

1 Title: **Biodiversity conservation in an uncertain world**

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25 **First paragraph**

26 Despite being key instruments in conservation efforts, protected areas are vulnerable to risks associated
27 with (i) weak enforcement and governance¹, (ii) pressure from land-use intensification², and (iii)
28 climate change³, any of which can reduce their effectiveness. Although failing to consider such risk
29 factors in planning diminishes the ability of protected areas to uphold international biodiversity goals⁴,
30 accounting for them can require additional expenditure. Here we show that plans for expanding the
31 global protected area system that explicitly account for such risks require remarkably small (1%)
32 increases in the amount of land protected relative to ignoring risk. Using a multi-objective spatial
33 optimization routine, we developed plans to expand the existing protected area estate – ensuring
34 adequate coverage of all known terrestrial vertebrate species – that accounted for these three categories
35 of risk. Among the three risk categories, governance drove the greatest variation in the location of land
36 prioritized for protection. In particular, conserving wide-ranging species required countries with
37 relatively strong governance to protect more land when bordering nations with comparatively weak
38 governance. Our results both underscore the need for cross-jurisdictional coordination and demonstrate
39 how risk can be efficiently incorporated into global planning efforts.

40

41 **Main text**

42 Protecting habitat is one of the best strategies for stemming the alarming decline of biodiversity⁵. As
43 such, the cornerstone of the new global framework for biodiversity conservation is to protect at least
44 30% of terrestrial land area by 2030⁴. Most current approaches for identifying important areas to
45 protect rely upon estimations of the conservation value of the land for biodiversity and the threats it
46 faces^{4,6,7}. Seldom articulated in such plans is the tacit assumption that protection is enforced, effective,
47 and permanent, yet it is well known many protected areas are subject to risks from weak governance,
48 land use intensification, and climate change. For example: the quality of governance relates to

investment in conservation^{8,9}; political instability and corruption can reduce protected area effectiveness^{10,11}; protected areas with high deforestation rates are at greater risk of degazettement and failure to meet protection goals¹²; and increased extreme weather events cause declines and extirpations in native populations¹³. Thus, to make effective use of limited conservation resources, planning for investment in protected areas must account for these risks^{14,15}. Here we demonstrate how accounting for governance, land-use, and climate risks can influence decisions for establishing protected areas at a global scale and may ultimately improve the resilience of protected areas and the species they support. The risks we consider here represent unstoppable risks that are best avoided, which stand in contrast to stoppable risks that can be abated through effective protected areas management alone^{16,17}.

We defined the following three broad categories of risk, which we considered to be factors likely to diminish the long-term effectiveness of protected areas: (i) governance, (ii) land-use, and (iii) climate. For governance risk, we used a national-scale metric that combines six governance indicators from the World Bank¹⁸: accountability, political stability, government effectiveness, regulatory quality, rule of law, and control of corruption (Figure S1). For land-use risk, we estimated the average change in biodiversity per land-use category using methods¹⁹ that model the risk of biodiversity loss for land systems due to agricultural expansion and intensification (Figure S2). For climate risk, we used the duration of extreme heat events, calculated using a probabilistic framework that estimates the novelty of temperatures relative to historical year-to-year variation from 1979 to 2019 (Figure S3), identifying areas where heat events are likely to have the most significant effects on biodiversity²⁰. Although we used these three risk categories for illustrative purposes, the approach we propose is flexible and can easily incorporate other risk metrics too²¹.

We considered the influence of risk categories on allocating protection decisions at a global scale for all 30,930 known distributions of vertebrate species from the IUCN Red List of Threatened Species²² using a multi-objective optimization approach. To incorporate risk categories, we built on a

classical problem formulation from the systematic conservation planning literature – the minimum set problem - where the objective is to reach species distribution protection targets, while accounting for one constraint such as land cost or area^{23–25}. We expand this approach to include multiple objectives accounting for varying risk in the problem formulation, by treating each risk layer as a separate objective in the problem formulation²⁶. We use a hierarchical approach that assigns a priority to each objective, and optimizes for the objectives in decreasing priority order. At each step, the approach finds the best solution for the current objective, but only from among those that would not degrade the solution quality for higher-priority objectives.

In total 16 planning scenarios were created, such that solutions accounted for all possible combinations of risk categories within each hierarchical level (Table S1). We then compared these risk-based solutions to those produced with a null scenario that adopted the traditional area-minimizing approach to optimization without considering risk²⁷. Because our scenarios aimed to build upon the current protected area portfolio globally, we incorporated current protected areas into our solutions. For each scenario we protected 30% of the range of all vertebrate species, which is broadly analogous to the more general 30% total area Convention on Biological Diversity (CBD) target²⁷. Surprisingly, scenarios that incorporated all the three risk categories required only 0.9% more global area on average (0.34 – 1.14 %) than the null scenario to meet the target of protecting 30% of vertebrate ranges. Thus, accounting for risks cost relatively little compared to the potential gains from selecting a more resilient conservation network (Figure 1). Notably, the target of protecting 30% of each vertebrate species range was achieved by all 16 scenarios without exceeding the post-2020 CBD target of protecting 30% of global land area²⁷. When only looking at scenarios that included one risk factor, land-use risk forces the greatest increase in global protected area, compared to scenarios only including governance and/or climate extreme risks (Table S1).

We found that protected areas identified across scenarios overlapped spatially, with the same 22 million km² (6.9% of global land area) being prioritized for expansion of the current protected area

99 system in at least eleven scenarios and 3.6 million km² (2.4% of global land area) in all fifteen risk
100 scenarios (Figure 2). These “no regrets” areas provide examples of places that should be immediate
101 priorities for international agencies aiming to maximize the resilience of protected area networks, as
102 they are robust to assumptions of the relative importance of risk factors. Example countries that have
103 contiguous areas of high overlap among different scenarios are Canada, Egypt, Finland, Kazakhstan
104 and Peru (Figure S4). There is some overlap among the priorities across scenarios within Conservation
105 International’s global biodiversity hotspots²⁸, but many high overlap areas lie either outside these
106 hotspots (83.1%) or occur within small portions of the biodiversity hotspots, likely because these areas
107 are important to protect regardless of future risk (Figure S5).

108 We also found variation in the locations of priorities for protection when risks were introduced
109 (Figure 3; Table S2). These differences were driven largely by governance (Figure S6). Countries with
110 relatively high governance scores had greater area requiring protection under risk scenarios relative to
111 the null scenario, especially when species were wider ranging and when neighbouring countries had
112 low governance scores. Thus, risk is connected across jurisdictions, where planning scenarios favour
113 protection of species in nearby countries with low governance risk (i.e., high governance scores). For
114 example, many vertebrate species ranges span northeastern Russia, Finland, and Sweden, with one of
115 the most iconic being caribou (*Rangifer tarandus*), which has an IUCN conservation status of
116 vulnerable. Because Russia suffers from low scores for ‘voice and accountability, rule of law, and
117 control of corruption’ (Table S3), whereas Finland and Sweden have relatively high governance scores,
118 the scenarios including governance pressures led to a selection of 99.4% and 48.9% of Finland and
119 Sweden’s land areas respectively compared to the null scenario with 30.8% and 15.2% (Figure 4).
120 These results do not mean the majority of land inside Finland needs to be protected to ensure the long-
121 term persistence of caribou, but indicate that prioritizing areas in Sweden and Finland is predicted to be
122 far less of a risk than areas in Russia.

123 Land-use and climate change also influenced variation in the locations of priorities for
124 protection compared to the null scenario. For example, large areas of Sierra Leone are experiencing
125 high risk of biodiversity loss due to expanding intensive land-use practices (Fig. S2), whereas this same
126 risk is lower in neighbouring Liberia. Scenarios including land-use risk selected 50.1% of the land area
127 in Liberia compared to 21.9% in the null scenario (Figure 4). Large areas of Algeria are experiencing
128 increasingly frequent extreme heat events (Fig. S3), whereas neighbouring Libya is not experiencing as
129 many extreme heat events. Scenarios including climate impact risk selected 30.8% of Libya's land
130 area compared to the null scenario with 20.9% (Figure 4).

131 These results emphasize the importance of coordinated cross-jurisdictional conservation
132 planning initiatives²⁹ and identify countries where opportunities for collaboration would yield more
133 resilient protected area systems. To illustrate this point, we consider the Great Green Macaw (*Ara*
134 *ambiguus*), with <2500 individuals remaining³⁰ and a range that stretches from southern Honduras to
135 western Colombia. Because Great Green Macaw habitat spans several countries differing in
136 governance, land use, and climate risk, coordinated efforts among countries will be necessary for the
137 species to persist in the future. For countries with a predominance of wide-ranging species whose
138 ranges will be impacted by varying climate, land-use, and governance risk across borders, conservation
139 projects can focus on cooperative governance frameworks³¹ (Figure 3). These governance frameworks,
140 both within and between countries, would need to be developed in an environmentally just and
141 equitable way to deliver benefits to biodiversity and local communities³².

142 In contrast, there is little difference in protection priorities in some countries at high risk from
143 climate change, land-use, and low governance scores, but with high endemism. Given high endemic
144 biodiversity, and homogeneity of risk, these countries all require high rates of protection within their
145 borders. Moreover, some countries closer to reaching the CBD's 30% land area protection target, for
146 example Brazil, which already has 30.3% of its land area protected, had lower differences between
147 scenarios that incorporate risk and the null scenario that does not incorporate risk, despite having high

148 climate, land-use, and governance risk. This outlines the importance of further considering the
149 effectiveness of existing protected areas in planning analyses, where pressure from cropland conversion
150 in tropical protected areas has increased to similar rates outside protected areas³³.
151 Previous work has incorporated individual risk factors analogous to those we used, including
152 governance^{1,34}, climate change³ and land-use change^{2,35}. Yet, our results show that protected area
153 expansion decisions can be profoundly influenced by all three risk factors combined. If data on risk
154 alters the effectiveness of biodiversity protection, our results show that they should be used together to
155 support decisions for resilient protected area networks. As an example, climate metrics such as
156 disappearing climates³⁶ might be relevant if the consideration is on small-ranged and threatened
157 species. Our flexible framework and methods can allow conservation agencies looking to set priorities
158 from the global to local scale and incorporate different metrics to explore the influence of individual
159 parameters and metrics on decisions.

160

161 **Conclusion**

162 The conservation community has traditionally neglected to estimate how future changes in climate³⁷,
163 land-use³⁵, and socio-economic conditions might compromise the effectiveness of protected areas. Our
164 results show that the spatial distribution of protected areas, rather than the land area *per se*, can be
165 profoundly influenced by risk, particularly from governance. Surprisingly, incorporating risk into
166 decision-making adds <1% to the total global area required to meet biodiversity targets. Accounting
167 for risk comes at limited extra cost, but potentially large benefits to achieving global biodiversity
168 targets. Our results also emphasize the importance of cross-jurisdictional conservation initiatives,
169 especially in adjacent countries sharing wide-ranging species where risk varies considerably from
170 country to country. Considering risk in conservation decision-making will result in more resilient and

171 effective conservation plans into the future to help safeguard our planet's biodiversity in the face of the
172 current extinction and climate crises.

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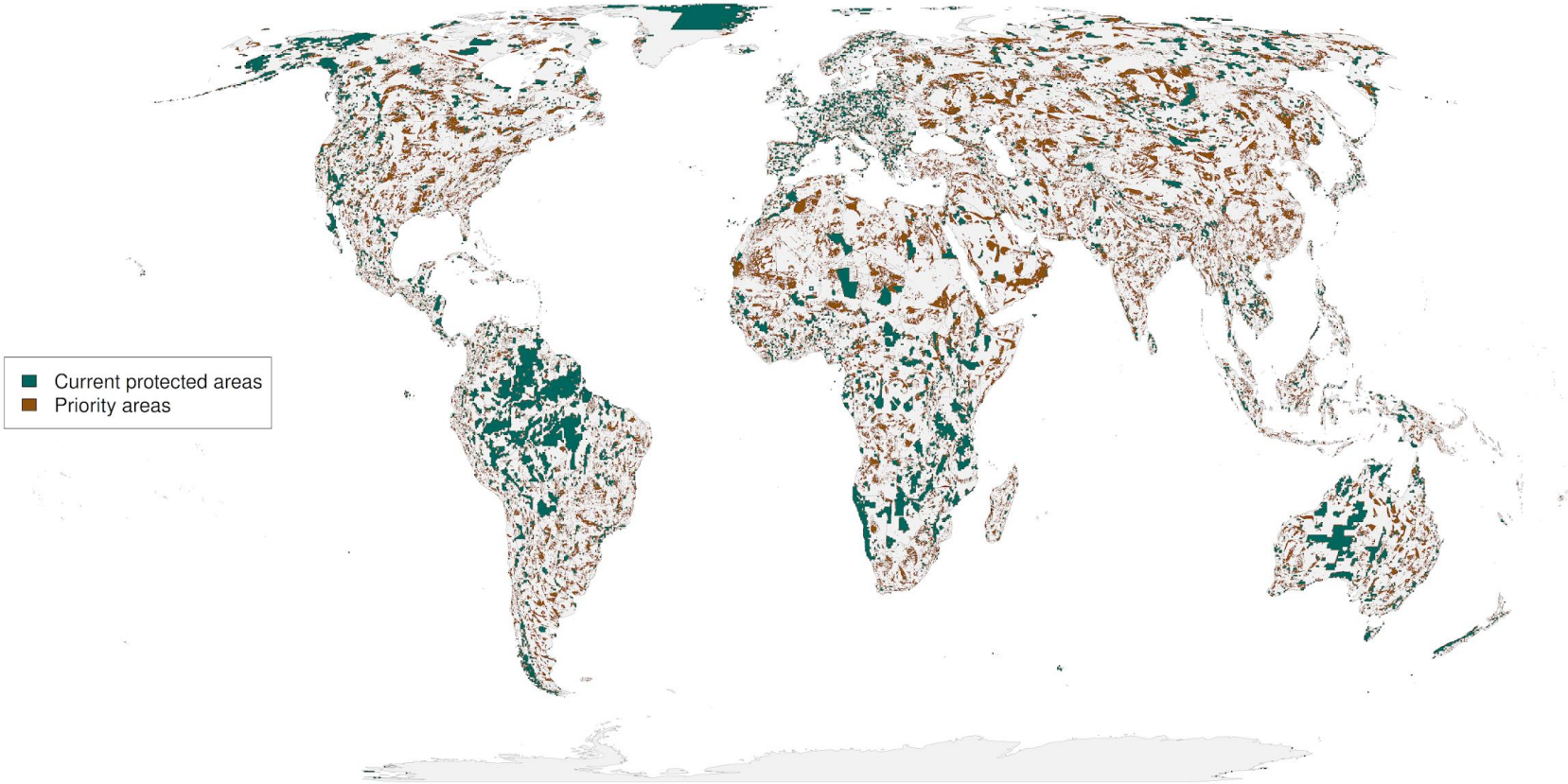
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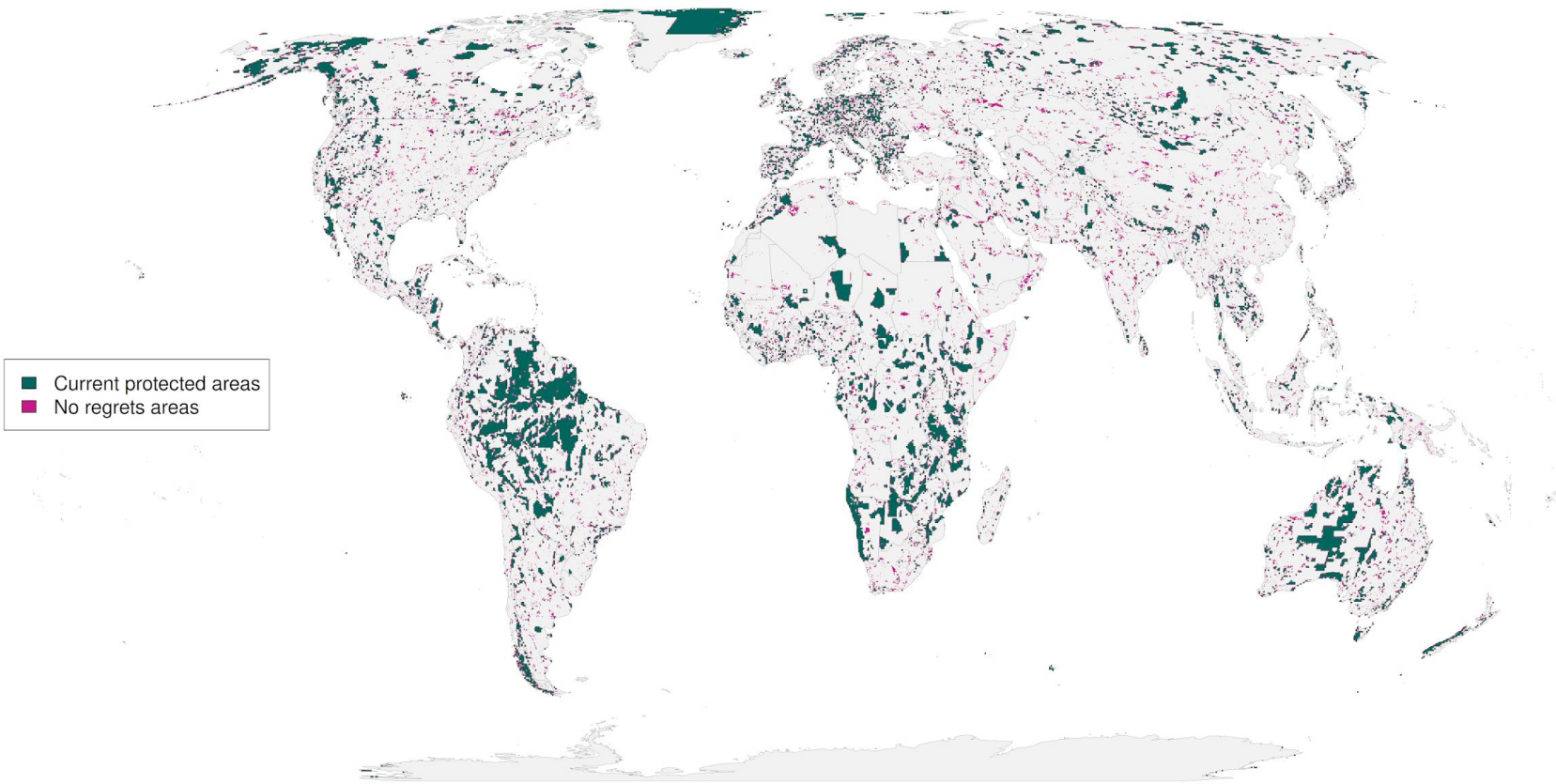
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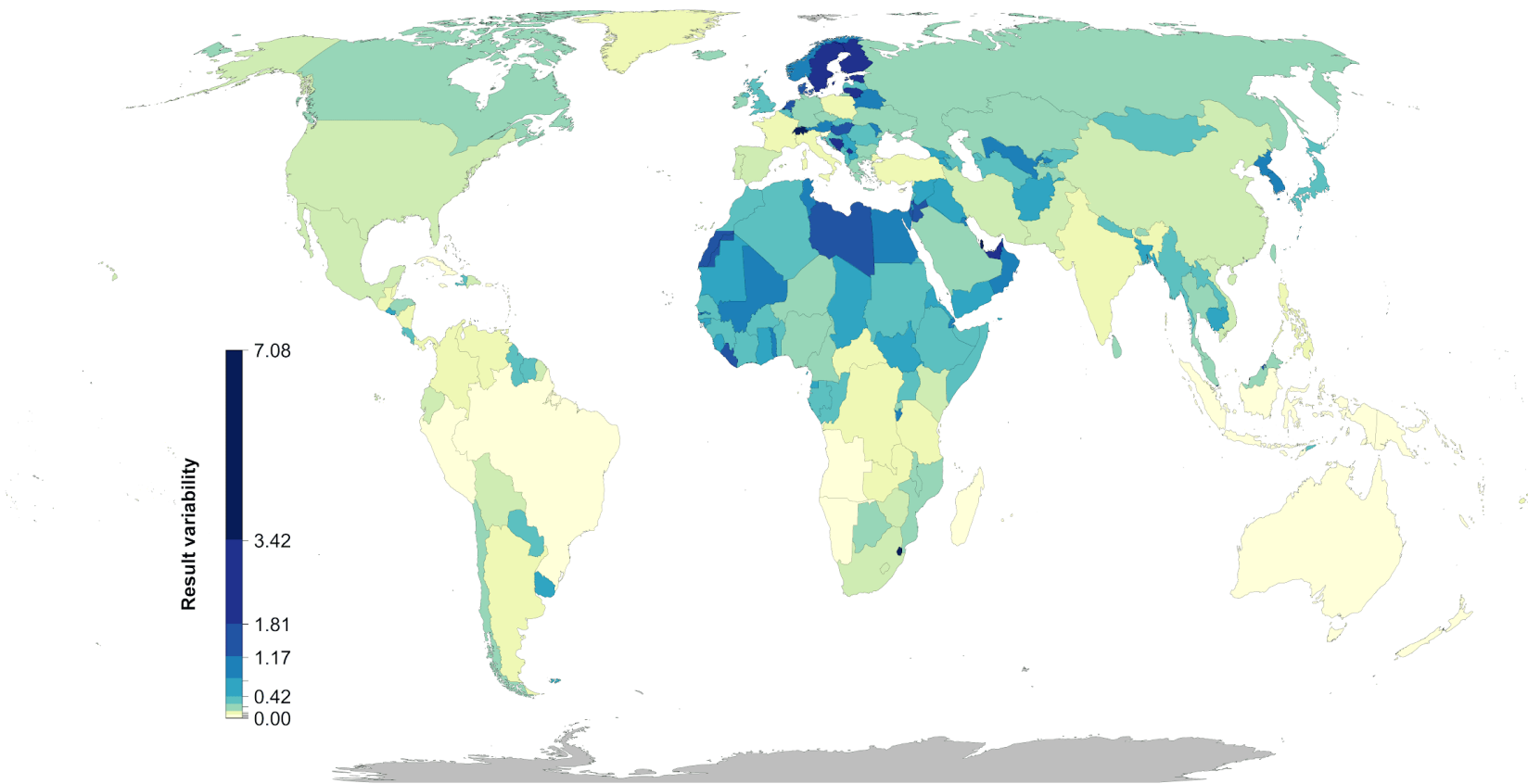
320 Figure 1: Spatial representation of priority areas for protection to account for governance, land use and climate risk. Accounting for these
321 risks to protected area effectiveness to produce more resilient conservation networks would require 29.17% of land surface to protect 30% of
322 threatened species' ranges.



324 Figure 2: “No regrets” areas comprising 3.57 million km² of land that was identified as priority habitat for protection regardless of the risks
325 included in our analysis.

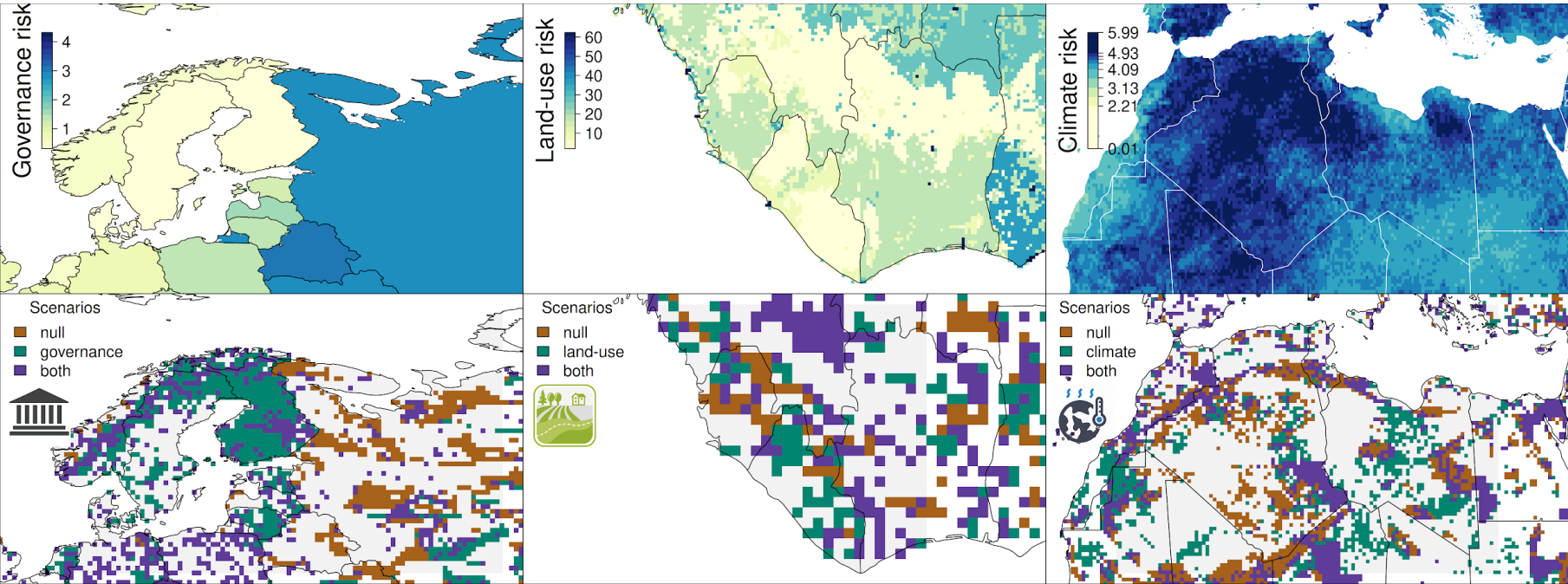


327 Figure 3: Percent country-level variation between the null scenario and the 15 scenarios including risk. Countries whose results are
328 consistent across the 15 scenarios (e.g. Brazil) have low variation, while countries whose results are less consistent across the 15 scenarios
329 have high variation (e.g. Sweden). The kmeans method³⁸ was used to generate class intervals for visualization.



330
331

332 Figure 4: Contrast of using individual risk objectives (governance, land-use, climate) to the null scenario of uniform objective structure. The
333 top panels represent the individual risk data for the focal regions. In the bottom panels brown shows null, green the specific risk objective
334 scenario results, and purple where both scenarios agree. The figures show how the spatial configuration of the solutions changes when risk is
335 considered in a scenario. Governance focus is on Sweden, Finland and Russia, land-use risk on Sierra Leone and Liberia, and climate risk on
336 Algeria and Liberia.



338 **Methods**

339 We used a multi-objective optimization approach that incorporated governance, land use and climate
340 constraints to prioritize the conservation of 30,930 vertebrate species. All scenarios we investigated
341 assumed the current global protected area portfolio is locked in. We further set a target to protect 30%
342 of the range of each species, which is broadly analogous to current CDB discussions on post-2020
343 biodiversity targets⁴.

344

345 *Species selection*

346 Our species list included all terrestrial vertebrate species from the IUCN Red List of threatened
347 species, following Pouzols et al.². For mammal, amphibian and reptile species ranges, we used the
348 IUCN Red List website (<http://www.iucnredlist.org/>, accessed 2019-11-14) and for birds we used the
349 BirdLife International data zone webpage (<http://www.birdlife.org/datazone/home>, accessed 2019-11-
350 14). We used these taxa because no analogous data are available for a high proportion of species in
351 other taxonomic groups such as insects³⁹. These data have certain limitations, including possible
352 underestimation of the extent of occurrence and overestimation of the true area of occupancy², but they
353 have been shown to be robust to commission errors as long as the focus is on species assemblages
354 rather than single species⁷. They are currently the most frequently used and updated source for
355 vertebrate species distributions⁴⁰.

356 For each taxonomic group, we restricted our analysis to species that fell into the presence
357 category of ‘Extant’, the origin categories of ‘Native’ or ‘Reintroduced’ and the seasonality categories
358 ‘Resident’, ‘Breeding Season’ or ‘Non-breeding Season’, thus only focusing on stationary periods of
359 the life cycle of migratory species. This resulted in the following final numbers of amphibian, bird,
360 mammal and reptile species ranges: 5660, 13375, 5442, and 6153, respectively.

361

362 *Basic administrative delineations*

National boundaries were derived from the Global Administrative Areas database

(<http://gadm.org/>, accessed 2019-10-31). We obtained protected area boundaries from the World Database on Protected Areas (WDPA, <https://www.protectedplanet.net>). Following standard procedures for cleaning the protected area dataset^{41,42}, we (i) projected the data to an equal-area coordinate system (World Behrman), (ii) excluded reserves with unknown or proposed designations, (iii) excluded UNESCO Biosphere Reserves⁴³, (iv) buffered sites represented as point localities to their reported area, (v) dissolved boundaries to prevent issues with overlapping areas, and (vi) removed slivers (code available at <https://github.com/jeffreyhanson/global-protected-areas>). After the protected area data were modified as described above, we overlaid the protected area boundaries with a 10 x 10 km grid covering the Earth. These spatial data procedures were implemented using ArcMap (version 10.3.1) and python (version 2.7.8).

Governance risk

Conservation risk due to governance can affect the outcomes of strategies, and effective governance can promote the resilience of conservation in the face of sociopolitical and economic shocks. We used worldwide governance indicators from the World Bank¹⁸ to capture these pressures. The indicators include six scaled measures: voice and accountability; political stability and absence of violence; government effectiveness; regulatory quality; rule of law; and control of corruption (see Table S4 for definitions). We chose these indicators because evidence suggests that they reliably predict protected area effectiveness⁴⁴ and state investment and efforts for biodiversity conservation⁸. For each country, we used a mean of annual averages of all six measures⁸ (Figure S1).

Land use risk

We used a recently developed global land systems map produced by Kehoe et al.¹⁹ to incorporate the risk of land-use change. This map is based on a global land systems map for the year

2000⁴⁵ at a 9.25 km² spatial resolution, but is refined based on recent land-cover and land-use datasets to a spatial resolution of 1 km². Kehoe et al.¹⁹ further estimated the impact of land use and land use intensity on biodiversity, with data originating from the PREDICTS project⁴⁶. They first matched their land-systems classes to varying intensity levels for each land-use type (for detailed conversion table, see ref⁴⁷). This allowed Kehoe et al.¹⁹ to calculate average biodiversity loss per land system (relative to an unimpacted baseline) by taking the mean model estimates of biodiversity loss per land-use intensity class from previous work⁴⁷. The result gives average relative biodiversity gain or loss per land-system class. Here, we used their modelled mean estimates (following Newbold et al.⁴⁷) of relative percent biodiversity change for each land-system class for species abundance as a measure of the land-use pressure (Figure S2).

398

399 *Climate risk*

Anthropogenic climate change is affecting the frequency and duration of extreme heat events^{48,49}. Exposure to these events can adversely affect human populations^{50–52} and natural systems^{13,53}. For species in natural systems, these events can further the decline and extirpation of populations, increasing the chances of extinction^{13,54}. EHE and ECE can also promote the formation of novel ecosystems⁵³, generate enhanced selection pressures^{55,56}, and change the phenology of life history events^{57,58}. There are a number of climate indices that have been used to estimate the occurrence of these events^{59,60}. These indices are often context specific and there is little consensus on the most appropriate technique⁶¹.

We estimated climatic risk based on the estimated trend in the annual proportion of days containing extreme heat events from 1979 to 2019¹⁷. Extreme heat events were estimated using hourly air temperature at 2 m above the surface and gridded at a 31 km (0.28125° at the equator) spatial resolution (DOI: 10.24381/cds.adbb2d47). The temperature data was acquired from the European Centre for Medium-Range Weather Forecasts (ECMWF) fifth generation atmospheric reanalysis of the

413 global climate (ERA5)^{62,63}. The approach first extracted daily minimum and maximum temperature for
414 each grid cell over the 41-year period. To reduce the influence of warming trends, the daily minimum
415 and maximum temperature was then detrended across years for each day and grid cell using empirical
416 mode decomposition (EMD)^{64,65}. The occurrence of extreme heat events was estimated using the
417 following approach: The detrended minimum and maximum temperature data was treated as normally
418 distributed across years for each day and grid cell. The probability density function for the detrended
419 minimum and maximum temperature was then estimated using the mean and standard deviation
420 calculated across years for each day and grid cell. Extreme heat events occurred when the probabilities
421 for both minimum and maximum temperature on a given day and grid cell were within the 0.95-1.00
422 quartile of the probability density function. The trend in the annual proportion of days containing
423 extreme heat events for each year was calculated for each grid cell using beta regression with a logit
424 link function and an identity function in the precision model^{66,67}. (Figure S3). See La Sorte et al.²⁰ for
425 additional details.

426

427 *Multi-objective optimization of pressure reduction*

428 We processed all data described previously to a 10 x 10 km resolution and clipped data to the
429 extent of land based on the global administrative areas database. We then developed an extension on
430 the minimum set problem, which has the goal to identify a set of sites within a planning area that
431 represents all conservation targets in the fewest number of sites²⁴. Instead of including a single
432 objective in the problem formulation, we expanded it to include multiple objectives. Specifically, we
433 used a hierarchical (lexicographic) approach that assigns a priority to each objective, and sequentially
434 optimizes for the objectives in order of decreasing priority. At each step, it finds the best solution for
435 the current objective, but only from among those that would not degrade the solution quality for higher-
436 priority objectives. We considered up to three objectives in our prioritization scenarios, i) governance
437 risk, ii) land-use risk, and iii) climate risk. To compare different scenarios, we calculated solutions for

438 each unique objective combination ($n = 15$), as well as one where we use a constant objective function
439 as the null scenario, as the order of the hierarchy can influence the results.

440 In systematic conservation planning, conservation features describe the biodiversity units (e.g.,
441 species, communities, habitat types) that are used to inform protected area establishment. Planning
442 units describe the candidate areas for protected area establishment (e.g., cadastral units). Each planning
443 unit contains an amount of each feature (e.g., presence/absence, number of individuals). A
444 prioritization describes a candidate set of planning units selected for protected establishment. Each
445 feature has a representation target indicating the minimum amount of each feature that ideally should
446 be held in the prioritization (e.g., 50 presences, 200 individuals). To minimize risk, we have a set of
447 datasets describing the relative risk associated with selecting each planning unit for protected area
448 establishment. Thus, we wish to identify a prioritization that meets the representation targets for all of
449 the conservation features, with minimal risk.

450 Let I denote the set of conservation features (indexed by i), and J denote the set of planning
451 units (indexed by j). To describe existing conservation efforts, let p_j indicate (i.e., using zeros and ones)
452 if each planning unit $j \in J$ is already part of the global protected area system. To describe the spatial
453 distribution of the features, let A_{ij} denote (i.e., using zeros and ones) if each feature is present or absent
454 from each planning unit. To ensure the features are adequately represented by the solution, let t_i denote
455 the conservation target for each feature $i \in I$. Next, let D denote the set of risk datasets (indexed by d).
456 To describe the relative risk associated with each planning unit, let R_{dj} denote the risk for planning
457 units $j \in J$ according to risk datasets $d \in D$.

458

459 The problem contains the binary decision variables x_j for planning units $j \in J$.

$$x_j = \begin{cases} 1, & \text{if } j \text{ selected for prioritisation,} \\ 0, & \text{else} \end{cases} \quad (\text{eqn 1a})$$

460

461 The reserve selection problem is formulated following:

462

$$\text{lexmin } f_1(x), f_2(x), \dots, f_D(x) \quad (\text{eqn 2a})$$

$$\text{subject to } f_d(x) = \sum_{j \in J} R_{dj} x_j \quad \forall d \in D \quad (\text{eqn 2b})$$

$$\sum_{j \in J} A_{ij} \geq t_i \quad \forall i \in I \quad (\text{eqn 2c})$$

$$x_j \geq p_j \quad \forall j \in J \quad (\text{eqn 2d})$$

$$x_j \in \{0, 1\} \quad \forall j \in J \quad (\text{eqn 2e})$$

463

464 The objective function (eqn 2a) is to hierarchically (lexicographically) minimize multiple
 465 functions. Constraints (eqn 2b) define each of these functions as the total risk encompassed by selected
 466 planning units given each risk dataset. Constraints (eqn 2c) ensure that the representation targets (t_i)
 467 are met for all features. Constraints (eqn 2d) ensure that the existing protected areas are selected in the
 468 solution. Finally, constraints (eqns 2e) ensure that the decision variables x_j contain zeros or ones.

469 For all scenarios we locked in current protected areas and used the same feature set of 30,930
 470 vertebrates. The target for each feature was set to 30% of their range. The optimality gap, which
 471 specifies how far from numerical optimality we would allow the solution to be, was 10% for each
 472 objective in the hierarchy. We chose a 10% optimality gap to allow for some flexibility in the result of
 473 each step in the hierarchy to avoid getting too restricted in the solution space.

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480

481 **Author contributions**

482 R.S., R.B. and J.B. designed the study. R.S., R.B., J.O.H., J.P., and F.A.L.S. obtained the data. R.S.
483 performed the analysis. R.S. and R.B. drafted the manuscript. All authors discussed the results,
484 contributed critically to the drafts, and gave final approval for publication.

485

486 **Competing interest declaration**

487 No competing interests to declare

488

489 **Data availability**

490 All data, scripts and full results are available on Open Science Framework (OSF) and will be assigned a

491 DOI once the manuscript is in print:

492 https://osf.io/e2fuw/?view_only=46eb2e525daf42d29df318a92762d885

493

494 **Table S1.** Scenarios explored and global protection results. The risk factor order represents the order
495 risk factors were included in the hierarchical prioritization. (G = governance, L = land use, C =
496 Climate).

497

Scenario	Risk factors included	Global land area protected [%]
null	-	28.08
1	G	28.44
2	L	29.23
3	C	28.45
4	G > L	29.2
5	L > G	29.23
6	G > C	28.43
7	C > G	28.45
8	L > C	29.19
9	C > L	29.19
10	G > L > C	29.17
11	G > C > L	29.2
12	L > G > C	29.19
13	L > C > G	29.19
14	C > G > L	29.2
15	C > L > G	29.19

498

499

500 **Table S2.** Country specific results for the 15 scenarios investigated. Numbers represent % of land area
 501 of a country selected.
 502 (As an example 5 countries included here, full list in csv. N = null, G = governance, L = land use, C =
 503 Climate)
 504 https://drive.google.com/file/d/1eD4y4K8XG4nxnRL5fNtiTqzuqfIJ_DfB/view?usp=sharing
 505

	Afghanistan	Akrotiri and Dhekelia	Åland	Albania	Algeria
N	22.94	50	0	18.75	32.66
G	15.76	50	91.67	17.71	20.52
L	26.58	50	33.33	21.88	30.02
C	24.82	50	0	22.92	22.53
GL	26.54	50	0	22.22	29.87
LG	26.65	50	25	21.88	29.97
GC	15.93	50	75	17.36	20.66
CG	24.68	50	0	22.92	22.52
LC	26.72	50	16.67	21.18	30.02
CL	26.52	50	0	21.88	30.44
GLC	26.51	50	0	21.18	29.83
GCL	26.52	50	0	21.88	30.49
LGC	26.71	50	25	20.83	29.99
LCG	26.72	50	16.67	21.18	30.02
CGL	26.54	50	0	21.88	30.19
CLG	26.52	50	0	21.88	30.44

506

 507

508 **Table S3. Governance risk score table (see csv)**

509 https://drive.google.com/file/d/1g_LePBfCbphXzTiCOXCzQtNLSSYoV6me/view?usp=sharing

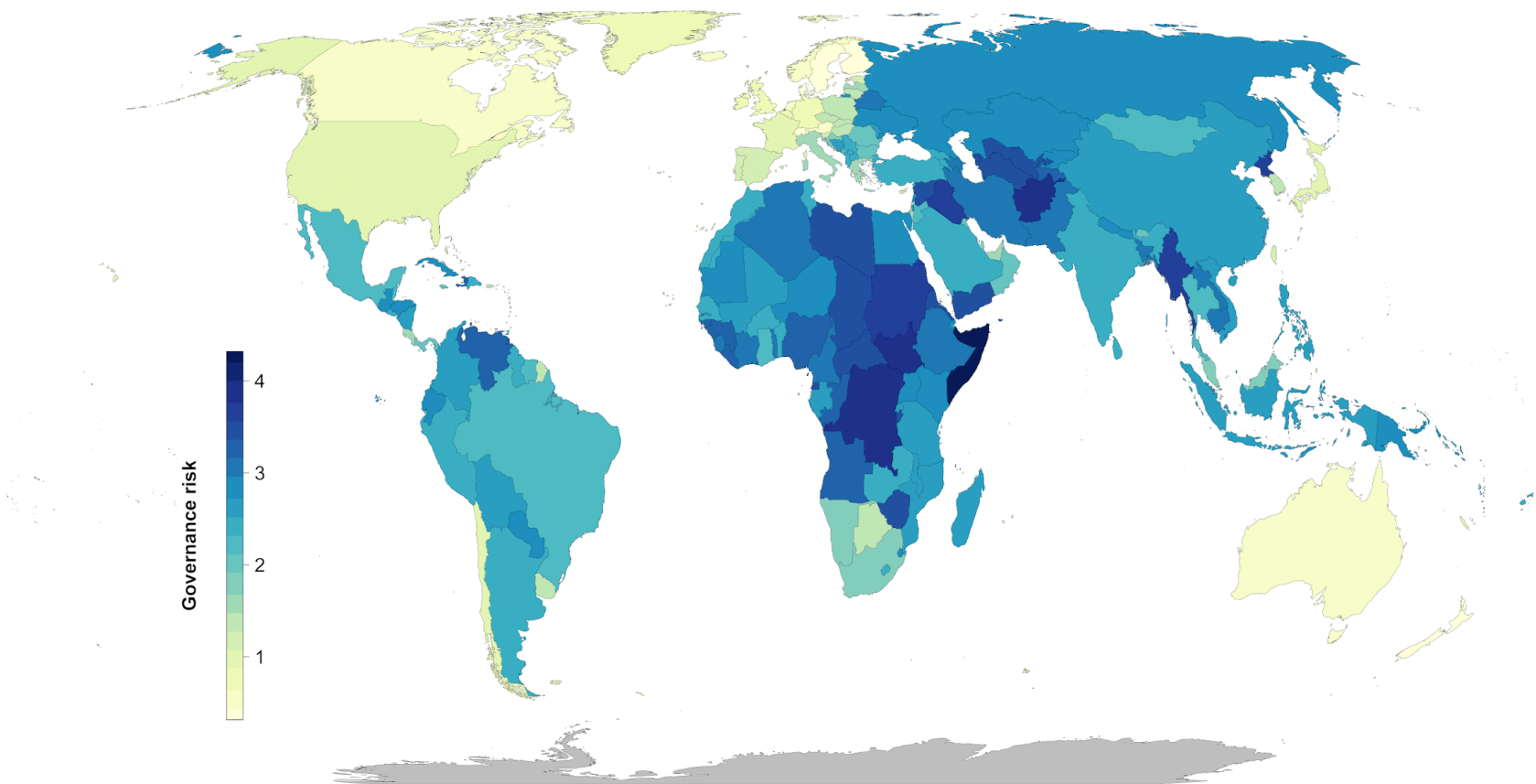
Indicator	Definition
	<p>Source: World Bank, 2020</p> <p>(https://datacatalog.worldbank.org/dataset/worldwide-governance-indicators)</p>
Voice and accountability	<p>“Voice and accountability captures perceptions of the extent to which a country's citizens are able to participate in selecting their government, as well as freedom of expression, freedom of association, and a free media.”</p>
Political stability and absence of violence	<p>“Political Stability and Absence of Violence/Terrorism measures perceptions of the likelihood of political instability and/or politically-motivated violence, including terrorism.”</p>
Government effectiveness	<p>“Government effectiveness captures perceptions of the quality of public services, the quality of the civil service and the degree of its independence from political pressures, the quality of policy formulation and implementation, and the credibility of the government's commitment to such policies.”</p>
Regulatory quality	<p>“Regulatory quality captures perceptions of the ability of the government to formulate and implement sound policies and regulations that permit and promote private sector development.”</p>
Rule of law	<p>“Rule of law captures perceptions of the extent to which agents have confidence in and abide by the rules of society, and in particular the</p>

quality of contract enforcement, property rights, the police, and the courts, as well as the likelihood of crime and violence.”

Control of
corruption

“Control of corruption captures perceptions of the extent to which public power is exercised for private gain, including both petty and grand forms of corruption, as well as "capture" of the state by elites and private interests.”

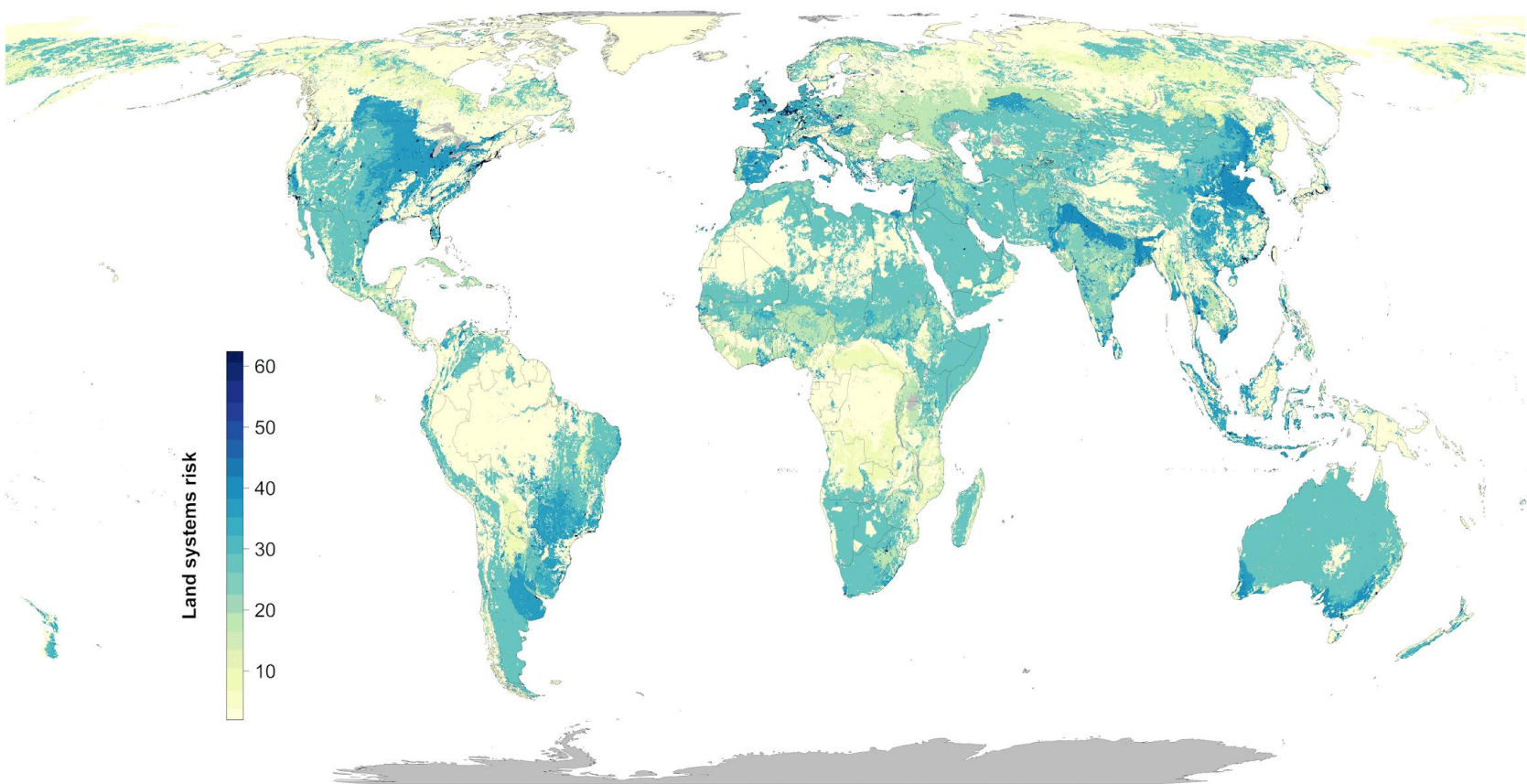
512 **Figure S1. Governance risk (yellow = low, blue= high)**



513

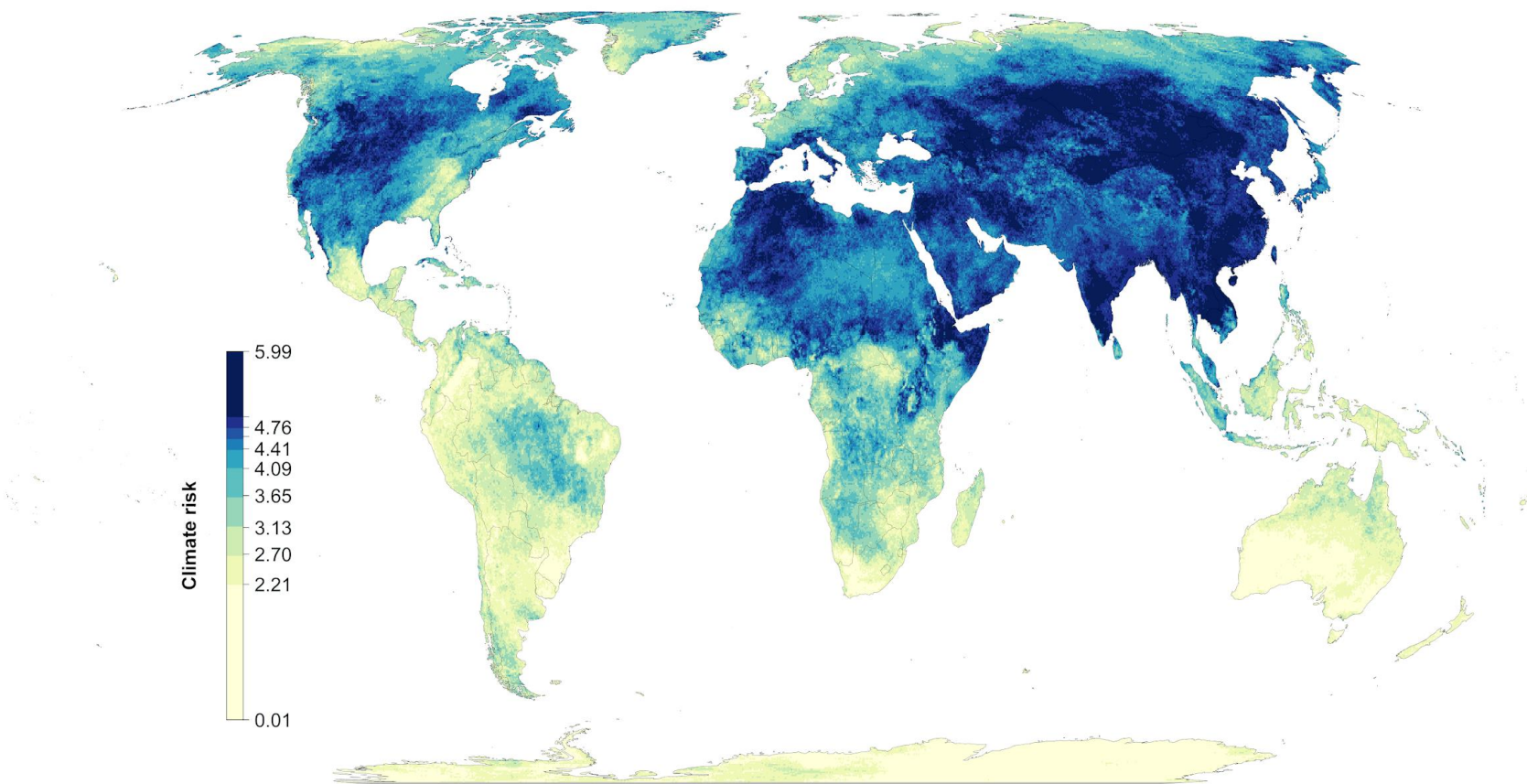
514

515 **Figure S2. Land systems risk (yellow = low, blue= high)**



516
517
518

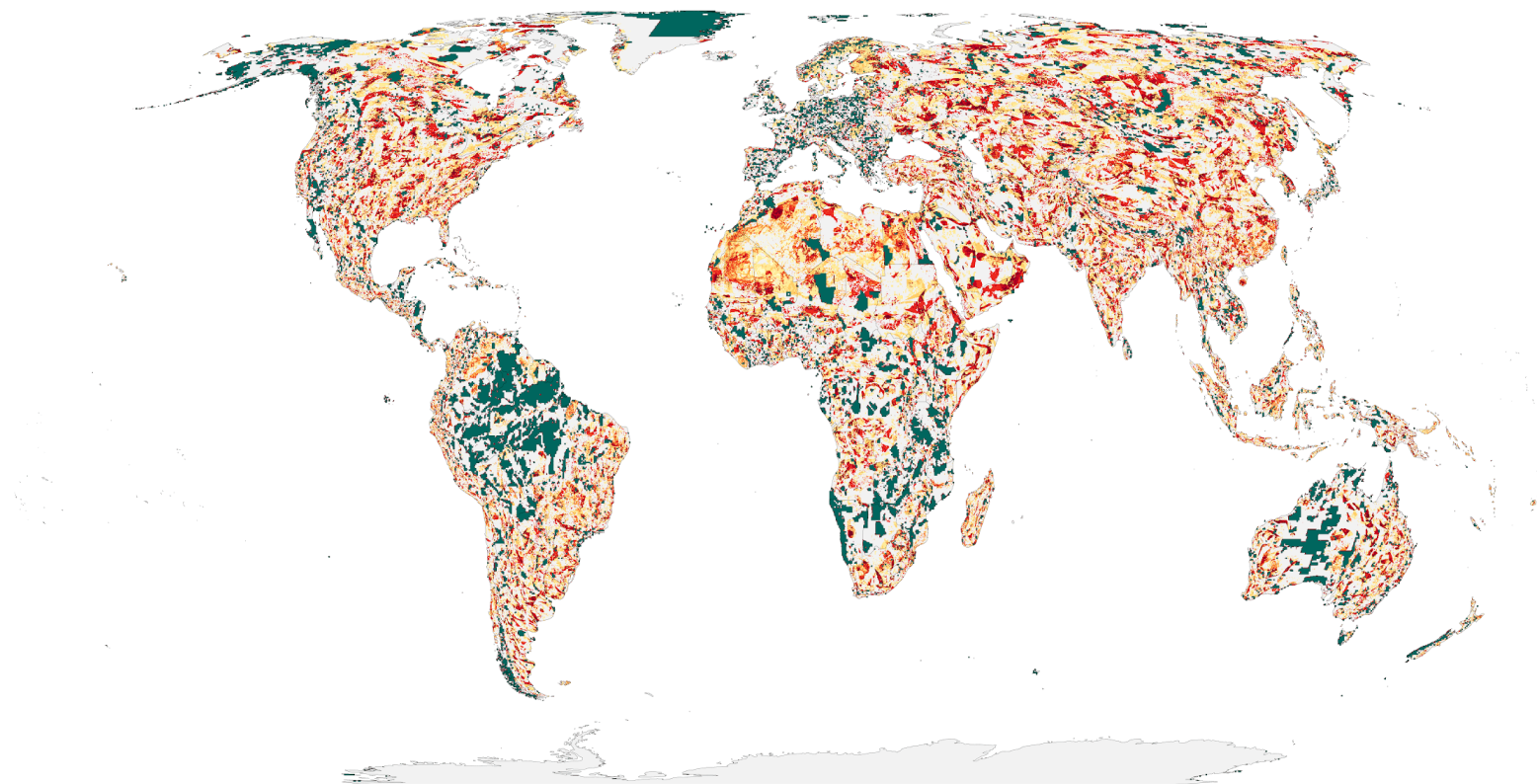
519 **Figure S3. Climate risk (extreme heat events) (yellow = low, blue= high)**



520

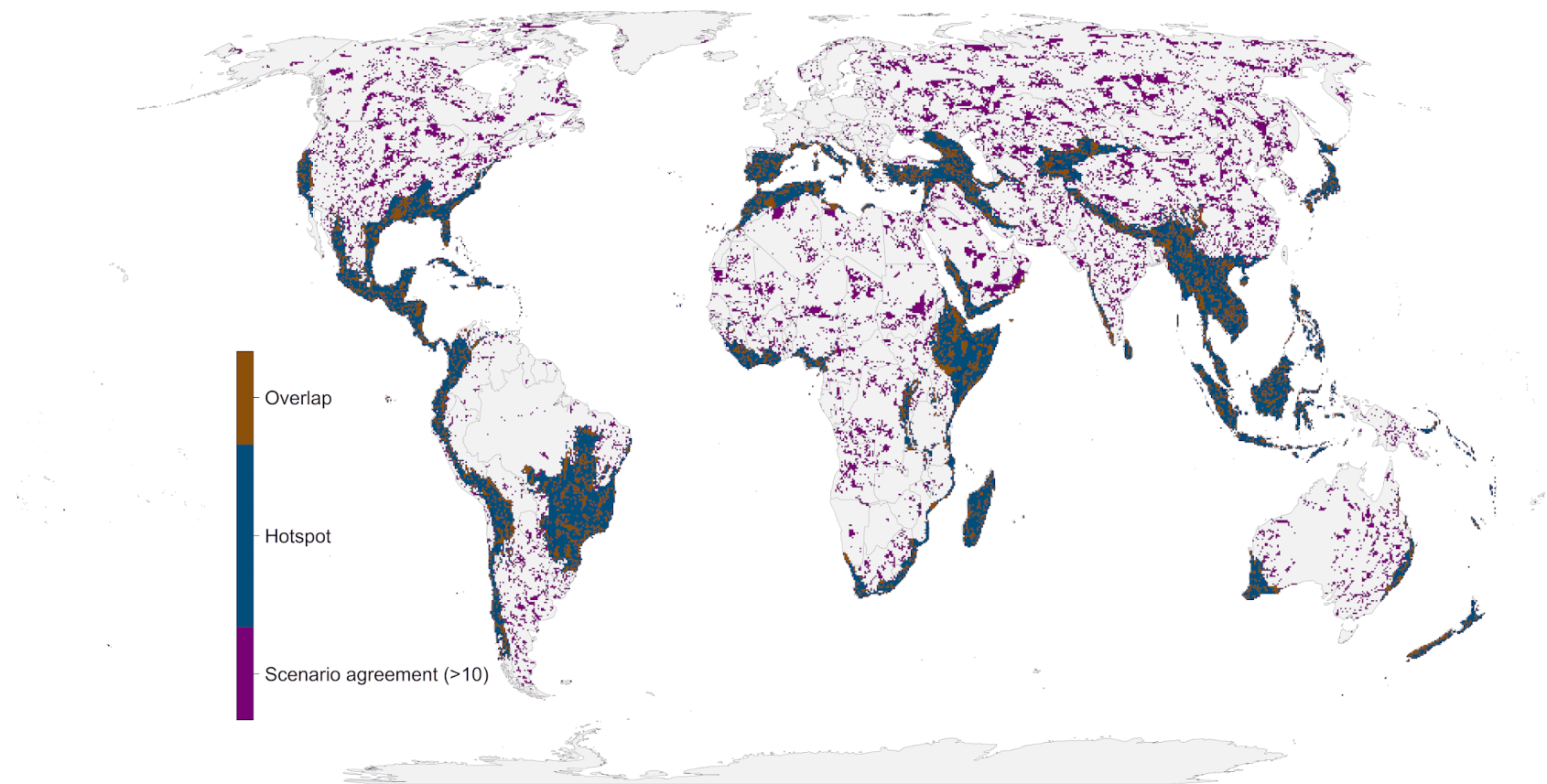
521

522 **Figure S4: Scenario overlap. green = protected areas. Color gradient from yellow (one scenario) to red (15 scenarios) = overlap.**



523
524
525
526

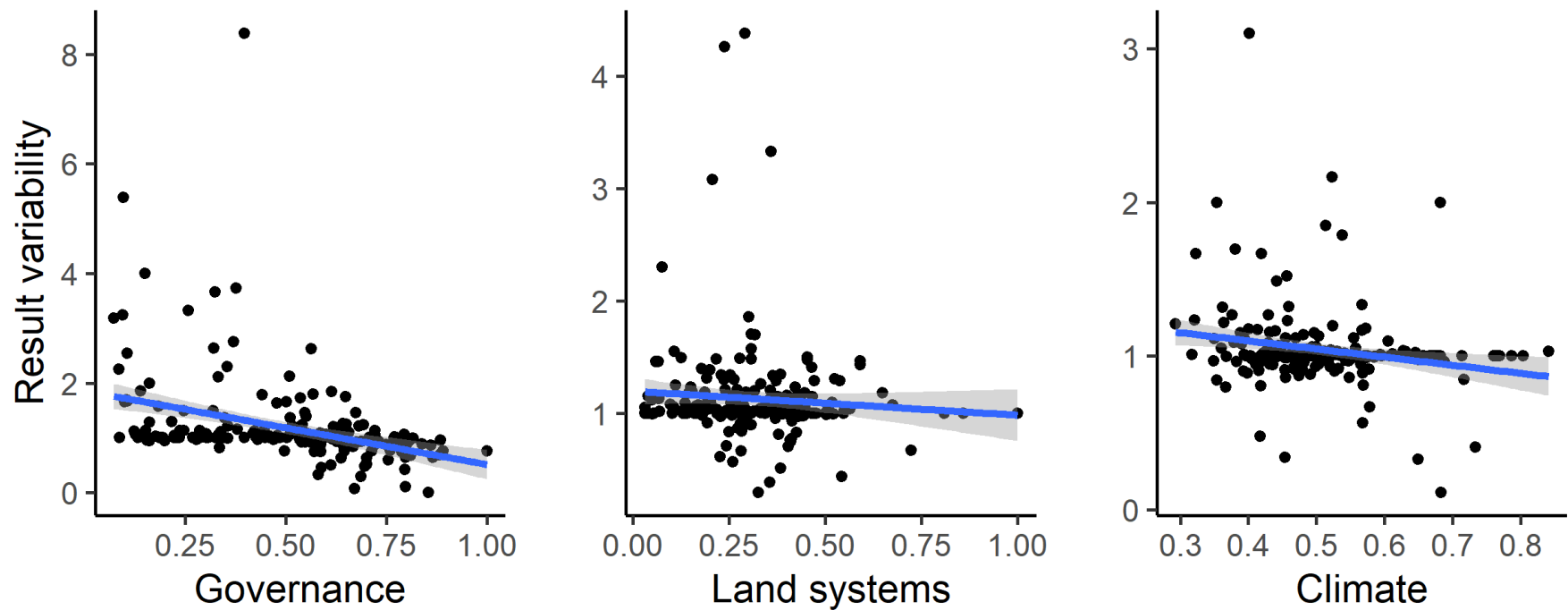
527 **Figure S5. Areas of high scenario overlap (>10 scenarios, green) compared to Meyers et al. biodiversity hotspots (blue).**



528

529

530 **Figure S6: Influence of average country specific risk factors on the optimization outcomes compared between null scenario and the**
531 **scenarios including one of the risk factors. Each data point represents the results for one country. The fitted blue lines and 95%**
532 **confidence bands are from ordinary least-squares regression.**



533

534