

# Development and Integration of System-of-Systems Models for Unmanned Aircraft

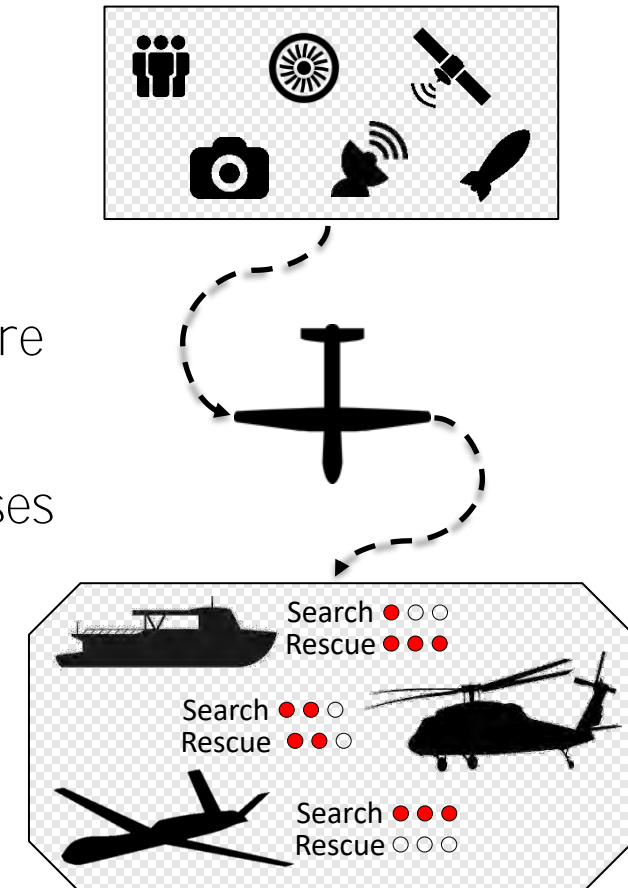
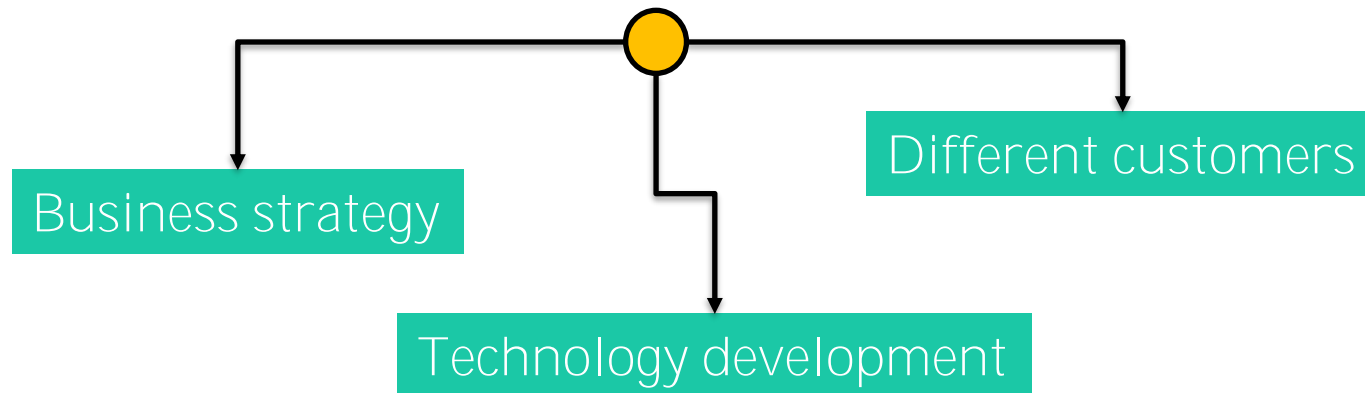
Athanasios Papageorgiou

MODPROD 2020



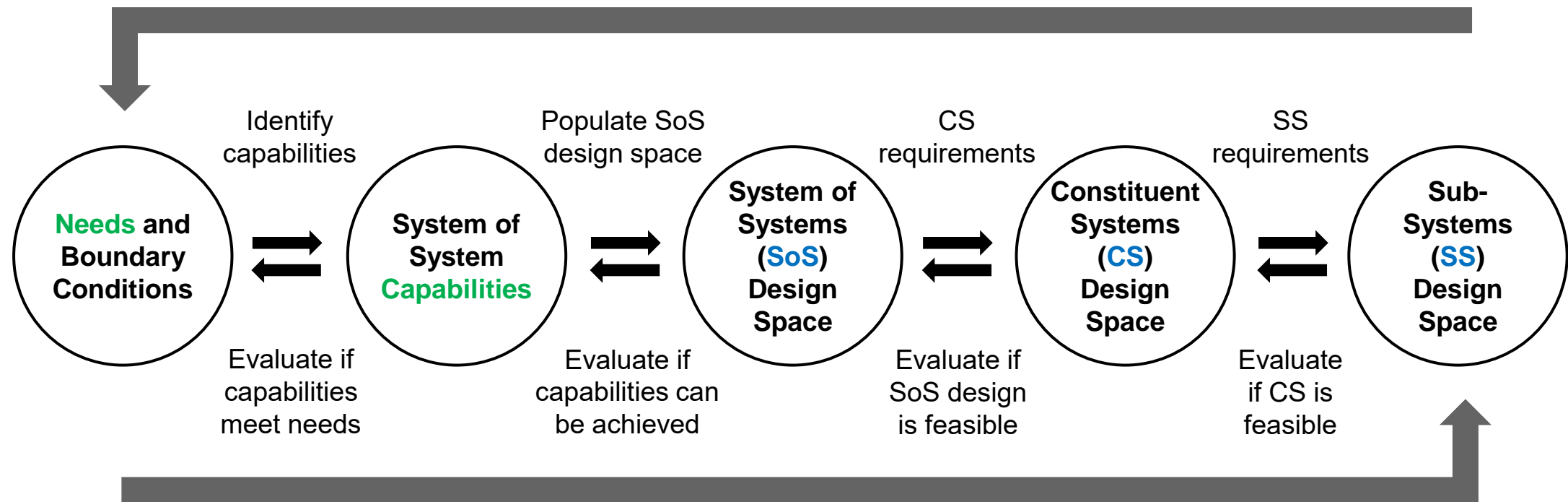
# Background

- Aerospace products are part of a network or a “System of Systems”
  - SoS analyses have been used in the way customer acquire new assets
  - Manufacturers should be able to perform similar analyses

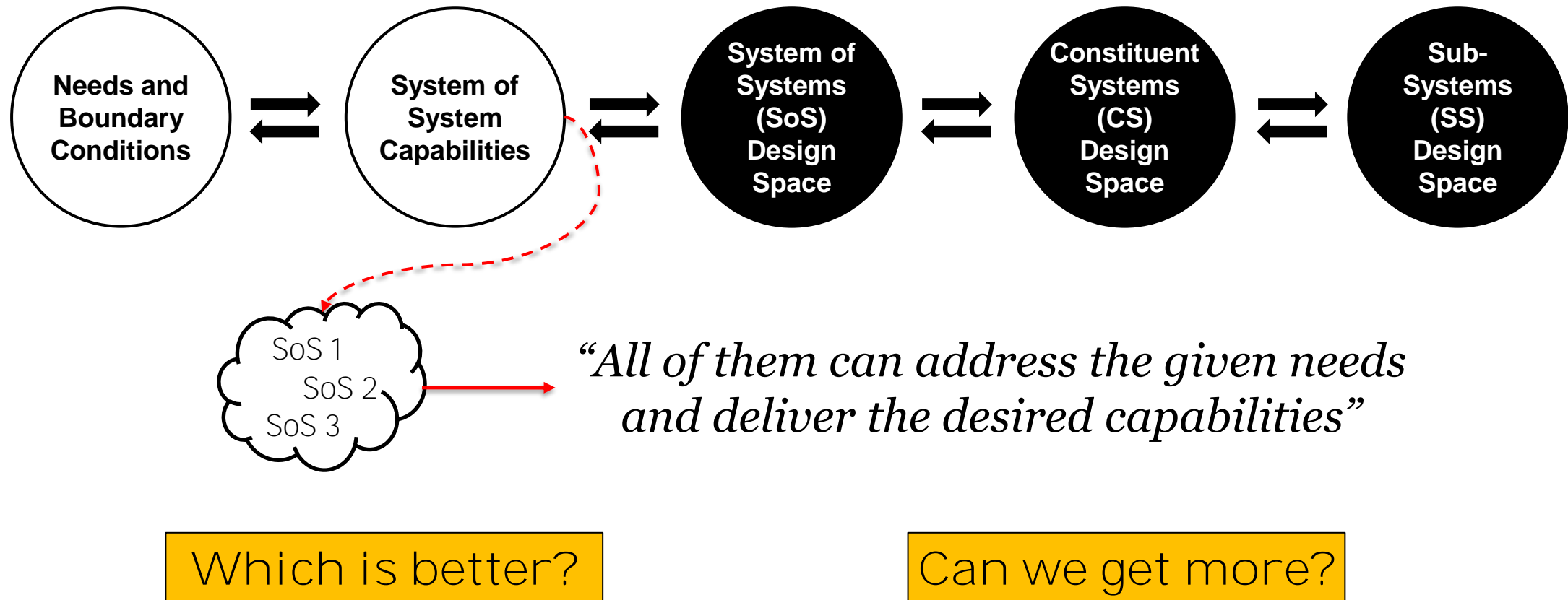


# Background

*“A holistic engineering approach to aeronautical product development”*

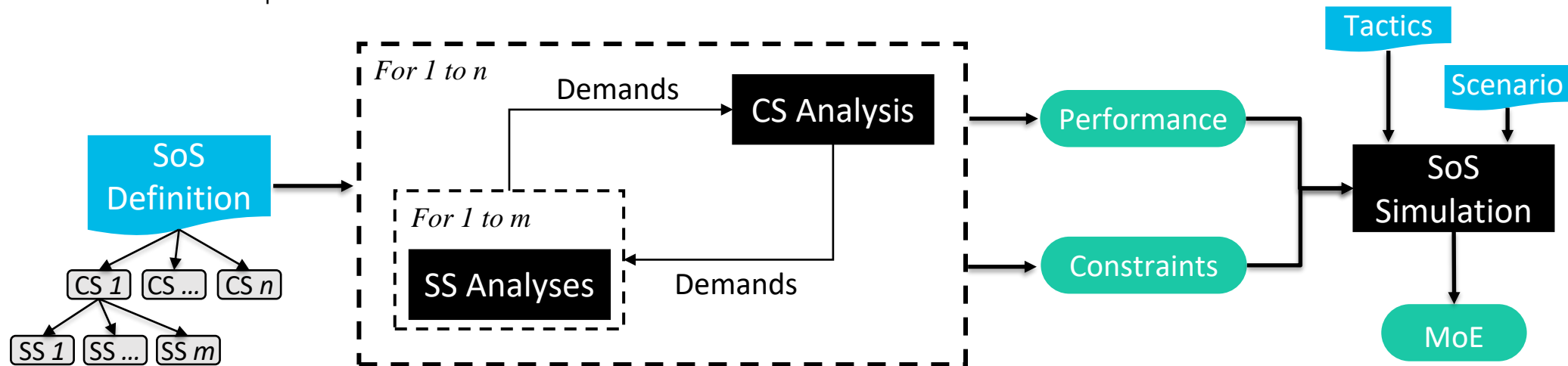


# Aim



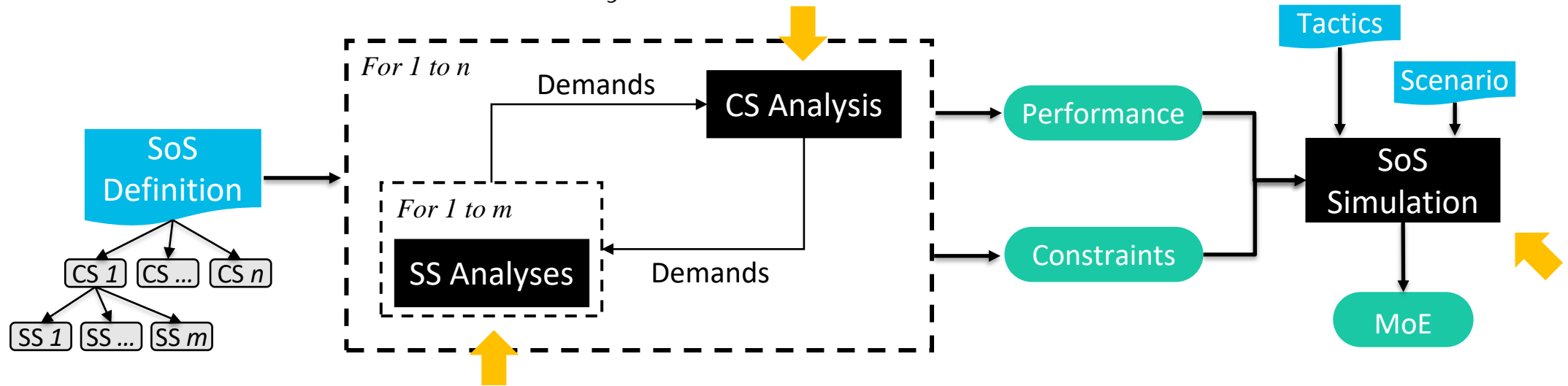
# Identifying SoS Capabilities

- Framework for SoS design space population
  - First step is to define the SoS combinations to be evaluated
  - Second step is to identify the performance of each CS and SS
  - Third step is to simulate the entire SoS to extract the MoE

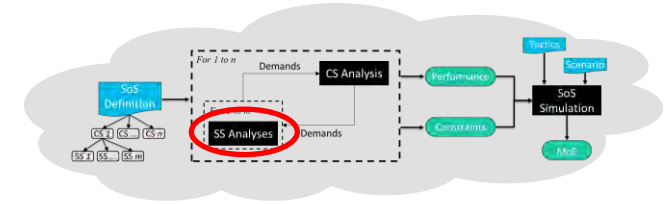


# Identifying SoS Capabilities

- Framework for SoS design space population
  - Addresses all three levels of design
  - Not bound to any design space
  - Allows the use of multi-fidelity tools

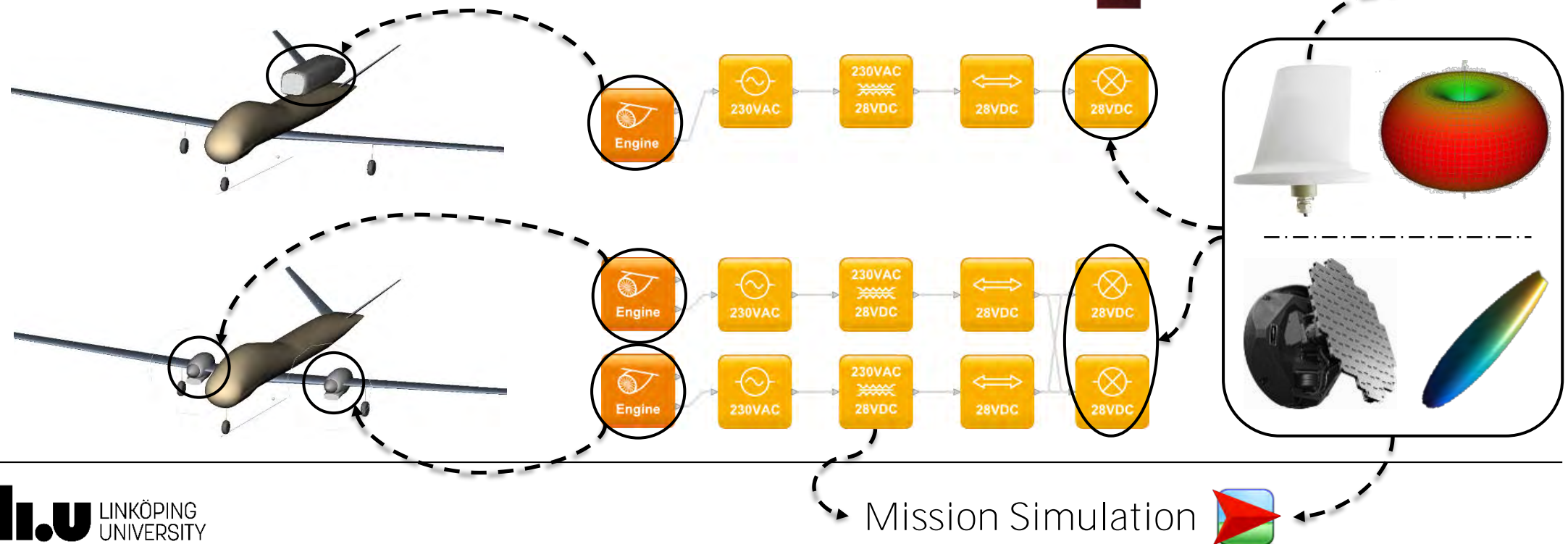


# Implementation

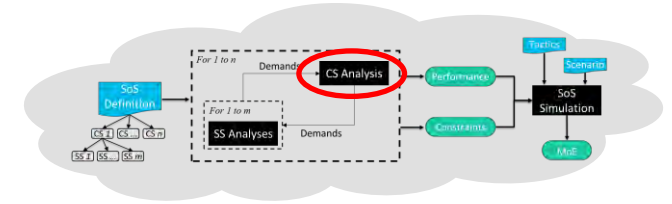


# Sub-System (SS) Models

- Expanding the SS level models
  - Need to capture the effects of sensors/communications
  - Need to represent the electrical architecture/propulsion







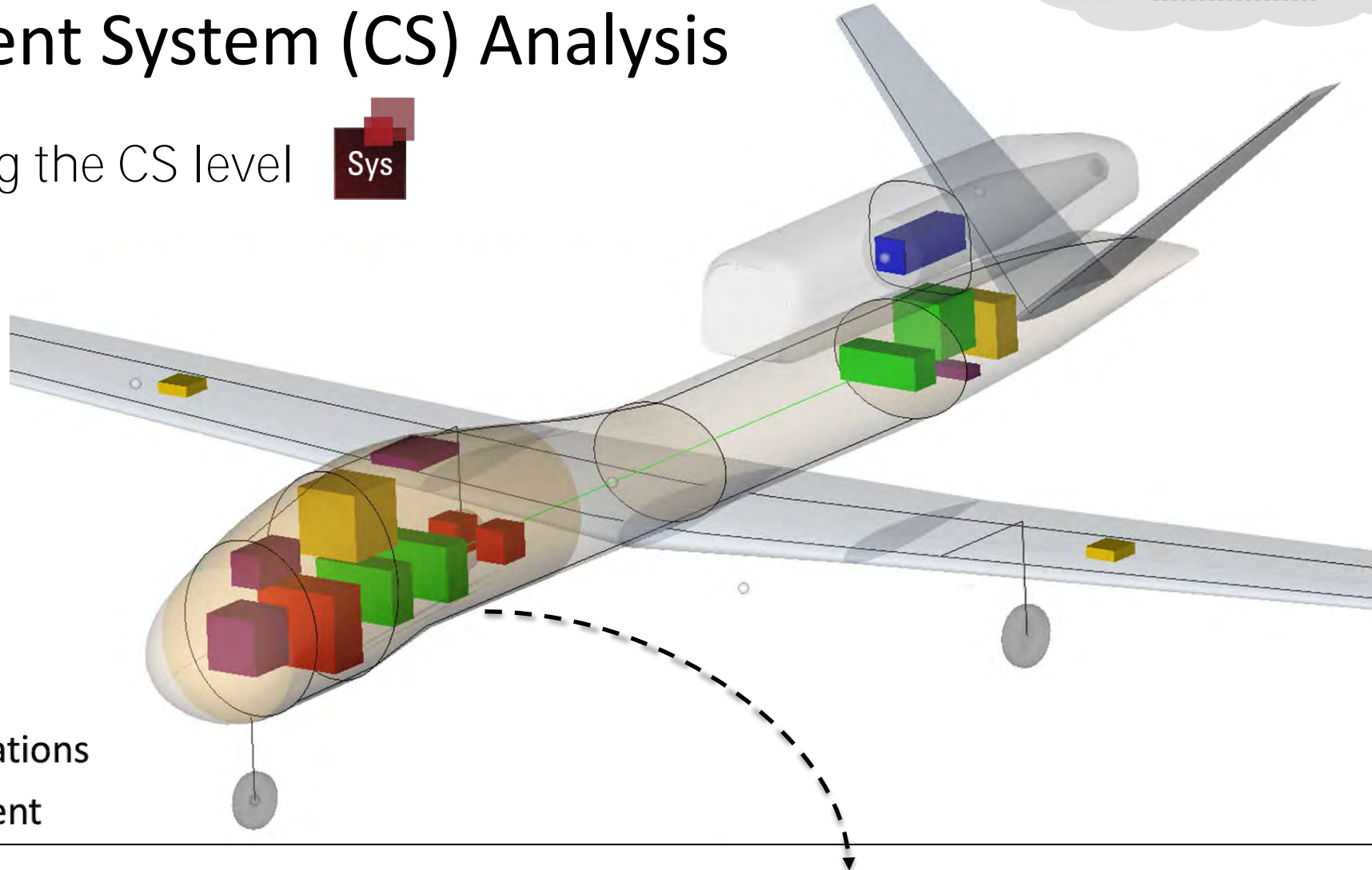
# Constituent System (CS) Analysis

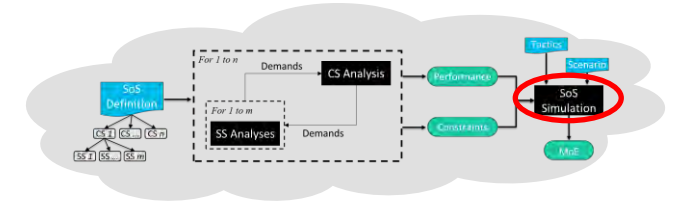
- Enhancing the CS level



— Routing  
— Pathways

- Sensors
- Engine
- Electrical
- Avionics
- Communications
- Compartment





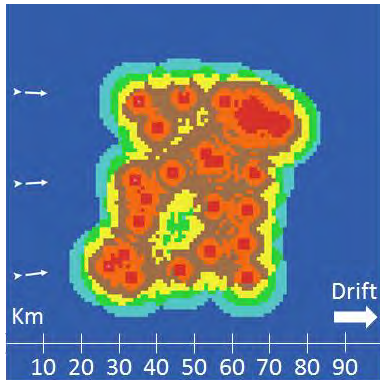
# System-of-Systems (SoS) Simulations

- Capturing the SoS level interactions
  - Collaboration (divide search, avoid overlap)
  - Realism (failure modes, false positives, drift)

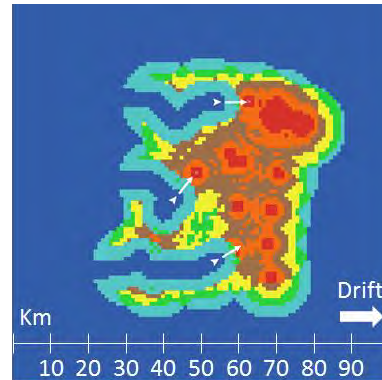
Agent-based  
in NETLOGO



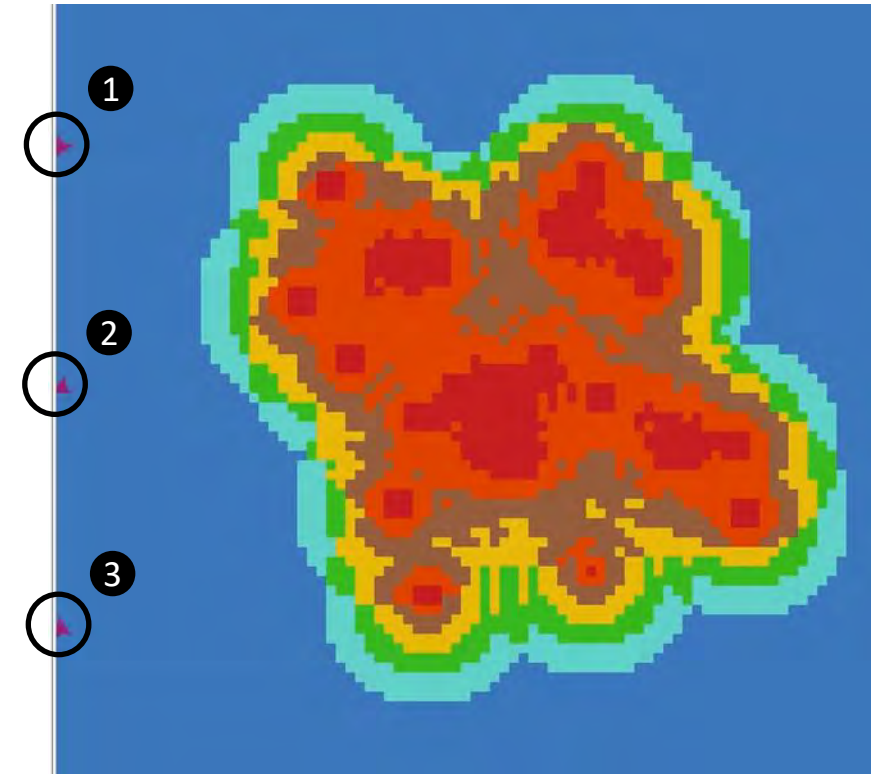
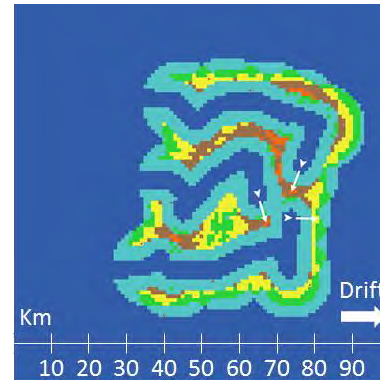
t = 26min  
 $P_d = 0\%$



t = 39min  
 $P_d = 34\%$

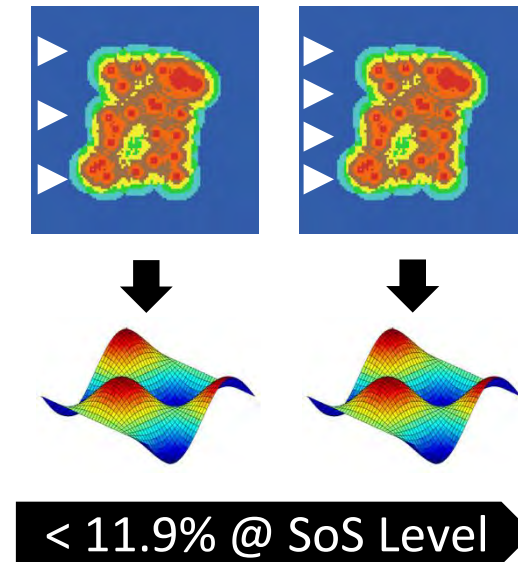
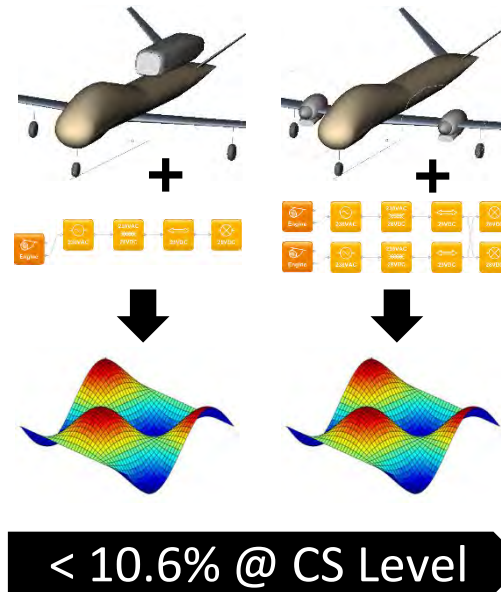
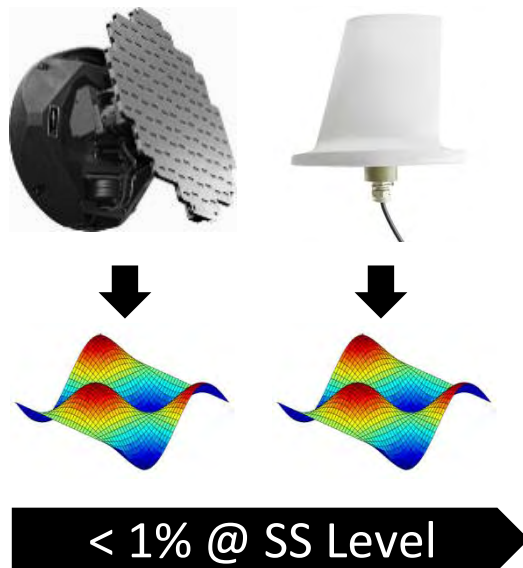
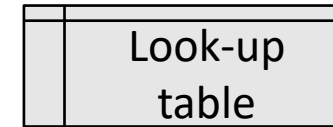


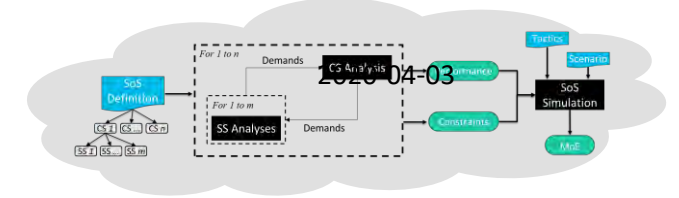
t = 52min  
 $P_d = 82\%$



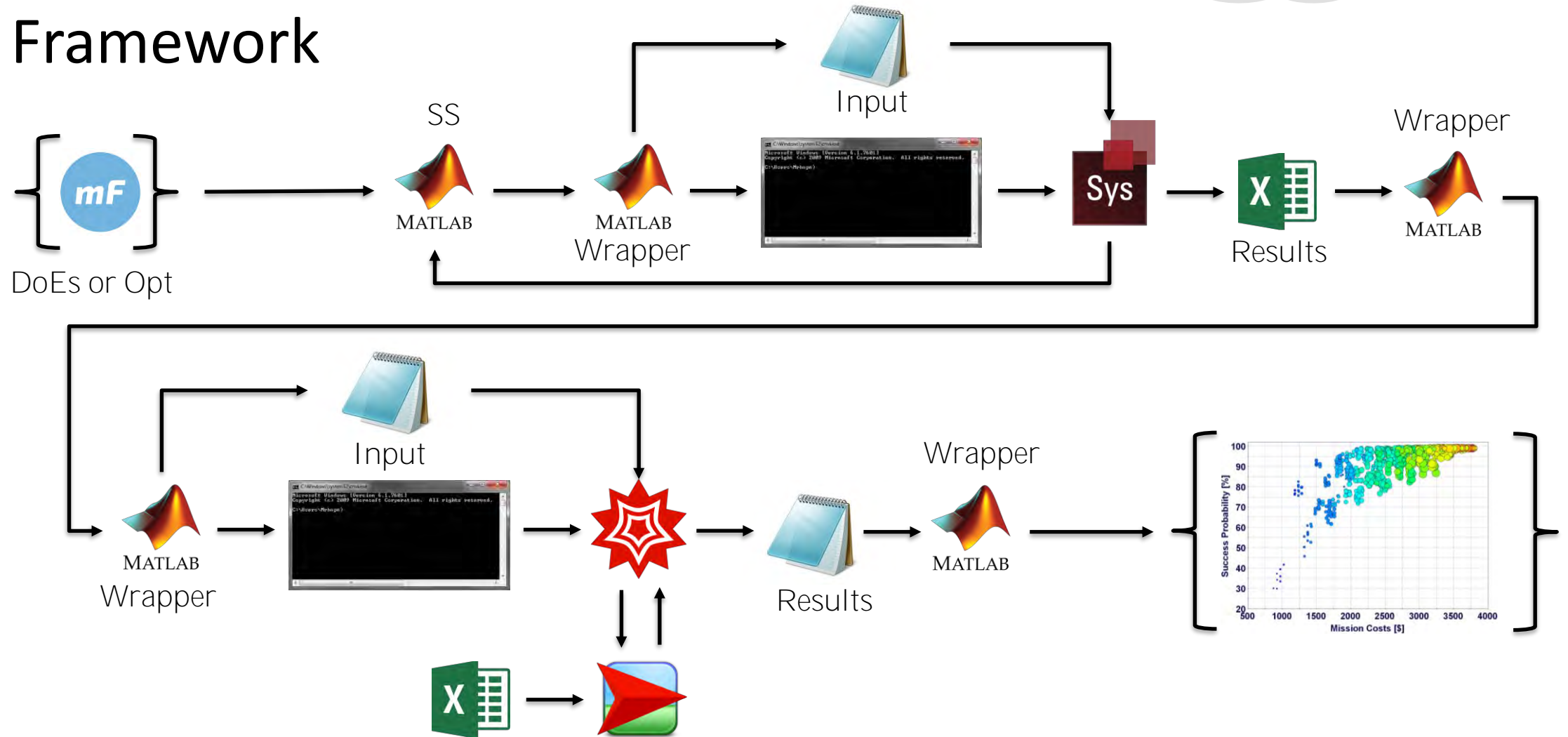
# Multi-fidelity Computations

- Enabling faster computations
  - Metamodels at each one of the design levels
  - Approach of creating multiple metamodels





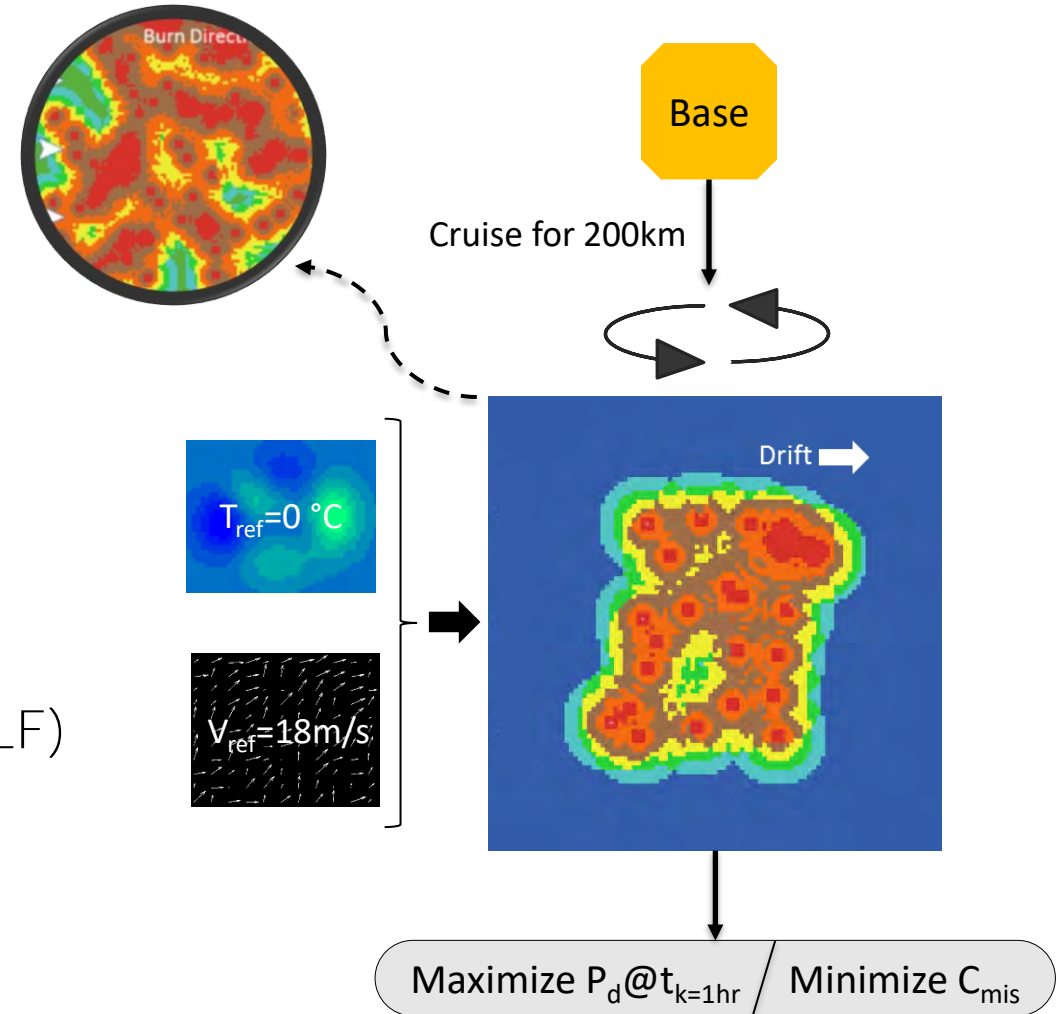
# Framework



# Proof Of Concept

# Identifying SoS Capabilities

- Setting up a case study
  - Search for missing survivors/objects
  - Dynamic weather (sea & air) conditions
- Two operational scenarios
  - A) fleet of 3 existing UAV designs (HF)
  - B) fleet of 2-4 yet-to-be-designed UAVs (LF)
- Monitored capabilities (MoEs)
  - Detection probability VS Mission costs
  - Total payload / Fleet maintenance costs





# Case Study 1 (HF)

10 existing UAV designs (A-J)

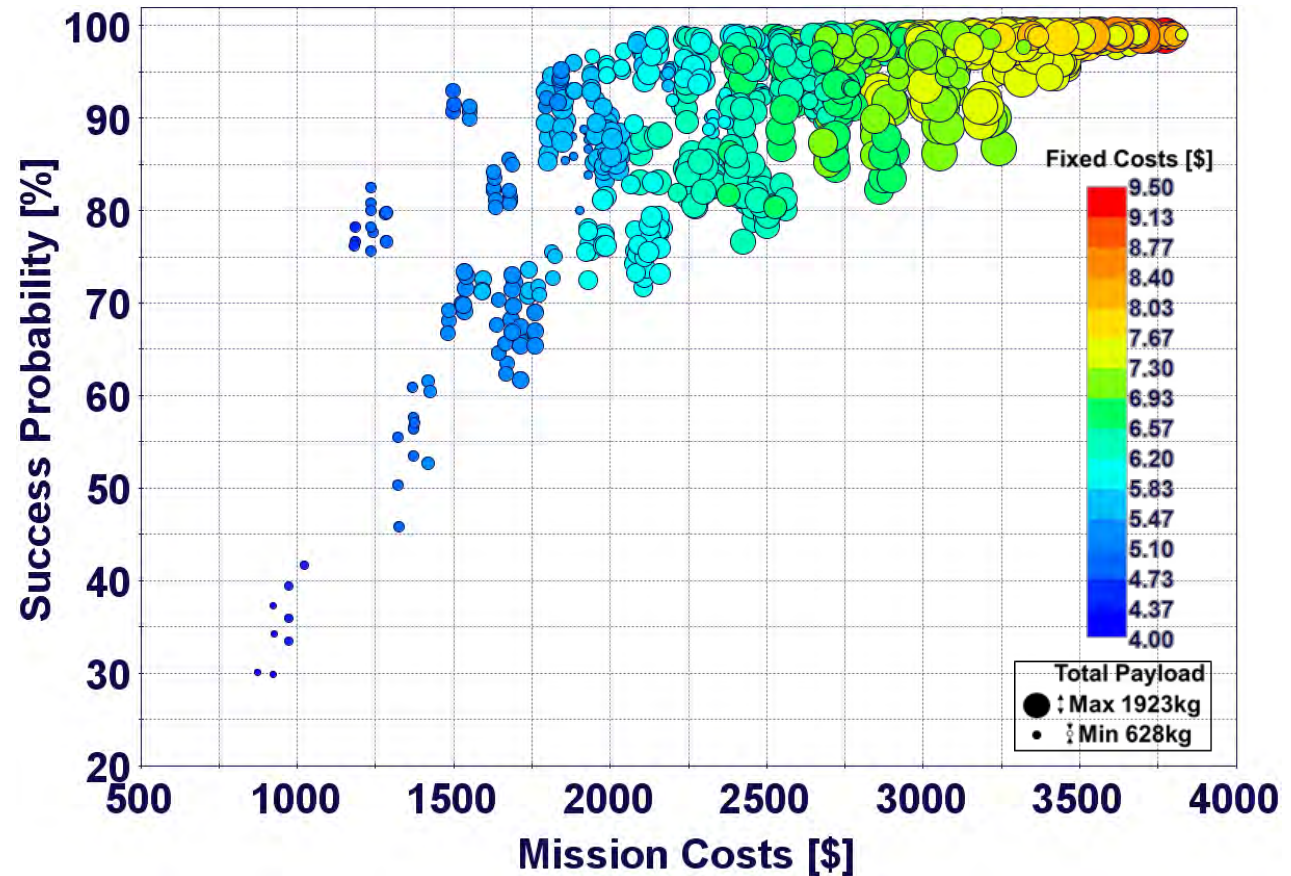
3 ACs combinations



Original  
framework

# Identifying SoS Capabilities

- Results part A
  - A fleet of 3 existing UAV designs



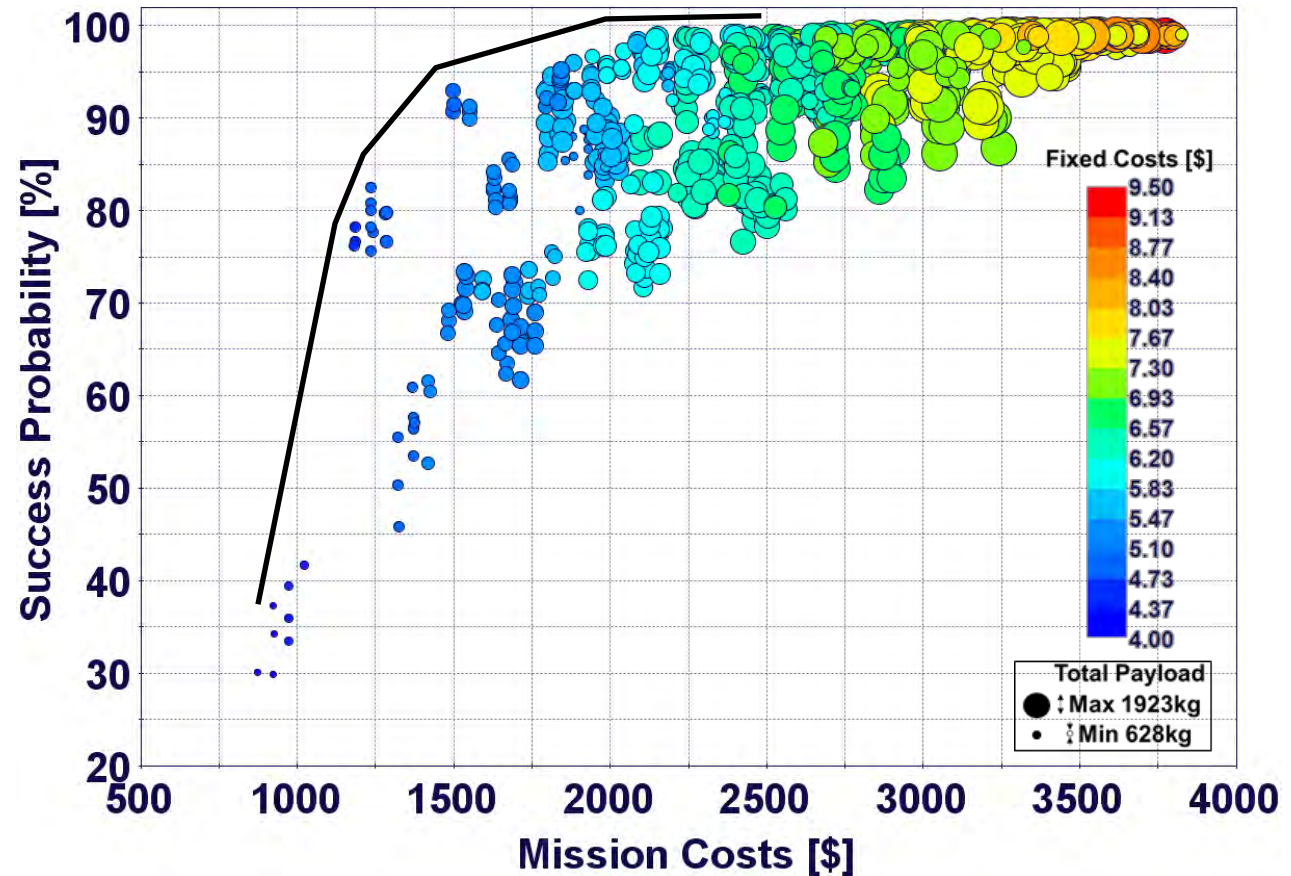


Original  
framework

# Identifying SoS Capabilities

- Results part A
  - A fleet of 3 existing UAV designs

Pareto front



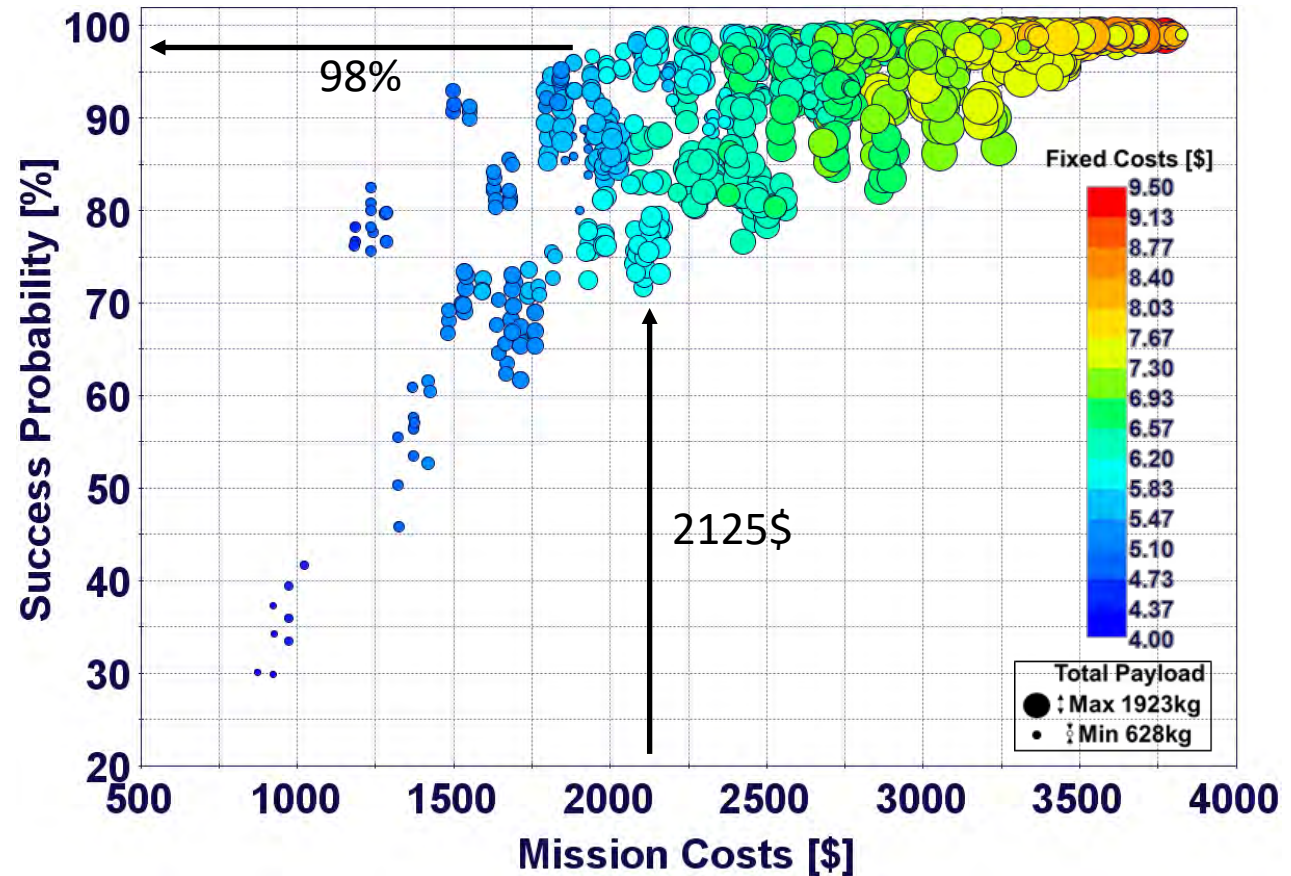
Original  
framework

# Identifying SoS Capabilities

- Results part A
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Pareto front

“Stagnation points”



Original  
framework

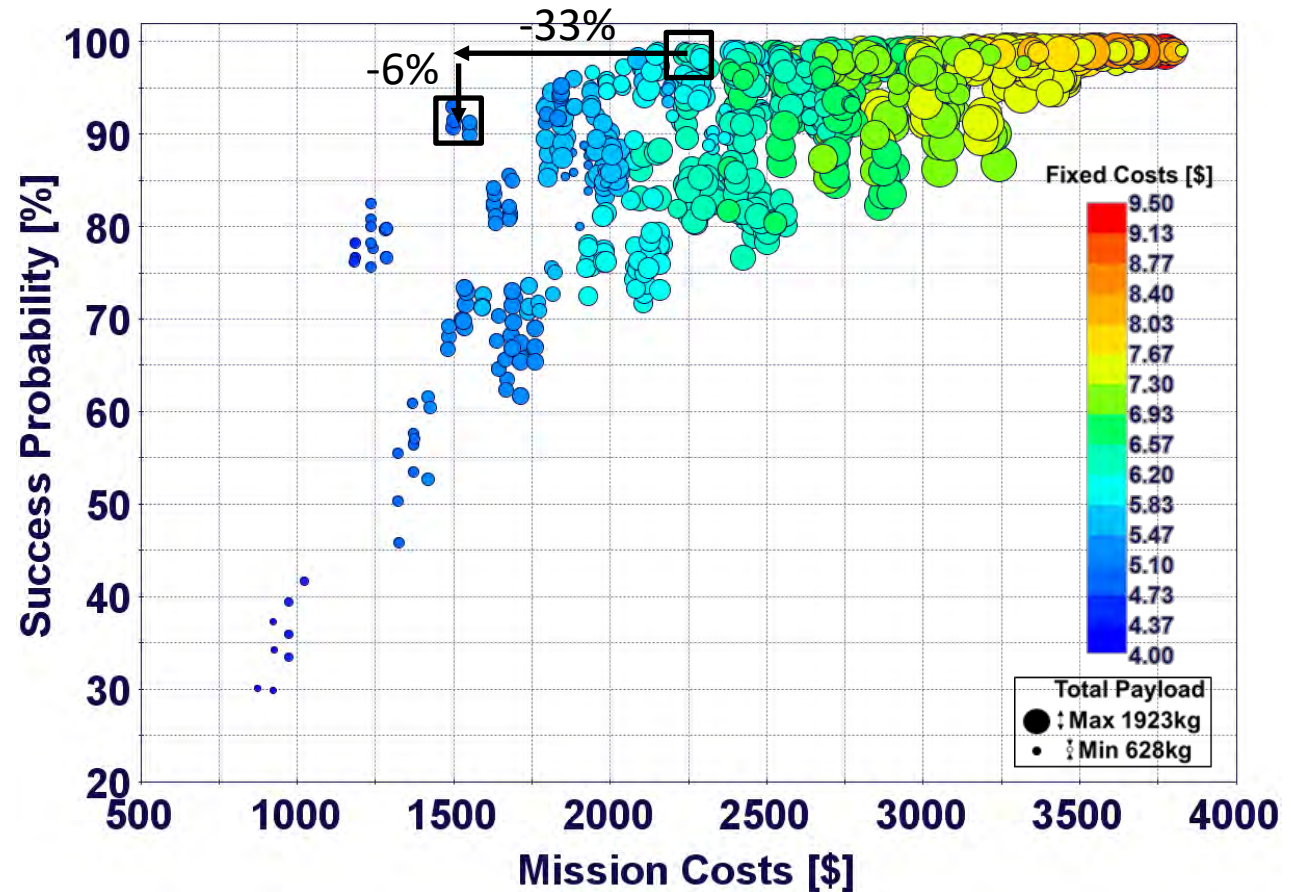
# Identifying SoS Capabilities

- Results part A
  - A fleet of 3 existing UAV designs

Pareto front

"Stagnation points"

Trade-off studies





# Identifying SoS Capabilities

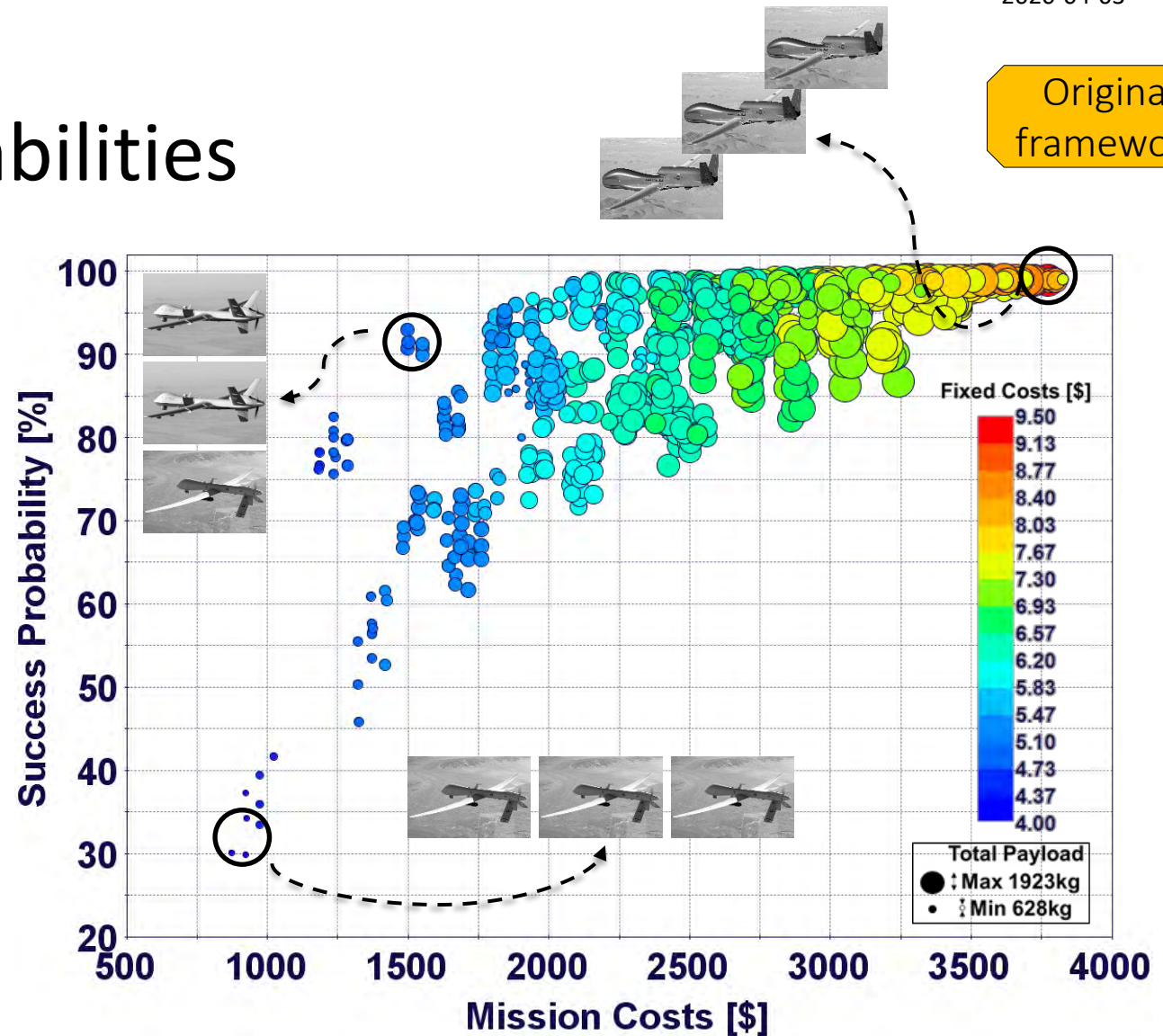
- Results part A
  - A fleet of 3 existing UAV designs

Pareto front

“Stagnation points”

Trade-off studies

UAV combinations



Original  
framework

# Identifying SoS Capabilities

- Results part A
  - A fleet of 3 existing UAV designs

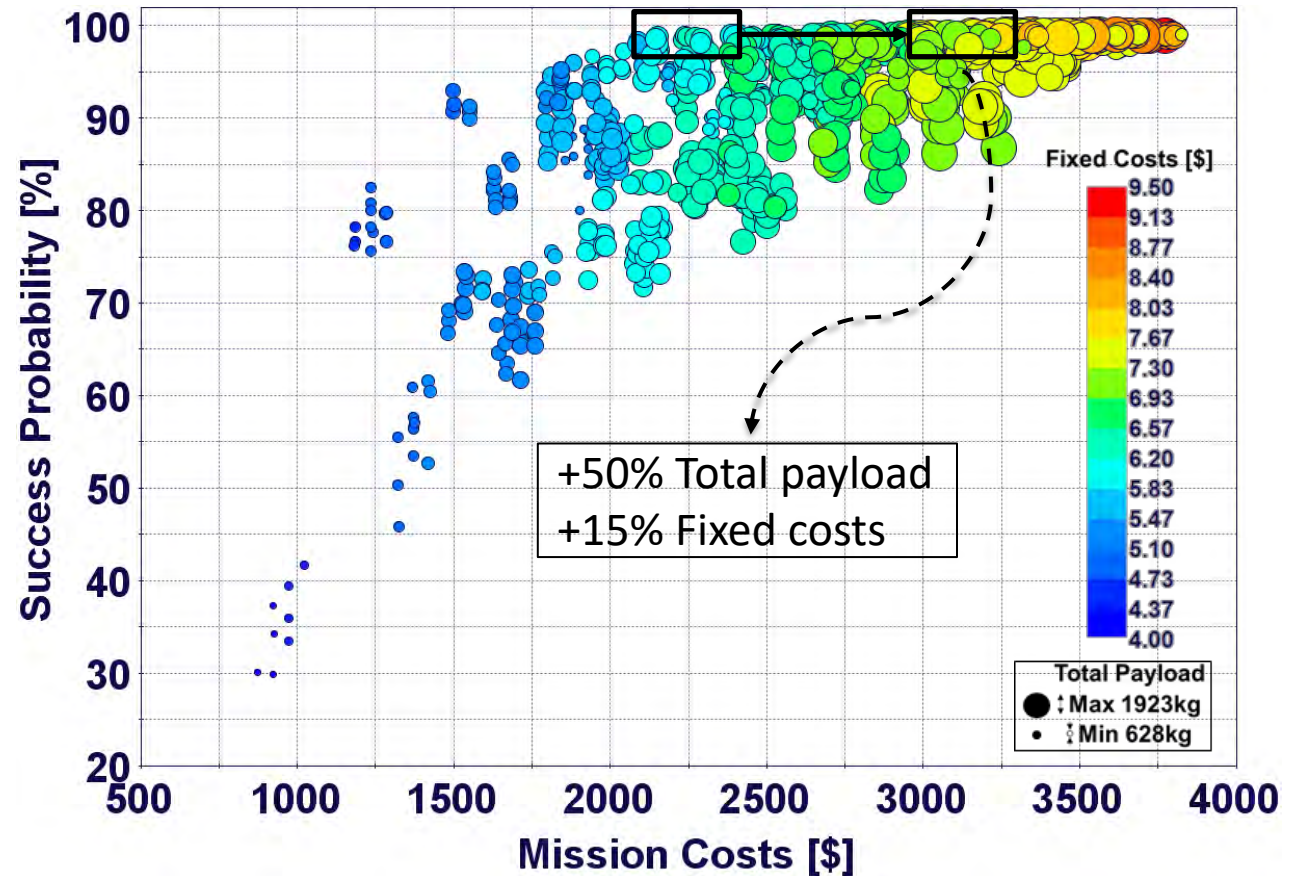
Pareto front

"Stagnation points"

Trade-off studies

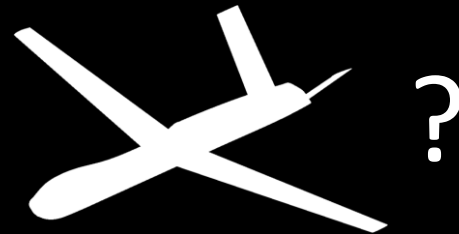
UAV combinations

More capabilities



# Case Study 2 (LF)

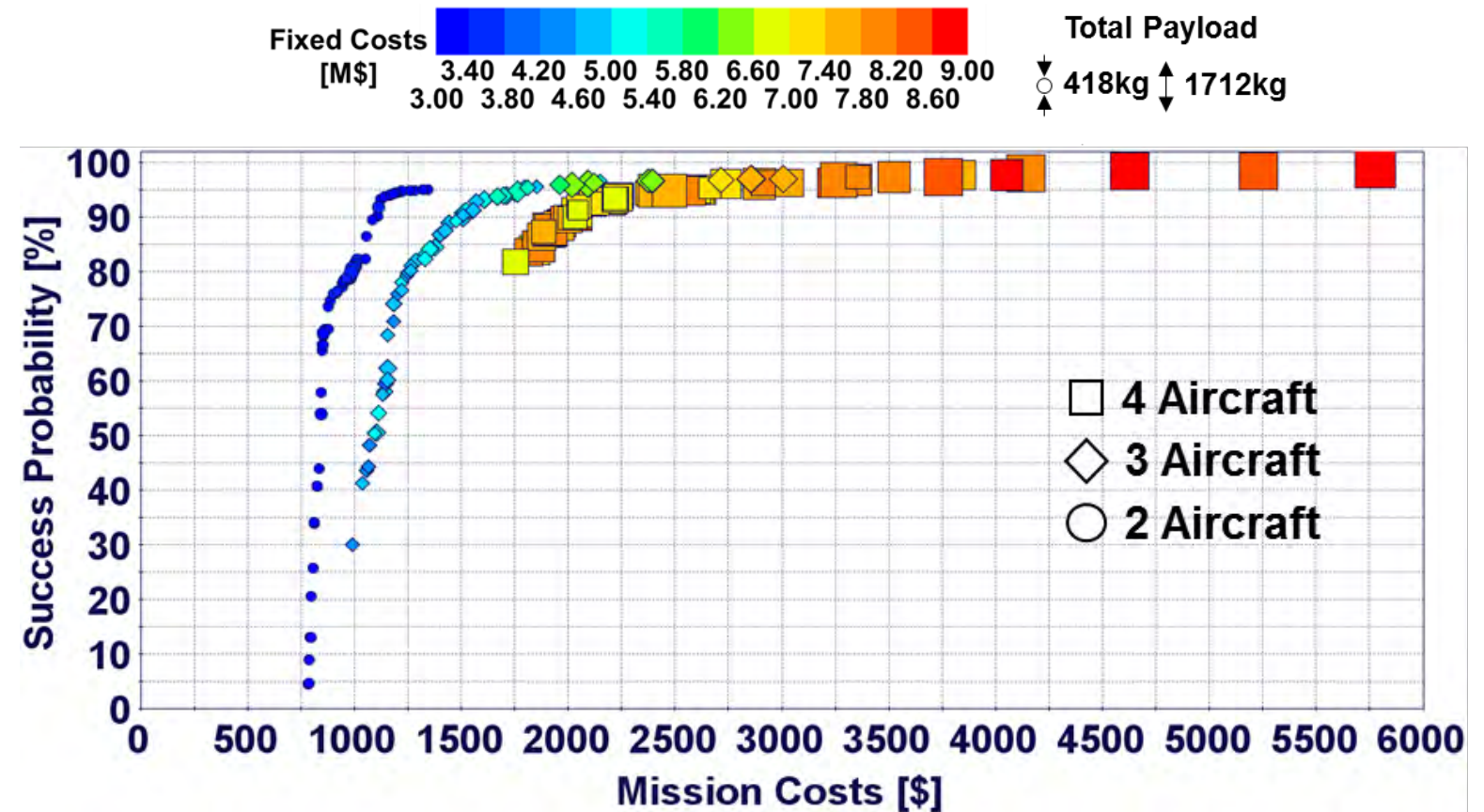
Yet-to-de-designed UAVs  
Combinations of 2-3-4 ACs



Metamodel  
framework

# Identifying SoS Capabilities

- Results part B
  - A fleet of 2-4 yet-to-be-designed UAVs



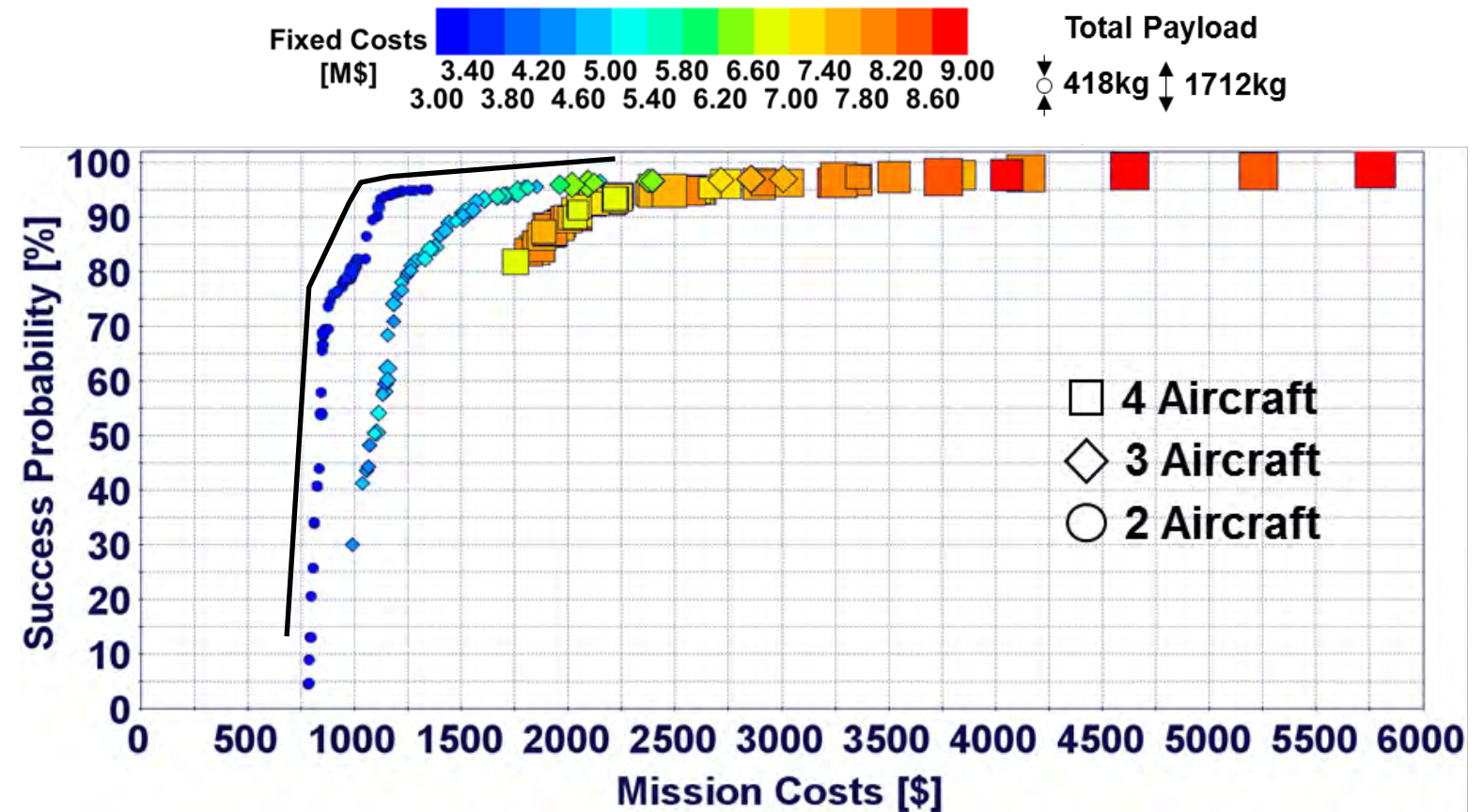


Metamodel  
framework

# Identifying SoS Capabilities

- Results part B
  - A fleet of 2-4 yet-to-be-designed UAVs

Extended Pareto front





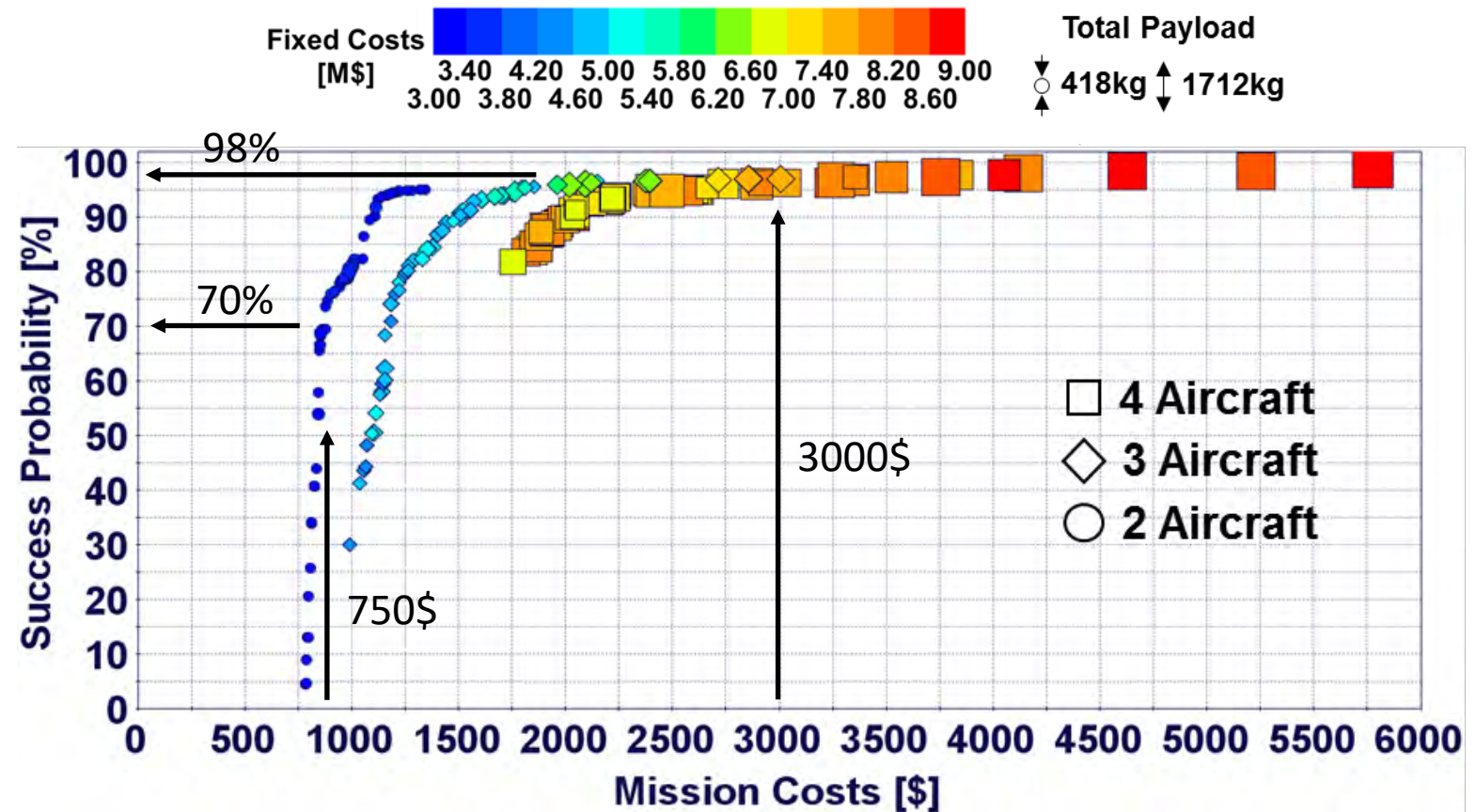
Metamodel  
framework

# Identifying SoS Capabilities

- Results part B
  - A fleet of 2-4 yet-to-be-designed UAVs

Extended Pareto front

"Stagnation points"



Metamodel  
framework

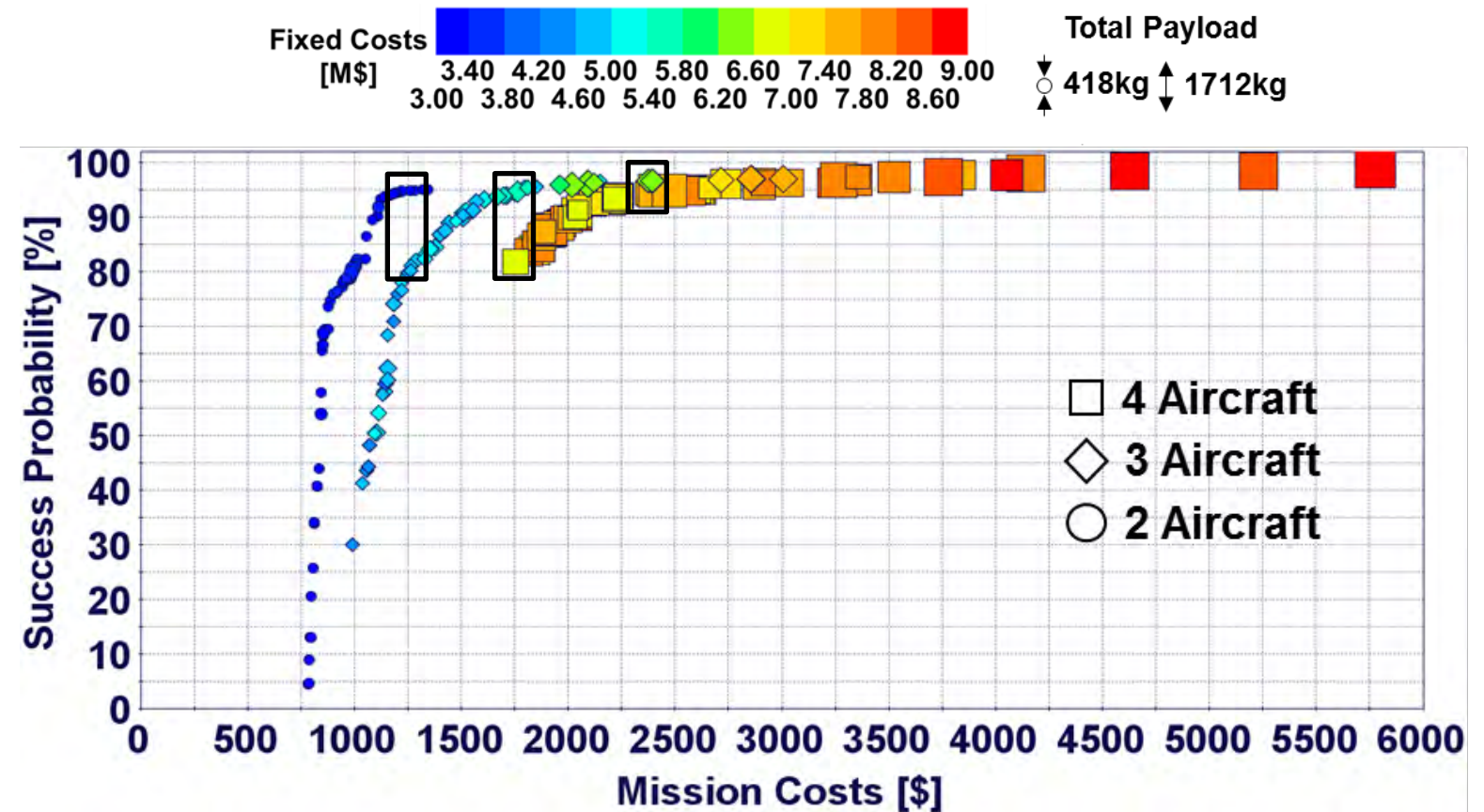
# Identifying SoS Capabilities

- Results part B
  - A fleet of 2-4 yet-to-be-designed UAVs

Extended Pareto front

"Stagnation points"

Trade-off studies



Metamodel  
framework

# Identifying SoS Capabilities

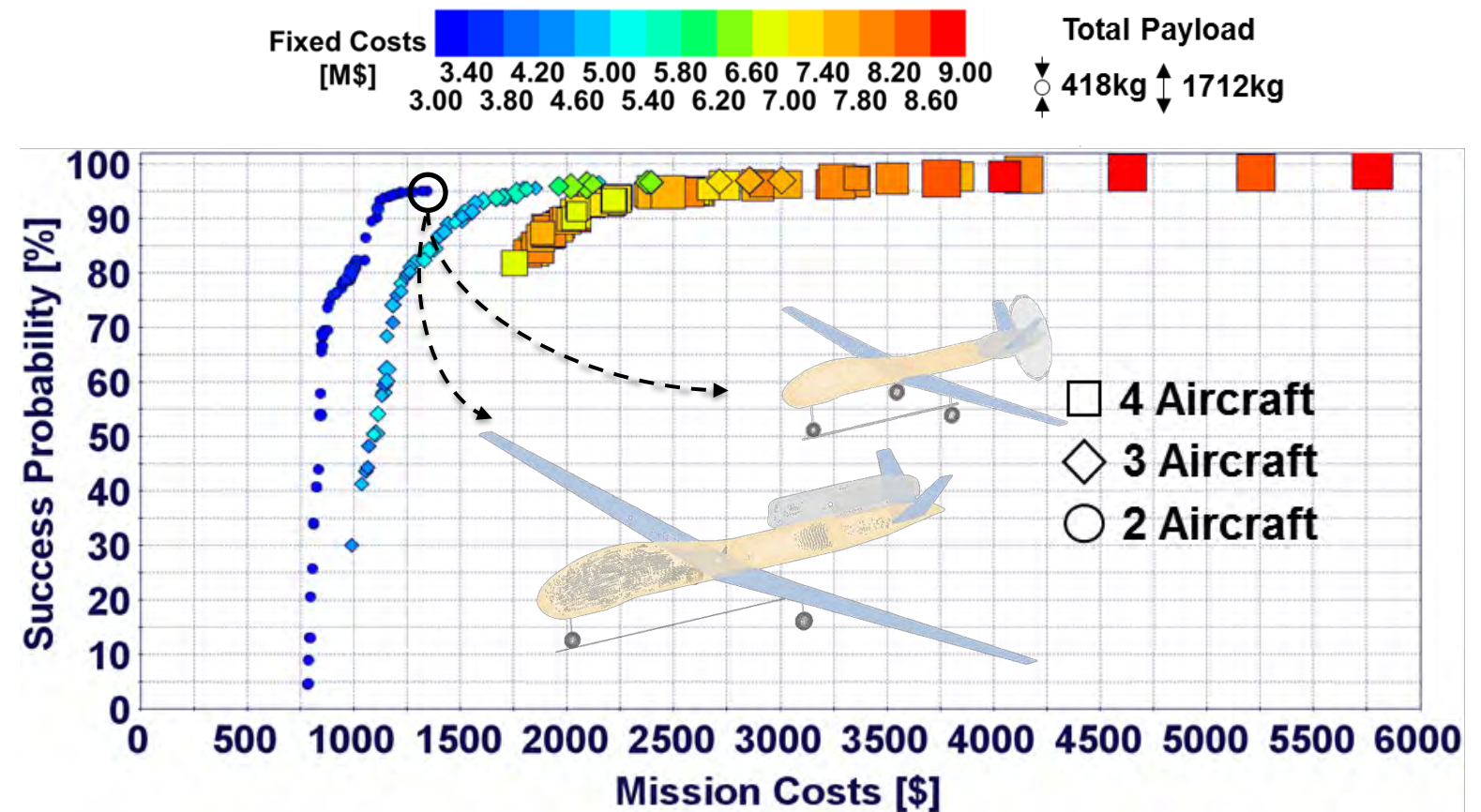
- Results part B
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Extended Pareto front

"Stagnation points"

Trade-off studies

UAV designs



# Concluding Remarks

# Summary

- Technical developments
  - A methodology for populating the design space
  - Model development at all three system levels
  - A multi-fidelity design exploration framework
  - Surrogate models as a low-fidelity alternative
- Case study results
  - MoE depend on the chosen SoS
  - SoS bring forward new capabilities
  - Strong effect of scenario, tactics, and fidelity



# What comes next?

- Airborne Early Warning & Control (AEW&C)



# Thank you for your attention

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