

# A System of Systems Approach for Search and Rescue Missions

Ludvig Knöös Franzén and Sofia Schön

# Agenda

- Introduction
- Method
- Implementation of Case Study
- Conclusions

# Introduction

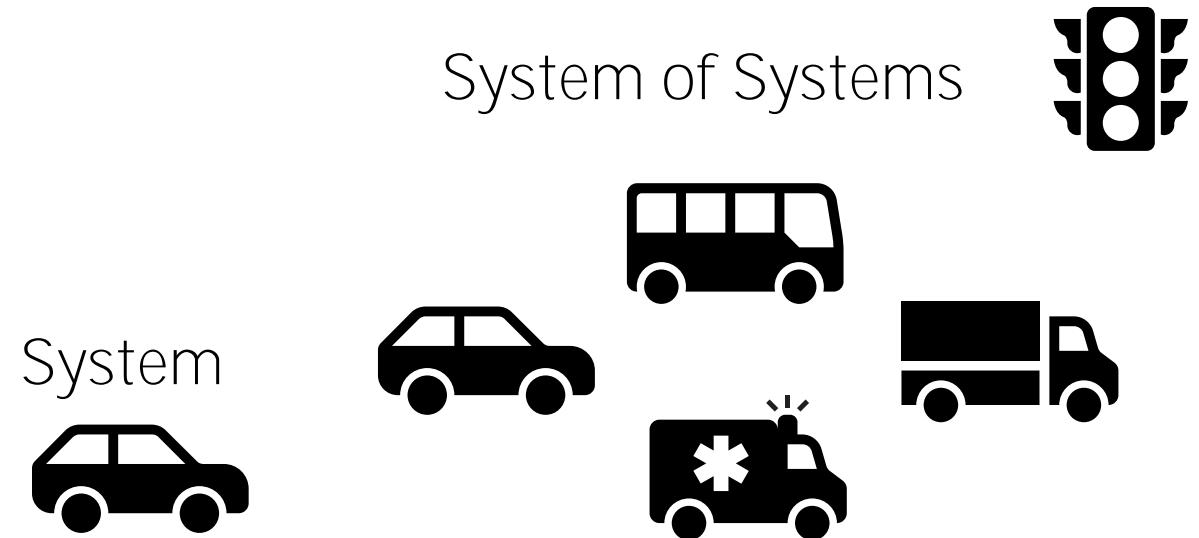
System of Systems, Holistic View, Purpose of Paper

# System of Systems

*"A System of Systems (SoS) is a collection of independent systems, integrated into a larger system that delivers unique capabilities. The independent constituent systems collaborate to produce global behavior **that they cannot produce alone.**" INCOSE*

## Maiers Characteristics

1. Operational Independence of Elements
2. Managerial Independence of Elements
3. Evolutionary Development
4. Emergent Behaviour
5. Geographic Distribution

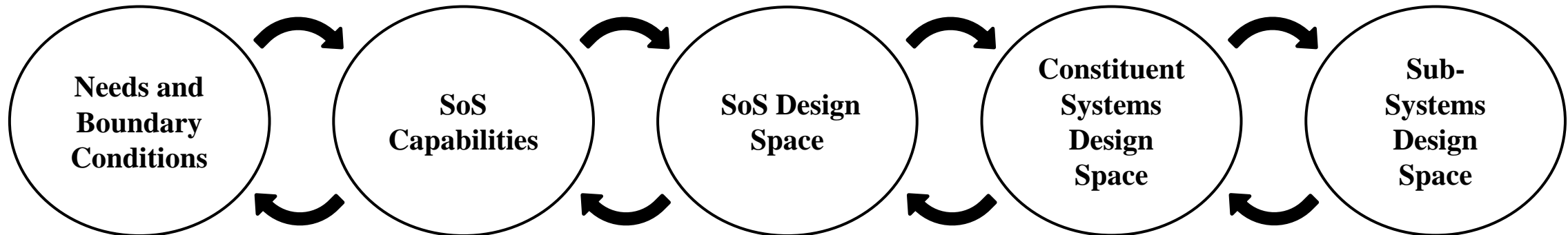


# Challenges

- Increased complexity
- Interconnections between systems and the operational environment
- Changing operational environment
- Long lead times during development and long expected lifespans
- Changing requirements
- Forecasts needs to be incorporated early in the design process
- **Predicting the future and facilitating system's survivability**
- Desire to deliver capabilities over time

# Holistic View

- Five intercorrelated levels of interest
- Design space explorations



# Purpose of Paper

- An approach for realizing parts of the Holistic View
- Generate, reduce and evaluate a System-of-Systems design space
- Taking a System-of-Systems from a highly abstract level to a lower and more detailed level

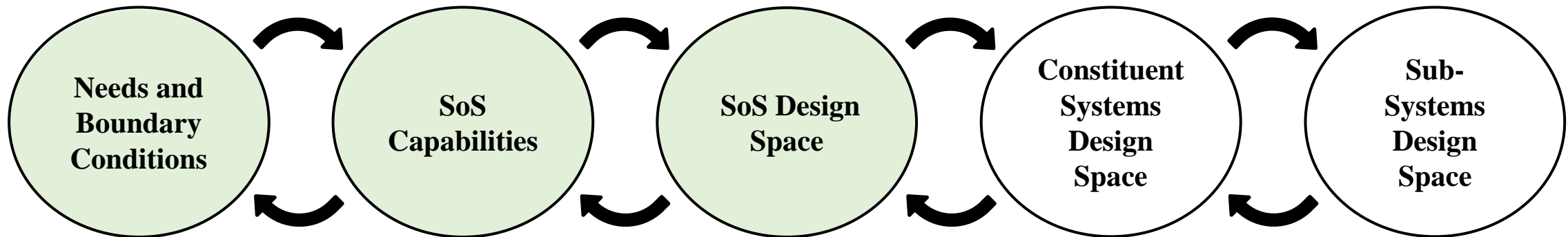
# Method

Approach, Method

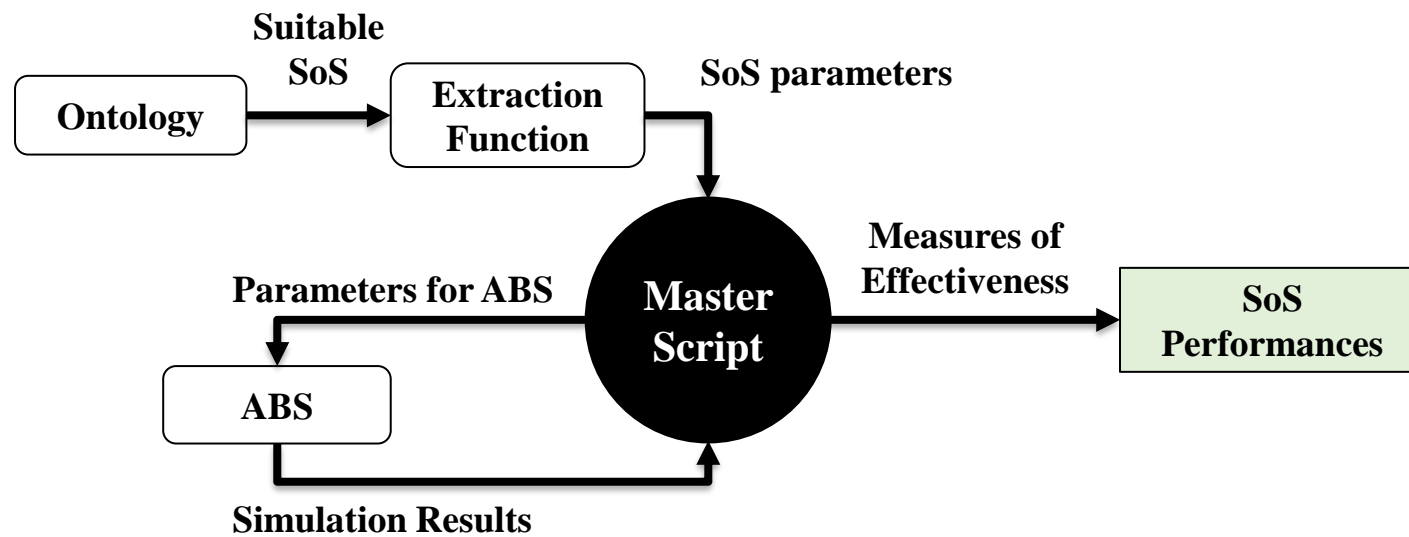


# Approach

- Ontology to describe a System of Systems on an abstract level
- Agent-Based Simulation to evaluate performance on a more detailed level



# Method

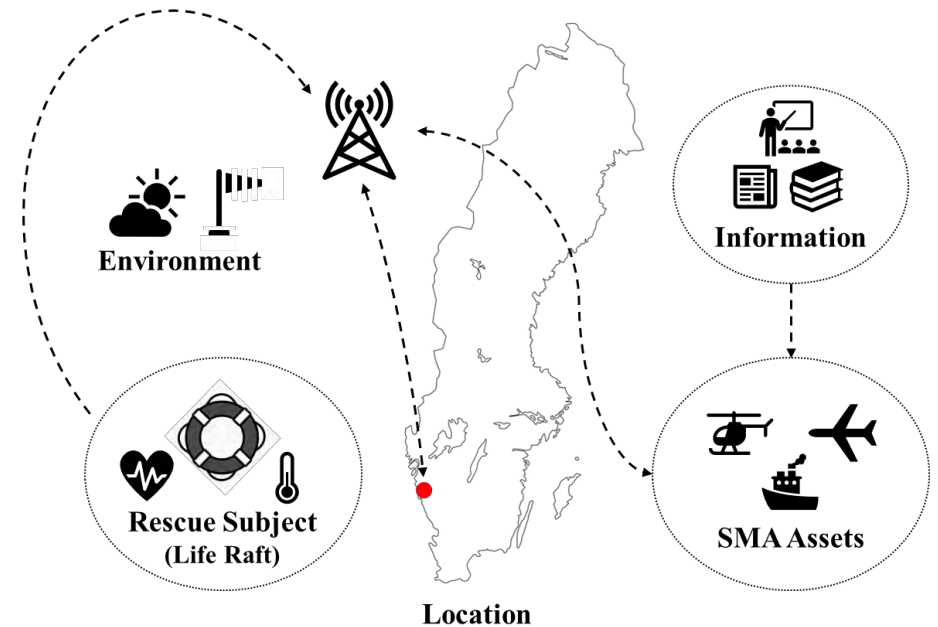
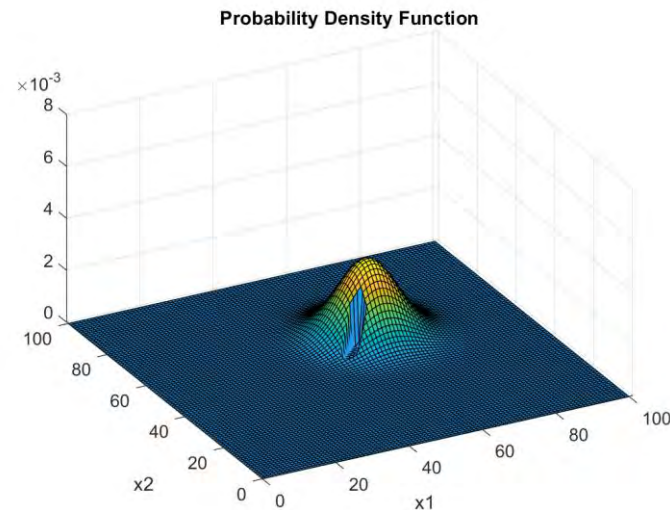
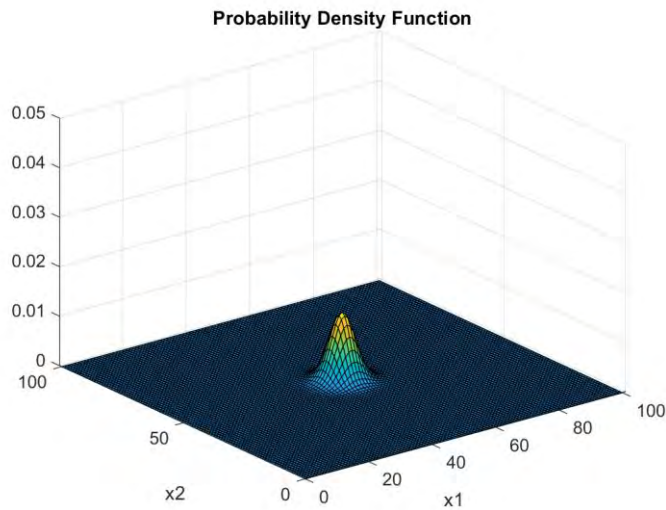


# Implementation of Case Study

Search and Rescue, Ontology, Agent-Based Simulation

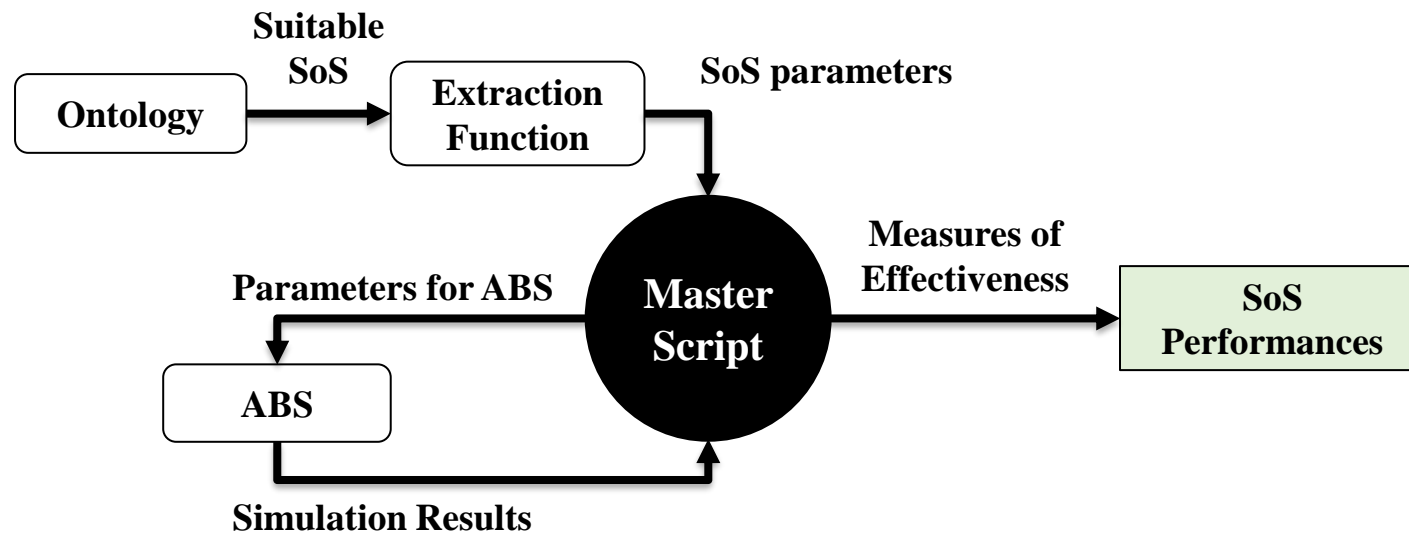
# Search and Rescue Case Study

- 6 types of assets available
- Life Raft lost at sea with a Last Known Position
- Bayesian approach with PDF
- Constant drift in north east direction

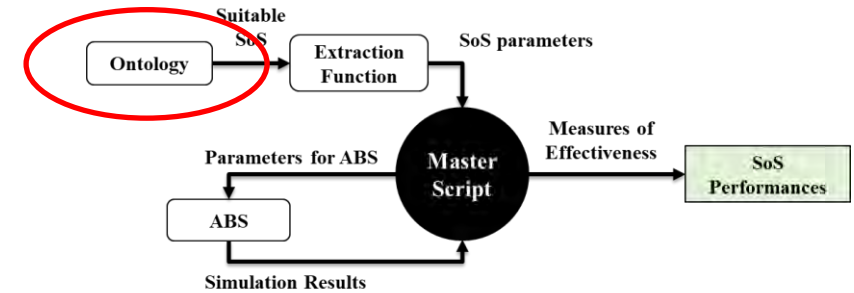
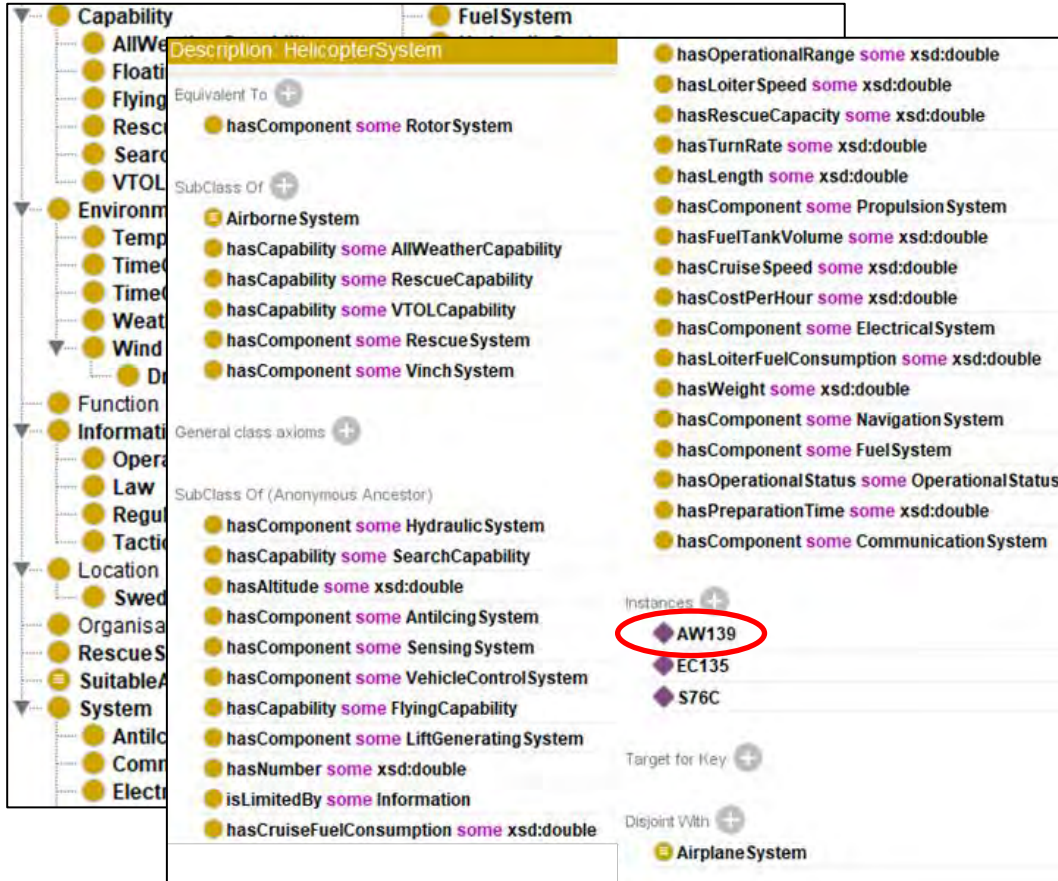


# Search and Rescue Case Study

- Use method to generate, reduce and evaluate a SoS Design Space of different constellations of Search and Rescue assets



# Ontology



Property assertions: AW139	
Object property assertions	Data property assertions
hasComponent Anti_Icing_System_Type1	hasCruiseSpeed "85.0"^^xsd:double
hasComponent Turboshift_System_Type2	hasCostPerHour "1830.0"^^xsd:double
hasComponent Fuel_System_Type3	hasAltitude "500.0"^^xsd:double
hasComponent Hydraulic_System_Type1	hasSweepWidth "1.0"^^xsd:double
hasComponent Electrical_System_Type1	hasNumber "2.0"^^xsd:double
hasComponent Visual_Based_System_Type2	hasDetectionProbability "70.0"^^xsd:double
hasComponent In_Service	hasLength "16.66"^^xsd:double
hasComponent Vinch_System_Type3	hasOperationalRange "1061.0"^^xsd:double
hasComponent Rotor_Example	hasLoiterFuelConsumption "600.0"^^xsd:double
hasComponent Radar_System_Type1	hasFuelTankVolume "2.5"^^xsd:double
hasComponent Navigation_System_Type2	hasWeight "6400.0"^^xsd:double
hasComponent Communication_System_Type2	hasRescueCapacity "15.0"^^xsd:double
hasComponent Vehicle_Control_System_Type1	hasTurnRate "8.0"^^xsd:double
	hasCruiseFuelConsumption "682.0"^^xsd:double
	hasPreparationTime "900.0"^^xsd:double
	hasLoiterSpeed "75.0"^^xsd:double
	hasIntroductionYear "2004.0"^^xsd:double



# Ontology

- Identified needs
- Reasoner
- Suitable Assets

## Inferred Ontology

Description: SuitableAsset

Equivalent To +

- (hasCapability some FlyingCapability)
- and (hasCapability some SearchCapability)
- and (hasOperationalStatus value InService)
- and (hasCruiseSpeed some xsd:double[>= "60.0"^^xsd:double])

SubClass Of +

- AirborneSystem

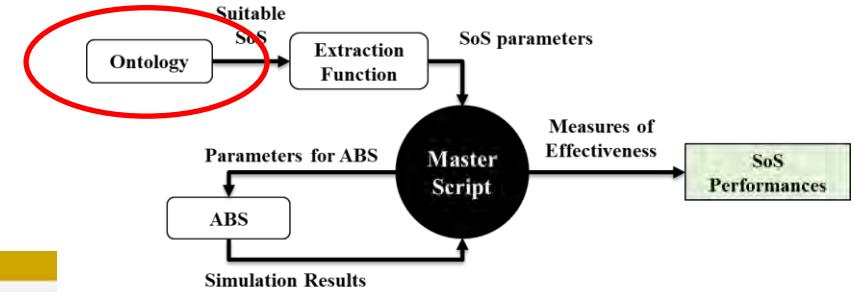
General class axioms +

SubClass Of (Anonymous Ancestor)

- hasComponent some HydraulicSystem
- hasCapability some SearchCapability
- hasAltitude some xsd:double
- hasComponent some AntilcingSystem
- hasComponent some SensingSystem
- hasComponent some VehicleControlSystem
- hasCapability some FlyingCapability
- hasComponent some LiftGeneratingSystem

Instances +

- AW139
- Dash8Q300
- EC135



## Asserted Ontology

Description: SuitableAsset

Equivalent To +

- (hasCapability some FlyingCapability)
- and (hasCapability some SearchCapability)
- and (hasOperationalStatus value InService)
- and (hasCruiseSpeed some xsd:double[>= "60.0"^^xsd:double])

SubClass Of +

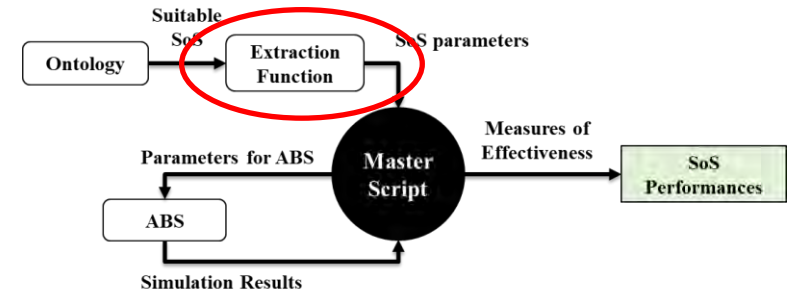
General class axioms +

SubClass Of (Anonymous Ancestor)

Instances +

# Extraction Function

- Extracting ontology information
- XML-structure
- MATLAB navigation and variable assignments



Property assertions: AW139

Object property assertions

- hasComponent Anti\_Icing\_System\_Type1
- hasComponent Turboshaft\_System\_Type2
- hasComponent Fuel\_System\_Type3
- hasComponent Hydraulic\_System\_Type1
- hasComponent Electrical\_System\_Type1
- hasComponent Visual\_Based\_System\_Type2
- hasOperationalStatus InService
- hasComponent Vinch\_System\_Type3
- hasComponent Rotor\_Example
- hasComponent Radar\_System\_Type1
- hasComponent Navigation\_System\_Type2
- hasComponent Communication\_System\_Type2
- hasComponent Vehicle\_Control\_System\_Type1

Data property assertions

- hasCruiseSpeed "85.0"^^xsd:double
- hasCostPerHour "1830.0"^^xsd:double
- hasAltitude "500.0"^^xsd:double
- hasSweepWidth "1.0"^^xsd:double
- hasNumber "2.0"^^xsd:double
- hasDetectionProbability "70.0"^^xsd:double
- hasLength "16.66"^^xsd:double
- hasOperationalRange "1061.0"^^xsd:double
- hasLoiterFuelConsumption "600.0"^^xsd:double
- hasFuelTankVolume "2.5"^^xsd:double
- hasWeight "6400.0"^^xsd:double
- hasRescueCapacity "15.0"^^xsd:double
- hasTurnRate "8.0"^^xsd:double
- hasCruiseFuelConsumption "682.0"^^xsd:double
- hasPreparationTime "900.0"^^xsd:double
- hasLoiterSpeed "75.0"^^xsd:double
- hasIntroductionYear "2004.0"^^xsd:double

```

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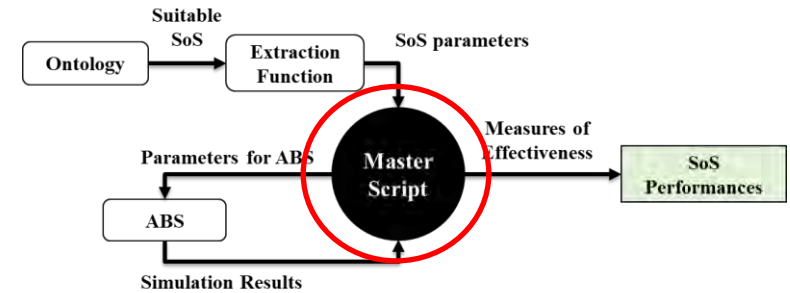
Workspace

Name	Value
AW139	1x1 DeferredElementImpl
AW139_altitude	500
AW139_altitudeValue	1x1 String
AW139_altNode	1x1 DeferredElementImpl
AW139_costPerHour	1830
AW139_costPerHourNode	1x1 DeferredElementImpl
AW139_costPerHourValue	1x1 String
AW139_cruiseFuelConsum...	682
AW139_cruiseFuelConsum...	1x1 DeferredElementImpl
AW139_cruiseFuelConsum...	1x1 String
AW139_cruiseSpeed	85
AW139_cruiseSpeedNode	1x1 DeferredElementImpl
AW139_detectionProbability	70
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AW139_detectionProbabili...	1x1 String
AW139_fuelTankVolume	2.5000
AW139_fuelTankVolumeN...	1x1 DeferredElementImpl
AW139_fuelTankVolumeN...	1x1 String
AW139_loiterFuelConsum...	600
AW139_loiterFuelConsum...	1x1 DeferredElementImpl
AW139_loiterFuelConsum...	1x1 String
AW139_loiterSpeed	75
AW139_loiterSpeedNode	1x1 DeferredElementImpl
AW139_loiterSpeedValue	1x1 String
AW139_number	2
AW139_numberNode	1x1 DeferredElementImpl
AW139_numberValue	1x1 String
AW139_preparationTime	900
AW139_preparationTimeN...	1x1 DeferredElementImpl
AW139_preparationTimeN...	1x1 String
AW139_sweepWidth	1
AW139_sweepWidthNode	1x1 DeferredElementImpl
AW139_sweepWidthValue	1x1 String
AW139_turnRate	8
AW139_turnRateNode	1x1 DeferredElementImpl
AW139_turnRateValue	1x1 String
AW139_Variables	1x12 double



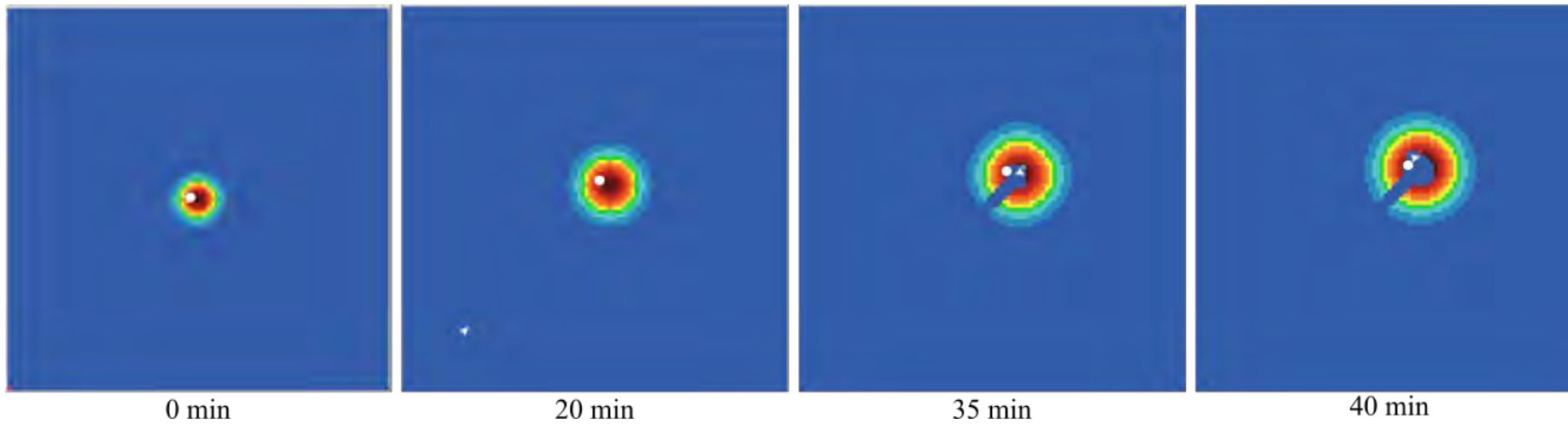
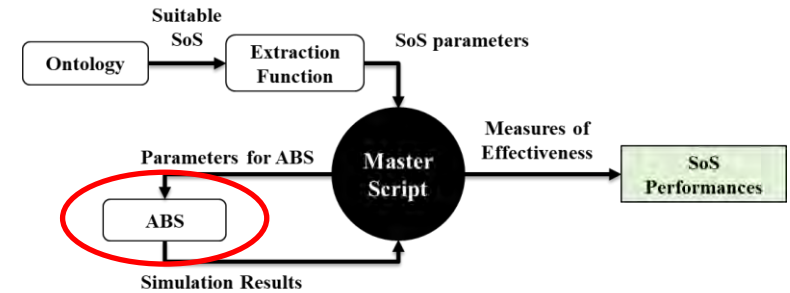
# Master Script

- Imports SoS data from Ontology
  - Number of each asset [AW139 Dash8Q300 EC135]
  - Asset performance values
  - Scenario values
- Sets up constellations of assets
- Define simulation control parameters
- Saves mission results and mission time



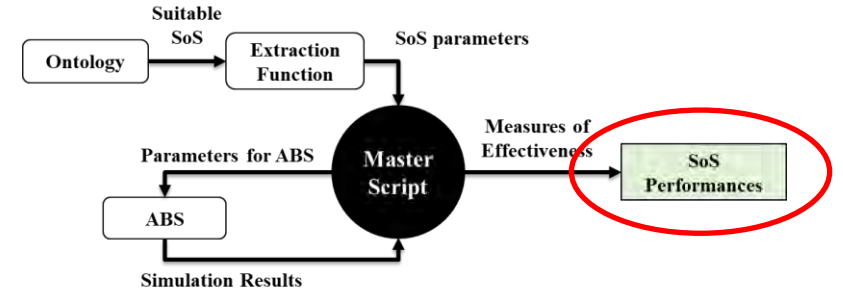
# Agent-Based Simulation

- Modeled in NetLogo
- PDF updated in MATLAB during simulation
- Greedy search tactic

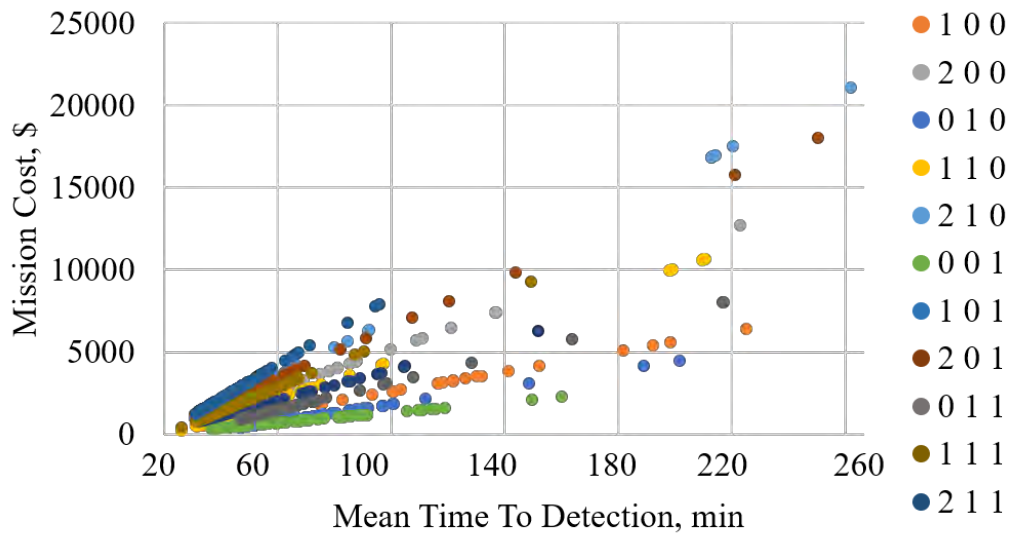


# SoS Performances

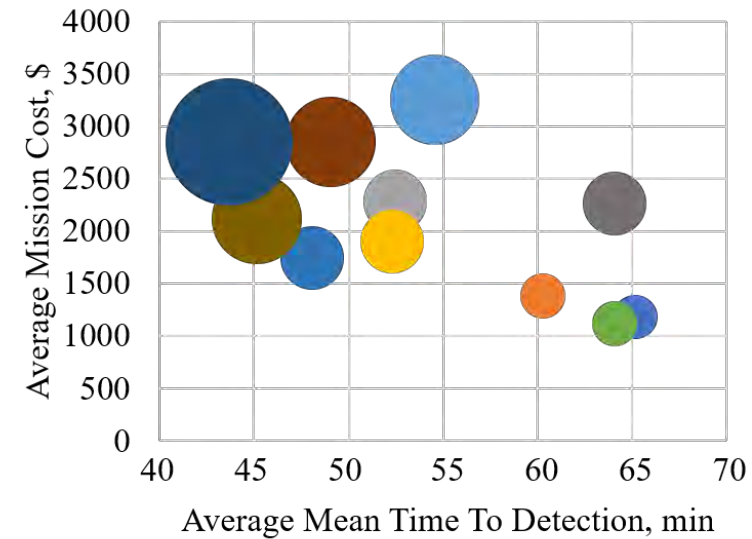
[AW139 Dash8Q300 EC135]



Raw Data



Averages

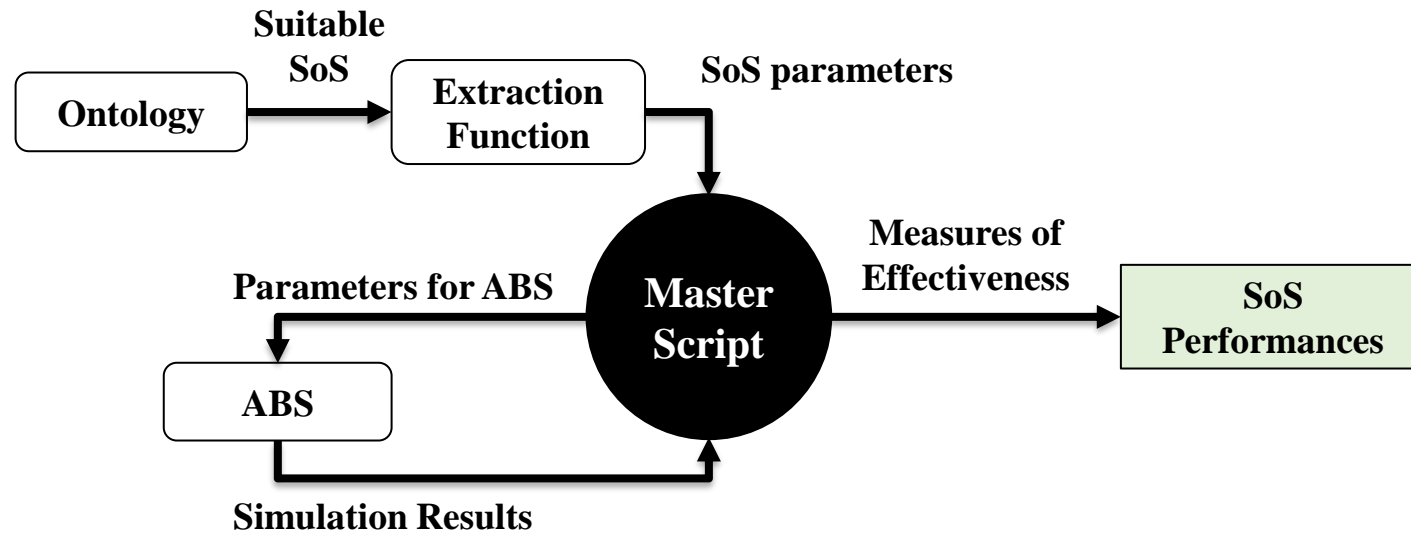


# Conclusions

Results, Future Work

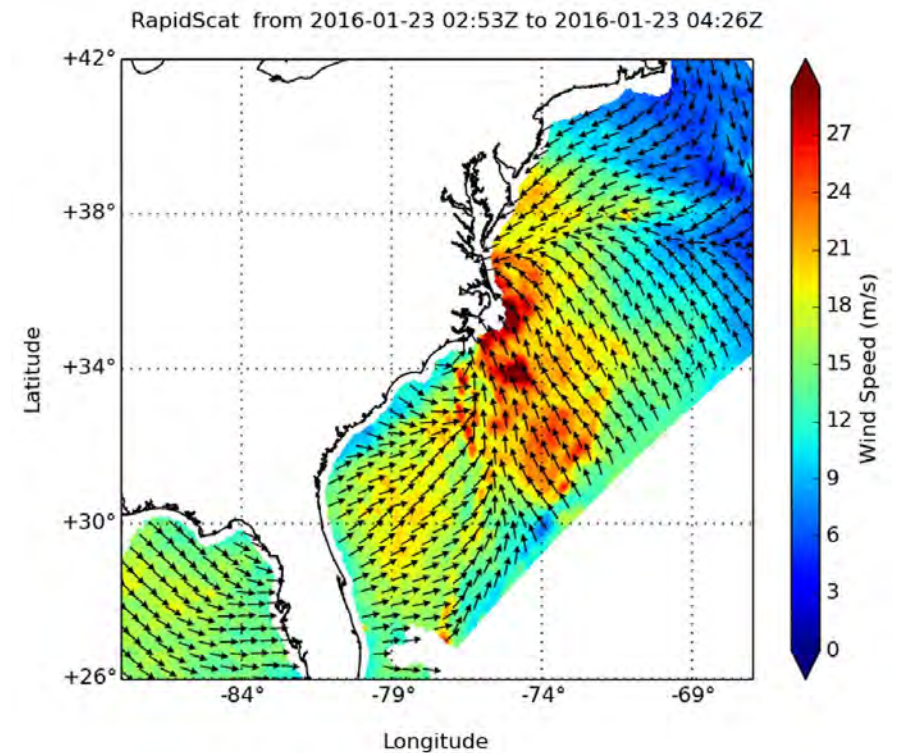
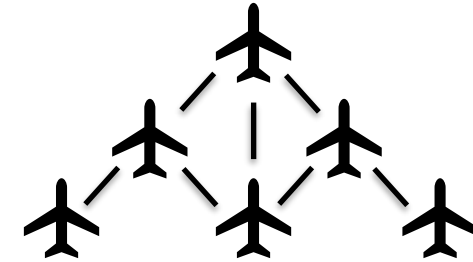
# Results

- Generate, reduce and evaluate a System-of-Systems design space
- Taking a System-of-Systems from a highly abstract level to a lower and more detailed level



# Future Work

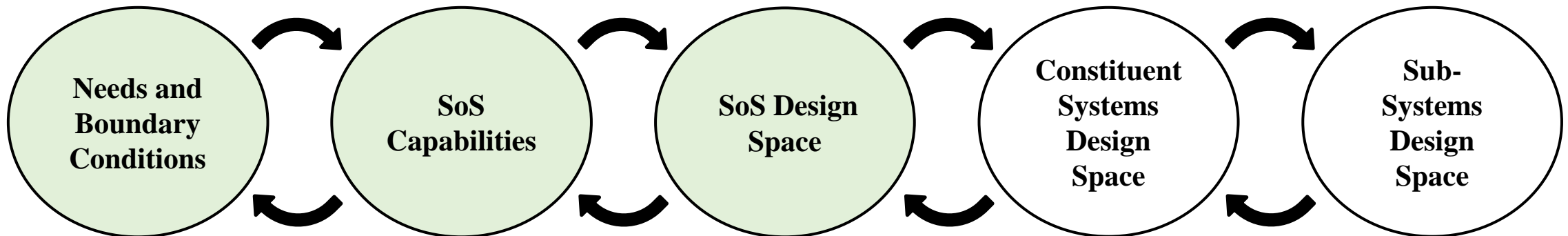
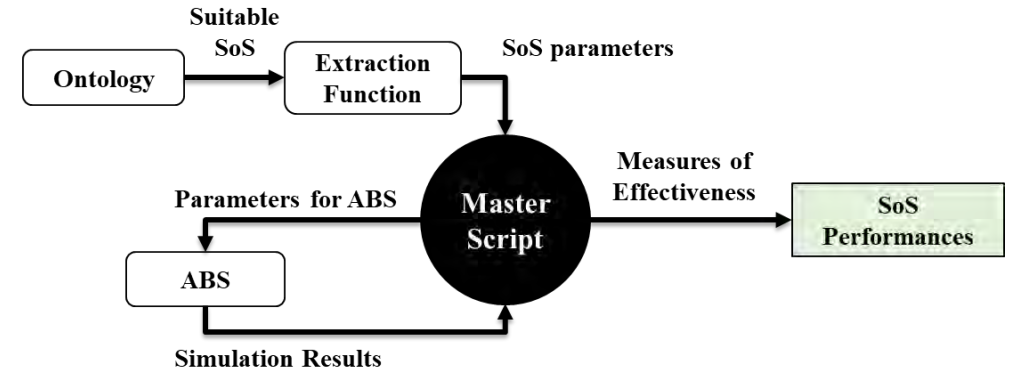
- Search and Rescue Case
  - Investigate different tactics
  - More approaches of PDF modeling
  - Use wind data and ocean currents data
- Method
  - Include constituent system and subsystem analyses
  - Introduce changes in external factors and explore the influence on the design space. What if?



<https://www.jpl.nasa.gov/spaceimages/index.php?search=ISS-RapidScat>

# Conclusions

- Realizes parts of the holistic view
- An initial approach



Thank you!

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