

## Complexity classes

The following list contains common time complexities of algorithms:

- $O(1)$  The running time of a **constant-time** algorithm does not depend on the input size. A typical constant-time algorithm is a direct formula that calculates the answer.
- $O(\log n)$  A **logarithmic** algorithm often halves the input size at each step. The running time of such an algorithm is logarithmic, because  $\log_2 n$  equals the number of times  $n$  must be divided by 2 to get 1.
- $O(\sqrt{n})$  A **square root algorithm** is slower than  $O(\log n)$  but faster than  $O(n)$ . A special property of square roots is that  $\sqrt{n} = n/\sqrt{n}$ , so the square root  $\sqrt{n}$  lies, in some sense, in the middle of the input.
- $O(n)$  A **linear** algorithm goes through the input a constant number of times. This is often the best possible time complexity, because it is usually necessary to access each input element at least once before reporting the answer.
- $O(n \log n)$  This time complexity often indicates that the algorithm sorts the input, because the time complexity of efficient sorting algorithms is  $O(n \log n)$ . Another possibility is that the algorithm uses a data structure where each operation takes  $O(\log n)$  time.
- $O(n^2)$  A **quadratic** algorithm often contains two nested loops. It is possible to go through all pairs of the input elements in  $O(n^2)$  time.
- $O(n^3)$  A **cubic** algorithm often contains three nested loops. It is possible to go through all triplets of the input elements in  $O(n^3)$  time.
- $O(2^n)$  This time complexity often indicates that the algorithm iterates through all subsets of the input elements. For example, the subsets of  $\{1, 2, 3\}$  are  $\emptyset$ ,  $\{1\}$ ,  $\{2\}$ ,  $\{3\}$ ,  $\{1, 2\}$ ,  $\{1, 3\}$ ,  $\{2, 3\}$  and  $\{1, 2, 3\}$ .
- $O(n!)$  This time complexity often indicates that the algorithm iterates through all permutations of the input elements. For example, the permutations of  $\{1, 2, 3\}$  are  $(1, 2, 3)$ ,  $(1, 3, 2)$ ,  $(2, 1, 3)$ ,  $(2, 3, 1)$ ,  $(3, 1, 2)$  and  $(3, 2, 1)$ .

An algorithm is **polynomial** if its time complexity is at most  $O(n^k)$  where  $k$  is a constant. All the above time complexities except  $O(2^n)$  and  $O(n!)$  are polynomial. In practice, the constant  $k$  is usually small, and therefore a polynomial time complexity roughly means that the algorithm is *efficient*.

Most algorithms in this book are polynomial. Still, there are many important problems for which no polynomial algorithm is known, i.e., nobody knows how to solve them efficiently. **NP-hard** problems are an important set of problems, for which no polynomial algorithm is known<sup>1</sup>.

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<sup>1</sup>A classic book on the topic is M. R. Garey's and D. S. Johnson's *Computers and Intractability: A Guide to the Theory of NP-Completeness* [28].