

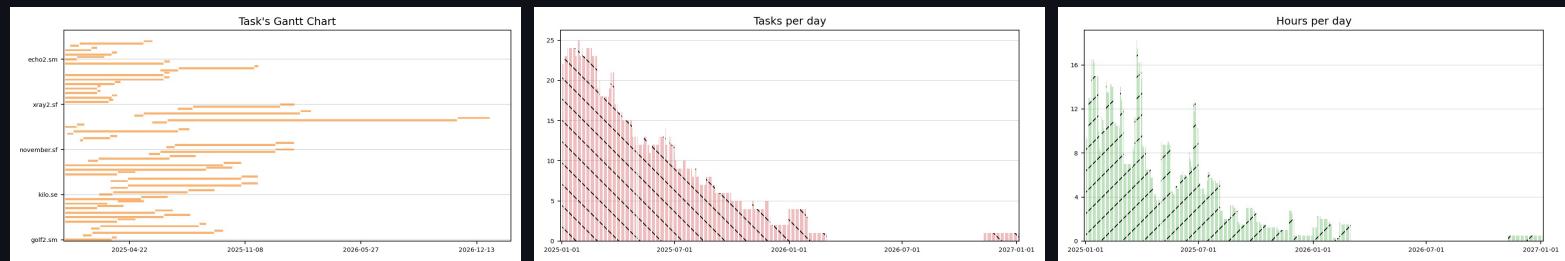
# Yumbo. Scheduling, Planning and Resource Allocation

Zbigniew Romanowski, Paweł Koczyk

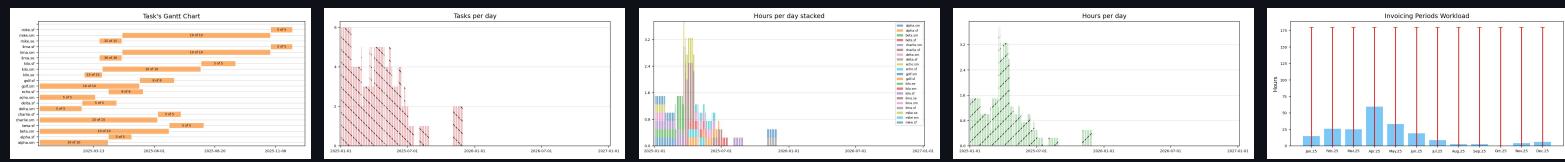
Source code, documentation and sample Excel input files can be found on [Yumbo's GitHub repository](#).

28 January 2025, 16:19:36 PM

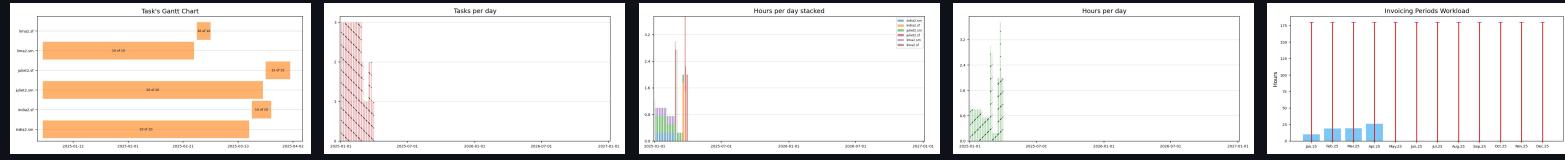
## Experts overview



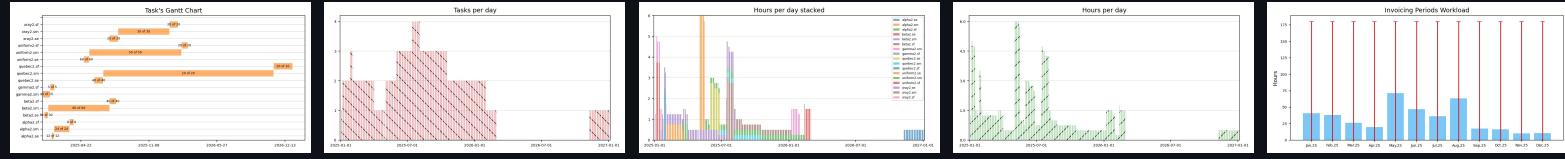
## SA.Adrian the 1st unit



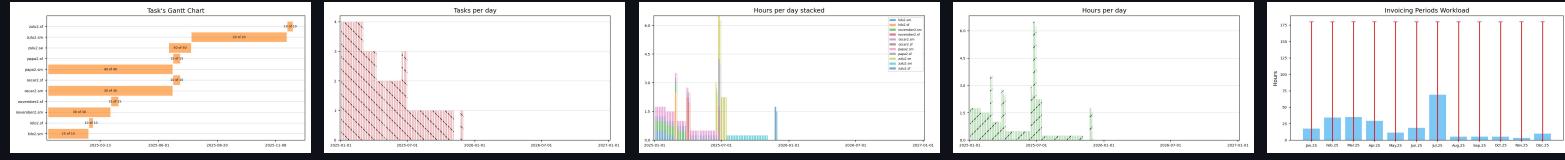
## SA.Justin the 2nd unit



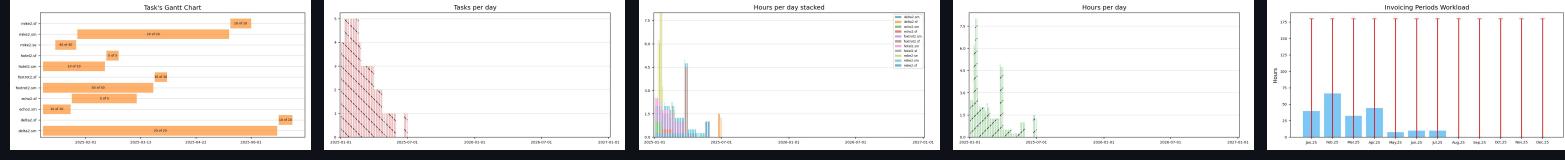
## SA.Kevin the 2nd unit



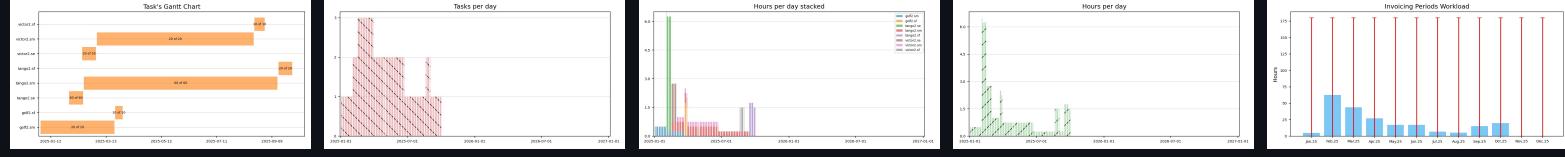
## SA.Martha the 2nd unit



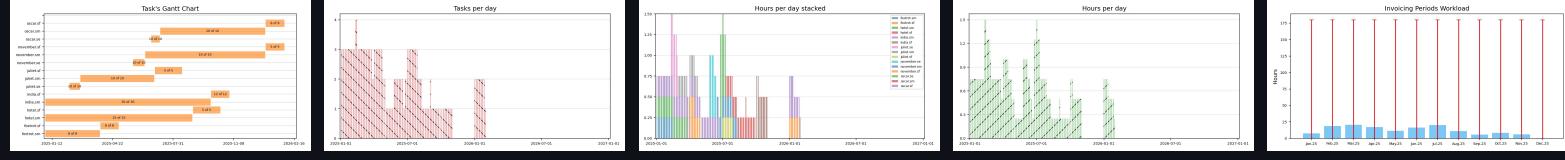
## SA.Melanie the 2nd unit



## SA.Peter the 2nd unit



## SA.Robert the 1st unit



Solver output at 28 January 2025, 16:19:41 PM

HIGHS 1.8.1: tech.outlev = 1

Running HIGHS 1.8.1 (git hash: 4a7f24a); Copyright (c) 2024 HiGHS under MIT licence terms

```

Coefficient ranges:
 Matrix [1e+00, 3e+01]
 Cost [1e+00, 1e+00]
 Bound [1e+00, 5e+02]
 RHS [2e+01, 2e+02]
Presolving model
60124 rows, 61600 cols, 124479 nonzeros 0s
98 rows, 31587 cols, 4427 nonzeros 0s
95 rows, 4173 cols, 4229 nonzeros 0s
93 rows, 4101 cols, 4157 nonzeros 0s

Solving MIP model with:
 93 rows
 4101 cols (2684 binary, 1417 integer, 0 implied int., 0 continuous)
 4157 nonzeros
MIP-Timing:      0.54 - starting analytic centre calculation

Src: B => Branching; C => Central rounding; F => Feasibility pump; H => Heuristic; L => Sub-MIP;
P => Empty MIP; R => Randomized rounding; S => Solve LP; T => Evaluate node; U => Unbounded;
z => Trivial zero; l => Trivial lower; u => Trivial upper; p => Trivial point



| Src | Proc | InQueue | Nodes  |         | B&B Tree     |              | Objective Bounds |      |      | Dynamic Constraints |         |      | Work |  |
|-----|------|---------|--------|---------|--------------|--------------|------------------|------|------|---------------------|---------|------|------|--|
|     |      |         | Leaves | Expl.   | BestBound    | BestSol      | Gap              | Cuts | InLp | ConfL.              | LpIters | Time |      |  |
| R   | 0    | 0       | 0      | 0.00%   | 11034.187377 | inf          | inf              | 0    | 0    | 0                   | 0       | 0.5s |      |  |
|     | 0    | 0       | 0      | 0.00%   | 16849.949861 | 16849.949861 | 0.00%            | 0    | 0    | 0                   | 81      | 0.6s |      |  |
|     | 1    | 0       | 1      | 100.00% | 16849.949861 | 16849.949861 | 0.00%            | 0    | 0    | 0                   | 86      | 0.6s |      |  |


```

Solving report

```

Status          Optimal
Primal bound   16849.9498607
Dual bound     16849.9498607
Gap            0% (tolerance: 0.01%)
P-D integral   1.13390511677e-18
Solution status feasible
              16849.9498607 (objective)
              0 (bound viol.)
              0 (int. viol.)
              0 (row viol.)
Timing         0.56 (total)
              0.00 (presolve)
              0.00 (solve)
              0.00 (postsolve)
Max sub-MIP depth 0
Nodes          1
Repair LPs    0 (0 feasible; 0 iterations)
LP iterations  86 (total)
              0 (strong br.)
              0 (separation)
              0 (heuristics)

HiGHS 1.8.1: optimal solution; objective 16849.94986
86 simplex iterations
1 branching nodes
absmipgap=3.63798e-12, relmipgap=2.15904e-16

"option abs_boundtol 7.105427357601002e-15;" or "option rel_boundtol 1.431744869493965e-16;" will change deduced dual values.

```

## Elapsed time for chart creation

Chart title	Chart short name	Number of calls	Elapsed time [s]	Average time per chart [s]
Hours per day stacked	simg	7	79.441	11.349
Tasks per day	timg	7	9.953	1.422
Hours per day	himg	7	9.424	1.346
Task's Gantt Chart	gimg	7	1.981	0.283
Invoicing Periods Workload	wimg	7	1.843	0.263
Plot task with its constraints	bimg	0	0.000	0.000