

## Hamiltonian systems

$H[\bar{q}, \bar{p}; t]$ :

$$\begin{cases} \dot{q}_i = \frac{\partial H}{\partial p_i} & i = 1, 2, \dots, n \\ -\dot{p}_i = \frac{\partial H}{\partial q_i} & q_i(t_0) = q_i^0, p_i(t_0) = p_i^0 \end{cases}$$

$q_i$  - generalized coordinates

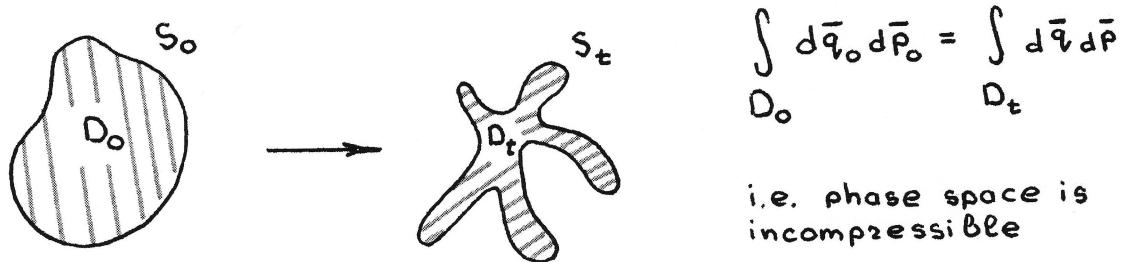
$p_i$  - generalized momentums

$n$  - number of degrees of freedom

$(q_i, p_i) \equiv (q, p)$  - canonical variables, which form phase space

### Properties of the phase space

- 1) Phase space trajectories never cross each other
- 2) Phase space volume is conserved (Liouville Theorem).
- 3)  $S_0 \rightarrow S_t$



In order to describe behavior of the system it is useful to know integrals of motion:

$$f(\bar{q}, \bar{p}) = \text{const} \quad \forall t$$

Problem 1. Show that for autonomous system, the Hamiltonian is an integral of motion.  
(i.e. that phase space trajectory lies on a  $(2n-1)$ -D hyper surface)

Hamiltonian systems allow canonical transformations, which are preserving form of equations of motion:

$$(\bar{q}, \bar{p}) \rightarrow (\bar{q}', \bar{p}') : H(\bar{q}, \bar{p}) \rightarrow H'(\bar{q}', \bar{p}') : \dot{q}'_i = \frac{\partial H'}{\partial p'_i} \quad \& \quad \dot{p}'_i = -\frac{\partial H'}{\partial q'_i}$$

## Action angle variables

Consider a canonical transformation of the form:

$$(\bar{q}, \bar{p}) \rightarrow (\bar{\alpha}, \bar{\beta}):$$

$$H(\bar{q}, \bar{p}) \rightarrow H(\bar{\beta}) \rightarrow \begin{cases} \dot{\alpha}_i = \frac{\partial H'}{\partial \beta_i} & \bar{\alpha} = \bar{\alpha}_0 + \bar{\omega}t, \quad \omega_i = \frac{\partial H'}{\partial \beta_i} \\ \dot{\beta}_i = -\frac{\partial H'}{\partial \alpha_i} = 0 & \bar{\beta} = \bar{\beta}_0 = \text{const} \end{cases}$$

If  $\exists$  canonical transformation such a  $(\bar{q}, \bar{p}) \rightarrow (\bar{\alpha}, \bar{\beta})$ , then system is called to be integrable.

$n=1$

$$H[q, p] = \frac{p^2}{2m} + U(q)$$

Using the first integral of motion:

$$E = \frac{p^2}{2m} + U(q) = \text{const}$$

$$\Rightarrow \frac{dq}{dt} = \sqrt{2m(E - U(q))}$$

$$(t - t_0) = \sqrt{2m}^{-1} \int_{q_0}^q \frac{d\tilde{q}}{\sqrt{E - U(\tilde{q})}}$$

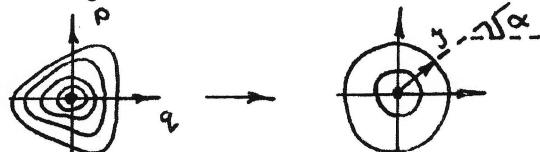
$E, t_0$  are const

Motion is possible only for  $U(q) < E$

$q_{\pm}$ :  $U(q) = E$  - stop points

$q$ :  $\partial_q U(q) = 0$  - elliptic/hyperbolic stationary points

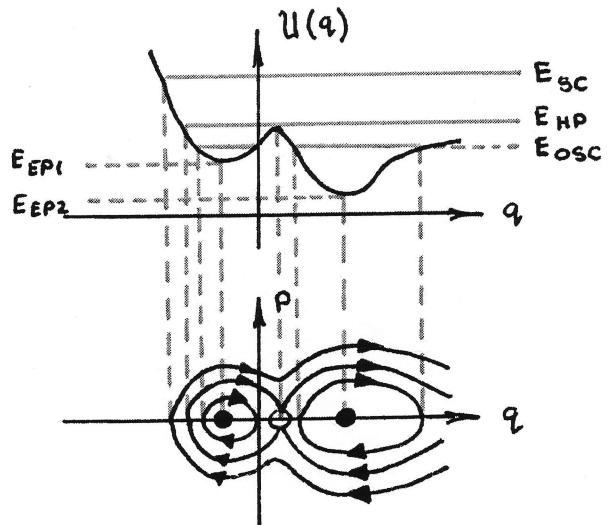
Using action-angle variables (which are always exist for  $n=1$ )



$$J = \frac{1}{2\pi} \oint p dq$$

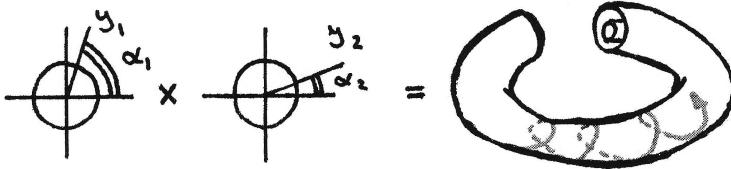
Problem 2. Consider a pendulum  $H = \frac{p^2}{2ml^2} - mgl \cos\varphi$

- show that equation of motion is  $\ddot{\varphi} + \omega_0^2 \sin\varphi = 0$
- describe the phase space
- How u can describe the dynamics around  $\varphi = 0, \pi$
- Find period of oscillations and action-angle variables



$n=2$

If it is possible to perform canonical transformation to action-angle variables  $(q_1, q_2, p_1, p_2) \rightarrow (\alpha_1, \alpha_2, \gamma_1, \gamma_2)$ , the phase-space is fibrated of toruses:



Phase space of the integrable system with 2 degrees of freedom

In general, from torus to torus, one will have different value of

$$\frac{\omega_1}{\omega_2} = \frac{\omega_1(\gamma_1, \gamma_2)}{\omega_2(\gamma_1, \gamma_2)}$$

- commensurate frequencies, i.e.  $\omega_1/\omega_2 = k/m$ ,  $k, m \in \mathbb{N}$ :

$$\alpha_1(t) = \omega_1 t + \alpha_1^0 \Rightarrow \alpha_1(t+T) = \omega_1 t + \alpha_1^0 + 4\pi K$$

$$\alpha_2(t) = \omega_2 t + \alpha_2^0 \Rightarrow \alpha_2(t+T) = \omega_2 t + \alpha_2^0 + 4\pi m$$

where  $T = 2\pi \left( \frac{k}{\omega_1} + \frac{m}{\omega_2} \right)$ , which means the motion is periodic.

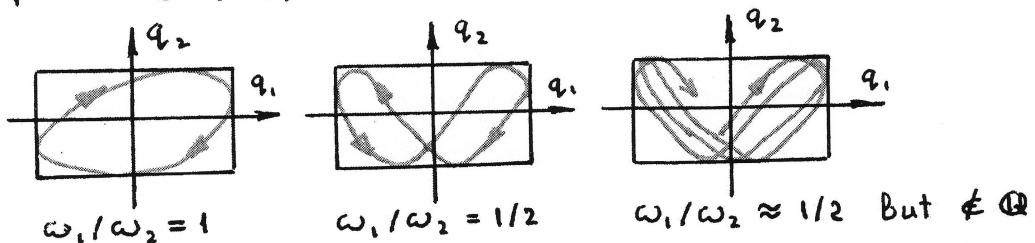
- incommensurate frequencies, i.e.  $\omega_1/\omega_2 \notin \mathbb{Q}$ ,  $\in \mathbb{I} = \mathbb{R}/\mathbb{Q}$ :

the motion is quasi-periodic and phase space trajectory covering the whole surface of torus.

The  $n$ -D torus ( $n \geq 2$ ) is called resonance torus if

$$\sum_{i=1}^n k_i \omega_i(\gamma_1, \dots, \gamma_n) = 0 \quad \text{where } k_i \in \mathbb{Q}, i=1, 2, \dots, n.$$

Projection of the phase space trajectory onto coordinate plane  $(q_1, q_2)$  is called Lissajous curves



Problem 3. Consider a 2-D harmonic oscillator

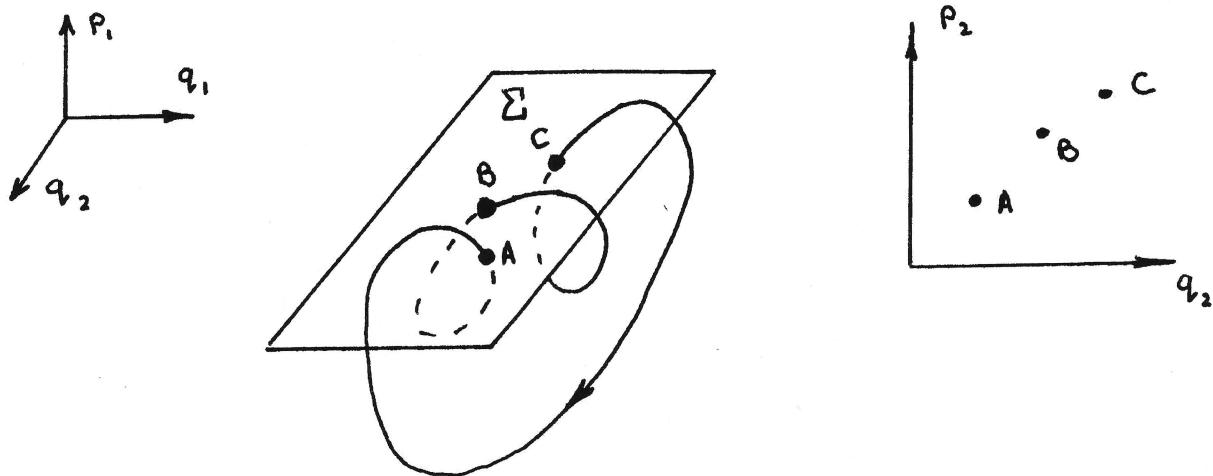
$$H = \frac{1}{2}(p_1^2 + p_2^2) + \frac{1}{2}(\omega_1^2 q_1^2 + \omega_2^2 q_2^2).$$

Find canonical transformation to action-angle variables & expression for  $H(\gamma_1, \gamma_2)$ . Draw phase space torus, and show where is  $\alpha_1, \alpha_2, \gamma_1, \gamma_2$ .

## Poincare map

Consider a Hamiltonian system with 2 degrees of freedom. The motion is constrained on the 3-D hypersurface in 4-D phase space:

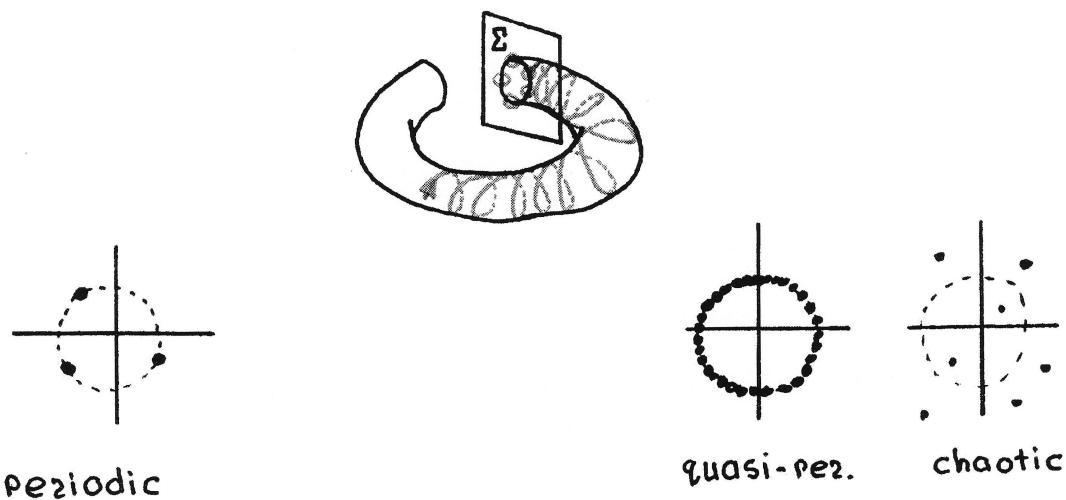
$$H(\bar{q}, \bar{p}) = E \rightarrow p_2 = p_2(q_1, q_2, p_1) = p_2(q_1, q_2, p_1, E)$$



Then we can fix a surface  $\Sigma$ , and study intersection of it and phase space trajectory:

$$p_2(q_1, q_2, p_1) \Big|_{\Sigma: q_2 = \text{const}} \\ q_1(t_i^* + \delta t) - q_1(t_i^*) > 0$$

which gives us a map  $A \rightarrow B = \Phi(A) \rightarrow C = \Phi(B) = \Phi \circ \Phi(A)$



## Anharmonicity

Consider a non-linear oscillator with a Hamiltonian:

$$H = \frac{p^2}{2} + \frac{\omega_0^2}{2} q_v^2 + \frac{\alpha}{3} q^3 + \frac{\beta}{4} q^4$$

$$\left\{ \begin{array}{l} \frac{\partial H}{\partial p} = \dot{q}_v \rightarrow -\alpha q_v^2 - \beta q^3 = \ddot{q}_v + \omega_0^2 q_v \\ -\frac{\partial H}{\partial q} = \dot{p} \end{array} \right. \quad (1)$$

We will look for solution in a form:

$$q_v = q_v^{(1)} + q_v^{(2)} + q_v^{(3)} + \dots$$

$$\text{where } q_v^{(1)} = a \cos \omega t \quad \text{with } \omega = \omega_0 + \omega^{(1)} + \omega^{(2)} + \dots$$

Rewriting (1) as

$$\frac{\omega_0^2}{\omega^2} \ddot{q}_v + \omega_0^2 q_v = -\alpha q_v^2 - \beta q^3 - \left(1 - \frac{\omega_0^2}{\omega^2}\right) \ddot{q}_v$$

- For  $q_v = q_v^{(1)} + q_v^{(2)}$  and  $\omega = \omega_0 + \omega^{(1)}$ , and keeping terms up to a second order of smallness:

$$\begin{aligned} \ddot{q}_v^{(2)} + \omega_0^2 q_v^{(2)} &= -\alpha a^2 \cos^2 \omega t + 2\omega_0 \omega^{(1)} a \cos \omega t = \\ &= -\frac{\alpha a^2}{2} - \frac{\alpha a^2}{2} \cos 2\omega t + \underbrace{2\omega_0 \omega^{(1)} a \cos \omega t}_{\text{resonant condition}} \end{aligned}$$

$$\rightarrow \omega^{(1)} = 0 \quad \rightarrow \quad q_v^{(2)} = -\frac{\alpha a^2}{2\omega_0^2} + \frac{\alpha a^2}{6\omega_0^3} \cos 2\omega t$$

- For  $q_v = q_v^{(1)} + q_v^{(2)} + q_v^{(3)}$  and  $\omega = \omega_0 + \omega^{(2)}$  one have

$$\ddot{q}_v^{(3)} + \omega_0^2 q_v^{(3)} = -2\alpha q_v^{(1)} q_v^{(2)} - \beta q_v^{(1)} q_v^{(2)} + 2\omega_0 \omega^{(2)} q_v^{(1)}$$

$$\rightarrow \ddot{q}_v^{(3)} + \omega_0^2 q_v^{(3)} = -a^3 \left[ \frac{\beta}{4} + \frac{\alpha^2}{6\omega_0^2} \right] \cos 3\omega t + a \underbrace{\left[ 2\omega_0 \omega^{(2)} + \frac{5\alpha^2 \omega^{(2)}}{6\omega_0^2} - \frac{3}{4} \alpha^2 \beta \right]}_{\text{resonant condition}} \cos \omega t$$

$$\left\{ \begin{array}{l} \omega^{(2)} = \left( \frac{3\beta}{8\omega_0} - \frac{5\alpha^2}{12\omega_0^3} \right) a^2 \propto a^2 \\ q_v^{(3)} = \frac{a^3}{16\omega_0^2} \left( \frac{\alpha^2}{3\omega_0^2} + \frac{\beta}{2} \right) \cos 3\omega t \end{array} \right.$$

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## Sextupoles

Equations of motion:

$$\begin{cases} x'' + K_x(s)x = \frac{1}{2} m(s)(x^2 - z^2) \\ z'' + K_z(s)z = -m(s)xz \end{cases}$$

$$m(s) = \frac{S(s)}{B\rho} = \frac{1}{B\rho} \left. \frac{d^2 B_z}{dx^2} \right|_{x=z=0}$$

Unperturbed motion  $q_1(s) = \sqrt{2\beta} \cos(\phi(s) + \Phi_0)$ , where:

$$\begin{cases} 2\beta\beta'' - \beta'^2 + 4\beta^2 K(s) = 4 \\ \phi(s) = \int_0^s \frac{ds}{\beta(s)} \end{cases} \quad \mathcal{D} = \frac{1}{2\pi} \int_s^{s+C} \frac{ds}{\beta(s)}$$

Floquet transform:

$$q(s) = \sqrt{2\beta} \cos \psi(s) \rightarrow \xi = q/\sqrt{\beta} = \sqrt{2} \cos \psi(s)$$

$$\frac{d\xi}{d\psi} = \frac{\alpha q + \beta q'}{\sqrt{\beta}} = -\sqrt{2} \sin \psi(s)$$

$$2\ddot{\psi} = \dot{\xi}^2 + \left( \frac{d\xi}{d\psi} \right)^2 \rightarrow \frac{d^2\xi}{d\psi^2} + \mathcal{D}^2 \xi = 0$$

Therefore

$$x'' + K_x(s)x = f(x, s) \rightarrow \frac{d^2\xi}{d\psi^2} + \mathcal{D}^2 \xi = \mathcal{D}^2 \beta^{3/2} f(x, s)$$

## 1D case

If  $z \equiv 0$ ,  $K_x(s) = \text{const}$ ,  $m(s) = \text{const}$

$$\frac{d^2\xi}{d\psi^2} + \mathcal{D}_0^2 \xi = -\frac{1}{2} \mathcal{D}_0^2 m \beta^{5/2} \xi^2$$

$x = \xi$  and  $t = \psi$ ,  $\omega = \mathcal{D}$ ,  $\alpha = -\frac{1}{2} m \beta^{3/2}$  gives

$$x'' + \omega_0^2 x = \varepsilon \alpha \omega_0^2 x^2 \quad x_0 = A \cos \omega_0 t$$

$$\begin{cases} x = x_0 + \varepsilon x_1 + \varepsilon^2 x_2 + \dots \\ \omega = \omega_0 + \varepsilon \omega_1 + \varepsilon^2 \omega_2 + \dots \end{cases} \rightarrow x'' + x_1 = 2A \frac{\omega_1}{\omega_0} \cos \omega t + \frac{\alpha A^2}{2} (1 + \cos 2\omega t)$$

$$x_1 = \frac{1}{6} \alpha A^2 (3 - 2 \cos \omega t - \cos 2\omega t)$$

$$\text{Next order gives } x_2'' + x_2 = 2\alpha x_0 x_1 - 2x_0'' \frac{\omega_2}{\omega_0} \rightarrow \omega_2 = -\frac{5}{12} \alpha^2 \omega_0 A^2$$

$$\Delta \mathcal{D} = -\frac{5}{48} m A_x^2 \beta_x^4 \mathcal{D}_0$$

### time dependence

$x'' + \omega_0^2 x = g(t)$ , where one can perform Fourier expansion of R.H.S.:

$$g(t) = \frac{a_0}{2} + \sum_1^\infty a_n \cos n\Omega t$$

$$\rightarrow x_n(t) = \frac{a_n}{\omega_0^2 - n^2 \Omega^2} \cos n\Omega t \quad \underline{\omega_0 \approx \pm n\Omega - \text{resonance}}$$

### Hamiltonian formalism

$$H = \underbrace{\frac{1}{2} (p_x^2 + p_z^2)}_{H_0} + \underbrace{\frac{1}{2} (K_x x^2 + K_z z^2)}_{\in H_1} + \underbrace{\frac{1}{6} m (x^3 - 3xz^2)}$$

Unperturbed motion (azimuthally symmetric lattice)

$$q = \sqrt{2\beta} \cos(\vartheta\theta)$$

$$p = -\sqrt{\frac{2\beta}{\rho}} \sin(\vartheta\theta)$$

$$J = \frac{1}{2\pi} \int p dq = \frac{1}{2\pi} 2J_0 \int_0^{2\pi} d(\vartheta \frac{s}{R}) \sin^2(\vartheta \frac{s}{R}) = J$$

$$\rightarrow H_0 = \frac{J}{\rho(s)}$$

In general one need to use generating function

$$F_1 = -\frac{\alpha + t\varphi}{2\beta} x^2$$

$$\begin{cases} x' = \frac{\partial F_1}{\partial x} \\ y = \frac{\partial F_1}{\partial \varphi} \end{cases} \quad \bar{H} = H + \frac{\partial F_1}{\partial s}$$

Consider

$$\int \frac{ds}{\beta} - \vartheta \frac{s}{c} = \int \frac{ds}{\beta} - \vartheta \theta \quad \rightarrow \quad \text{one can use } \varphi = \varphi - \int \frac{ds}{\beta} + \vartheta \theta$$

$$F_2 = \bar{J} (\varphi - \int \frac{ds}{\beta} + \vartheta \theta)$$

$$J = \partial F_2 / \partial \varphi \quad \varphi = \partial F_2 / \partial \bar{J}$$

$$H_0 = \frac{\partial}{\partial R} \bar{J}$$

## Canonical Perturbation theory

### 10

$$H(y, \varphi) = H_0(y) + \epsilon H_1(y, \varphi, \Theta)$$

Unperturbed motion  $y_0 = \text{const}$ ,  $\varphi = \omega\Theta + \alpha$ ,  $\omega = \partial H_0 / \partial y$

We will look for  $(y, \varphi) \rightarrow (\bar{y}, \bar{\varphi})$ :

$$\bar{H}(\bar{y}, \bar{\varphi}) = \bar{H}_0(\bar{y}) + \epsilon \bar{H}_1(\bar{y}) + \epsilon^2 \bar{H}_2(\bar{y}, \bar{\varphi}, \Theta)$$

with help of  $F_2(\varphi, \bar{y}, \Theta)$ :

$$\begin{cases} y = \partial F_2 / \partial \varphi \\ \bar{\varphi} = \partial F_2 / \partial \bar{y} \quad \text{where } F_2 = \underbrace{F_{20}}_{\text{trivial}} + \epsilon F_{21} + \epsilon^2 F_{22} + \dots \\ \bar{H} = H + \partial F_2 / \partial \Theta \end{cases} \quad F_{20} = \varphi \bar{y}$$

$$y(\bar{y}, \bar{\varphi}) = \bar{y} + \epsilon \frac{\partial F_{21}}{\partial \varphi} + \epsilon^2 \frac{\partial F_{22}}{\partial \varphi} + \dots = \bar{y} + \Delta y$$

$$\varphi(\bar{y}, \bar{\varphi}) = \bar{\varphi} - \epsilon \frac{\partial F_{21}}{\partial \bar{y}} - \epsilon^2 \frac{\partial F_{22}}{\partial \bar{y}} - \dots = \bar{\varphi} + \Delta \varphi$$

Thus keeping only first term of smallness:

- $H_0(y) = H_0(\bar{y} + \Delta y) = H_0(\bar{y}) + \Delta y \frac{\partial H_0}{\partial \bar{y}} + \dots$

where the use of  $\omega_0 = \partial H_0 / \partial y$  gives

$$H_0(\bar{y}, \bar{\varphi}) = H_0(\bar{y}) + \epsilon \omega_0 \frac{\partial F_{21}}{\partial \varphi} + \dots$$

- $\epsilon H_1(y, \varphi, \Theta) = \epsilon H_1(\bar{y}, \bar{\varphi}, \Theta) + \dots$

$$\bar{H}(\bar{y}, \bar{\varphi}, \Theta) = H_0(\bar{y}) + \underbrace{\epsilon \left[ H_1(\bar{y}, \bar{\varphi}, \Theta) + \left( \omega_0 \frac{\partial}{\partial \varphi} + \frac{\partial}{\partial \Theta} \right) F_{21} \right]}_{\bar{H}_1} + \dots$$

Then we can treat  $\bar{H}_1$  as  $\bar{H}_1 = \underbrace{\langle \bar{H}_1 \rangle}_{\text{time independent term}} + \{ \bar{H}_1 \}$

$$\langle \bar{H}_1 \rangle = \frac{1}{(2\pi)^2} \oint \bar{H}_1(\bar{y}, \bar{\varphi}, \Theta) d\bar{\varphi} d\Theta$$

(\*)

$$\Rightarrow \omega_0 \frac{\partial F_{21}}{\partial \varphi} + \frac{\partial F_{21}}{\partial \Theta} = - \{ \bar{H}_1(\bar{y}, \bar{\varphi}, \Theta) \} \text{ gives}$$

$$\bar{H}_1(\bar{y}) = H_0(\bar{y}) + \epsilon \langle H_1(\bar{y}, \bar{\varphi}, \Theta) \rangle$$

$$\text{and } \omega_1(\bar{\gamma}) = \frac{\partial}{\partial \bar{\gamma}} \langle H_1 \rangle.$$

New phase space trajectories are given by

$$y(\bar{\gamma}, \varphi) \approx \bar{\gamma} + \epsilon \frac{\partial F_{21}}{\partial \varphi}$$

Periodicity gives

$$F_{21} = \sum_{m=-\infty}^{\infty} f_m(\bar{\gamma}, \bar{\theta}) e^{im\bar{\varphi}} \quad \text{and} \quad \{H_i\} = \sum_{m=-\infty}^{\infty} h_m(\bar{\gamma}, \theta) e^{im\bar{\varphi}}$$

Substitution of these eqns. into (\*) gives amplitudes of harmonics:

$$[im\omega_0 + \partial/\partial\theta] f_m = -h_m \rightsquigarrow f_m = \frac{i}{2\sin(\pi m\omega_0)} \int_{\theta}^{\theta+2\pi} h_m(\bar{\gamma}, \theta') e^{im\omega_0(\theta' - \theta - \pi)} d\theta'$$

One can choose another way:

$$F_{21} = \sum_{m,n=-\infty}^{\infty} f_{m,n}(\bar{\gamma}) e^{i(m\bar{\varphi} - n\bar{\theta})} \quad \{H_i\} = \sum_{m,n=-\infty}^{\infty} h_{m,n}(\bar{\gamma}) e^{i(m\bar{\varphi} - n\theta)}$$

$$\Rightarrow F_{21} = i \sum_{m,n} \frac{h_{m,n}(\bar{\gamma})}{m\omega_0 - n} e^{i(m\bar{\varphi} - n\theta)}$$

Example:

$$H = H_0 + \epsilon H_1 = \left( \frac{1}{2} p_x^2 + \frac{1}{2} K_x(s) x^2 \right) + \frac{1}{2} \Delta K_x(s) x^2 \quad (\epsilon = \Delta K_x(s))$$

$$H = \frac{y_x}{\beta_x(s)} + \frac{1}{2} y_x \Delta K_x(s) \beta_x(s) [1 + \cos 2\varphi_x]$$

new Hamiltonian can be obtained using averaging:

$$\bar{H} = \frac{\bar{y}_x}{\beta_x(s)} + \frac{1}{2} \bar{y}_x \Delta K_x(s) \beta_x(s)$$

$$\bar{\varphi}(s) = \int \frac{\partial H}{\partial \bar{\gamma}} ds = \int_0^s \frac{ds}{\beta_x(s)} + \frac{1}{2} \int_0^s \Delta K_x(s) \beta_x(s) ds$$

$$\Rightarrow \Delta \bar{\varphi}_x = \frac{1}{4\pi} \int \Delta K_x(s) \beta_x(s) ds$$

Only one Harmonic term  $\epsilon H_1 = h_2 \cos 2\varphi = \frac{1}{2} \bar{y}_x \Delta K_x(s) \beta_x(s) \cos 2\varphi$

$$F_{21}(s) = -\frac{\bar{y}_x}{4\sin(2\pi \bar{\varphi}_x)} \int_s^{s+C} \Delta K_x(s') \beta_x(s') \sin 2[\bar{\varphi}_x - \psi_x(s') - \pi \bar{\varphi}_x] ds'$$

$$y_x(\varphi_x, s) = \bar{y}_x + \frac{\partial F_{21}(\bar{y}_x, \varphi_x, s)}{\partial \varphi_x} \quad \text{with} \quad \bar{\varphi}_x \approx \varphi_x$$

Substitution of  $F_{21}$  gives

$$y_x(s) = \bar{y}_x \left\{ 1 - \frac{1}{2 \sin(2\beta D_x)} \int \dots \right\}$$

$$\frac{\Delta \bar{y}_x(s)}{\bar{y}_x} = - \frac{1}{2 \sin(2\beta D_x)} \int \dots = - \frac{\Delta \beta_x}{\beta_x}$$

### Resonance perturbation theory

$$F_{21} = i \sum_{m,n} \frac{h_{mn}(\bar{s})}{m\omega_0 - n} e^{i(m\varphi - n\theta)}$$

for 2 dimensions denominator becomes  $m_x D_x + m_z D_z - n$

$$H = H_0 + \epsilon \bar{H}_1 + \epsilon \{ \bar{H}_1 \}$$

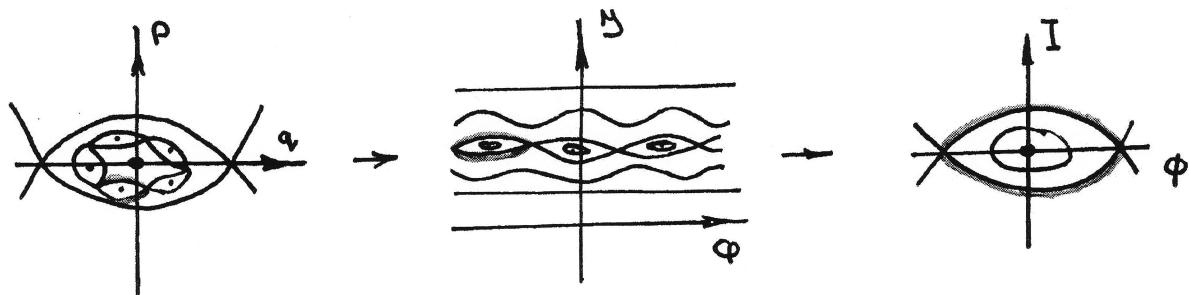
for  $D \approx n/m$   $A_{mn} \cos(m\varphi - n\theta) \approx \text{const}$

$$\Rightarrow H \approx D \bar{y} + \underbrace{\alpha(\bar{y})}_{\bar{H}_1(\bar{y})} + \underbrace{f(\bar{y})}_{A_{mn}(\bar{y})} \cos(m\varphi - n\theta)$$

Then using  $(\bar{y}, \varphi) \rightarrow (I, \phi)$ :  $F_2(I, \varphi) = (\varphi - \frac{n}{m}\theta) \cdot I$

$$\begin{cases} \bar{y} = \partial F_2 / \partial \varphi = I \\ \theta = \partial F_2 / \partial I = \varphi - \frac{n}{m}\theta \end{cases} \quad \Rightarrow \quad \bar{H} = H + \frac{\partial F_2}{\partial \theta} = H - \frac{D}{m}I = \sigma I + \alpha(I) + f(I) \cos m\phi$$

where  $\sigma = D - n/m$



### 1D Sextupole resonance

$$H_1 = \frac{1}{6} m(s) x^3 \Rightarrow \text{using } x = \sqrt{2\beta} \cos \varphi \text{ and } \cos^3 \varphi = \frac{1}{4} (\cos 3\varphi + 3 \cos \varphi)$$

$$H_1 = \frac{1}{6\sqrt{2}} \gamma^{3/2} \beta^{3/2} (s) m(s) (\cos 3\varphi + 3 \cos \varphi)$$

- Resonances:  $\delta = n/3$  &  $\delta = n$
- Averaging of  $\langle H_1 \rangle_\varphi = 0$  gives  $\Delta \delta = 0$

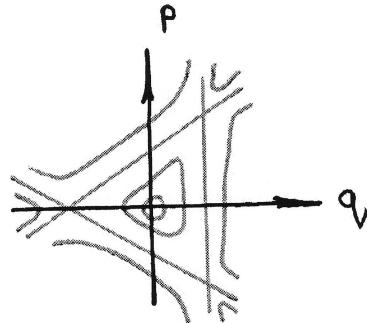
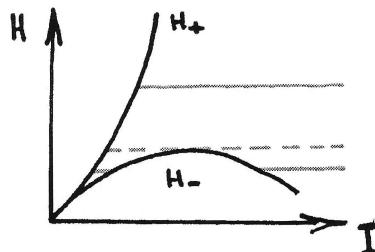
#### Resonance $3\delta = n$

Let us expand  $H_1$  with respect to  $\Theta = S/R$  and keeping only resonance term  $A_n = 2^{3/2} A_{3n}$

$$H \approx \delta I + \gamma^{3/2} A_n \cos(3\varphi - n\Theta)$$

$$H = \delta I + I^{3/2} A_n \cos 3\varphi$$

where  $\delta = \delta - n/3$  and  $\delta/A_n > 0$



Separatrix of motion gives 3 unstable equilibrium points:

$$\frac{\partial H}{\partial \varphi} = 3 \sin 3\varphi = 0 \quad \frac{\partial H}{\partial I} = \delta + \frac{3}{2} A_n \cdot I^{1/2} \cos 3\varphi = 0$$

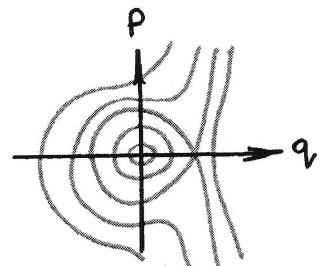
$$I^{1/2} = -2\delta / 3A_n \cos 3\varphi \Rightarrow \{\pi/3, \pi, 5\pi/3\}$$

$$I^{1/2} = 2\delta/3A_n \sim \text{dynamical aperture}$$

$$A_x = \sqrt{2\beta I} = 2\delta \sqrt{2\beta} / 3A_n$$

#### Resonance $\delta = n$

Only one hyperbolic point  $\varphi = 0$  ( $\varphi = \pi$ )



#### 4. Nonlinear Resonance Problem

Using the resonance perturbation theory discussed in the class, describe the behavior around the resonance  $3\nu = n$  for the lattice with sextupole and cubic nonlinearity:

$$H = \delta I + \alpha_0 I^2 + A_n I^{3/2} \cos 3\phi.$$

Consider cases  $\alpha_0 > 0$  and  $\alpha_0 < 0$ . What you can say about the behavior when detuning from resonance  $\delta = 0$ .  
(For simplicity assume that  $\delta > 0$  and  $A_n > 0$ ).