

## Basic Matrix and vector computations

$$(\mathbf{AB})_{ij} = \sum_{s=1}^n a_{is}b_{sj}$$

$$(\mathbf{Ax})_i = \sum_{j=1}^n a_{ij}x_j$$

**Theorem 1:** The following results hold

- i) Consider arbitrary  $m \times j$ ,  $j \times k$  and  $k \times n$  matrices  $\mathbf{A}$ ,  $\mathbf{B}$  and  $\mathbf{C}$ . Then  $(\mathbf{AB})\mathbf{C} = \mathbf{A}(\mathbf{BC})$ .
- ii) Consider arbitrary  $m \times n$  matrix  $\mathbf{A}$ ,  $n$ -dimensional vectors  $\mathbf{x}$  and  $\mathbf{y}$  and scalars  $a, b$ . We then have  $\mathbf{A}(a\mathbf{x} + b\mathbf{y}) = a\mathbf{Ax} + b\mathbf{Ay}$
- iii) Consider arbitrary  $m \times n$  matrices  $\mathbf{A}$ ,  $\mathbf{B}$  and an arbitrary  $n$ -dimensional vectors  $\mathbf{x}$ . We then have that  $(\mathbf{AB})^T = \mathbf{B}^T\mathbf{A}^T$  and  $(\mathbf{Ax})^T = \mathbf{x}^T\mathbf{A}^T$ .

# Linearly independent vectors

**Definition 3:** The vectors  $\mathbf{x}_1, \dots, \mathbf{x}_K$  in  $\mathbb{R}^n$  are **linearly independent** if the expression

$$c_1\mathbf{x}_1 + c_2\mathbf{x}_2 + \dots + c_K\mathbf{x}_K = 0$$

implies that

$$c_1 = c_2 = \dots = c_K = 0$$

**Definition 4:** Let  $\mathbf{A}$  be an arbitrary  $m \times n$  matrix where  $m \geq n$ . Now perceive the columns of  $\mathbf{A}$  as vectors in  $\mathbb{R}^m$ . The maximum number of linearly independent columns in  $\mathbf{A}$  is denoted the **rank** of  $\mathbf{A}$ . Furthermore, if the  $n$  columns of  $\mathbf{A}$  all are linearly independent  $\mathbf{A}$  is said to have full rank, i.e. the rank is  $n$ .

If  $\mathbf{A}$  does not have full rank it is said to be **singular**.

# Orthogonality and Orthonormality

**Definition 5:** The vectors  $\mathbf{x}_1, \mathbf{x}_2$  in a vectorspace  $\mathbb{R}^n$  are said to be **orthogonal** if  $\mathbf{x}_1 \cdot \mathbf{x}_2 = 0$ . Furthermore, if  $\mathbf{x}_1 \cdot \mathbf{x}_1 = \mathbf{x}_2 \cdot \mathbf{x}_2 = 1$  then  $\mathbf{x}_1, \mathbf{x}_2$  are said to be **orthonormal**.

**Theorem 3:** Orthonormal vectors are always linearly independent.

**Definition 6:** An  $m \times n$  matrix  $\mathbf{U}$  ( $m \geq n$ ) is said to be **column orthonormal** if it consists of  $n$  pairwise orthonormal columns (the columns are perceived as vectors in  $\mathbb{R}^n$ ).

If  $\mathbf{U}$  is an  $m \times n$  column orthonormal matrix then

$$(\mathbf{U}^T \mathbf{U})_{ij} = \sum_{k=1}^m \mathbf{U}_{ki} \mathbf{U}_{kj} = \begin{cases} 1 & \text{if } i = j \\ 0 & \text{if } i \neq j \end{cases} \quad \begin{matrix} \mathbf{U}^T \mathbf{U} = \mathbf{I}_n \\ \mathbf{I}_n \text{ is the } n \times n \text{ identitymatrix} \end{matrix}$$

**Definition 7:** An  $n \times n$  matrix  $\mathbf{V}$  is said to be **orthonormal** if it consists of  $n$  pairwise orthonormal columns (the columns are perceived as vectors in  $\mathbb{R}^n$ ).

## Subspace and Dimension

**Definition 8:** Consider  $S \subseteq \mathbb{R}^n$ . If for arbitrary elements  $\mathbf{x}_1, \mathbf{x}_2 \in S$  and arbitrary scalars  $c_1, c_2 \in \mathbb{R}$  applies that  $c_1\mathbf{x}_1 + c_2\mathbf{x}_2 \in S$  then  $S$  is said to be a *vector space*. The vector space  $S$  is also said to be a **subspace** of  $\mathbb{R}^n$ .

**Notice:**  $\mathbb{R}^n$  is thus a vector space.

**Definition 9:** Let  $S \subseteq \mathbb{R}^n$  be a vector space. The **dimension** of the vector space is the maximum number of linearly independent vectors, that can be found in  $S$ . Or stated differently: if  $\mathbf{u}_1, \dots, \mathbf{u}_K \in S$  are linearly independent and meet the condition that every  $y \in S$  can be written as  $y = c_1\mathbf{u}_1 + \dots + c_K\mathbf{u}_K$  then  $S$  has dimension  $K$ . The vectors  $\mathbf{u}_1, \dots, \mathbf{u}_K$  is then said to form a **basis** for  $S$ . If  $\mathbf{u}_1, \dots, \mathbf{u}_K$  are orthonormal,  $\mathbf{u}_1, \dots, \mathbf{u}_K$  is said to form an orthonormal **basis** for  $S$ .

**Notice:** Hence  $\mathbb{R}^n$  has dimension  $n$ .

# Coordinates and Distance computations

Assume that the vectors  $\mathbf{u}_1, \dots, \mathbf{u}_n$  form an orthonormal basis for  $\mathbb{R}^n$ . We know then that an arbitrary  $\mathbf{x}$  can be written as

$$\mathbf{x} = \alpha_1 \mathbf{u}_1 + \alpha_2 \mathbf{u}_2 + \dots \alpha_n \mathbf{u}_n$$

We call  $(\alpha_1, \dots, \alpha_n)$  the **coordinates** of  $\mathbf{x}$  w.r.t. the base  $\mathbf{u}_1, \dots, \mathbf{u}_n$ . We now immediately get for all  $i$  that

$$\mathbf{x} \cdot \mathbf{u}_i = \mathbf{x} \cdot (\alpha_1 \mathbf{u}_1 + \alpha_2 \mathbf{u}_2 + \dots \alpha_n \mathbf{u}_n) = \alpha_i$$

**Theorem 4:** Let  $\mathbf{u}_1, \dots, \mathbf{u}_K$  be orthonormal vectors and let

$$\mathbf{x} = \sum_{k=1}^K \alpha_k \mathbf{u}_k$$

Then  $\|\mathbf{x}\|^2 \equiv \mathbf{x} \cdot \mathbf{x} = \sum_{k=1}^K \alpha_k^2$ . "generalized Pythagorean Theorem"

## Gram-Schmidt method

Assume that the vectors  $\mathbf{x}_1, \dots, \mathbf{x}_k$  are linearly independent and let  $S$  be the subspace for which these vectors form a basis. Now we can construct a set of orthonormal vectors  $\mathbf{e}_1, \dots, \mathbf{e}_k$ , which form an orthonormal basis for  $S$  in this way:

**The Gram-Schmidt method:**

$$\mathbf{e}_1 := \mathbf{x}_1 / \|\mathbf{x}_1\|$$

For  $i := 2, \dots, k$  do {

$$\mathbf{e}_i := \mathbf{x}_i - \sum_{j=1}^{i-1} (\mathbf{x}_i \cdot \mathbf{e}_j) \mathbf{e}_j$$

$$\mathbf{e}_i := \mathbf{e}_i / \|\mathbf{e}_i\|$$

}

# Range, Null Space and the Least Squares solution

**Definition 10:** Let  $\mathbf{A}$  be an arbitrary  $m \times n$  ( $m \geq n$ ) matrix. The function  $f(\mathbf{x}) = \mathbf{Ax}$  is then said to be a **linear mapping** from  $\mathbb{R}^n \rightarrow \mathbb{R}^m$ . The **range** of the linear mapping is the set  $B(\mathbf{A}) \subseteq \mathbb{R}^m$ , that meets the condition that for any  $\mathbf{y} \in B(\mathbf{A})$  exists an  $\mathbf{x} \in \mathbb{R}^n$  such that  $\mathbf{Ax} = \mathbf{y}$ . **The null space** of the linear mapping is the set  $N(\mathbf{A}) \subseteq \mathbb{R}^n$ , that meets the condition that for any  $\mathbf{x} \in N(\mathbf{A})$  it applies that  $\mathbf{Ax} = 0$ .

**Theorem 5** Let  $\mathbf{u}_1, \dots, \mathbf{u}_K$  be an arbitrary orthonormal basis for  $B(\mathbf{A})$ . Then the least squares solution  $\mathbf{x}$  that minimizes  $\|\mathbf{Ax} - \mathbf{b}\|$  satisfies

$$\mathbf{Ax} = \sum_{k=1}^K (\mathbf{b} \cdot \mathbf{u}_k) \mathbf{u}_k \equiv \mathbf{b}_{LS}$$

# Singular Value Decomposition

**Theorem 6** Consider an arbitrary  $m \times n$  matrix  $\mathbf{A}$ . Then we can write  $\mathbf{A}$  as  $\mathbf{A} = \mathbf{U}\mathbf{W}\mathbf{V}^T$ , where  $\mathbf{U}$  is an  $m \times m$  column orthonormal matrix,  $\mathbf{V}$  is an  $n \times n$  orthonormal matrix and  $\mathbf{W}$  is an  $n \times n$  diagonal matrix having non-negative diagonal elements  $w_1, \dots, w_n$  ordered such that  $w_1 \geq w_2 \geq \dots \geq w_n$ . This is said to be a **Singular Value Decomposition** (SVD) of  $\mathbf{A}$ .

$$\begin{pmatrix} \mathbf{A} \end{pmatrix} = \begin{pmatrix} \mathbf{U} \end{pmatrix} \cdot \begin{pmatrix} w_1 & & & \mathbf{0} \\ & w_2 & & \\ & & \dots & \\ \mathbf{0} & & & \dots & w_n \end{pmatrix} \cdot \begin{pmatrix} \mathbf{V}^T \end{pmatrix}$$



$\mathbf{A} = \mathbf{U}\mathbf{W}\mathbf{V}^T$ , where  $\mathbf{U}$  is an  $m \times n$  column orthonormal matrix,  $\mathbf{V}$  is an  $n \times n$  orthonormal matrix and  $\mathbf{W}$  is an  $n \times n$  diagonal matrix having non-negative diagonal elements  $w_1, \dots, w_n$  ordered such that  $w_1 \geq w_2 \geq \dots \geq w_n$ .

**Theorem 7** Consider an arbitrary  $m \times n$  matrix  $\mathbf{A}$  and assume that for  $\mathbf{W}$  it applies that  $w_1, \dots, w_K$  are positive and  $w_{K+1}, \dots, w_n$  are equal to zero. Then it applies that

- i)  $N(\mathbf{A})$  has dimension  $n - K$  and the last  $n - K$  columns of  $\mathbf{V}$  form an orthonormal basis for  $N(\mathbf{A})$ .
- ii)  $B(\mathbf{A})$  has dimension  $K$  and the first  $K$  columns of  $\mathbf{U}$  form an orthonormal basis for  $B(\mathbf{A})$ .
- iii) The SVD solution  $\mathbf{x} = \mathbf{V}\tilde{\mathbf{W}}^{-1}\mathbf{U}^T\mathbf{b}$ , where  $[\tilde{\mathbf{W}}^{-1}]_{jj} = 0$  if  $\mathbf{W}_{jj} = 0$ , otherwise  $[\tilde{\mathbf{W}}^{-1}]_{jj} = 1/\mathbf{W}_{jj}$ , is the least squares solution to  $\mathbf{A}\mathbf{x} = \mathbf{b}$ . (Notice that it then follows that if all of the  $\mathbf{W}_{jj}$ 's are positive, i.e.  $\mathbf{A}$  has full rank it applies that  $\mathbf{x} = \mathbf{V}\mathbf{W}^{-1}\mathbf{U}^T\mathbf{b}$  is the least squares solution to  $\mathbf{A}\mathbf{x} = \mathbf{b}$ ).

$\mathbf{A} = \mathbf{U}\mathbf{W}\mathbf{V}^T$ , where  $\mathbf{U}$  is an  $m \times n$  column orthonormal matrix,  $\mathbf{V}$  is an  $n \times n$  orthonormal matrix and  $\mathbf{W}$  is an  $n \times n$  diagonal matrix having non-negative diagonal elements  $w_1, \dots, w_n$  ordered such that  $w_1 \geq w_2 \geq \dots \geq w_n$ .

IF !!!  $w_1, \dots, w_K$  are positive and  $w_{K+1}, \dots, w_n$  are equal to zero

- i)  $N(\mathbf{A})$  has dimension  $n - K$  and the last  $n - K$  columns of  $\mathbf{V}$  form an orthonormal basis for  $N(\mathbf{A})$ .
- ii)  $B(\mathbf{A})$  has dimension  $K$  and the first  $K$  columns of  $\mathbf{U}$  form an orthonormal basis for  $B(\mathbf{A})$ .

**Proof:** As  $\mathbf{V}$  is orthonormal the columns  $\mathbf{v}_1, \dots, \mathbf{v}_n$  are orthonormal and thus form an orthonormal basis for  $\mathbb{R}^n$ . Then we can write an arbitrary  $\mathbf{x} \in \mathbb{R}^n$  as  $\mathbf{x} = c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + \dots + c_n\mathbf{v}_n$ . Now we can calculate

$$\begin{aligned}\mathbf{Ax} &= \mathbf{U}\mathbf{W}\mathbf{V}^T(c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + \dots + c_n\mathbf{v}_n) \\ &= c_1\mathbf{U}\mathbf{W}\mathbf{V}^T\mathbf{v}_1 + c_2\mathbf{U}\mathbf{W}\mathbf{V}^T\mathbf{v}_2 + \dots c_n\mathbf{U}\mathbf{W}\mathbf{V}^T\mathbf{v}_n\end{aligned}$$

$$\mathbf{A}(a\mathbf{x} + b\mathbf{y}) = a\mathbf{Ax} + b\mathbf{Ay}$$

We notice that  $\mathbf{V}^T\mathbf{v}_i = (0, \dots, 0, 1, 0, \dots, 0)$  where the 1 is at the  $i$ 'th position. Insertion gives us

$$\mathbf{Ax} = c_1w_1\mathbf{u}_1 + c_2w_2\mathbf{u}_2 + \dots c_nw_n\mathbf{u}_n$$

$\mathbf{A} = \mathbf{U}\mathbf{W}\mathbf{V}^T$ , where  $\mathbf{U}$  is an  $m \times n$  column orthonormal matrix,  $\mathbf{V}$  is an  $n \times n$  orthonormal matrix and  $\mathbf{W}$  is an  $n \times n$  diagonal matrix having non-negative diagonal elements  $w_1, \dots, w_n$  ordered such that  $w_1 \geq w_2 \geq \dots \geq w_n$ .

iii) The SVD solution  $\mathbf{x} = \mathbf{V}\tilde{\mathbf{W}}^{-1}\mathbf{U}^T\mathbf{b}$ , where  $[\tilde{\mathbf{W}}^{-1}]_{jj} = 0$  if  $\mathbf{W}_{jj} = 0$ , otherwise  $[\tilde{\mathbf{W}}^{-1}]_{jj} = 1/\mathbf{W}_{jj}$ , is the least squares solution to  $\mathbf{A}\mathbf{x} = \mathbf{b}$ .

In order to show iii), i.e. that the SVD solution is the same as the least squares solution we exploit that we know that the first  $K$  columns of  $\mathbf{U}$  form an orthonormal basis for the range of  $\mathbf{A}$ . I.e. that the nearest point in  $B(\mathbf{A})$  (the least squares mapping) according to Theorem 5 is given by  $\mathbf{b}_{LS} = \sum_{j=1}^K (\mathbf{u}_j \cdot \mathbf{b}) \mathbf{u}_j$ . Now let  $\mathbf{x}$  be the SVD solution. I.e.

$$\mathbf{A}\mathbf{x} = \sum_{k=1}^K (\mathbf{b} \cdot \mathbf{u}_k) \mathbf{u}_k \equiv \mathbf{b}_{LS}$$

$$\begin{aligned} \mathbf{A}\mathbf{x} &= (\mathbf{U}\mathbf{W}\mathbf{V}^T)(\mathbf{V}[\tilde{\mathbf{W}}^{-1}]\mathbf{U}^T\mathbf{b}) = \mathbf{U}(\mathbf{W}[\tilde{\mathbf{W}}^{-1}]\mathbf{U}^T\mathbf{b}) \\ &= [\mathbf{u}_1 \dots \mathbf{u}_K | \mathbf{u}_{K+1} \dots \mathbf{u}_n] \begin{bmatrix} \mathbf{u}_1 \cdot \mathbf{b} \\ \mathbf{u}_2 \cdot \mathbf{b} \\ \vdots \\ \mathbf{u}_K \cdot \mathbf{b} \\ - - - \\ 0 \\ \vdots \\ 0 \end{bmatrix} = \sum_{j=1}^K (\mathbf{u}_j \cdot \mathbf{b}) \mathbf{u}_j = \mathbf{b}_{LS} \end{aligned}$$