

Chem3208 Lectures 1–4

Hückel Theory

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Theoretical/Computational ab initio quantum chemistry

- Computational Chemistry studies chemistry with computers
- Theoretical Chemistry creates the methods for Computational Chemistry
- Ab initio means “from the beginning”
- Ab initio quantum chemistry uses quantum mechanics
- In this course, we are interested by electrons!

Ultimate Goal of Quantum Chemistry

Erwin Schrödinger
(1887–1961)



Schrödinger Equation (1926)

$$\mathbf{H}\psi_i = E_i\psi_i$$

\mathbf{H} = Hamiltonian

ψ_i = wave functions

E_i = energies

Take-home message: Quantum Chemistry is all about solving integrals!!

But, how do we do it on a computer?

$$\mathbf{H}\mathbf{C} = \mathbf{S}\mathbf{C}\mathbf{E} \quad \text{or} \quad \mathbf{F}\mathbf{C} = \mathbf{S}\mathbf{C}\mathbf{E} \quad (\text{mean-field methods})$$

\mathbf{F} = Fock matrix

\mathbf{S} = Overlap matrix

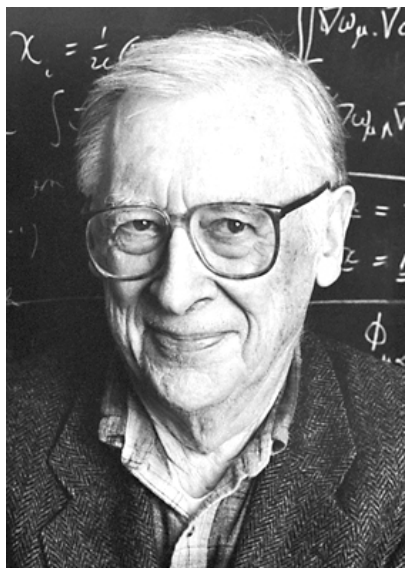
\mathbf{C} = Coefficient matrix

\mathbf{E} = Energy matrix

Generalized Eigenvalue Problem

1998 Nobel Prize in Chemistry

John Pople (1925–2004)



“...for his development of computational methods in quantum chemistry”

Walter Kohn (1923–2016)

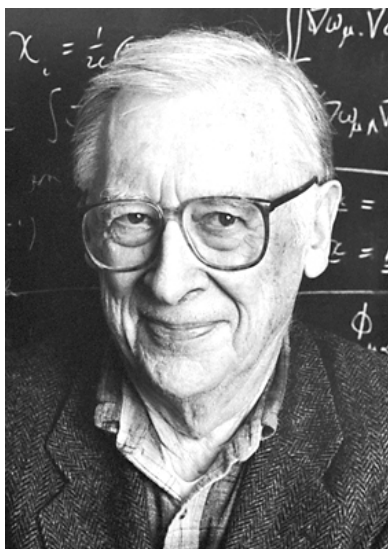


“...for his development of the density-functional theory”

Development of methods, algorithms and softwares

Electronic Structure Theory

John Pople



- Semi-empirical methods
(we shall talk about this later on)
- Gaussian suite of programs and Q-chem later
(There are many others...)
- Composite methods (G1, G2, etc)
(some people love these methods)
- density-functional theory
(nobody likes it but everyone's using it)

Idea behind density-functional theory (DFT)

Walter Kohn
(1923-2016)



Hohenberg-Kohn theorem

The ground state electronic energy is completely determined by the electron density ρ

There is a one-to-one correspondence between ρ and the energy E

Hohenberg-Kohn theorem shows that you can use the electron density $\rho(\mathbf{r})$ instead of the wave function $\Psi(\mathbf{r}_1, \dots, \mathbf{r}_n)$

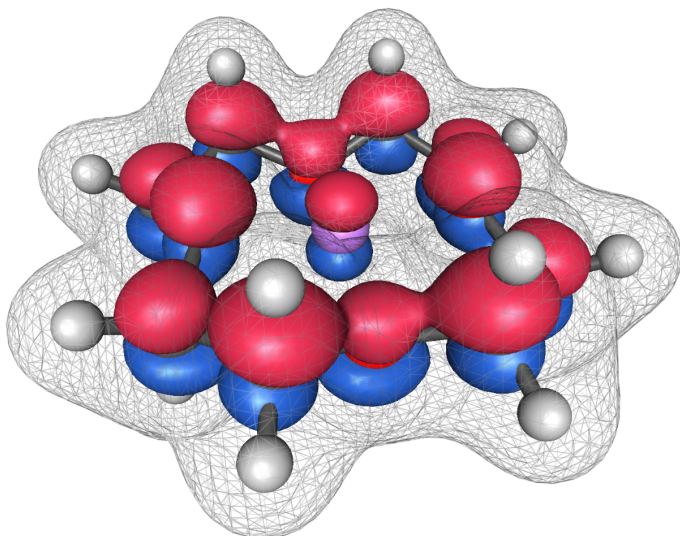
The functional connecting ρ and E is unknown....

The goal is to design functionals connecting the electron density with the energy...

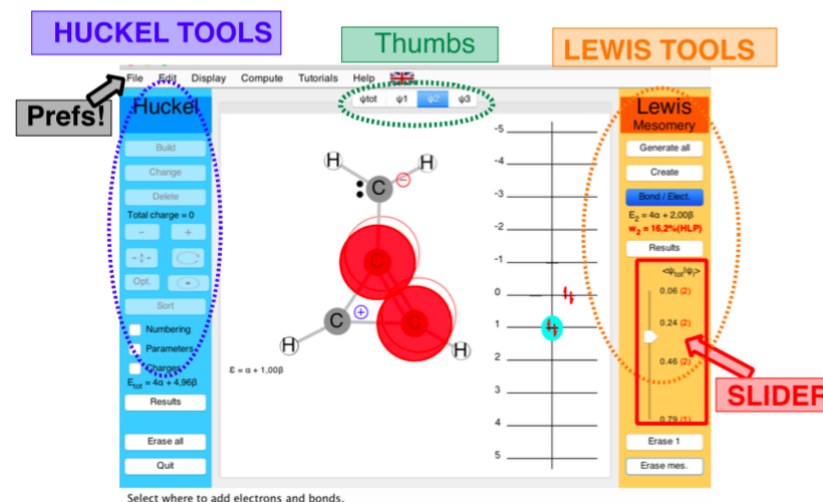
Hohenberg & Kohn, Phys Rev 136 (1964) B864

Cool softwares I'm going to use...

IQMol: <http://iqmol.org>



HuLiS:
<http://www.hulis.free.fr>



Q-Chem: <http://q-chem.com>



Crash course in Quantum Mechanics

$\langle\psi|$ = this is a **bra** $|\phi\rangle$ = this is a **ket** $\langle\psi|\phi\rangle$ = this is a **braket**

$\langle\psi|\phi\rangle$ means $\int \int \cdots \int \psi^*(\mathbf{r}_1, \mathbf{r}_2, \dots, \mathbf{r}_n) \phi(\mathbf{r}_1, \mathbf{r}_2, \dots, \mathbf{r}_n) d\mathbf{r}_1 d\mathbf{r}_2 \dots d\mathbf{r}_n$

An operator **O** applied to a **braket** is

$\langle\psi|\mathbf{O}|\phi\rangle$ means $\int \int \cdots \int \psi^*(\mathbf{r}_1, \mathbf{r}_2, \dots, \mathbf{r}_n) \mathbf{O} \phi(\mathbf{r}_1, \mathbf{r}_2, \dots, \mathbf{r}_n) d\mathbf{r}_1 d\mathbf{r}_2 \dots d\mathbf{r}_n$

Let's take a concrete example on $[-1, 1]$ for

$$|\psi_1\rangle = x \quad |\psi_2\rangle = x^2 \quad \mathbf{O} = \frac{d}{dx}$$

$$\mathbf{O}|\psi_1\rangle = 1 \quad \mathbf{O}|\psi_2\rangle = 2|\psi_1\rangle$$

In the **basis of ψ_1 and ψ_2** , the **matrix representation** of **O** is

$$\mathbf{O} = \begin{pmatrix} \langle\psi_1|\mathbf{O}|\psi_1\rangle & \langle\psi_1|\mathbf{O}|\psi_2\rangle \\ \langle\psi_2|\mathbf{O}|\psi_1\rangle & \langle\psi_2|\mathbf{O}|\psi_2\rangle \end{pmatrix} = \begin{pmatrix} 0 & 4/3 \\ 2/3 & 0 \end{pmatrix}$$

Crash course in Quantum Mechanics (Take 2)

Note that the basis is said to be orthogonal because the overlap matrix is diagonal

$$\mathbf{S} = \begin{pmatrix} \langle \psi_1 | \psi_1 \rangle & \langle \psi_1 | \psi_2 \rangle \\ \langle \psi_2 | \psi_1 \rangle & \langle \psi_2 | \psi_2 \rangle \end{pmatrix} = \begin{pmatrix} 2/3 & 0 \\ 0 & 2/5 \end{pmatrix}$$

We can diagonalize \mathbf{O} to find the eigenvalues and eigenvectors

Secular determinant: $\begin{vmatrix} 0 - \lambda & 4/3 \\ 2/3 & 0 - \lambda \end{vmatrix} = 0 \quad \Rightarrow \quad \boxed{\lambda = \pm \frac{2\sqrt{2}}{3}}$

The eigenvector associated with the eigenvalue λ is defined as

$$\begin{pmatrix} 0 & 4/3 \\ 2/3 & 0 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = \lambda \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} \quad \Rightarrow \quad \boxed{4c_2/3 = \lambda c_1}$$

which yields

$$\begin{pmatrix} -\sqrt{2} \\ 1 \end{pmatrix} \text{ for } \lambda = -\frac{2\sqrt{2}}{3} \quad \text{and} \quad \begin{pmatrix} \sqrt{2} \\ 1 \end{pmatrix} \text{ for } \lambda = \frac{2\sqrt{2}}{3}$$

Crash course in Quantum Mechanics (Take 3)

An eigenvector **is not unique** and sometimes we like it to be **normalized**, i.e.

$$c_1^2 + c_2^2 = 1$$

$$\begin{pmatrix} -\sqrt{2} \\ 1 \end{pmatrix} \text{ is **not normalized** and } \begin{pmatrix} \sqrt{2/3} \\ 1/\sqrt{3} \end{pmatrix} \text{ is **normalized**}$$

If you store the eigenvectors and eigenvalues in matrices

$$\mathbf{U} = \begin{pmatrix} \sqrt{2} & -\sqrt{2} \\ 1 & 1 \end{pmatrix} \quad \mathbf{o} = \begin{pmatrix} \frac{2\sqrt{2}}{3} & 0 \\ 0 & -\frac{2\sqrt{2}}{3} \end{pmatrix}$$

we have $\boxed{\mathbf{O} = \mathbf{U} \mathbf{o} \mathbf{U}^{-1}}$ where the **inverse** is defined as $\boxed{\mathbf{U} \mathbf{U}^{-1} = \mathbf{U}^{-1} \mathbf{U} = \mathbf{I}}$

Two last things:

Unitary matrix \Leftrightarrow **orthogonal** for reals $\Rightarrow \mathbf{U}^{-1} = \mathbf{U}^\dagger$ and $\det(\mathbf{U}) = 1$

Hermitian matrix \Leftrightarrow **symmetric** for reals $\Rightarrow \mathbf{U} = \mathbf{U}^\dagger$

How to calculate the determinant of a square matrix

2×2 determinant

$$\mathbf{A} = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \implies \det(\mathbf{A}) = \begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - cb$$

$$\det(\mathbf{A} \mathbf{B}) = \det(\mathbf{A}) \det(\mathbf{B})$$

$$\det(\mathbf{A}^{-1}) = \frac{1}{\det(\mathbf{A})}$$

3×3 determinant (rule of Sarrus)

$$\mathbf{A} = \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix} \implies \det(\mathbf{A}) = \begin{vmatrix} a & b & c \\ d & e & f \\ g & h & i \end{vmatrix} = aei + dhc + gbf - gec - ahf - dbi$$

Expanding wrt a row/column (Laplace's formula)

$$\det(\mathbf{A}) = \begin{vmatrix} a & b & c \\ d & e & f \\ g & h & i \end{vmatrix} = (-1)^{1+1} a \begin{vmatrix} e & f \\ h & i \end{vmatrix} + (-1)^{1+2} b \begin{vmatrix} d & f \\ g & i \end{vmatrix} + (-1)^{1+3} c \begin{vmatrix} d & e \\ g & h \end{vmatrix}$$