

Slightly Less Simple Mosquito Modeling

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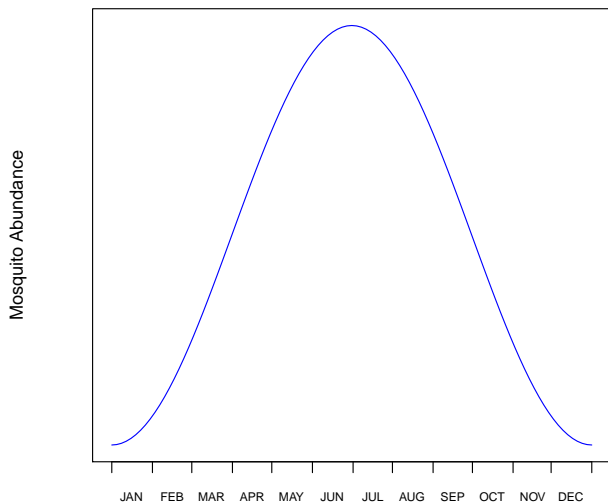
Emerging Pathogens Institute, University of Florida

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What's this talk really about?

- ▶ finding low-hanging fruit,
- ▶ expression with models,
- ▶ simple analytical approaches,
- ▶ a little dimensional analysis,
- ▶ how to connect those with experiments and get higher up the tree, and
- ▶ a little about work habits and tools

A Not Atypical Model of Vector Population



But...

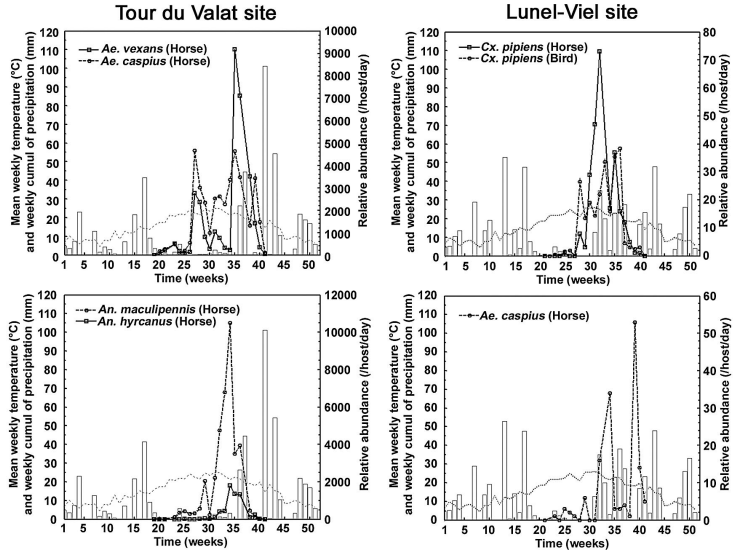


Figure: Bicout et al. J. Med. Entomol. 43(5): 936-946 (2006)

So, a Disconnect.

With

$$M(t) = C \sin(\omega t + \theta)$$

Impossible to match features like

- ▶ peak population,
- ▶ total population over a year, and
- ▶ turnover rate

These can be critical to predicting transmission dynamics.

Do Better, But Keep It Simple

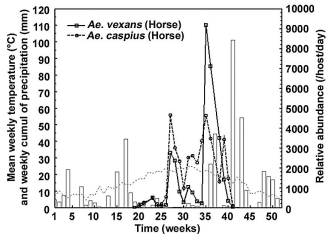
What's good about trigonometric representation? Simplicity:

- ▶ two parameters
- ▶ no spatial features
- ▶ “easy” analytical form

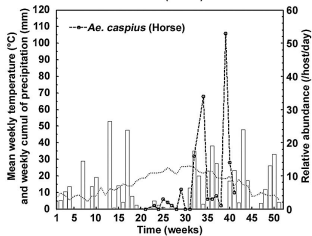
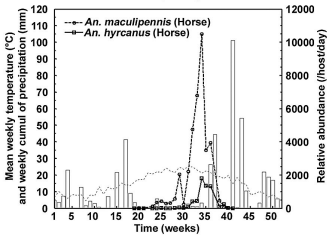
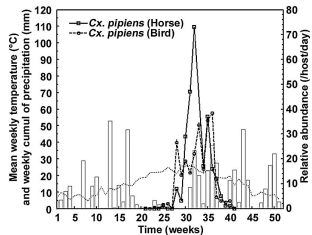
Possible to identify alternatives that *can* match salient features, but still retain these features?

What are those salient features? Let's look again.

Tour du Valat site



Lunel-Viel site



Salient Features

- ▶ every year,
- ▶ over a relatively short duration,
- ▶ the mosquito population rapidly increases,
- ▶ sits at a high level of activity,
- ▶ then rapidly declines,
- ▶ apparently connected with resource availability & environmental suitability

Salient Features in Trig. Representation

- ▶ every year, **CHECK!** ... *but not the rest of:*
- ▶ over a relatively short duration,
- ▶ the mosquito population rapidly increases,
- ▶ then rapidly declines,
- ▶ apparently connected with resource availability & environmental suitability

Getting at the Other Points

Need:

- ▶ worth connecting to external force
- ▶ “spikey”
- ▶ oscillatory

Can get that with repeating boundary conditions on

$$\dot{M}(t) = E(t) - \lambda M(t)$$

and appropriate $E(t)$.

Appropriate $E(t)$

Most of the criteria boil down to a “spikey” function options.
Suggestions?

What else would we need to ensure?

Alternatives I

$$E(t) = \begin{cases} \frac{M_+}{\Delta t} & t \in \Delta t \\ 0 & \text{otherwise} \end{cases} \quad (\text{Step})$$

$$E(\rho, t) = \begin{cases} \frac{2M_+}{\Delta t(2-\rho)} & t \in \Delta t(1-\rho) \\ \frac{2M_+}{\Delta t(2-\rho)\rho} \left(1 - \frac{2|t|}{\Delta t}\right) & t \in \rho\Delta t \\ 0 & \text{otherwise} \end{cases} \quad (\text{Modified Step})$$

$$E(t) = \frac{2M_+}{\Delta t} \sqrt{\frac{2}{\pi}} e^{-\frac{8t^2}{\Delta t^2}} \quad (\text{Approximate } \delta)$$

Alternatives II

$$E(t) = \frac{M_+}{\Delta t} \sqrt{\frac{2}{\pi}} e^{-\frac{\sin^2 \omega t}{\omega^2 \Delta t^2}} \quad \left(\omega = \frac{\pi}{T}\right) \quad (\text{Trig. Approximate } \delta)$$

$$E(t) = \frac{M_+}{T} \left(1 + \cos\left(\frac{2\pi}{T}t\right)\right) \quad (\text{Trig.})$$

$$E(t) = \frac{(2^n n!)^2}{(2n)!} \frac{M_+}{T} \cos^{2n}\left(\frac{4\pi}{T}t\right) \quad \left(n = \lfloor 2^{-1} \sin^{-2} \frac{\pi \Delta t}{2T} \rfloor\right) \quad (\text{Proper Trig.})$$

$$E(c, t) = \frac{M_+}{\Delta t} \left[\frac{1}{1 + e^{-c(t+\Delta t/2)}} - \frac{1}{1 + e^{-c(t-\Delta t/2)}} \right] \quad (\text{Double Logistic})$$

Aside: Dimensional Analysis

Those equations have a lot of parameters, as do the resulting integral solutions.

Fortunately, everything you learned in engineering coursework can apply here as well.

So, how can remove the scales?

Scale-free Alternatives I

$$\tilde{E}(\rho, \tau) = \begin{cases} \frac{1}{\rho} & |\tau| \leq \rho/2 \\ 0 & \text{otherwise} \end{cases} \quad (\text{Step})$$

$$\tilde{E}(\rho, \rho_{\Delta}, \tau) = \begin{cases} \frac{2}{\rho(2 - \rho_{\Delta})} & \tau \in \rho(1 - \rho_{\Delta}) \\ \frac{2}{\rho(2 - \rho_{\Delta})\rho_{\Delta}} \left(1 - \frac{2|\tau|}{\rho}\right) & \tau \in \rho\rho_{\Delta} \\ 0 & \text{otherwise} \end{cases} \quad (\text{Modified Step})$$

$$\tilde{E}(\rho, \tau) = \frac{2}{\rho} \sqrt{\frac{2}{\pi}} e^{-\frac{8}{\rho^2} \tau^2} \quad (\text{Approximate } \delta)$$

Scale-free Alternatives II

$$\tilde{E}(\rho, \tau) = \frac{1}{\rho} \sqrt{\frac{2}{\pi}} e^{-\frac{\sin^2 \pi \tau}{\pi^2 \rho^2}} \quad (\text{Trig. Approximate } \delta)$$

$$\tilde{E}(\tau) = (1 + \cos 2\pi\tau) \quad (\text{Trig.})$$

$$\tilde{E}(\rho, \tau) = \frac{(2^n n!)^2}{(2n)!} \cos^{2n} 4\pi\tau \quad (n = \lfloor 2^{-1} \sin^{-2} \frac{\pi\rho}{2} \rfloor)$$

(Proper Trig.)

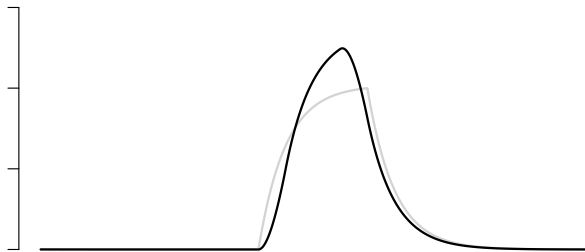
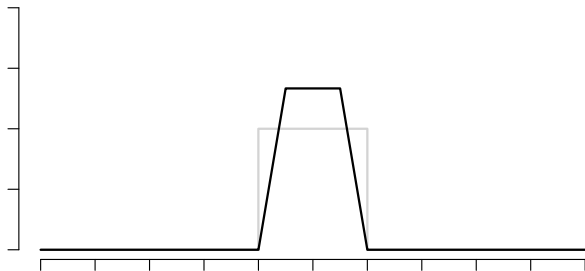
$$\tilde{E}(\tilde{c} = cT, \rho, \tau) = \frac{1}{\rho} \left[\frac{1}{1 + e^{-\tilde{c}(\tau + \rho/2)}} - \frac{1}{1 + e^{-\tilde{c}(\tau - \rho/2)}} \right]$$

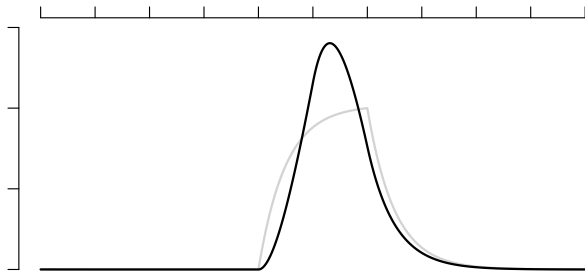
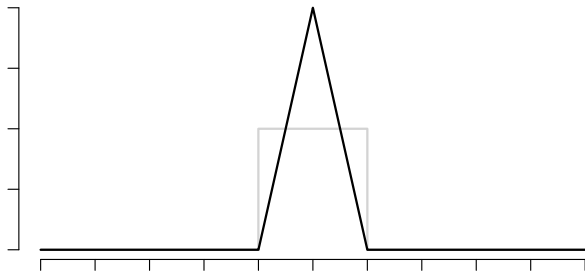
(Double Logistic)

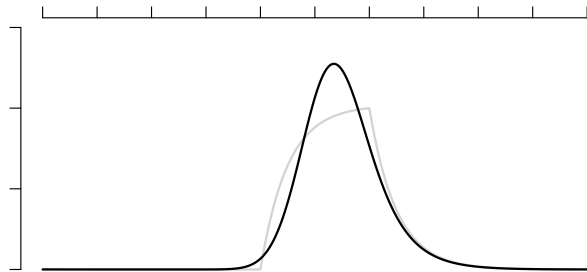
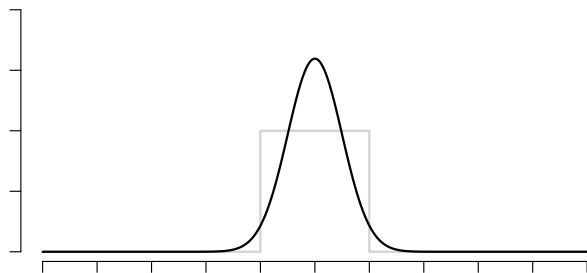
The Resulting Mosquito Populations

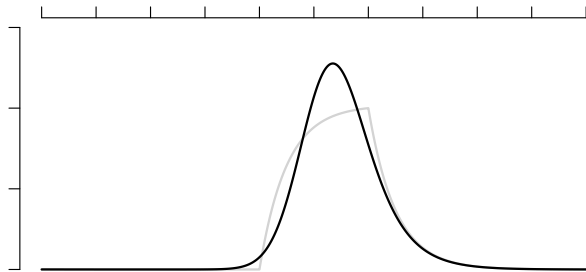
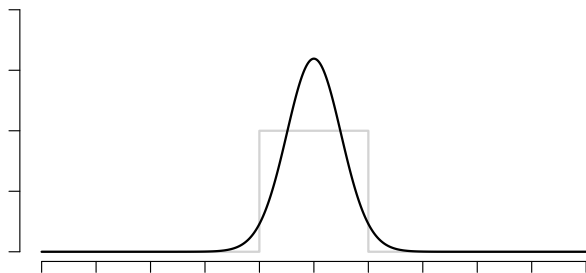
The analytical work to get exact $M(t)$ is. . . tedious. Thankfully, there are numerical integrators!

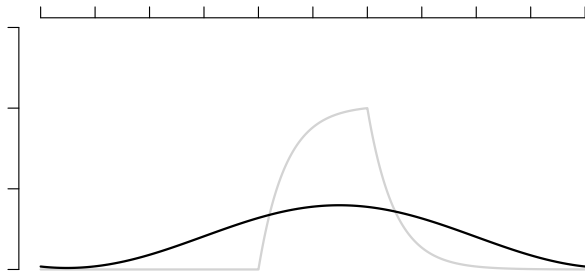
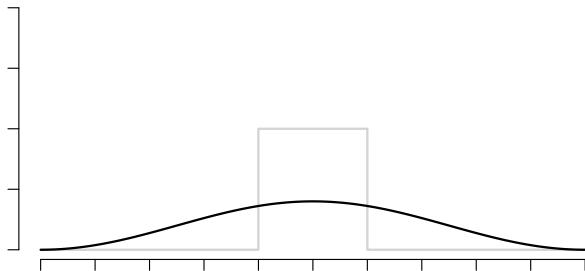
Which gives us a window to qualify these alternatives rapidly, and then decide which to thoroughly investigate.

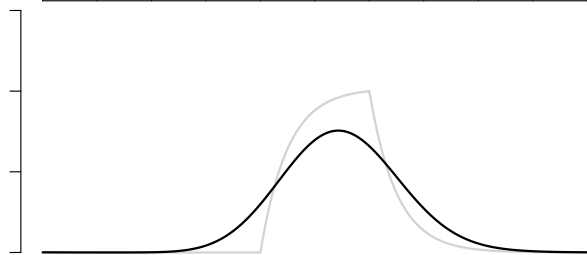
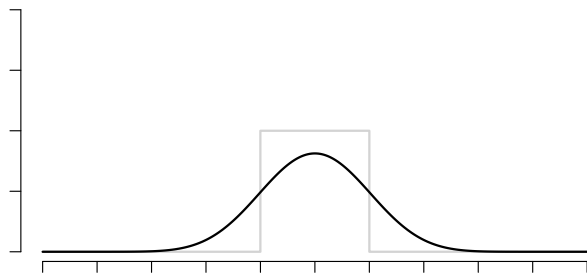


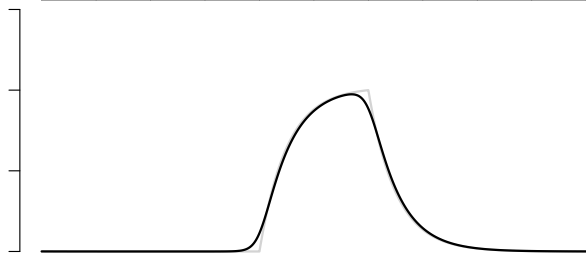
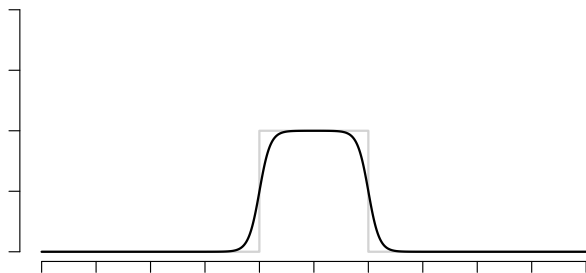






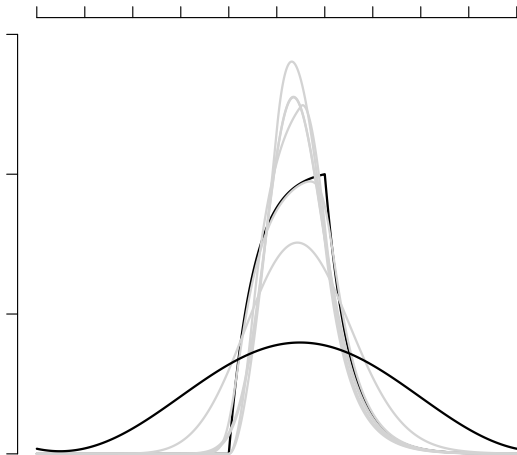






Thoughts?

What do *you* think about the options?



Back To Oversimplification Question

Are these alternatives still too simple?

They are all built assuming a stable driver, which is inaccurate.

But: this framework presents an easy way to consider $E(t)$ changes as perturbations.

So What?

What does this basic analysis give us?

- ▶ rough boundaries as input to other models,
- ▶ where more complex approaches are needed (agent-based, spatially explicit, *etc.*)
- ▶ a component connectable to other models

Seque: Need “New” Habits and Tools

New challenges to getting science done:

- ▶ lashing together methods from different fields,
- ▶ getting genuine peer-review, and
- ▶ the purely mechanical handling of different people simultaneously working on the same “thing”

How can we address these issues?

Solutions from Software Industry?

What tools and habits can we adopt from this field?

What risks are associated with that?

What's still missing?

The Good

- ▶ version control systems,
- ▶ collaborative tools on top of those,
- ▶ preference for code documentation leading to
 - ▶ bite-sized parts,
 - ▶ modularity,
 - ▶ re-usability, and
 - ▶ verifiability (a/k/a unit testing)
- ▶ open availability of all source,
- ▶ combines with version control to provide complete history of work product

The Bad

- ▶ openness can make for opportunity to be “scooped”,
- ▶ can focus more on process than product,
- ▶ learning curve for most scientists

The Ugly

- ▶ university contracts' intellectual property clauses,
- ▶ academic institutions don't “get” these tools,
- ▶ community adoption?

Committing to master



Uncommitted Changes



Commit

Commit summary

Extended description

moz-model-pres.Rnw

Tip: Click line numbers to select specific lines

OLD	NEW	
257	257	@@ -257,10 +257,13 @@ What does this basic analysis give us?
258	258	}
259	259	\frame{
260	260	+\frametitle{Why Come to These Meetings?}
261	261	+
262	262	+=}
263	263	+

Why bring this up?

It's a little bit advocacy, and I built this presentation using this work model.

<http://github.com/pearsonca/moz-model-pres>

/Volumes/Data/workspaces/moz-model-pres

No unsynced commits

271	275	... collaboration, and to increasingly digitally-based components
		%. The final specialist work product can be very intimidating
		specialities, which can make a collaboration's skeptical review
		difficult. That's on top of the pure mechanics of handling mu
		``thing''.
272	276	% I come from a background where all collaborators are respon
		just their narrowly focused piece
273	277	}

Why Come to These Meetings?