

RESEARCH INTERESTS

Machine Learning | Deep Learning | Computer Vision | Natural Language Processing | Robotics

EDUCATION

SUNY Binghamton PhD in Computer Science	Binghamton, New York Aug 2024–present
SUNY Binghamton MS in Computer Science	Binghamton, New York Jan 2023–May 2024
Bangladesh University of Engineering and Technology B.Sc. in Electrical and Electronic Engineering	Dhaka, Bangladesh Apr 2016–Jan 2022

WORK EXPERIENCE

SUNY Binghamton Research Assistant, RT Lab	Binghamton, New York May 2023 –Current
<ul style="list-style-type: none">– Developing an algorithm for efficient test time adaptation– Developed Deep Neural Network Architecture for Detecting Spotted Lanternfly Using Energy Efficient Wide Area Network	
Cobalt Speech and Language, Inc Research Scientist	Remote Mar 2022–Dec 2022
<ul style="list-style-type: none">– Specialized in Natural Language Processing (NLP) and Understanding (NLU), contributing significantly to the company’s ambitious “Call Summarization” project.– Trained large language models including BART, BERT, and LED, gaining extensive experience with transformer models and enhancing expertise in developing advanced NLP solutions.	

RESEARCH EXPERIENCE

Efficient Test Time Adaptation for vision language Supervisor: Dr. Kyoung-Don Kang	May 2024–March 2025
<ul style="list-style-type: none">– In this research, We developed a method to efficiently do test time adaptation for vision language model with competitive accuracy with the state of the art methods.	
System design to detect Spotted Lantern Fly Supervisor: Dr. Kyoung-Don Kang, Dr. Jayson Boubin and Dr. Dali Ismail	Aug 2023–May 2024
<ul style="list-style-type: none">– In this research, we developed a end to end system to detect spotted lantern fly using DNN model and LoRa network	
Security Threat in Source Free Domain Adaptation Supervisor: Dr. Adnan Siraj Rakin	Jan 2023–March 2023
<ul style="list-style-type: none">– We investigated the effect of a source adversary which may inject a hidden malicious behavior (Backdoor/Trojan) during source training and potentially transfer it to the target domain even after benign training by the victim (target do-main owner). We also built a defense method for the attack as well.	
Weight Pruning Supervisor: Dr. Manar Samad	May 2021–Dec 2021
<ul style="list-style-type: none">– We investigated the effect of weight pruning in unsupervised learning setup. We also proposed a weight perturbation method.	

PUBLICATIONS

1. **Rahim Hossain**, M.T Islam Bhuian, K.D Kang, “**TDA-L: Reducing Latency and Memory Consumption of Test-Time Adaptation for Real-Time Intelligent Sensing**,”Sensors 2025, 25, 3574. [[Paper](#)]
2. Sabbir Ahmed, Abdullah Al Arafat, Mamshad Nayeem Rizve, **Rahim Hossain**, Zhishan Guo, Adnan Siraj Rakin,“**SSDA: Secure Source-Free Domain Adaptation**,” International Conference on Computer Vision(ICCV), 2023. [[Paper](#)]
3. M. D. Samad, **R. Hossain** and K. M. Iftekharuddin,“**Dynamic Perturbation of Weights for Improved Data Reconstruction in Unsupervised Learning**,” 2021 International Joint Conference on Neural Networks (IJCNN), 2021, pp. 1-7, doi: 10.1109/IJCNN52387.2021.9533539. [[Paper](#)]
4. **R. Hossain** and M. D. Samad,“**A Hybrid Clustering Pipeline for Mining Baseline Local Patterns in 3D Point Cloud**,” 2021 6th International Conference for Convergence in Technology (I2CT), 2021, pp. 1-6, doi: 10.1109/I2CT51068.2021.9418095.[[Paper](#)]

SIGNIFICANT PROJECTS

- **Third Eye:** In this project, I extended my previous smart stick project. I added LoRa to communicate with a host. The camera module detects the objects and we then send the objects to a receiver node using LoRa .[[details](#)]
- **Reinforcement Learning for autonomous navigation using CARLA:** In this project, we presented a RL-based navigation system for autonomous vehicles using the CARLA simulation platform. The proposed system employs a Q learning RL algorithm method, to learn the optimal actions for navigating a complex urban environment. [[details](#)]
- **Source Hypothesis Transfer for Unsupervised Domain Adaptation:** In this project, we investigated the benchmark results achieved in SHOT(Source hypothesis transfer for unsupervised domain adaptation) paper. Furthermore, we evaluated the effectiveness of SHOT in closed-set domain adaptation for various benchmark datasets to demonstrate its effectiveness. [[details](#)]
- **Smart Stick for blind people Using Raspberry pi:** It uses two ultrasonic sensors HC SR 04 to detect the depth below or the obstacles in between. Along with that it uses Arduino and Raspberry pi as the main controller. Whenever there is any obstacle in the path. The sensor detects the distance from the obstacle and send to the controller. We used a camera module which is controlled by raspberry pi. The camera detects the yellow line to tell the blind person whether he is on the track or not. [[details](#)]

SKILLS

- **Programming Languages:** Python, MATLAB, C, C++, Golang, Intel-8086 Assembly
- **Simulation & Design Tools:** ROS, PSpice, Simulink, AutoCAD, Verilog
- **Machine Learning Libraries:** PyTorch, Tensorflow, Keras, Scikit-Learn

RELEVANT GRADUATE COURSE-WORKS

Machine Learning | Deep Learning | Intelligent Mobile Robotics | Computer Vision | Social Media Data Sci Pipeline| Design and Analysis of Algorithm | Computer Architecture | Computer Network | OS | HPC | Advanced AI security

AWARDS AND HONORS

- **Ebay ML Challenge 3rd Position (2023)**
- **Industrial Automation Challenge (Robotic Competition) Bangladesh University of Engineering and Technology**, Won *2nd* position among many teams from the whole country.
- **Technical Scholarship, Bangladesh University of Engineering and Technology (2016 and 2018)**
- **Bangladesh Education Board Scholarship in Higher Secondary Certificate (HSC) Examination (2015)**