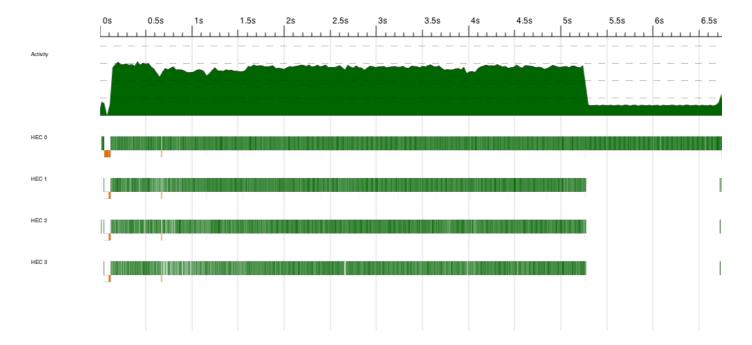
In the first parallelised version that we benchmark uses pseq but unfortunately the runtime is still around 6.5 seconds.

Benchmark 2.2 - mergesortPseq



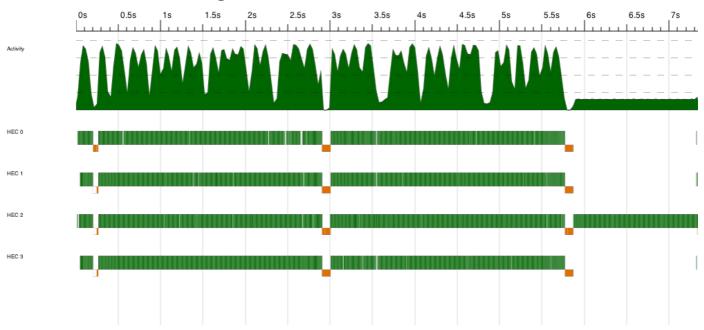
The third benchmark uses uses rpar and depth. Runtime is still around 6.5 seconds.

Benchmark 2.3 - mergesortRD



Finally we tried a version using the Par-monad which gave a runtime of roughly 7 seconds.

Benchmark 2.4 - mergesortP



Conclusions

Regarding the parallelised map we found that parMaps was the fastest by parallelising each element and not using depth. Even though this made the spark tasks small and possibly introducing excessive overhead, it was still fastest. One possible reason for not improving the

performance with depth could be that by manually controlling the granularity, we split the list in half and solve the halves in parallel. Before a final result can be returned, these sub lists must be joined again. The join operation (++) is **O(n)** which becomes relatively costly in our context. We believe that the time saved by reducing spark overhead is lost by the number of joins needed in our implementations with depth and granularity.

Unfortunately we were unable the improve the performance in the merge sort case. Even though merge sort should yield good results when parallelised. Still, it is not as "embarrassingly parallel" as map where all intermediate results a independent of each other. It was mentioned during the lectures that one should have a 4-core machine the really make the course "fun". Maybe the 2 cores of our benchmark machine was not enough to make the parallelisation really shine.