

xDash : RAPID-PROTOTYPING OF CYBER-PHYSICAL SYSTEMS IN WEB BROWSER

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- Context and motivations
- xDash : principles and features (+ demo)
- Some use-cases
- Conclusions and perspectives

- Eco-driving coaching (for truck fleet fuel reduction)
- Energy management (for hybrid or electric vehicle optimal battery use)
- CO2 footprint and Total Cost of Ownership (TCO) of a car based on usage questionnaire (for helping new car purchase decision)
- Cycle road network qualification using crowdsensing (for bike GPS app development)
- Pollutant emissions estimation (how driving style impacts real-driving emissions)

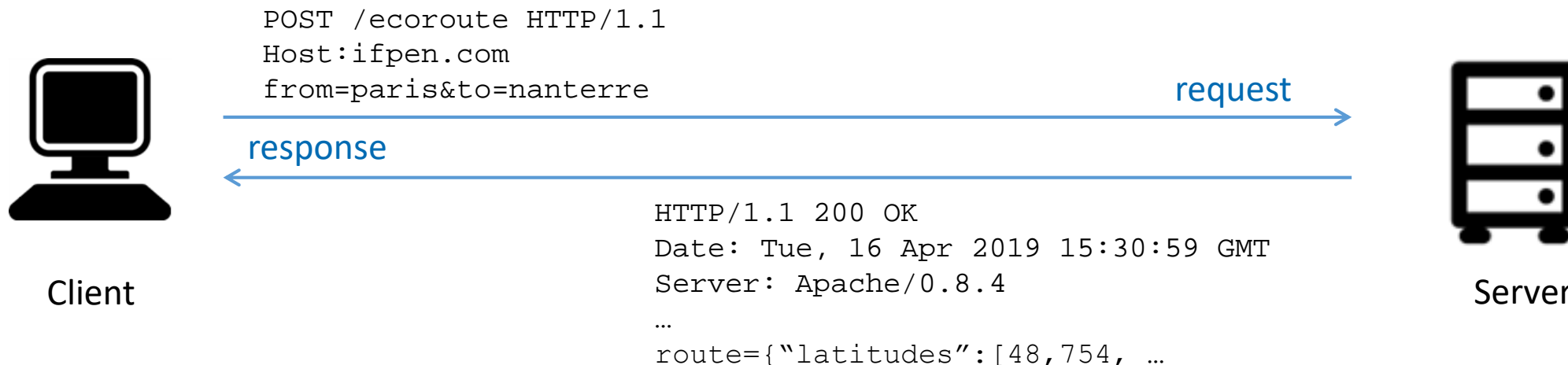


Algorithms deployed as web-services

- Connected vehicle : typical example of Cyber-physical system
- In our context, from a software engineering point of view
 - Vehicle-to-infrastructure (V2I) communications rely on web-services (over HTTP protocol)
 - Web-services follow microservices architectural principles (Service Oriented Architecture)
- Web-services bring new optimization parameters
 - At design phase
 - Open, community or company data access or query as web-service
 - Examples : road accidentology or pollution measures history, public bike stations, public transport theoretical fares ...
 - At operation phase
 - Live information about weather, traffic, routes, pollution is available from web-services ...
 - Use by real-time control algorithms (EMS, BMS, ECU) or on on-board display for driver ...
- Mobility as a Service paradigm shift

WHAT IS A WEB-SERVICE ? (IN CONNECTED MOBILITY CONTEXT)

- It is a (stateless) function (in the sense of compute science) running on a server
- Software interface is based on HTTP protocol over TCP/IP (core Internet Technology)
- Can be extended to run simulation as a web-service (adding state for long runs)



Client

Server

- Most programming languages or frameworks have libraries for calling web-services
- Many tools exist for the unit testing of web-services, such as Postman or SoapUI, but purely from software engineering point of view
- To the best of our knowledge, no cyber-physical system level tool exist for testing aggregation of web-services
 - With scientific or technologic oriented data interaction and visualization
 - With connection to simulation & scientific computation (Python)
 - With real-time execution capabilities
 - Closest tool was freeboard.io

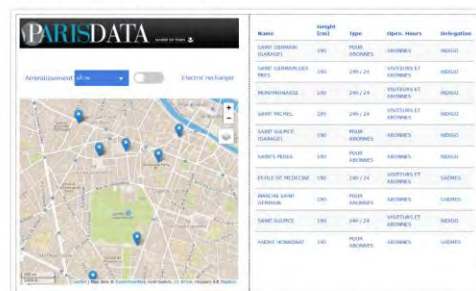
 **Need for a cyber-physical systems-level web-services aggregation and dashboarding tool**

- xDash allows technicians, scientists or engineers, not specialists in web technologies, to build their own web applications to answer these questions autonomously

Electrical mobility range

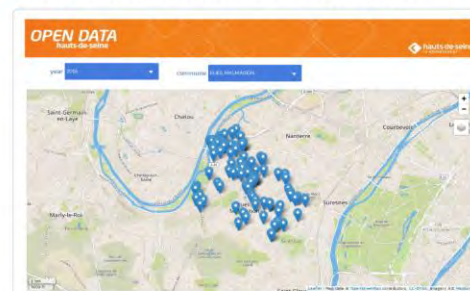
Select your departure address, your electric vehicle brand, your departure date, the weather conditions, your battery state of charge and eventually your extra load. Get average and conservative estimation of your electrical mobility range. Get the energetic characteristics of your trip

Parkings in Paris



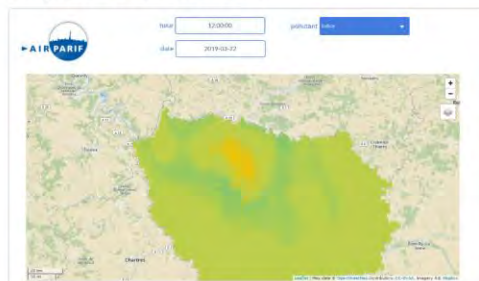
Select the Paris "arrondissement", whether electric recharger is needed. Paris open data about parkings is illustrated

Accidents in Hauts-de-Seine (92)



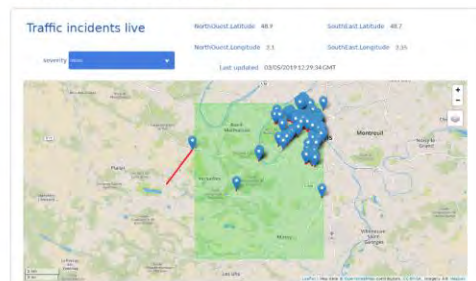
Location and description of road accidents in the Hauts-de-Seine (92) department from 2014 to 2016

Airparif map real-time



Select the date and the hour, and get pollution map of the Ile-de-France region (pollution index, NO2, O3, PM10 and PM25)

Traffic incidents live



Select a latitude/longitude box, and criticality value, to get updated about traffic incidents in that area

STIF isochrones



Fill an address, and a maximal trip duration. STIF webservices will compute the isochrones around that position

● JSON variable

```
{  
  "x": [0, 1, 2, 3, 4],  
  "y": [0, 1, 4, 9, 16],  
  "rectangle" : {  
    "longueur" : 1.23,  
    "largeur" : 5.5  
  },  
  "message" : "Success"  
}
```

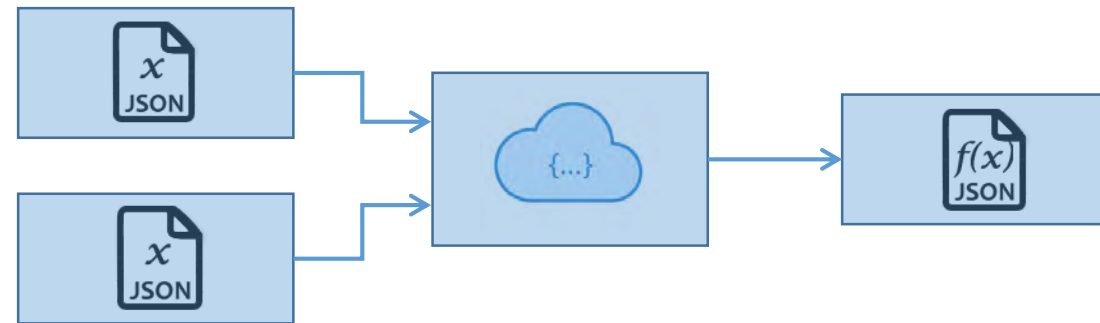
● *datasources* keyword in scripts

- Specifies a data dependency
- Specifies an execution order dependency

● Datasources (operations)

- Are stateless
- May have input, always have one output
- Have a status
 - None : never executed
 - Pending : is being executed
 - OK : successful execution
 - Error : error reported when executed
- May have an execution period
- xDash keeps track of a workspace of JSON variables corresponding to latest datasources successful evaluation

- Synchronous-reactive language
- Direct acyclic graph
 - Vertices : operations
 - Edges : data dependencies
- Data flows are JSON variables
- Execution rules
 - Datasource is executed if and only if all its predecessors completed their execution with status *OK*
 - Every time a datasource is successfully computed (status "OK"), it triggers the execution of all its successors
 - Graph execution is interrupted at datasources with status *Error* : their successors are not executed
- Similar concept as Simulink or Synchronous Modelica, but runs on a web-browser



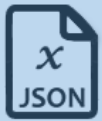
SIMPLE EXAMPLE : GEOCODING VISUALIZATION



DATASOURCE CATEGORIES

SUSTAINABLE MOBILITY

Base functions



JSON Variable



Web-service REST



Python Script



JS Script

Mobility



Map-matching



Trip conversion

IoT & real-time



Clock



MQTT



Websockets



Geolocation

Transversal



FMI simulation

Files



CSV Reader



CSV Player

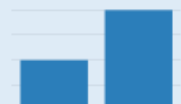


Generic reader

Plotly



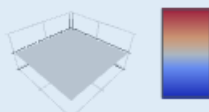
Line



Bar



Pie



3D surface



Generic

Simple controls



Checkbox



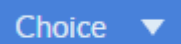
Switch



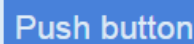
Vertical slider



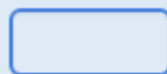
Horizontal slider



Selector



Button

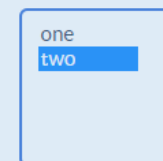


Value

Controls and displays

0	1	2
0	10	20

Table



List

Type text

Label



Image



Gauge

Maps



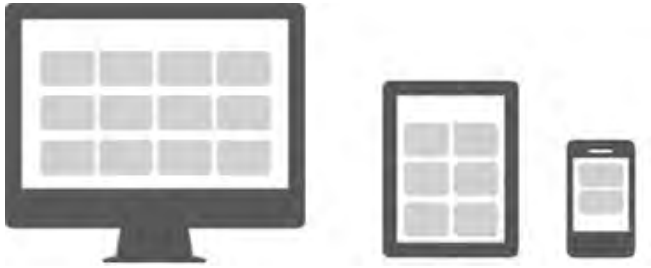
Leaflet

france

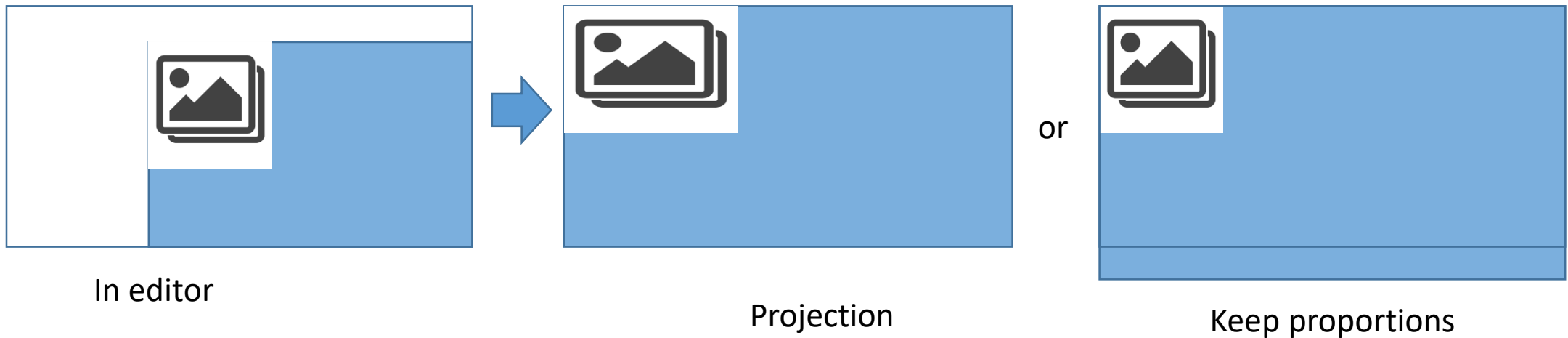
France
Flandre, Belgique

Address auto completion

- « Bootstrap » rows and columns

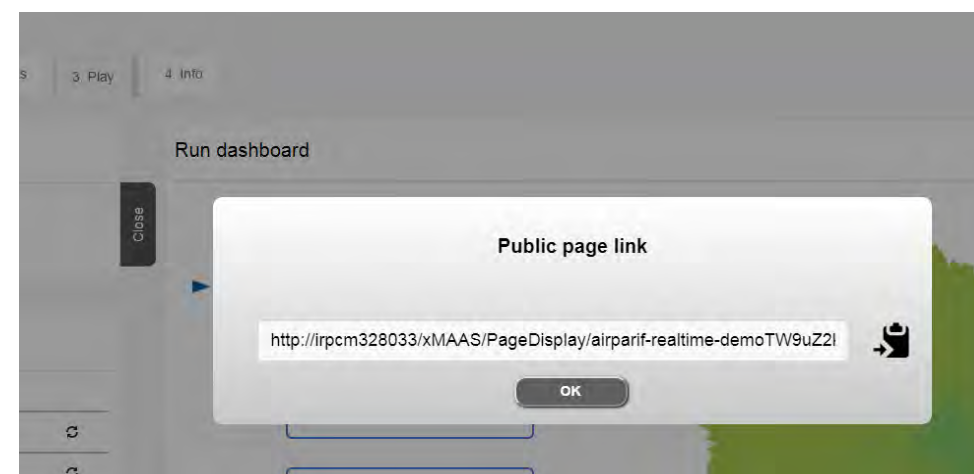
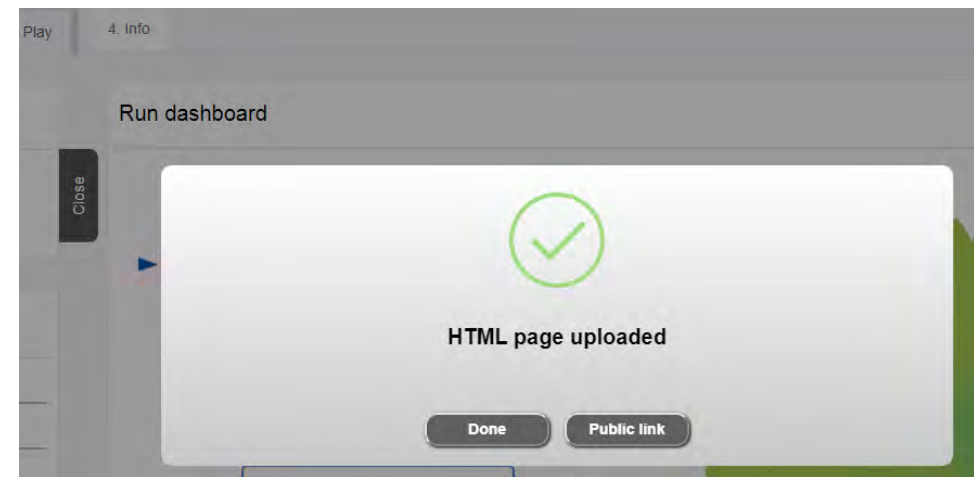
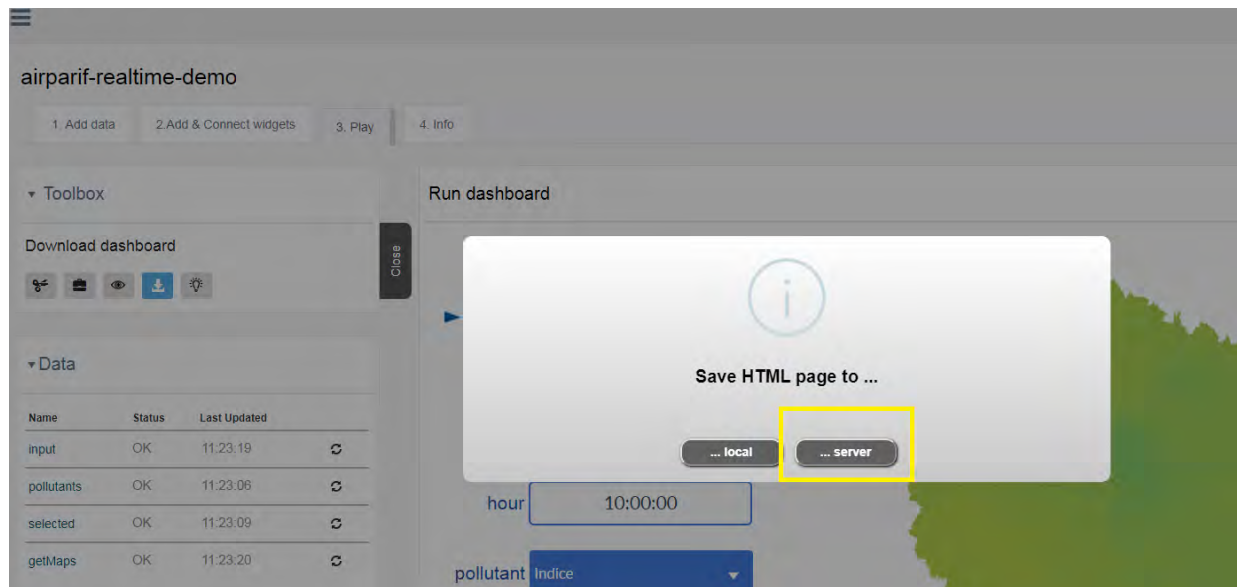


- Scaling methods



SHARING APPLICATIONS

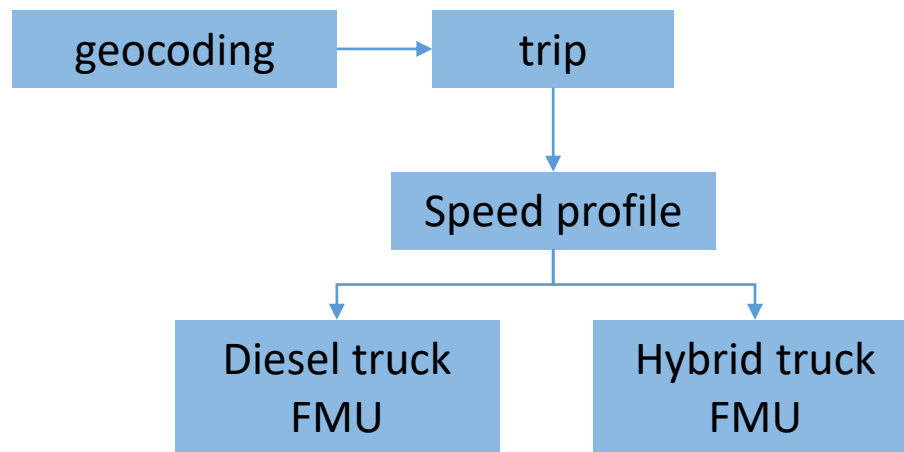
SUSTAINABLE MOBILITY



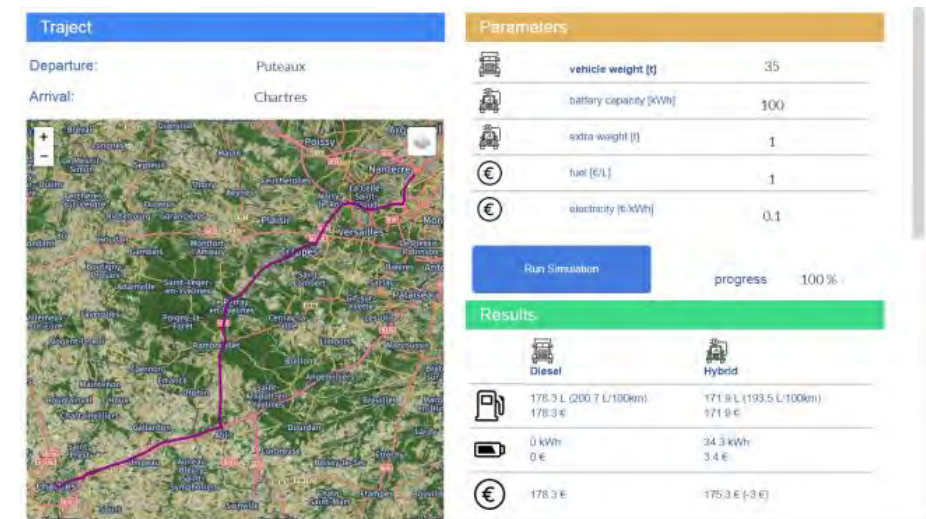
Sharing a dashboard in 3 clicks

- Main inputs : start and destination address, truck parameters, fuel & electricity prices ...
- Main outputs : cost of trip of conventional truck vs. hybrid truck
- Truck dynamic simulation models are FMUs generated from Amesim models

Aggregated web-services



Rapid prototype in xDash



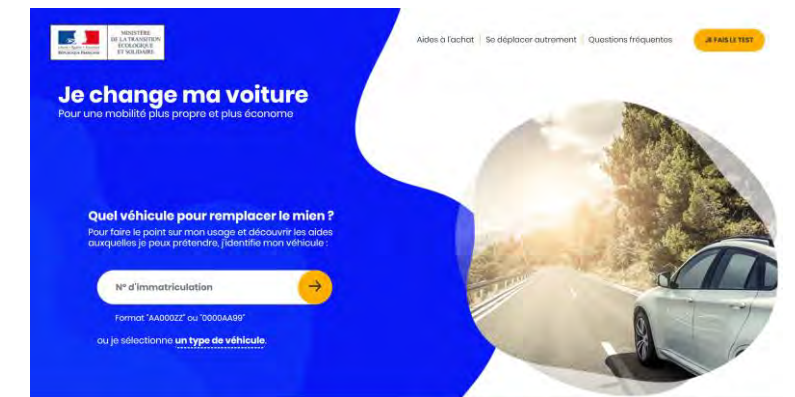
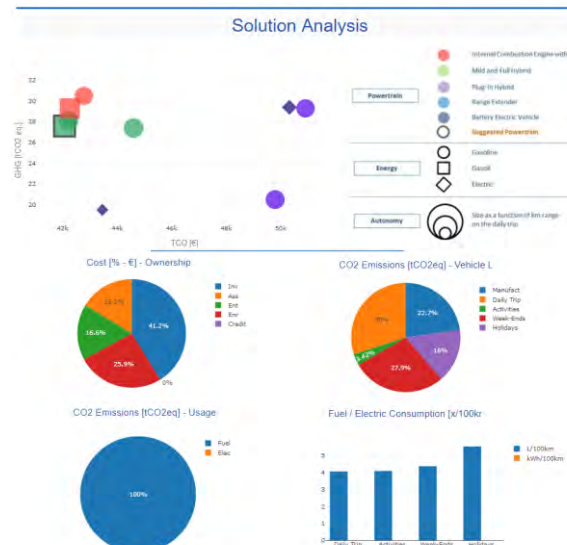
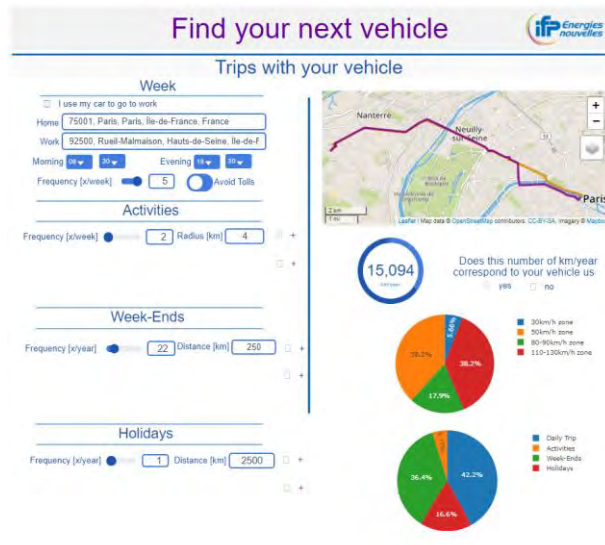
TCO & CO2 ESTIMATION FOR CAR PURCHASE ADVISE

SUSTAINABLE MOBILITY

- Main inputs : home & work addresses, other usages, ownership duration, desired segment ...
- Main outputs TCO (€) and CO2 footprint (kg) ...

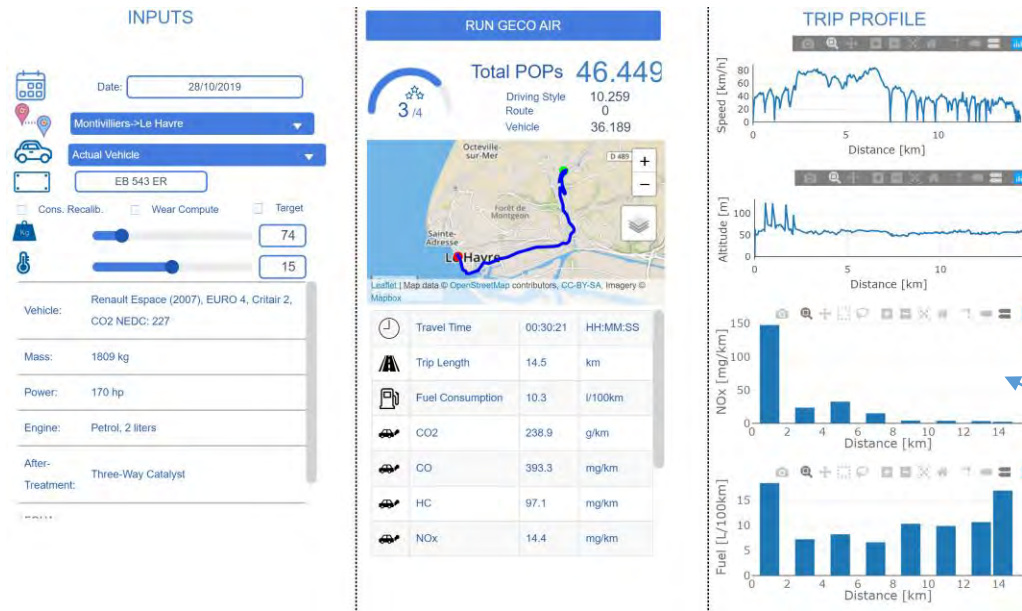
Rapid prototype in xDash

General public site : <https://jechangemavoiture.gouv.fr/>



- Main inputs : vehicle parameters, trip, road conditions from test database ...
- Main outputs : fuel consumption, CO₂, CO, HC, NO_x, PM, PM tires, PM brakes ...

Rapid prototype in xDash



Digital twin debugging

Gecoair app



● Conclusions

● xDash for

- rapid-prototyping of CPS
- demonstration
- sharing, collaboration

● Web technologies have the potential of bringing “social” and “collaborative” features to scientific computing

● xDash supports both on cloud or on-premises deployments

● We are looking for beta-testers!

● Perspectives

● xDash for AI & crowdsensing

● xDash will be publicly available soon for free use